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# *FLoware Software Guide*

Version 1.7  
July 8, 2022  
PN 22100080D

*for dispense system models:*

DS Series  
MAX Series  
MAX II Series

*for use with:*

FLoware® Software v2.9J +

prepared by GPD Global® Documentation Department



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**IMPORTANT:** Operation of a damaged machine may cause personal injury and invalidate the warranty.

<p><b>IMPORTANT:</b> L'utilisation d'une machine endommagée peut entraîner des blessures personnelles et invalider la garantie.</p>	<p><b>WICHTIG</b> Die Bedienung einer beschädigten Maschine kann zu Verletzungen des Bedieners sowie zur Ungültigkeit der Garantie führen.</p>	<p><b>IMPORTANTE</b> Il funzionamento di un'apparecchiatura danneggiata può causare lesioni personali e invalidare la garanzia.</p>	<p><b>IMPORTANTE</b> La utilización de una máquina averiada puede provocar lesiones e invalidar la garantía.</p>
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# Safety Notices

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The complete translation of notices used throughout this document may be referenced here. Links to these translations are provided in the procedural text when applicable.

Translated versions of the following safety precautions are used throughout this document and are listed together here:

**Translations:**

- [Consignes de sécurité](#)
- [Sicherheitsanweisungen](#)
- [Istruzioni di sicurezza](#)
- [Instrucciones de seguridad](#)

## Warnings

 **WARNING** The content of this section is NOT recommended for use by anyone besides GPD Global personnel or those working under the direct guidance of GPD Global personnel. Improper application of this information can lead to serious complications in FLOWare Software operations. Any non-GPD Global employee who uses this information beyond the stated application specified by GPD Global Service Department personnel is in danger of causing personal injury and invalidating their machine warranty.

 **WARNING** GPD Global is NOT responsible for loss of configuration or programs if a current backup is not available.

 **WARNING** Care must be taken if subtypes are moved from one machine to another since subtypes relate to both the hardware and software..

## Precautions

 **CAUTION** DO NOT override the safety package or else personal injury could result.

 **CAUTION** DO NOT open the safety shielding while a program is running or a safety violation message will appear and the program will abort.

 **CAUTION** The gantry moves IMMEDIATELY to the coordinates designated in the corresponding coordinate fields. MOVE TO can be used to verify previously taught coordinates.

 **IMPORTANT** Making adjustments to camera focus or lighting conditions may affect all patterns used by your programs and thus require you to modify your patterns accordingly.

 **IMPORTANT** Only program (or shape) lines with no feature ID or with selected feature ID will run.

## Precaution Translations

### Consignes de sécurité

 **ATTENTION** Le contenu de cette section N'est PAS recommandé pour une utilisation par d'autres personnes en dehors du personnel de GPD Global ou des personnes travaillant sous les ordres directs du personnel de GPD Global. Une mauvaise application de ces informations peut aboutir à de sérieuses complications dans le fonctionnement du logiciel FLOWare. Toute personne qui n'est pas un/e employé/e de GPD Global et qui utilise ces informations en dehors de l'application spécifiée ici par le personnel du service d'entretien de GPD Global risque de se blesser et de vicier la garantie de leur machine. Bien que nos clients souhaitent souvent utiliser cette fonction de leur logiciel, GPD Global n'est pas responsable de son utilisation. Le contrôle direct des fonctions peut endommager l'équipement et interrompre le fonctionnement du programme si l'opérateur active ces contrôles au mauvais moment ou dans le désordre.

 **ADVERTISSEMENT** GPD Global n'est PAS responsable de la perte de configuration ou de programmes si une copie de sauvegarde tenue à jour n'est pas disponible.

 **ATTENTION** Faire attention si les sous- types sont déplacés d'une machine à l'autre car les sous-types communiquent à la fois avec la machine et le logiciel.

 **ATTENTION** NE PAS neutraliser le dispositifs de sécurité pour éviter des blessures corporelles.

 **ATTENTION** NE PAS ouvrir l'écran de protection quand un programme est en cours d'exécution, sinon un message de violation de la sécurité apparaîtra et le programme sera interrompu.

 **ATTENTION** Le portique se déplace IMMEDIATEMENT lorsque le bouton MOVE TO (ALLER VERS) est activé. Avant d'utiliser le bouton MOVE TO (ALLER VERS), vérifier que le passage est dégagé entre la position courante du portique et les coordonnées de destination.

 **IMPORTANT** Tout changement de la mise au point de la caméra ou des conditions d'éclairage peut affecter tous les modeles utilisés par vos programmes. Vous devez donc modifier vos modeles en conséquences.

 **IMPORTANT** Seules les lignes de programmation (ou de traçage de forme) sans code-objet ou avec code-objet sélectionné seront exécutées.

## Sicherheitsanweisungen

-  **WARNUNG** Der Inhalt dieses Abschnitts ist NICHT zur Anwendung durch Dritte empfohlen, sondern ausschließlich für Mitarbeiter von GPD Global bzw. für geschultes Personal unmittelbar unter Anleitung von GPD Global bestimmt. Eine unsachgemäße Ausführung dieser Anweisungen kann zu erheblichen Problemen beim Betrieb der FLOWare Software führen. Jeder nicht von GPD Global autorisierte Mitarbeiter, der diese Anleitungen außerhalb der vom GPD Global Service Department Personal spezifizierten Applikationen anwendet, setzt sich der Gefahr von Personenschäden aus; gleichzeitig erlöschen dadurch sämtliche Gewährleistungsansprüche für die Maschine. Obwohl unsere Kunden oftmals Zugriff auf diesen Software-Zusatz verlangen, übernimmt GPD Global keinerlei Haftung für deren Einsatz. Die direkte Steuerung der Features kann zu Beschädigungen der Fertigungsausstattung und zur Störung des Programmablaufs führen, wenn die Bedienperson diese Steuerungen zum falschen Zeitpunkt oder in nicht korrekter Reihenfolge aktiviert.
-  **ACHTUNG** GPD Global haftet NICHT für den Verlust der Konfiguration oder von Programmen, wenn kein Notstrom zur Verfügung steht
-  **VORSICHT!** Vorsicht beim Transferieren von Teilen des Programms von einer Maschine auf die nächste; diese Routinen sind sowohl an die Hardware als auch an die Software gekoppelt.
-  **VORSICHT!** Setzen Sie NIEMALS die Sicherheitseinrichtungen ausser Kraft, es koennte Personenschaden entstehen.
-  **VORSICHT!** Bei laufendem Programm dürfen Sie die Schutzabdeckung NICHT öffnen. Andernfalls wird ein Sicherheitsverstoß gemeldet und das Programm abgebrochen.
-  **VORSICHT!** Die bewegliche Portal-Einheit wird durch Drücken des MOVE TO Knopfes SOFORT in Gang gesetzt. Bevor der MOVE TO Knopf aktiviert wird, muss sichergestellt sein, dass ein klarer Pfad zwischen der aktuellen Position des Portals und den spezifizierten Koordinaten gegeben ist.
-  **WICHTIG!** Jegliche Justierungen des Kamera-Fokus' oder der Beleuchtungskonditionen können Auswirkungen auf sämtliche im Programm verwendeten Modelle haben. Demzufolge müssen auch die betreffenden Modelle entsprechend modifiziert werden.
-  **WICHTIG!** Nur Programmzeilen (oder Zustandszeilen) ohne Funktions-ID oder mit gewähltem Funktions-ID können laufen.

## Istruzioni di sicurezza



**ATTENZIONE** Il contenuto di questa sezione NON è destinato all'utilizzo di altri al di fuori del personale GPD o del personale autorizzato da GPD stessa. Un'applicazione impropria di queste informazioni può comportare gravi problemi nella funzionalità del software FLOWare. Nonostante i nostri clienti desiderino utilizzare questa funzione software, GPD Global non assume alcuna responsabilità per il suo utilizzo. Il controllo diretto delle funzioni software può danneggiare il sistema e il programma di lavoro se l'operatore attiva questi controllo nel momento sbagliato e in sequenza errata



**AVVERTENZA** La GPD Global Global NON è responsabile della perdita di configurazione o di programma se non si dispone di un backup corrente



**ATTENZIONE** Prestare attenzione in caso di passaggio di un sottotipo da una macchina all'altra dato che sono associati sia al software che all'hardware.



**ATTENZIONE** NON aggirate le disposizioni sulla sicurezza, potrebbero verificarsi danni alle persone.



**ATTENZIONE** NON aprire la protezione di sicurezza durante l'esecuzione di un programma altrimenti apparirà un messaggio di violazione di sicurezza ed il programma verrà interrotto.



**ATTENZIONE** Il gantry si muove IMMEDIATAMENTE all'attivazione del pulsante MOVE TO. Prima di attivarlo verificare che il percorso tra la posizione attuale del gantry e la coordinate designate sia libero



**IMPORTANTE** Regolazioni al fuoco della telecamera o all'illuminazione possono influenzare tutti gli schemi utilizzati da vostri programmi. E' necessario quindi modificare anche gli stessi di conseguenza



**IMPORTANTE** Si eseguiranno solo righe di programmi (o di forma) senza caratteristica identificativa o con caratteristica identificativa selezionata.

## Instrucciones de seguridad

 **ADVERTENCIA** NO SE RECOMIENDA la utilización del contenido de esta sección a personal ajeno a GPD Global o a aquéllos que trabajen bajo la supervisión directa del personal de GPD Global. La aplicación inadecuada de esta información puede comportar complicaciones serias en el funcionamiento del software FLOWare. El personal ajeno a GPD Global que utilice esta información más allá de la aplicación indicada por el personal del Departamento de asistencia al cliente de GPD Global corre el riesgo de causar daños personales y de anular la garantía de la compañía. A pesar de que nuestros clientes a menudo quieren utilizar esta función del software, GPD Global no se responsabiliza de su utilización. El control directo de las funciones también puede dañar el equipo y puede detener el funcionamiento del programa si el operario activa estos controles en mal momento o en la secuencia incorrecta.

 **ADVERTENCIA** GPD Global NO ASUME ninguna responsabilidad por la pérdida de configuración o programas si no se dispone de una copia actualizada de seguridad

 **PRECAUCIÓN** Precaución al mover subtipos de una máquina a otra ya que los subtipos están relacionados tanto con el hardware como con el software.

 **PRECAUCIÓN** NO saltarse el paquete de Seguridad, o alguna persona podría sufrirdaños.

 **PRECAUCIÓN** NO ABRA la protección de seguridad mientras se esté ejecutando un programa, si lo hace aparecerá un mensaje de violación de seguridad y se abortará el programa.

 **PRECAUCIÓN** El pórtico se desplaza INMEDIATAMENTE cuando se activa el botón MOVE TO (MOVER HACIA). Antes de utilizar el botón MOVE TO (MOVER HACIA), compruebe que hay espacio libre entre la posición del pórtico y las coordenadas designadas.

 **IMPORTANTE** Los ajustes al enfoque de la cámara o a las condiciones de iluminación pueden afectar a todos los patrones que utilizan sus programas. El resultado es que debe modificar sus patrones en consecuencia

 **IMPORTANTE** Sólo se ejecutarán las líneas (o formas) del programa sin identificación de funciones o con la identificación de funciones seleccionada

# 1 Overview

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This chapter provides an overview of the performance, programming, and data transfer aspects of the FLOWare control software and its related documentation.

- [Introduction to FLOWare Software](#) (pg 1.1)
- [About the Documentation](#) (pg 1.4)

## Introduction to FLOWare Software

FLOWare software, used by GPD Global dispensers to perform high speed, precision dispensing, part pick-up and placement, and many other operations on single or multiple components on boards, boats, or pallets, is a programmable, real time, true multi-tasking operating system with a graphical user interface.

Designed with the concepts of great flexibility and ease-of-use in mind, the FLOWare software system enables easy programming of dots, lines, fills, arcs, and other custom shapes.

- [Performance](#) (pg 1.1)
- [Programming](#) (pg 1.2)
- [Data Transfer](#) (pg 1.3)

## Performance

### Real Time Operation

All processes sent to the CPU are processed according to a system of priority levels. High priority processes, such as safety issues and motor and motion control, are completed immediately in real time.

Every 0.5 ms the CPU checks for incoming processes to complete. If a process with a higher priority than the one currently being executed appears, the CPU stops the low priority process and immediately begins completing the higher priority process. For example, if a safety violation occurs or a motion control command is required, the CPU immediately processes those commands even though the operator is currently editing a program, thus maintaining safe and constant operations with accurate monitoring and greater control.

### True Multi-Tasking

Because the system computer can perform multiple tasks at the same time, the user can perform tasks such as editing a program at the same time the dispenser is processing products. At no time is the dispensing speed slowed or machine safety compromised.

### Optimization

Three methods for optimizing dispense patterns are available:

- point-to-point,
- fixed divisions, and
- floating square.

The point-to-point algorithm, the most basic of the methods and used as the foundation of the other two methods - determines the nearest component centroid to the present needle position.

The fixed divisions method divides the product into a number of divisions as specified by the operator, and then utilizes the point-to-point method within each smaller division.

The floating square method is similar to the fixed divisions method except the operator specifies the dimensions of the square used to divide the product into divisions.

## Programming

FLOware software gives the user control over all dispensing parameters. Just a few examples of dispensing parameters are material selection, valve on time, and dispense speed. Selection lists and default values are supplied for many parameters to help the user with proper value selection.

Manually teaching a program - one of the three methods of programming a new board (the other two being ASCII Pick & Place Data and CAD/GERBER Data Translation) - is a straight forward process:

1. Create a new program file and name.
2. Teach the data origin.
3. Teach fiducial locations and patterns. Standard fiducial patterns are supplied, however, custom patterns can be taught.
4. Specify the material, valve, and needle to be used. If multiple valves are used, parameters for each separate valve are specified.
5. Select the component shape from a component list.
6. Teach component locations using the Jog feature.
7. After using Inspection Mode to verify all locations, production level dispensing can begin.

## Programs

A program library lists all programs available to be run or edited. Programs may be grouped by a Class designation. Preferences for each program are selected by the user. A virtually endless number of subroutines can be generated for later recall.

## Shapes

Shapes are the building blocks for most programs. Any shape can be defined. Shapes can range from a simple dot pattern to a complex, convoluted fill pattern. Shapes are created using simple commands (dot, line, arc, circle, move, etc.) in combination such that the desired pattern shape is achieved.

## Pattern Recognition

Any pattern can be taught as the fiducial. All standard fiducials are included with the system, but the system can be taught to recognize custom fiducials, even those represented using text.

## Access

The passworded system of access rights can be used to limit the access of each user. The system administrator can set a user name and the functions available to each operator. The system tracks log-in activity and operations performed by individual.

## Data Transfer

### Data Converter

Take CAD data from desk to dispenser using the system data converter. The system translates pick-and- place data and other ASCII formats compatible with many data translation companies. An integrated part number library relates your part number to the system component library with assistance for easy part type recognition, so you can edit at your leisure.

### Data Exporting

The user can export all data from any GPD Global dispenser as an ASCII formatted file using the Data Exporting utility. Any program file is selectable for export. Exported data may be transferred between any of the GPD Global dispensers. The data may also be sent via e-mail to another facility or to GPD Global for programming assistance.

# About the Documentation

## **IN EFFECT AS OF FLOWare software version 2.9**

This manual, written for the FLOWare software, is intended to provide the user with the concepts, instructions, and reference material needed to create and modify programs.

## Intended Audience & Equipment

This manual is intended as a software guide for the Engineer assigned to the GPD Global dispensing equipment. Use this document to create and modify dispenser programs. The assumption is made here that you have read and are familiar with the contents of the *Dispenser Operator Guide*.

## Organization of Manual

This manual is organized as follows:

**Overview.** Describes the version of control software described in this document; describes many general aspects of the FLOWare software package; gives an overview of how this document is organized; and lists the titles of associated documents.

**Getting Started.** System start up and power down instructions; descriptions of all interface features and instructions on how to use them; and likewise for features that function as system-wide commands.

**Using FLOWare Software.** Operating instructions for how to use existing programs, how to use basic programming features, how to create new programs, and how to achieve successful programming results using specific features. Calibration and configuration topics are also included.

**References.** Reference material and procedures for specific topics often used when creating or modifying programs.

**System Management.** Describes administrative, account management, routine backup, troubleshooting, and security level features and procedures.

**Appendices.** Describes engineer-level procedures that should only be used while under the direct guidance of GPD Global personnel. Instructions for capturing screen grabs is also included here.

## Related Documents

For additional information about the dispenser, refer to the following associated documents:

- *Dispense System Operator Guide* (PN 22100079K)
- *Dispense System Service Guide* (PN 22290008D)
- *Mechanical & Electrical Reference Documents* (PN custom)
- *FLOWare Software Import/Export Data Reference Guide* (PN 22100024)
- *FLOWare Base Locations Reference Guide* (PN 22100025)
- *FLOWare Messages Reference Guide* (PN 22100026)
- *CMOS Set Up* (PN 22100114-x)
- *Upgrading FLOWare Software* (PN 22100086)
- *Installing Data Converter* (PN 22100038DOC)
- *Dispenser Software Recovery* (PN 22144015 or 22100109CD.29)

## 2 Getting Started

This chapter discusses system start up and power down, and guides the user through an in-depth description of the software interface features and how they function.

- [Start Up, Home, Shutdown](#) (pg 2.1)
- [User Interface](#) (pg 2.3)
- [System-wide Commands](#) (pg 2.21)

### Start Up, Home, Shutdown

#### Power On

The startup sequence initializes the computer, loads the operating system, and implements FLOWare software programming changes. Some FLOWare software programming functions, such as teaching base locations for example, require the system to be booted before changes will take effect.

To start the system:

1. Read all safety and operating instructions prior to operating the machine.
2. If the machine is equipped with an optional, uninterruptible power supply control, then perform the UPS startup sequence. For details, refer to the *Dispenser Operator Guide* (see *UPS Control* under *Operating Detail*).
3. Verify the black Power Off button is pulled out.
4. Turn on the machine by pressing the green Power On switch. The system will prompt you to home the XYZ gantry when you turn on the power and the booting process has finished. The system must complete the homing sequence before other operations are possible.

#### Home the System

Homing the system is a standard part of the power on procedure.

1. Wait until the system has completed the boot sequence. This may require waiting several minutes while status information displays. The main window and a prompt to home the system will display when the booting process is complete.
2. Click OK to home the system. Homing defines where the gantry is for the system and is complete when all homing status messages disappear. When only the main window remains, you may proceed with normal operations.



**CAUTION** DO NOT override the safety package or else personal injury could result.

<b>ATTENTION</b> <a href="#">NE PAS neutralizer</a>	<b>VORSICHT!</b> <a href="#">Setzen Sie NIEMALS</a>	<b>ATTENZIONE</b> <a href="#">NON aggirate le</a>	<b>PRECAUCIÓN</b> <a href="#">NO saltarse el paquete</a>
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**CAUTION** DO NOT open the safety shielding while a program is running or a safety violation message will appear and the program will abort.

<b>ATTENTION</b> <a href="#">NE PAS ouvrir l'écran</a>	<b>VORSICHT!</b> <a href="#">Bei laufendem Programm</a>	<b>ATTENZIONE</b> <a href="#">NON aprire la protezione</a>	<b>PRECAUCIÓN</b> <a href="#">NO ABRA la protección</a>
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## Power Off

Before powering off the machine, end any active program and perform a proper shutdown described in the following procedure.

### Prepare for Shutdown

Before you can perform the shutdown procedure, you must end any active program. It is also recommended that you unload all product from the dispense area and remove and clean the heads.

To prepare for shutdown:

1. Stop program execution with one of these methods:
  - If the Mount Board prompt is displayed, click ABORT, or
  - click CANCEL on the main button bar.
2. After the program has ended, remove all product from the dispenser area. For details, refer to *Unload Product* under *Set Up Instructions* section of the *Dispenser User Guide*.
3. To begin the process of unloading all heads (valves and tools), click REFRESH on the main button bar to move the gantry to the front of the machine where you can access the heads.
4. Remove the heads. For details, refer to *Mount Heads* in *Mount Heads & Materials* in the *Set Up Instructions* section of the *Dispenser User Guide*.
5. Clean the heads. For details, refer to head cleaning instructions detailed in *CLEAN Valves* in the *Periodic Operations* section of the *Dispenser Service Guide*.

### Shutdown

The machine can be left powered on as long as the safety system has not been bypassed; however, GPD Global recommends that you power off equipment when it is not in use.

To shutdown and power off the machine:

1. Perform the [Prepare for Shutdown](#) (pg 2.2) procedure.
2. If the machine is equipped with an optional, uninterruptible power supply control, perform the UPS shutdown sequence specified in *UPS Control* in the *Operating Detail* section of the *Dispenser User Guide*.
3. From the main menu bar, click on Operations > Shutdown System. A shutdown verification prompt displays.
4. Click YES to shutdown the system or CANCEL to abort the shutdown. Wait until a System Stopped prompt displays.
5. Power off the machine by pressing the black Power Off button.

## User Interface

The dispenser system is controlled through the trackball, keyboard, and software windows. The operator uses these to run processes; the engineer uses these to design processes. All typed entries, except passwords, are insensitive to case. File selection windows are widely available throughout the software, enabling you to select any file in the system.

- [Keyboard & Mouse/Trackball](#) (pg 2.3)
- [Jogging the Gantry](#) (pg 2.7)
- [USB Port](#) (pg 2.9)
- [Screen, Window, Pane, & Panel](#) (pg 2.10)
- [Menu Structure](#) (pg 2.13)
- [Buttons](#) (pg 2.15)
- [Lists](#) (pg 2.18)
- [Sliders: Scales & Scroll Bars](#) (pg 2.20)
- [Faded Items](#) (pg 2.20)
- [Passwords](#) (pg 2.20)

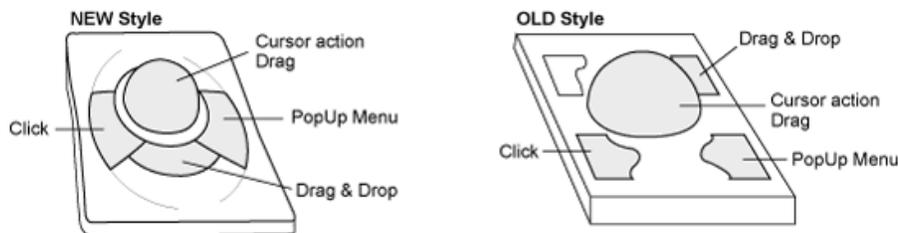
## Keyboard & Mouse/Trackball

### Cursor

The cursor (pointer) can be moved anywhere on the monitor screen with the ball section of the trackball.

### Trackball

Use the trackball to position the cursor on the monitor screens and to move the gantry.



You can select all or part of the contents in a field. There are several ways to select field contents, and each method obtains slightly different results. You can either click-and-drag or multiple-click on a field.

1. If you **single-click** on a field, press the lower left trackball key, and drag the cursor, you can be selective about the data selected.
2. If you **double-click** on a specific item within a field, you can select that single item (a single word, a value, or a unit of measure).
3. By **triple-clicking** on a field, you can select the total contents (a value AND the unit of measure or all text) of a field.

The following conventions are used in this manual for trackball actions:

**Table 1: Trackball Conventions**

Term	Action
click	Press the Click trackball button and immediately release it.
double-click triple-click	In rapid succession, click the Click trackball button for the applicable number of times.
drag	As you move the cursor down a menu with the trackball, each menu selection is highlighted in turn. Frequently, you will select a menu item by dragging the cursor down the menu until the item you want is highlighted, and then releasing (or sometimes clicking) the Click trackball button.
drag & drop (move)	Press and hold the Drag & Drop trackball button while moving the cursor, then release the button.
position cursor	Move the cursor by moving the Ball portion of the trackball.
open Pop-up menu	Position the cursor at the appropriate screen location and press the Click trackball button.

## Keyboard

When used in reference to hardware, the term *key* is understood to refer to a control located on the keyboard and *button* is understood to refer to a control located on the trackball.

## Accelerator Keys

Various accelerator keys are provided to accommodate navigation by keyboard rather than by trackball.

**Table 2: Using Accelerator Keys**

Item Affected	Use These Keys	Notes
select a menu item	ALT key + first letter	A menu item that displays with an underlined first letter may be selected by pressing the ALT key and the underlined letter.
select a panel	CTRL key + first letter	A <i>selection panel</i> may be selected by pressing the CTRL key and the first letter of the panel title (rather than clicking the Panel Selection button). For example, to select the Vision panel in the Program Detail window, press the CTRL key and the V key.
enter mount location	ALT key + 1, 2, 3, 4, or 5 key	Enter a value in any Mount Position field by pressing the ALT key and a number (1-5) key.
enter gantry	ALT key + A, B, or C key	Enter a value in any Gantry field by pressing the ALT key and a letter (A-C) key.

## Arrow Keys

Use the arrow keys to move the cursor sequentially up/down lists or forward/backward through text and numeric values.

## Tab Key

Either move the cursor with the trackball and click on a field to select it or press the TAB key repeatedly to move through the fields sequentially until the cursor has reached the destination field.

Use the TAB key to move the cursor sequentially from field to field. Normally, the TAB key will not tab through a text field; rather, use of the TAB key within a text field creates tab spaces. However, pressing down the CTRL key while using the TAB key will move the cursor through all fields, in sequence, without exception.

**NOTE:** The TAB key does not always work on the main window.

## Text Entry

Use the keyboard to type text entries after positioning the cursor in the appropriate field. When entering text or values:

**Table 3: Field Text Entry**

To	Action
select desired field	click on desired field
move forward from field to field	<Tab> to desired field
move backward from field to field	<Shift> + <Tab> to desired field
select all text/numbers in a field	double-click OR click and drag

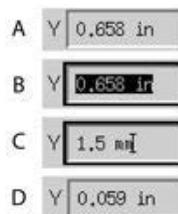
## Numeric Entry

Select desired field and type a numeric value using the keyboard, or click the default box next to the field to return the field to its default value. When entering a value, you may need to erase (backspace key) the prior value before entering the new value.

### Units of Measure

Units of measure can be included in entries and need not be the same as the displayed units. The displayed value will be properly converted and displayed when an entry is applied; the system reverts the entry to the default (displayed) units. For example, suppose you want to enter a value of 1.5 millimeters in a field that is currently displaying a value in inches:

- Let's say you intend to enter a value in a field already displaying a value of 0.658 in (refer to item A).



- Select the field contents, including the units of measure (B).
- Type in the new value and the new units (C).
- Press ENTER. The newly entered value and units, 1.5 mm, is converted and displayed in default units as 0.059 inches (D).

## Global Units of Measure

Units of measure can be displayed as English or metric. The global default for units of measure is set up in the configuration file and can be changed from English to metric or vice versa if needed. For instructions and a complete list of valid units, refer to [Unit Abbreviations](#) (pg 7.2).

## Jogging the Gantry

Gantry movement in the X, Y, and Z axes can be directly controlled by the operator with the trackball and keyboard. This manual control over the gantry, or jogging, is typically used to position the camera and teach program coordinates, align offset points, and reposition the gantry when necessary.

### How to Jog

To jog the gantry:

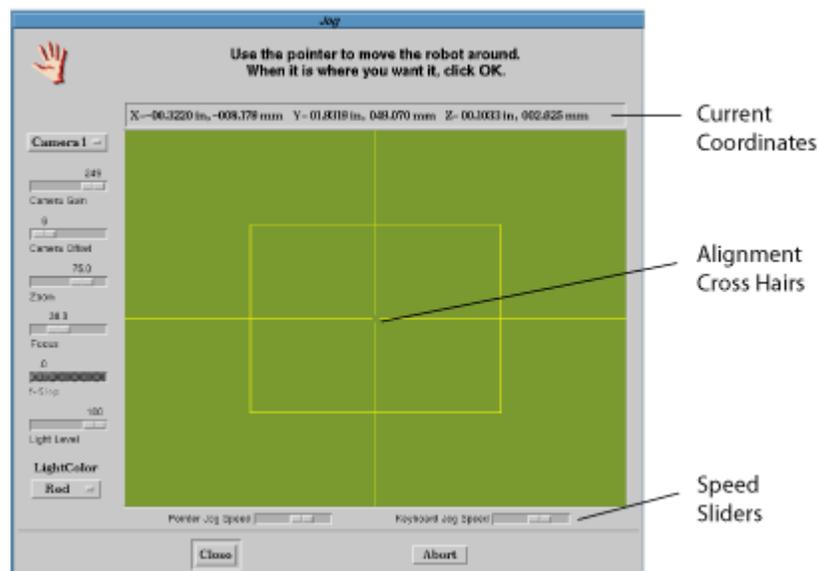
1. ALWAYS observe ALL jog rules:



**CAUTION:** Observe all jog rules or else damage to the machine may occur as a result of moving the gantry too quickly in an unintentional direction.

- **Rule #1** - Visually monitor the gantry response *EVERY TIME* you activate gantry movement.
  - **Rule #2** - Prior to using the jog feature, verify that the gantry is raised up sufficiently to clear all obstructions.
2. Click JOG in the main button bar of the main window or use the Jog window that displays automatically during various procedures.
  3. Move the gantry using the [Jog Controls](#) (pg 2.8).
  4. When the gantry is positioned where you want it, click CLOSE to exit the Jog window.

### About the Jog Window



**Current camera coordinates** relative to the active reference point display at the top of Jog.

The **alignment cross hairs** are guides for precise alignment.

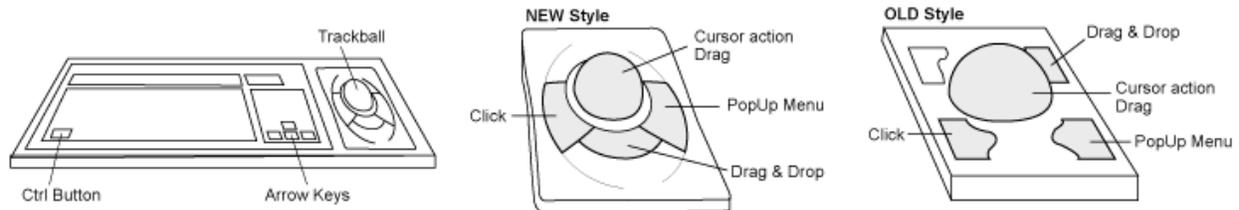
The **speed sliders** are used to change the overall operating speed of the cursor and keyboard controls.

The lens and lighting **controls located along the left side** of Jog are only available when the dispenser is equipped with the associated optional equipment. For further lens and lighting controls information, refer to [Vision Lighting & Focus](#) (pg 3.74).

## Jog Controls

Gantry movement is controlled with the trackball and keyboard, and directly relates to the movement of the cursor in Jog.

 **WARNING:** The gantry moves IMMEDIATELY when the jog controls are activated. Gantry motion stops immediately upon release of the jog controls.



**Table 4: Jog Controls - How They Work**

To control:	Do this:
X-Y movement	<ol style="list-style-type: none"> <li>1 - Position the screen cursor in Jog.</li> <li>2 - Press and hold the <b>Click</b> trackball button to activate jog control over the gantry, while simultaneously moving the trackball to correspond with desired direction.</li> <li>3 - Release the Click trackball button when desired movement has occurred.</li> </ol>
Z movement	<ol style="list-style-type: none"> <li>1 - Position the screen cursor in Jog.</li> <li>2 - Press and hold the <b>Ctrl button</b> and the <b>Click</b> trackball button to activate jog control over the gantry, while simultaneously moving the trackball to correspond with desired direction.</li> <li>3 - Release the Ctrl button and the Click trackball button when desired movement has occurred.</li> </ol>
speed	<p>Speed is dynamic with the distance between the cursor and the center of the Jog cross hairs; that is, the greater the length of the line in the Jog window created by trackball action, the greater the speed of the gantry.</p> <p>To control jogging speed more precisely, use the speed sliders to change the overall operating speed of the cursor and keyboard controls.</p>
fine tuning	<p>To move the gantry in smaller increments of motion, use the keyboard arrow keys to control gantry motion.</p>

## USB Port

When a USB (universal serial bus) device is plugged into the USB port, the computer operating system recognizes the device as a removable drive and assigns it a drive of:

```
/dos/c.
```

A USB device can be used with the Import and Export features and all types of Backup and Restore utilities except a full system backup.

## Loading USB

A USB device can be plugged into the USB port any time the system is running. If a USB device is loaded prior to starting an import, export, backup, or restore function, the system will skip displaying the *mount a USB device* prompt.

## Removing USB

To remove the USB device, either:

- wait until a system prompt tells you to remove the USB device, or
- click in the main control window menu bar on Utilities > Unmount USB and then remove the USB device.



**CAUTION:** Do not remove a USB device unless the system prompts you to do so or unless you have used the Unmount USB command; otherwise, the USB port will be unusable until the system is rebooted and anything you may have written to the USB device may be lost.

## Data Transfer Utilities

### Using USB with Import & Export

---

**IN EFFECT AS OF FLOWare software version 2.6**

The USB port now works with the [Import Data](#) (pg 3.2) and [Export Data](#) (pg 3.10) functions.

In the Import and Export windows, a drive letter of `c` will be assigned:

```
/dos/c/filename
```

**NOTE:** Wait for the prompt before removing the USB device.

### Using USB with Backup & Restore

---

A USB device can be used with all types of Backup and Restore utilities except a full system backup due to issues of licensing preservation.

A prompt will display asking if the USB port is available. If you opt to use the USB port, the USB path will display for directory and file.

## Screen, Window, Pane, & Panel

### Screen vs. Window

The term *screen* is used to indicate the full monitor viewing area, whereas the term *window* represents a section of the screen dedicated to displaying specific types of information.

### Moving & Resizing Windows

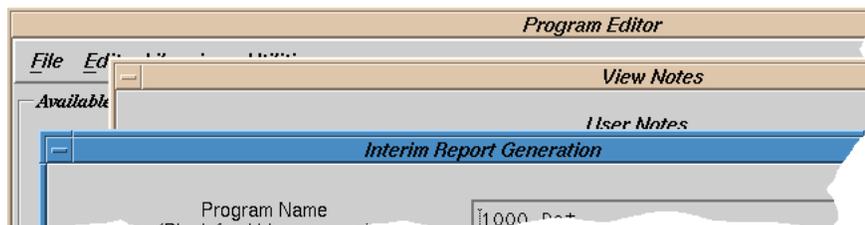
Windows can be moved about on the screen in one of two ways:

- by positioning the cursor on the title bar, holding down the lower left trackball button and dragging the window to its new position with the ball portion of the trackball.
- clicking on the upper left corner of the window, selecting Move, dragging the window to its new position with the ball portion of the trackball, and then clicking to release the window.

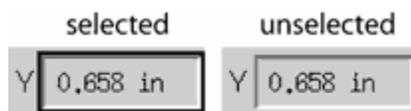
Many of the main windows are static in size and cannot be resized. Secondary windows can usually be resized using the typical Windows system of drag-and-release of a window side or corner.

### Active Window & Field

An active window has a blue border, whereas an inactive window has a beige border. When multiple windows are displayed, clicking on a window you want to use makes it the active window and changes its border color to indicate its active status.



Similarly, the border around each field indicates its selection status: selected/active or unselected/inactive. A selected field is indicated by a heavy black line emphasizing its border.



## Pane

A pane is an area within a window that contains a group of related data; all objects within a pane apply to the same subject. Each pane has a title to indicate its purpose. Panes can be grouped within a pane, as illustrated in the right hand half of the window shown below.

**Figure 1:** Pane - each shaded area indicates a different pane.

The screenshot displays the **SubBoard Editor** window, which is divided into several panes, each enclosed in a dashed border. The panes are:

- Board Info**: Contains three fiducial markers (Fiducial 1, 2, and 3) and a Bad Mark Location section. Each fiducial marker has X and Y coordinates (0.000 in) and a Teach button. The Bad Mark Location section has X and Y coordinates (0.000 in), a Teach button, and a Pattern dropdown set to NONE. Below this is a checkbox for "Process if mark present = 1, absent=2, unused=0".
- Sub Board Info**: A large empty pane on the right side of the window.
- Sub Board Specifics**: Contains Name and Feature text boxes, X and Y coordinates (0.000 in), an Angle (0.00 deg), and buttons for Move To and Teach.
- Across Dimensions**: Contains Span X and Y (0.000 in), Count X and Y (0), and a checkbox for "Suppress Auto Height Probe".

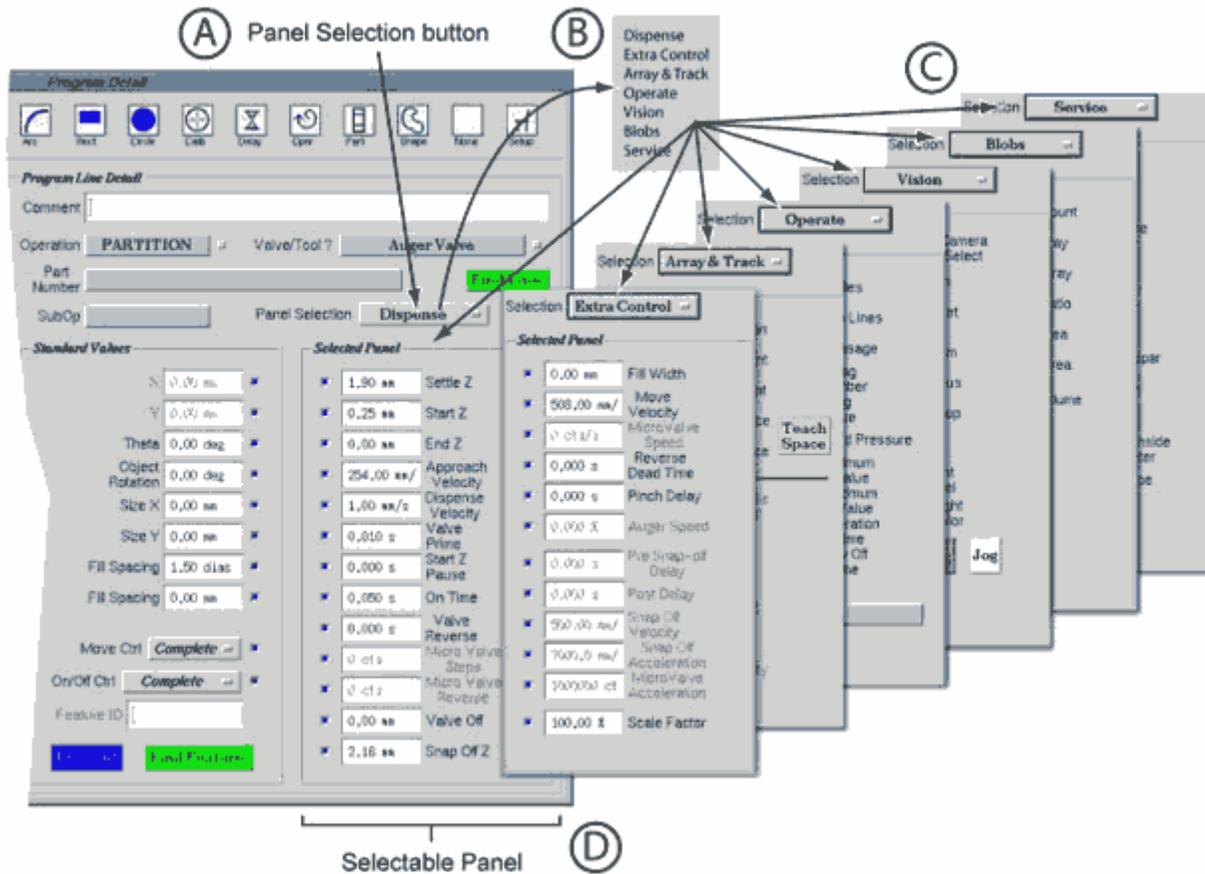
At the bottom of the window are buttons for **Done**, **Cancel**, **Apply**, **Add**, and **Delete**.

## Selectable Panels

Selectable panels are used to organize and present subsets of related fields when their volume would otherwise exceed the limitations of a single window. A pull-down menu of the panel choices displays when you click on the Panel Selection button.

For example, a set of selectable panels (refer to item **D** in the following image) is available from the Program Detail window.

In the example shown below, clicking on the Panel Selection button (**A**) and selecting the Dispense choice from the pull-down menu (**B**) has displayed the Dispense panel within the Program Detail window. Clicking on the Panel Selection button again and selecting a different panel choice would replace the Dispense panel with the newly selected panel (**C**).



## Menu Structure

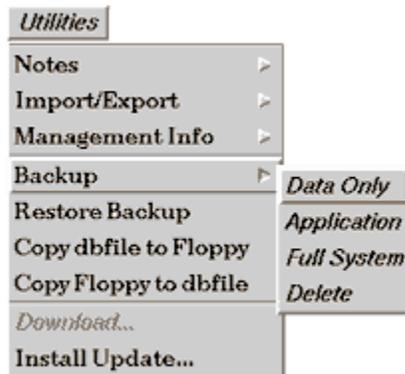
There are only minor functional differences among the various types of menus used in the FLOWare software

### Menu Convention

The > symbol is used to identify a sequence of menu selections. For example, the phrase *Utilities > Backup > Data Only* replaces the instruction to *click on Utilities, and then from the resulting menu click on Backup, and then from the resulting menu click on Data Only.*

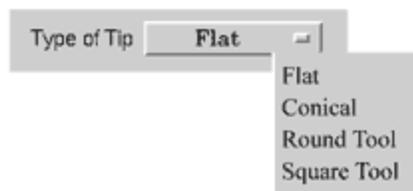
### Pull-down Menu

Pull-down or drop-down menus make it easy to find and use program features. To display a pull-down menu, click on a menu bar item. There may be several layers of pull-down menus.



### Option Menu

Option menus provide an additional level of menu choices. Option menus display whenever you click on a button with a small embedded rectangle.

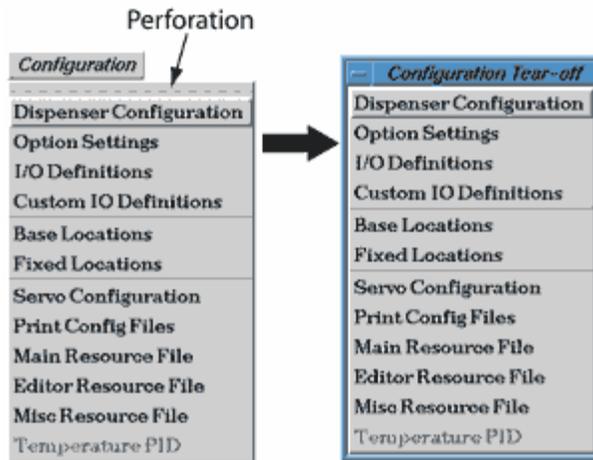


### Pop-up Menu

Pop-up menus are usually hidden and only *pop up* when you click the lower right trackball button at the appropriate screen location. Generally, the only pop-up menu used on the system will be the IOviewer menu.

## Tear-off Menu

A tear-off menu is a pull-down, pop-up, or option menu that can be posted as a sub-window that displays until you close it. Tear-off menus are convenient for menus you use frequently. If a menu can be torn off, a perforation (perforated line) will show at the top.



To tear off a menu, position the pointer (cursor) on the menu tear line, and then click the trackball's lower left button. Move the resulting tear-off window wherever you want on the screen.

To close a tear-off window, double-click its upper left corner or press the ESC key.

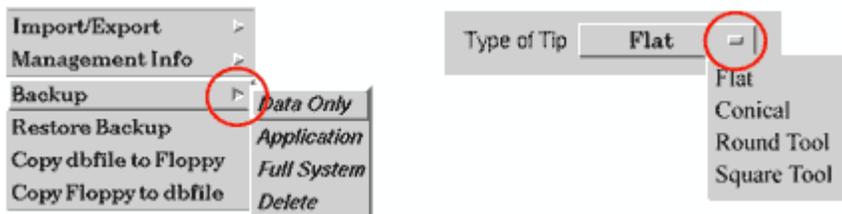
## Buttons

### Push Buttons

Push buttons perform a direct action. Each button has a text label corresponding to its function. Clicking on a push button invokes that function. Both an OK and Cancel button are typically included on most windows so you can either save changes or you can exit the window without saving changes. Help buttons are not generally implemented yet.



Push buttons that appear as small triangles (see below at left) generate pull-down menus. Push buttons with a small embedded rectangle (see below at right) generate option menus.



### Toggle Buttons

Clicking on a toggle button changes its state from on/used to off/unused and vice versa. Toggle buttons appear in various shapes and colors, with each type having a different function.

**Table 5: Guide to Toggle Buttons**

Shape	Function	On	Off
square (small)	default status	Dark blue The default value is used.	Gray The displayed value is used.
square (large)	selection	Red, yellow, or green The corresponding item is used.	Gray The corresponding item is not used.
diamond	option selection		

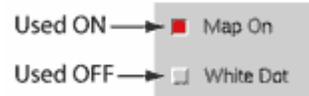
#### Used Button - Diamond

A diamond (of any color) determines the active option within a group of options. A diamond-shaped used button is always located to the left of the item it controls.



### Used Button - Square

A somewhat larger square of any color other than blue (usually red, yellow, or green) controls whether or not an item is selected for use. Except in rare cases, a used button is always located to the left of the item it controls.



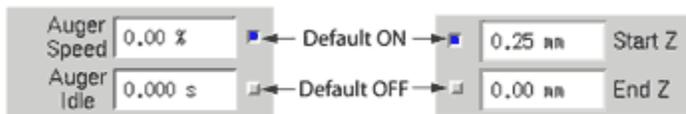
#### Location Exception

A used button is usually located to the immediate left of the item it controls, however, in the rare case when the used button is located to the right of an item, it will be labeled *Used*.



### Default Button

Typically, a small blue square controls whether or not the default value of an item is to be used. A default button can be located either to the right or left of the item it controls.



- Turning a default button ON (square turns blue), returns the item to its default value.
- Entering a value in that same field (square turns gray) automatically changes the state of the default button to OFF, overriding the default value.

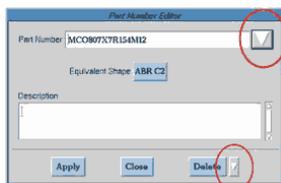
#### Is it a Default or Used Button?

An item will oftentimes have both a default button and a used button associated with it. Since both button types are represented by a square shape, note the differences: Default buttons are smaller in size than Used buttons and are limited to the color blue (when on), whereas Used buttons (when on) may be any color except blue.



### Triangle Buttons

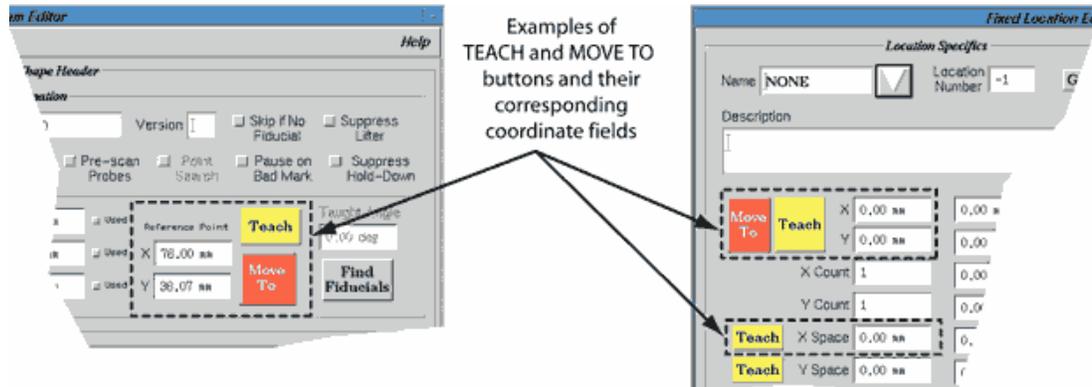
A triangle button indicates that a drop-down list of items is available. You have the choice of making a selection from this list. For more detail, refer to [Item List Buttons](#) (pg 2.18).



## Buttons for Teaching Coordinates

Instead of manually entering coordinate values, they can be taught using the MOVE TO and TEACH buttons. Use the MOVE TO button to move the gantry to the currently entered coordinates and then use the TEACH button to fine tune and re-teach the coordinates.

Typically found in close proximity to each other, the TEACH and MOVE TO buttons appear in the editor windows (e.g., Program Editor, Fixed Locations Editor, and SubBoard Editor). Occasionally, the TEACH button appears without a corresponding MOVE TO button.



**NOTE:** When teaching new coordinates, it is recommended that you first install the valve or tool you will be using during the program run. Teaching coordinates using the actual valve or tool and mount station position designated for use with the new coordinates will ensure accuracy and help prevent equipment damage.

## TEACH

Clicking on a TEACH button invokes a Jog window so you can locate and align the camera on the desired visual references. Clicking OK enters the current camera coordinate values in the coordinate fields that correspond to the TEACH button. Depending on the situation, the TEACH button may have a set of coordinate fields (X,Y) or only a single coordinate field (X or Y) associated with it.

## MOVE TO

MOVE TO buttons move the gantry IMMEDIATELY to the coordinates designated in the corresponding coordinate fields. MOVE TO can be used to visually verify previously taught coordinates.

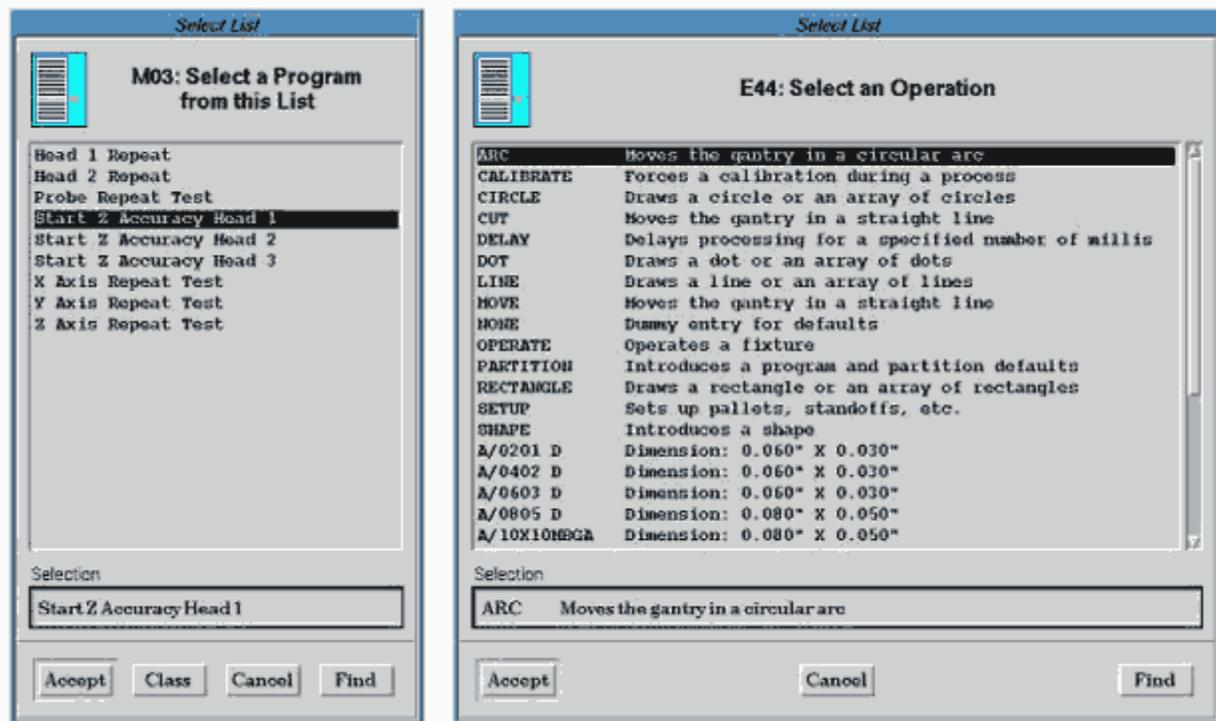
**CAUTION** The gantry moves IMMEDIATELY to the coordinates designated in the corresponding coordinate fields. MOVE TO can be used to verify previously taught coordinates.

<b>ATTENTION</b> <a href="#">Le portique se déplace</a>	<b>VORSICHT!</b> <a href="#">Die bewegliche Portal-</a>	<b>ATTENZIONE</b> <a href="#">Il gantry si muove</a>	<b>PRECAUCIÓN</b> <a href="#">El pórtico se deslaza</a>
--	--	---	--

## Lists

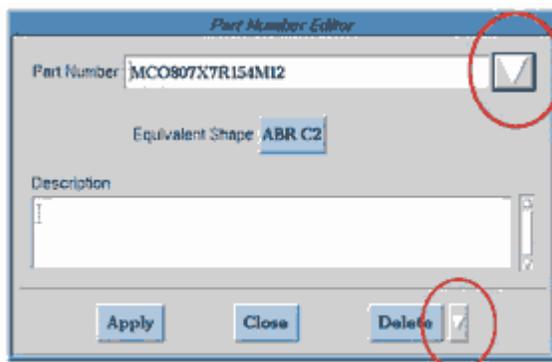
When needed, you can make a selection from the list of items presented in the form of a Select List window. The appearance of each window and the type of control buttons used by each window may vary somewhat but the basic window function remains the same.

Various features will generate a Select List window. For example, clicking SELECT on the main button bar allows you to select from a list of program names, or clicking ADD LINE on Program Detail allows you to select from a list of operation types. A list window will also appear whenever you click on a triangle button (continue reading for further details).



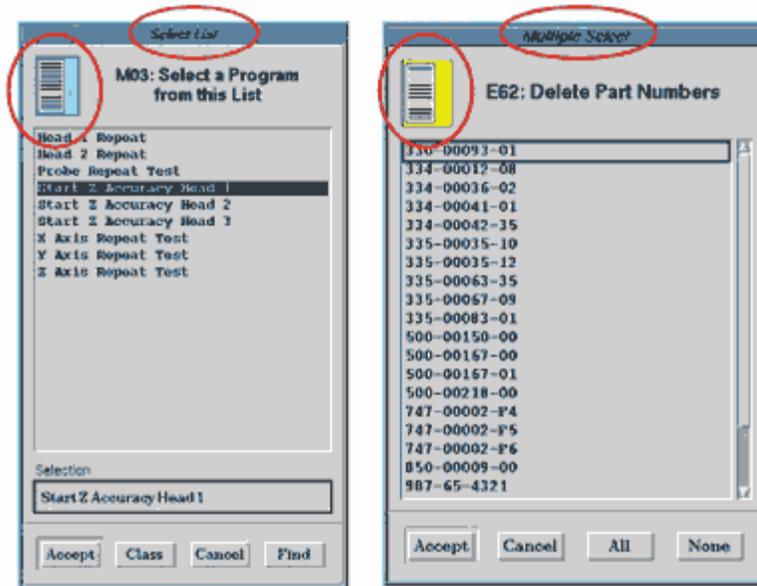
## Item List Buttons

A list of items is available to you whenever you see a triangle button. For example, clicking on the upper triangle button in the window shown below opens a list of part numbers from which you may make a selection to be entered in the Part Number field. The lower triangle button opens a list of part numbers. Use the DELETE triangle button to select one or more part numbers for deletion.



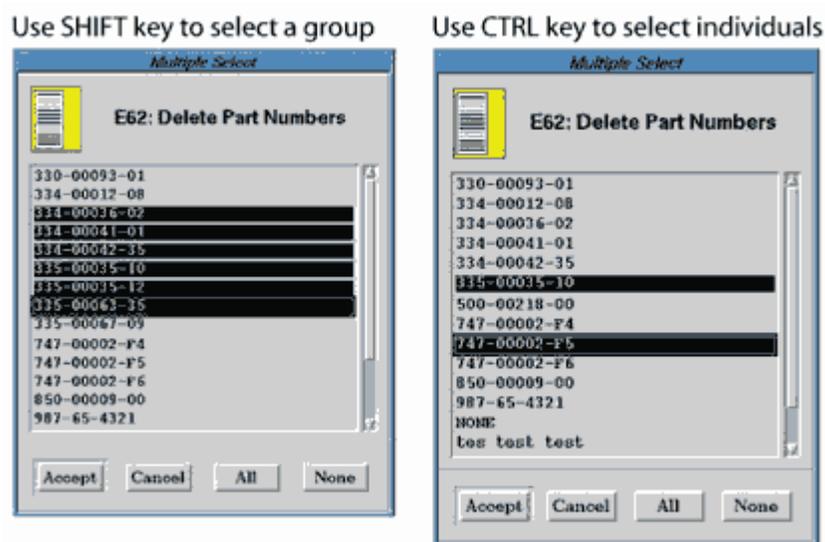
## Select List and Multiple Select

The list windows that open as a result of a click on a triangle button come in two basic forms: a Select List window (use to select a single item), and a Multiple Select window (use to select any number of items). Note the visual features that will help you distinguish between the single and multiple list windows - the icons in the upper left corner and the window titles.



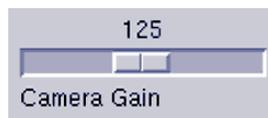
## SHIFT and CTRL Key Usage

Multiple Select windows, in addition to letting you select one, all, or none of the items listed, also let you select multiple items, either as a group or individually. To select a group of items, press and hold down the SHIFT key while you click on the first and last items in the group (see example below at left). To select a collection of individual items, press and hold down the CTRL key while you click on each of the items you want to select (see example below at right).

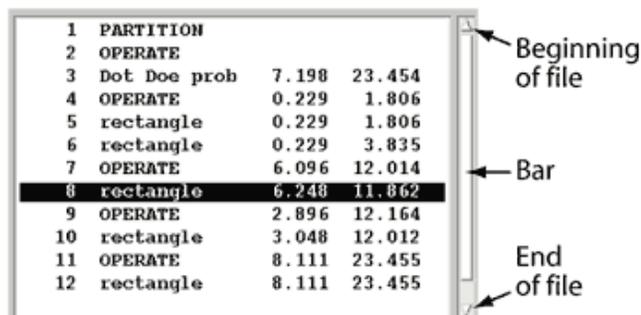


## Sliders: Scales & Scroll Bars

Scales change a value. You can either click and drag the slider bar until the value you want is displayed or click on the slider bar and then use the left and right arrow keys to move it.

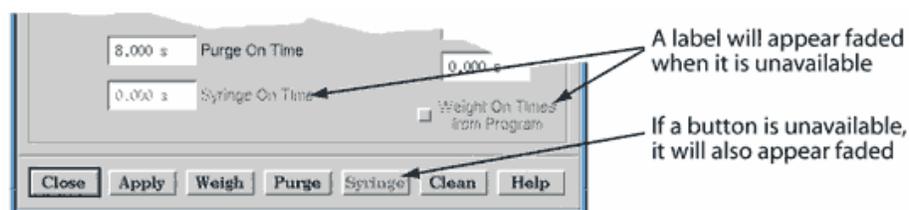


Scroll bars lets you move through a list when the list is not completely visible due to its length. Click and drag the Scroll Bar or click on the beginning or end of file buttons until the portion of the list you wish to see is displayed.



## Faded Items

Buttons and field labels appear faded when they are unavailable or only partially implemented. Sometimes these items are unavailable because they do not apply in the current context. They will appear *grayed out* (the label will be displayed in a lighter typeface) when they are not available for selection.



## Passwords

The dispenser utilizes an access by function password system. To use the dispenser requires the entry of a password and a user name. A user must be authorized to access each system function with a unique, user-defined password before access is allowed. Any combination of access rights can be assigned to any user name.

Whenever the dispenser is powered on, the default password in effect allows minimal access (at the Operator level) to the system.

## System-wide Commands

File selection windows can select any file in the system and are widely available throughout the FLOWare software under various file-type-specific titles. VEdit is a text editor that can be used to edit any file in the system.

- [File Selection](#) (pg 2.21)
- [Edit Any File](#) (pg 2.23)
- [File Editor](#) (pg 2.24)
- [Online Help](#) (pg 2.24)

## File Selection

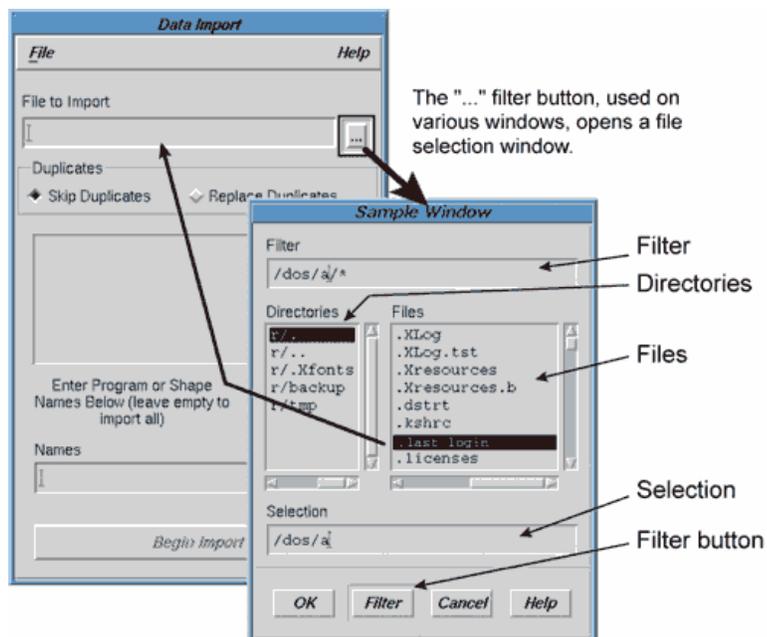
A file selection window serves to retrieve or send file data by providing a way to find a particular file and its path. There are numerous file selection windows — they all function the same way using a basic template of features while serving their various file selection purposes (to import from, export to, convert to, save to, or load data from a file).

There are several choices to be made during the file selection process. You may choose to enter the exact path and file name or use the filtering search function provided in the file selection window. You will also choose the source of the file being selected – a floppy diskette or the dispenser hard drive.

The window title for each of the file selection windows reflects the type of information the window filters.

The windows shown below are only examples. The file selection window is entitled Sample Window, and the Data Import window is used to represent the retrieval/sending window.

**Figure 2:** The windows shown here are examples only.



To select a file:

1. Prior to beginning the actual file selection process, load the diskette if the file to be selected resides on a floppy diskette; otherwise, skip this step if the file to be selected resides on the dispenser hard drive.
2. Open the retrieval or sending window; that is, open the import, export, convert, save, or load data window. For purposes of our example, we opened the Data Import window.
3. Click the ... button on the retrieval/sending window (Data Import). The file selection window (Sample Window) displays.
4. Choose one of the following file selection sources and follow the corresponding directions.

**Table 6: Choose a File Selection Sources**

Select a file from	Additional Criteria	Action
dispenser hard drive	Diskette may or may not be present in the floppy drive. If present, define file path as described in the following step.	Click the FILTER button. The system will read and display the <b>home/dispenser</b> directory.
floppy diskettes	A diskette was loaded in the floppy drive during step 1.	Click the FILTER button. The system will read and display the <b>/dos/a</b> directory.
	No diskette is present in the floppy drive.	<ol style="list-style-type: none"> <li>1. Load the floppy diskette.</li> <li>2. Type <b>/dos/a/*</b> in the Filter field.</li> <li>3. Click the FILTER button. The system will read and display the <b>/dos/a</b> directory.</li> </ol>

5. Choose one of the following scenarios and follow the corresponding directions.

**Table 7: Path & File Name Scenarios**

Path & File Name	Action
known	<ol style="list-style-type: none"> <li>1. Type desired path and file name in the Selection field.</li> <li>2. Click OK.</li> </ol>
unknown	<ol style="list-style-type: none"> <li>1. Either use the path supplied in the Filter field or, using wild cards, type a partial path in the Filter field of the general location of the files you want.</li> <li>2. Click the FILTER button.</li> <li>3. To change to a different directory, click a directory and click FILTER again.</li> <li>4. Repeat these steps until you locate the file you want to select.</li> <li>5. Click on the desired file name. The complete path and file name will display in the Selection field.</li> <li>6. Click OK.</li> </ol>

The Sample Window closes and the selected path and file name should be displayed in the file definition field of the retrieval/sending window (Data Import).

## Filter Defaults

The default entered by the system when the FILTER button is activated on a file selection window depends upon whether or not a diskette is present in the floppy drive.

- If a diskette is present in the floppy drive when you click the FILTER button, the system will enter a default of **/dos/a/\*** in the Filter field.
- If there is no diskette present in the floppy drive and **/dos/a/** is specified in the Selection field when you click the FILTER button, the system will enter a default of **/home/dispenser** in the both the Filter and Selection fields.

## Edit Any File

The Edit Any File function, available from the main menu bar under System Functions > Edit Any File, is used infrequently. For example, it is used if you want to delete a backup; otherwise, you will not need to use this function unless you are directed to do so by GPD Global Service personnel.



**WARNING** The content of this section is NOT recommended for use by anyone besides GPD Global personnel or those working under the direct guidance of GPD Global personnel. Improper application of this information can lead to serious complications in FLOWare Software operations. Any non-GPD Global employee who uses this information beyond the stated application specified by GPD Global Service Department personnel is in danger of causing personal injury and invalidating their machine warranty.

<b>ATTENTION</b> <a href="#">Le contenu de cette</a>	<b>WARNUNG</b> <a href="#">Der Inhalt dieses</a>	<b>ATTENZIONE</b> <a href="#">Il contenuto</a>	<b>ADVERTENCIA</b> <b>NO SE RECOMIENDA</b>
---	---	---	---

## File Editor

A file editing utility, VEdit, is provided to edit files in a shell-style window environment. If you inadvertently open a shell file, close it immediately by simultaneously pressing the ALT and X keys and then exiting the window without saving.

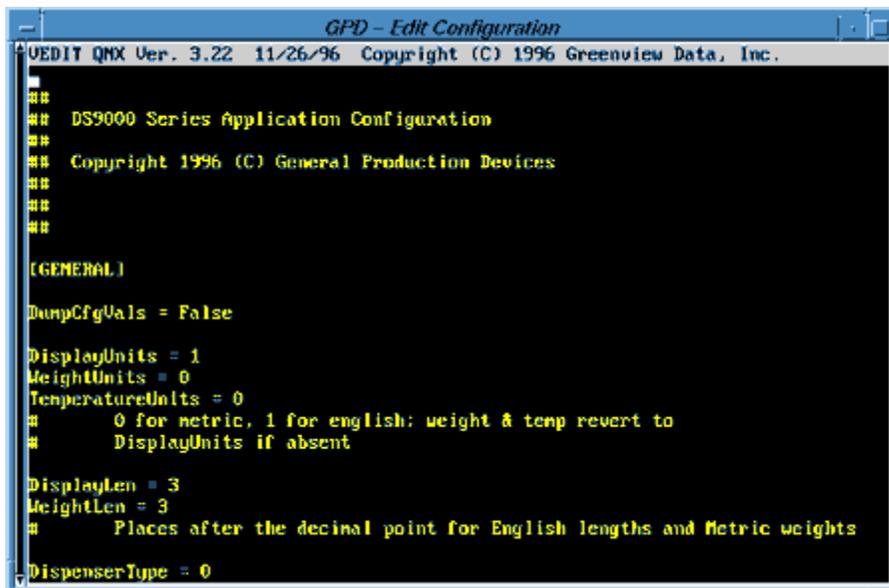
You should never access the shell environment unless expressly directed to do so by GPD Global Service personnel. Disregard for this directive can lead to serious complications in control software operations and invalidate your warranty.

 **WARNING** The content of this section is NOT recommended for use by anyone besides GPD Global personnel or those working under the direct guidance of GPD Global personnel. Improper application of this information can lead to serious complications in FLOWare Software operations. Any non-GPD Global employee who uses this information beyond the stated application specified by GPD Global Service Department personnel is in danger of causing personal injury and invalidating their machine warranty.

<b>ATTENTION</b> <a href="#">Le contenu de cette</a>	<b>WARNUNG</b> <a href="#">Der Inhalt dieses</a>	<b>ATTENZIONE</b> <a href="#">Il contenuto</a>	<b>ADVERTENCIA</b> <a href="#">NO SE RECOMIENDA</a>
---	---	---	--

## Exit Shell-Style Windows

*Figure 3: Sample of a Shell-style window*



```

GPD - Edit Configuration
VEDIT QNX Ver. 3.22 11/26/96 Copyright (C) 1996 Greenview Data, Inc.
##
## DS9000 Series Application Configuration
##
## Copyright 1996 (C) General Production Devices
##
##
[GENERAL]
DumpCfgVals = False
DisplayUnits = 1
WeightUnits = 0
TemperatureUnits = 0
# 0 for metric, 1 for english; weight & temp revert to
# DisplayUnits if absent
DisplayLen = 3
WeightLen = 3
# Places after the decimal point for English lengths and Metric weights
DispenserType = 0

```

To exit from a shell-style window:

1. Simultaneously press the ALT and X keys.
2. To exit without saving, answer NO to the prompt that appears.

## Online Help

The only help button currently active is the one found in the main window menu bar. The About button displays copyright information as well as the title and version number of the currently installed control software.

# 3 Using FLOWare Software

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- [Using Existing Programs](#) (pg 3.2)
- [Programming - Basics](#) (pg 3.17)
- [Programming - Keys to Success](#) (pg 3.71)
- [Calibration](#) (pg 3.125)
- [Configuration](#) (pg 3.136)

## Using Existing Programs

This section provides details about how to use existing programs.

- [Import Data](#) (pg 3.2)
- [Convert Data](#) (pg 3.5)
- [Export Data](#) (pg 3.10)
- [Optimize a Program](#) (pg 3.12)
- [Update a Program](#) (pg 3.13)
- [Alter Reference Point & Fiducial Points](#) (pg 3.15)

### Import Data

Data import provides the means for importing dispenser programs and operating information from various external sources.

The import selection function has improved; it is now more flexible and presented in a window format, it is now faster and provides more selection options for expanded data import results. Data files used and created by previous versions of Import can be used with this newer version.

Refer to the *Import/Export Data Reference Guide* for a complete discussion of data conversion and related, in-depth details.

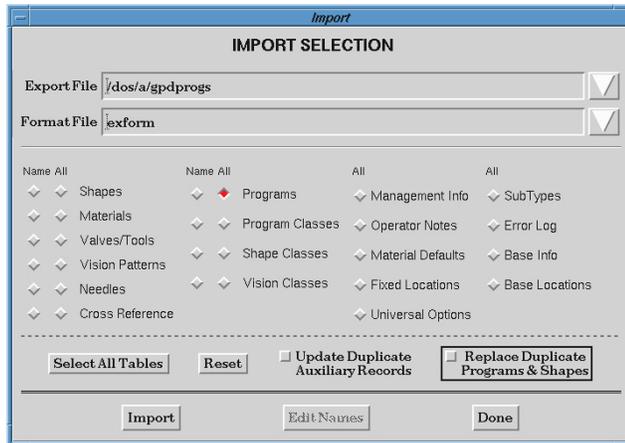
### File Structure

Information automatically added to the file structure of an export file is added as comments and can be viewed in an editor if desired.

## Using the Importer

Use the import data feature to import data from a dispenser, a network, or a floppy disk. To import data:

1. At the main menu bar, click on Utilities > New Import. The Import window displays.



2. In the Export File field, enter the name of the file containing the data to be imported by either of the following means:
  - Type in the path and name, or
  - Click the Export File Name triangle button to select the file path and name. For details on how to make a selection, refer to [File Selection](#) (pg 2.21).
3. The format file is not usually needed, but if it is, it has to be created by the editor (e.g., VEdit). The format file lists only the fields (tables) you want to select in the order you want them to appear in the import file. Refer to the *Import/Export Data Reference Guide* for further details.

In the Format File field, enter the file name of the desired format by either of the following means:

- Type in the path and name, or
  - Click the Format File Name triangle button to select the file path and name.
4. Select any combination of options. Choose whether to import everything or limit selections imported according to the following choices. Entries can be added to and subtracted from the list of tables to be imported until you click the IMPORT button.

**Table 8: Import Options**

To:	Do this:
import everything	click on SELECT ALL TABLES. Every ALL button will be activated.
import everything for a particular table	click the ALL button for the desired table.
import some, but not all, available items from a table	Not implemented yet. Click the NAME button for the desired table to invoke a list, then choose names for import from the list.

**Table 8: Import Options (Continued)**

To:	Do this:
add additional names	Not implemented yet. Click the desired NAME button off and then on. The complete list of currently selected names for that table will reappear so additional selections can be made. To verify that your additions have been added to the import format file, click EDIT NAMES.
remove names	Not implemented yet. Click EDIT NAMES to invoke the list of currently selected names, then delete any number of names.
reset to the default setting	click on RESET. Only the ALL button for Programs will be activated.
reset an individual ALL button	click on the NAME or ALL button to turn it off. This cancels any selections associated with the button from being included in the import format file.

5. Click IMPORT to execute file import. A prompt will indicate when importation is complete.

## Convert Data

The data converter is used to import data from various external sources after converting it to a specific format that meets dispenser requirements. External sources can include pick-and-place programs, feeder files, and cross references.

**NOTE:** If import data is already in the proper dispenser format, use the directions for [Import Data](#) (pg 3.2).

Data conversion consists of selecting the type of conversion (based on the machine that produced the data) and entering information about where the data can be found. The conversion is then performed and the converted file is imported.

A [Generic Example](#) (pg 3.7) is provided, as well as a complete discussion of data conversion and related, in-depth details, in the *Import/Export Data Reference Guide*.

## Format Requirements

All material to be imported directly into the dispenser must be in a specific format. This format is very flexible and allows import of as much or as little information as desired.

Convert programs all have the same general command line. These programs create dispenser data for a cross-reference file, shape names, and dispenser program data as appropriate. If input data has a separate feeder or component file, this file must be first in the list of files to be processed.

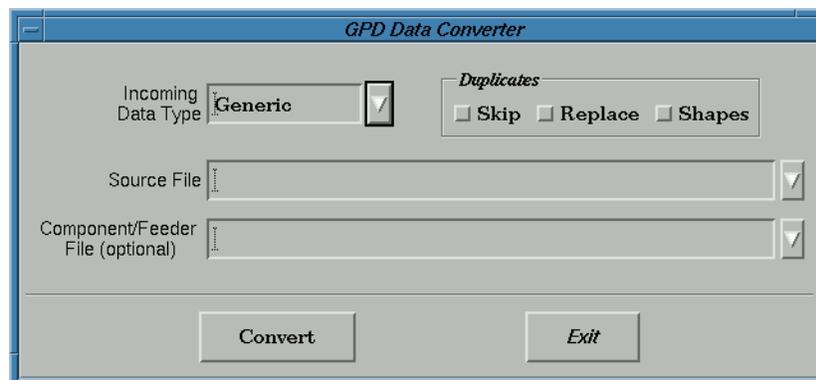
Formatted material can be created easily with a spreadsheet, by hand, or obtained through any of several conversion programs. Material can reside in any of the following locations: the dispenser, a floppy disk in either QNX/UNIX form, or another computer connected to the dispenser through a network.

## Using the Data Converter

Use the Convert Data feature to convert and import data from an external source into dispenser form.

To convert and import data:

1. At the main menu bar, click on Utilities > Import/Export > Convert. The GPD Data Converter window displays.



2. Click on the INCOMING DATA TYPE button and select the data type to be converted from the pop-up menu that displays.

3. Enter the source file path and name in Source File by either of the following means:
  - Type in the path and name, or
  - Click the Component/Feeder File triangle button to select the file path and name.
4. If applicable, enter the feeder file path and name in Component/Feeder File by either of the following means:
  - Type in the path and name, or
  - Click the Component/Feeder File triangle button to select the file path and name.
5. Select the preferred method of handling duplication by clicking either the Skip or Replace toggle control.
6. Choose whether or not to generate shapes by enabling or disabling the Shapes toggle control.
7. Click CONVERT to execute conversion. A prompt will indicate when conversion is complete and the converted file is imported.

## Converter Programs

Various conversion programs are available or can be developed for you based on a sample of a particular format. The following pertains to the generic conversion program; for information about customized programs, contact the GPD Global Service Department.

### Generic Conversion Program Format

---

The generic conversion program converts special format files designed for easy construction in a spread sheet, or even in an ordinary editor such as Microsoft editor EDIT. The following rules apply:

1. The input file(s) consist of a sequence of lines for each dispenser program.
2. Lines are optional and in order of descriptor.
3. Fields in the line are separated by tabs or spaces as follows:

Descriptor	XCoord	YCoord	Angle	Text
------------	--------	--------	-------	------

4. Each line is one of the following:

0	X	Y	U	Program name	(U=0 metric, 1 English)
1	X	Y			(Program/Pallet fiducial location)
2	X	Y	A	Subboard name	(SubBoard location)
3	X	Y			(SubBoard fiducial)
6	X	Y	A	Operation	(Program operation)

**Table 9: Conversion Lines Types Described**

Type 0	Each program is initiated by a type 0 record containing the (X,Y) distances of the reference point from the lower right corner of the board/pallet, the conversion units, and the program name. This record can be omitted for the first (or only) program in the file, or the program name or units/name may be omitted in these circumstances. If data is not available, (X,Y) is assumed at (0,0); units are assumed metric; and the program name is the data file name.
Type 1	Type 1 records are optional. If present, they define the relative coordinates of board/pallet fiducials. Only the first three type 1 records are used.
Type 2	Type 2 records define the position and orientation of sub-boards of a pallet, where the angle is in degrees and the sub-board name or angle/name may be omitted. If the angle is omitted, 0 is assumed.
Type 3	Type 3 records are optional. If present, they define the relative coordinates of sub-board fiducials. They are recognized only if they follow the first type 2 record. Only the first three type 3 records are used.
Type 6	Type 6 records define the operations to be performed and the position and orientation of the operation, where the angle is in degrees and the Operation or angle/Operation may be omitted. If the angle is omitted, 0 is assumed; if the Operation is omitted, DOT is assumed. These records follow other records for the program and appear in the order the operations occur. Typically, the operations are shapes. If Shapes are requested, shape records are generated only for non-primitive operations.

- CVT generic uses an optional file CVTgeneric.prim if it is present. This file may contain up to 20 primitive. The first primitive is the default operation type when OpType is omitted. This file is usually used only for a foreign language.

## Generic Example

```

0      10      1      1      SampleProg
1      0       0      Fid1
1      0      10     Fid2
1      10     10     Fid3
2      0       0      Sub1
2      0      10     90   Sub2
2      10     0      180  Sub3
2      10     10     270  Sub4
6      0       0      S/0805
6      1       0      90   S/1206
6      1       2      180  S/1210

```

## Example Explained

The generic example of data converter shown above will create a program named **SampleProg** using **English** measurements (inch) with a reference point which is ten (**10**) inches left and one (**1**) inch behind the work-area origin. The program will also contain the following elements:

The program will have three (3) **fiducials**:

- Fid1 [0,0]
- Fid2 [0,10]
- Fid3 [10,10]

There will be four (4) **sub-boards**:

- Sub1 [0,0,0°]
- Sub2 [0,10,90°]
- Sub3 [10,0,180°]
- Sub4 [10,10,270°]

Each sub-board will dispense the following three **shapes with rotation** relative to the sub-board rotation:

- S/0805 [0,0,0°]
- S/1206 [1,0,90°]
- S/1210 [1,2,180°]

## Subsections Explained

---

The same example used on the previous page is shown again here. An explanation of each subsection (set of lines) follows.

0	10	1	1	SampleProg	← Program
1	0	0	Fid1		
1	0	10	Fid2		← Fiducials
1	10	10	Fid3		
2	0	0	0	Sub1	
2	0	10	90	Sub2	
2	10	0	180	Sub3	← Sub-boards
2	10	10	270	Sub4	
6	0	0	0	S/0805	
6	1	0	90	S/1206	← Program Detail
6	1	2	180	S/1210	

## Program

---

The following portion of the above generic example defines the *program* to be converted:

```
0      10      1      1      SampleProg
```

- Field 1: 0 defines a new *program line*
- Field 2: *X coordinate* of reference point
- Field 3: *Y coordinate* of reference point
- Field 4: value 1: defines English units
- Field 5: defines the *program name*

### ***Fiducials***

---

The following portion defines the *fiducials* for the program:

```
1      0      0      Fid1
1      0      10     Fid2
1      10     10     Fid3
```

Field 1: 1 defines a *fiducial line*

Field 2: *X coordinate* of each fiducial point

Field 3: *Y coordinate* of each fiducial point

Field 4: declares the name of the *pattern* to use

### ***Sub-boards***

---

The following portion defines the *sub-boards* of the program:

```
2      0      0      0      Sub1
2      0      10     90     Sub2
2      10     0      180    Sub3
2      10     10     270    Sub4
```

Field 1: 2 defines a *sub-board line*

Field 2: *X coordinate* of reference of each sub-board

Field 3: *Y coordinate* of reference of each sub-board

Field 4: *theta rotation* (in degrees) of each sub-board

Field 5: defines the *name* of the sub-board

### ***Program Detail***

---

The following portion defines the *program detail* for each sub-board:

```
6      0      0      0      S/0805
6      1      0      90     S/1206
6      1      2      180    S/1210
```

Field 1: 6 defines an *operation line*

Field 2: *X coordinate* of each operation

Field 3: *Y coordinate* of each operation

Field 4: *theta rotation* (in degrees) of each operation

Field 5: declares the name of the *operation* to use

## Export Data

Export Data exports dispenser programs and operating information in dispenser format, commonly used for data base and spreadsheet data transfers, to any of the following: file on the dispenser, network file, or floppy disk.

Refer to the *Import/Export Data Reference Guide* for a complete discussion of data conversion and related, in-depth details.

### **IN EFFECT AS OF FLOWare software version 2.6**

The export selection function has been improved and is now faster, more flexible, and provides more selection options for expanded data export results. Data files used and created by previous versions of Export can be used with this newer version.

**Transferring Data between Dispensers.** Exported files are very useful when transferring data from one GPD Global dispenser to another.

### **IN EFFECT AS OF FLOWare software version 2.0 and later**

Export files can be used to export data from one version of the dispenser software and import it to another version, although some fields may be lost in the transition.

### **IN EFFECT AS OF FLOWare software version 1.9 and earlier**

Export files can be used to export data from one version of the dispenser software and import it to another version.

## File Structure

### **IN EFFECT AS OF FLOWare software version 2.6**

Additional information is automatically added to the file structure of an export file. Each time an export file is created, it will now contain the following elements for identification purposes:

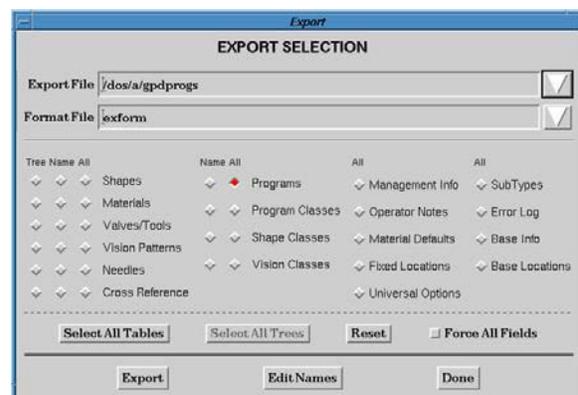
- the date and time the export was performed,
- the version of FLOWare software used to perform the export, and
- the name of the machine where the export was performed.

## Using the Exporter

Use the Export Data feature to export data to a dispenser file, a network, or a floppy disk.

To export data:

1. At the main menu bar, click on Utilities > New Export. The Export window displays.
2. In the Export File field, enter the name of the file to receive the export by either of the following means:
  - Type in the path and name, or
  - Click the Export File Name triangle button to select the file path and name. For details on how to make a selection, refer to [File Selection](#) (pg 2.21).



3. The format file is normally created by an editor and lists only the fields (tables) you want to select in the order you want them to appear in the export file. In the Format File field, enter the file name of the desired format by either of the following means:
  - Type in the path and name, or
  - Click the Format File Name triangle button to select the file path and name.
4. Select any combination of options. Choose whether to export everything or limit selections exported according to the following choices. Entries can be added to and subtracted from the list of tables to be exported until you click the EXPORT button.

**Table 10: Export Options**

To:	Do this:
export everything	click on SELECT ALL TABLES. Every ALL button will be activated.
export everything for a particular table	click the ALL button for the desired table.
force the creation of all fields	click on FORCE ALL FIELDS.
export some, but not all, available items from a table	click the NAME button for the desired table to invoke a list, then choose names for export.
add additional names	click the desired NAME button off and on. The complete list of currently selected names for that table will reappear so additional selections can be made. To verify that your additions have been added to the export format file, click EDIT NAMES.
remove names	click EDIT NAMES to invoke the list of currently selected names, then delete any number of names.
reset to the default setting	click on RESET. Only the ALL button for Programs will be activated.
reset an individual NAME or ALL button	click on the NAME or ALL button to turn it off. This cancels any selections associated with the button from being included in the export format file.

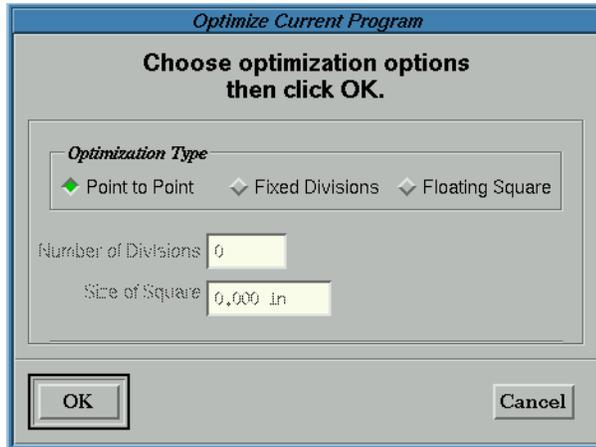
5. Click EXPORT to execute file export. A prompt will indicate when exportation is complete.

## Optimize a Program

The Optimize feature reorganizes the current program to minimize execution time. Typically, Optimize is used on programs originally optimized for pick-and-place machines.

**NOTE:** Optimize is not intended for use on programs containing drawing-type operations such as Move and Arc.

From the Program Editor, click on Utilities > Optimize. The Optimize Current Program window displays.



### Fastest Program

To obtain the best program execution time, try each optimization option on a copy of your program and then compare the results.

### Shape Optimization

To optimize a shape, create the shape as a program, optimize the program, and then convert the program to a shape.

## Update a Program

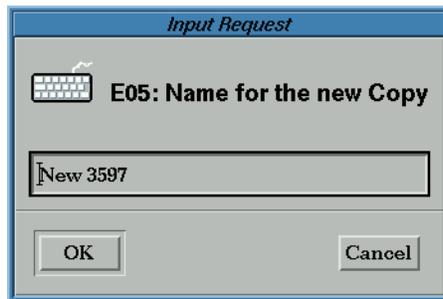
Easily update a program by copying or renaming an existing program before making any necessary changes to make the new program unique.

### Copy Program

The copy program feature enables you to copy the currently selected program or shape and assign a new name to the copy.

To copy a program or shape:

1. In the Program Editor, select the program to be copied.
2. In the Program Editor menu bar, click on Edit > Copy. An Input Request window displays.



3. Type the new name to be assigned to the program or shape copy.
4. Click OK. A copy of the selected program or shape is created.

### Rename Program

1. In the Program Editor, select the program to be renamed.
2. In the Program Editor menu bar, click on Edit > Rename Program. An Input Request window displays with the word "New" preceding the name of the selected program.



3. Type the new program name.
4. Click OK. The new name is assigned to the selected program.

## Convert Program

Use the Convert feature to perform any of the following conversions while leaving the original program or shape unaffected:

- convert a shape to a program,
- convert a program to a shape, or
- convert a program to a subboard.



**IMPORTANT:** Limit your use of program-to-shape conversion to programs containing only a single partition line because shapes cannot contain multiple partition lines.

To convert a program or shape:

1. From the Program Editor, select the program or shape to be converted.
2. From the Program Editor menu bar, click Edit > Convert... and then select the appropriate choice:
  - Program -> Shape
  - Program -> SubBoard
  - Shape -> Program
3. Enter a name for the new shape, program, or subboard at the prompt that displays.

Newly converted programs or shapes will display in the list of available programs or shapes in the Program Editor. Newly converted subboards will display in the list of defined boards in the [SubBoard Editor](#) (pg 5.101).

## Refresh Program

Use the Refresh Program function when the list of programs or shapes displayed in the Available Items panel of the Program Editor might not be accurate. For example, newly imported programs will not display until Refresh Program is activated.

## Alter Reference Point & Fiducial Points

Changing reference points and making corrections to fiducial points requires an understanding of the relationship between these two different types of coordinates.

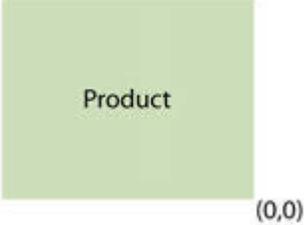
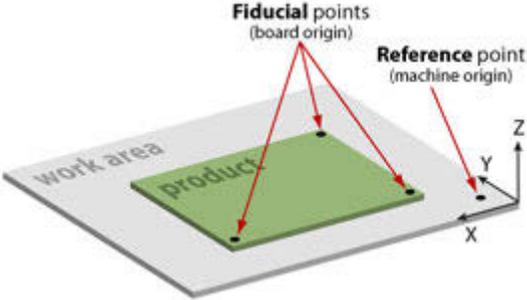
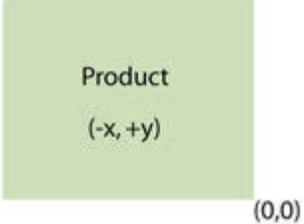
**CAUTION:** Changing the reference point for an existing program WILL shift dispense placement. Changing fiducial points for an existing program has the same potential; it MAY shift dispense placement.

### Relation of Reference Point to Fiducial Points

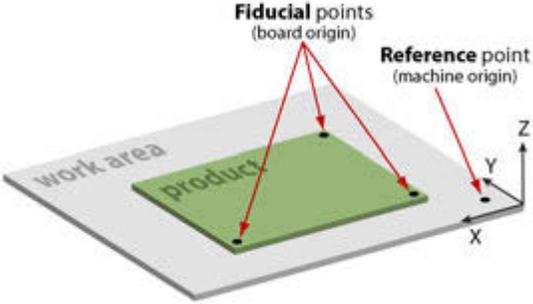
A reference point and from one to three fiducial points are both used to locate product in relation to the gantry.

Reference point is measured in relation to the machine, while fiducial points are measured in relation to the reference point. Other distinguishing characteristics are listed below to illustrate how the reference point and fiducial points are used together but are, in fact, different.

**Table 11:** Comparing Characteristics of Reference Point & Fiducial Point

Reference Point	Fiducial Point
<p>The Reference Point associates the default with the work area origin point (0,0).</p> 	<p>A Fiducial Point is measured in relation to the Reference Point.</p> 
<p>The Reference Point is a product-related point. Everything on the product is measured from the Reference Point.</p> <p>If Reference Point uses the default coordinates (0,0), then all product values and defaults will have (-x, +y) coordinates.</p> 	<p>A Fiducial Point is used to align product with all other product features. Three-point fiducial correction is used to compensate for product stretch and rotation. [Further details at <a href="#">Using Multiple Fiducials</a> (pg 3.38)].</p>

**Table 11:** Comparing Characteristics of Reference Point & Fiducial Point (Continued)

Reference Point	Fiducial Point
<p>The Reference point is typically located on the product, but can be located anywhere on or off the product.</p> <p>If the Reference Point uses coordinates other than the default, then product value and default coordinates will be defined (as shown here) in reference to the Reference Point, wherever it may be located.</p>	<p>A Fiducial Point is a mark located on the product.</p> 
<p>Alternate coordinates are generally used when converting pick-and-place data or CAD data; data coordinates are all measured from <i>somewhere</i>; the <i>somewhere</i> coordinates become the Reference Point.</p>	
<p>The Reference Point and Fiducial 1 frequently use the same location. This scenario requires Fiducial 1 coordinates of 0,0.</p>	

## Programming - Basics

This section provides details about how to use various program creation features. For insight into how these features work together, refer to the [Creating a Basic Program](#) (pg 4.1).

- [Dispense Parameters](#) (pg 3.18)
- [Main Window](#) (pg 3.24)
- [Program Editor](#) (pg 3.31)
- [Program Detail](#) (pg 3.43)
- [Operator Instructions](#) (pg 3.47)
- [Print a Program](#) (pg 3.48)
- [Programming with Shapes](#) (pg 3.50)
- [Teaching a Pattern](#) (pg 3.62)
- [Setting Up Valves & Tools](#) (pg 3.66)

## Dispense Parameters

This overview of the fundamental dispense parameters for gantry motion and valve control illustrates how these parameters interrelate with the programming to produce desired dispense results for a basic dot, rectangle, circle, line, or pillar.

- The terms used in the following samples of dispense operations are defined in [Parameter Definitions](#) (pg 3.20).
- An understanding of the basic [Operation Stages](#) (pg 3.21) is also helpful while reviewing the following samples.
- [Sample Dispense Operations](#) (pg 3.18)
- [What are the Differences between a Line and a Move?](#) (pg 3.22)

## Sample Dispense Operations

Each of the following graphics illustrates all of these concepts:

- a complete dispense operation,
- the three basic stages that comprise each operation,
- the needle movement through time and space involved, and
- the interrelation of the dispense parameters applicable to each step of the operation.

**Figure 4:** Sample of basic Dot operation

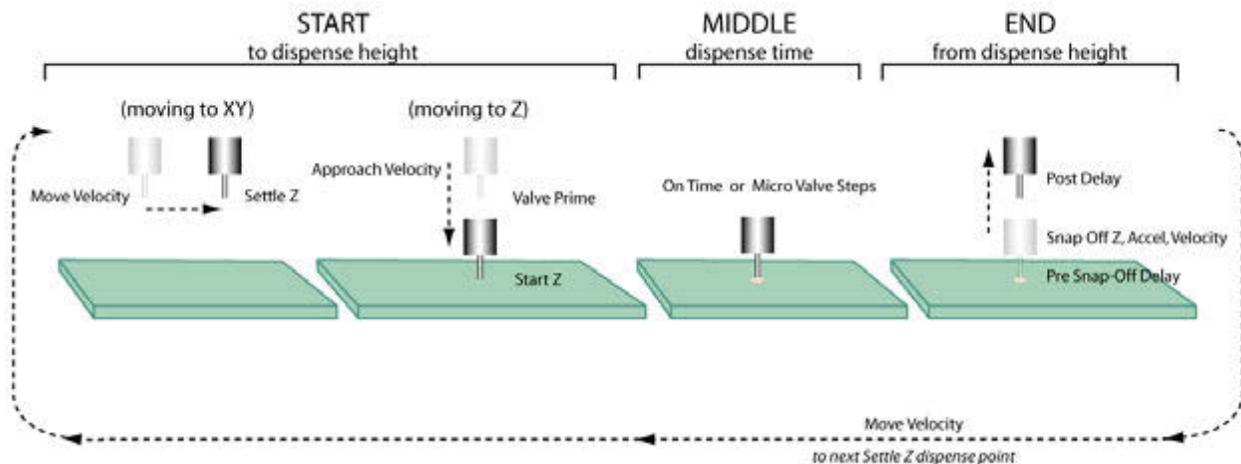


Figure 5: Sample of Pillar (tall dot) operation

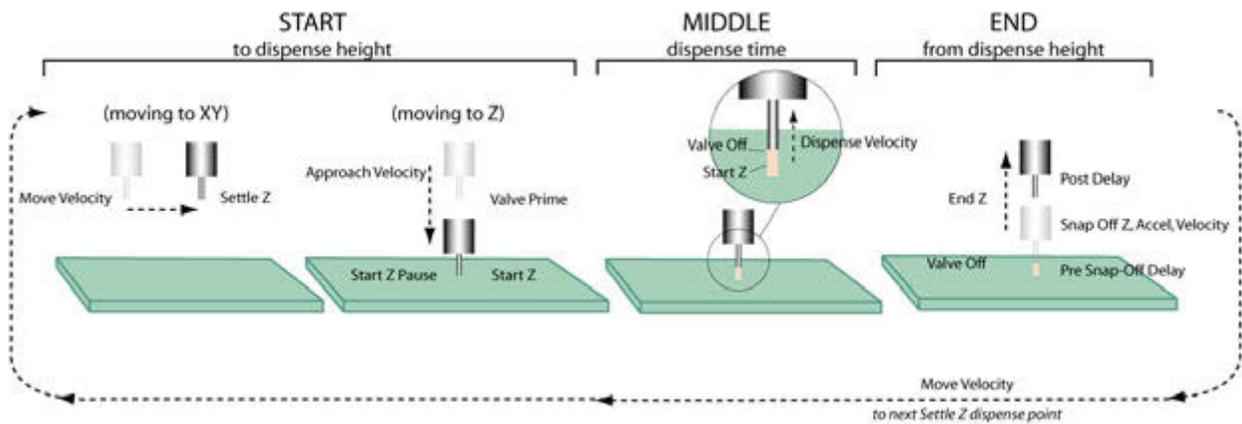
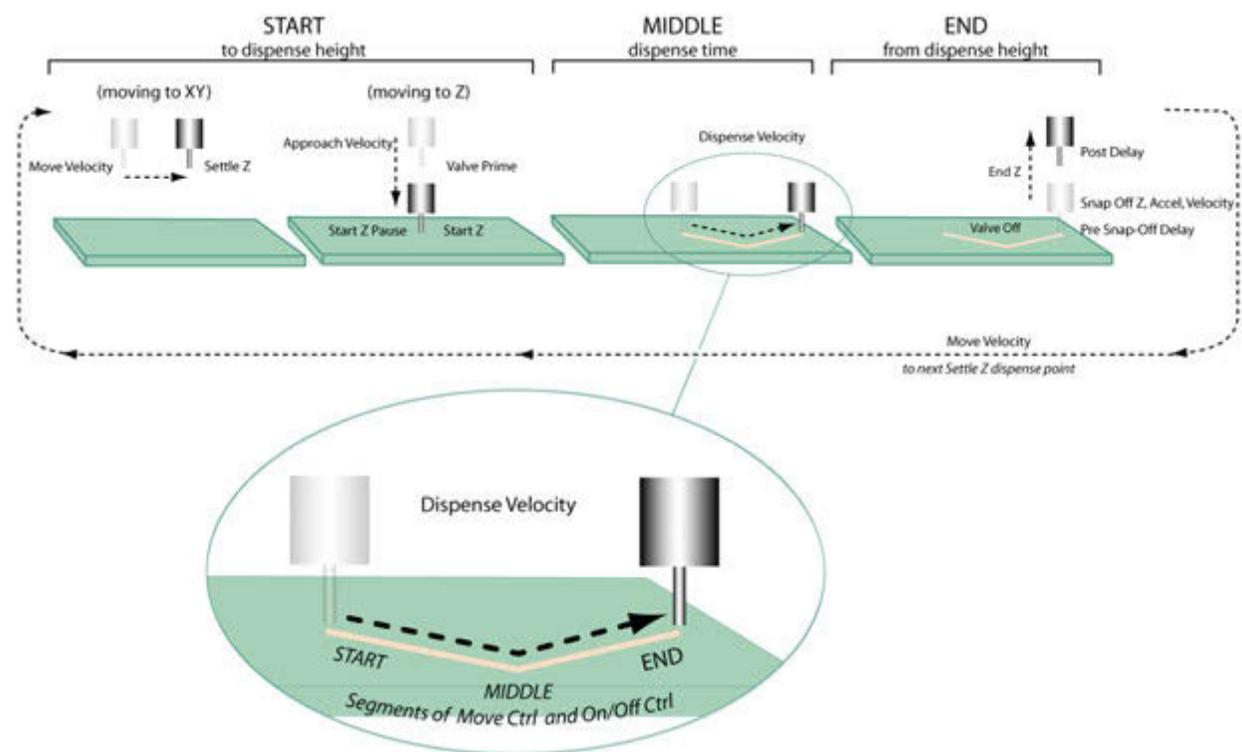


Figure 6: Sample of Connected Move (rectangle, circle, line) operation



## Parameter Definitions

This list of parameter definitions is only a *starter kit* of the most commonly used dispense parameters. It is by no means a complete listing of all available dispense parameters.

### Move Velocity

Coordinated XYZ axis movement to the next dispense location at Settle Z height. Typically, the default for system velocity is used for increased production throughput even though this is a programmable parameter.

### Approach Velocity

Speed of needle movement from Settle Z height to Start Z height. Used to minimize the Z axis from overshooting the Start Z value.

### Settle Z

Distance from Start Z at which the needle/gantry settles and then only Z axis motion begins moving toward the board surface at Approach Velocity. Used to avoid running the needle into tall board elements. Can be used in conjunction with Snap Off Z to maintain a high needle height during movement to the next dispense location.

### Valve Prime

Time the valve turns on prior to reaching Start Z height. Used to prime the needle tip with material so material is ready to flow from the tip when the needle reaches Start Z height.

### Start Z

Initial needle height above the substrate surface. This is the starting point for the program.

### Start Z Pause

When the system reaches Start Z height, the valve turns on and pauses for the set time prior to needle movement. Used to wet material to the substrate surface in order to prevent voids in the material at the beginning of the dispense.

### On Time

(does not apply to Micro-Dot valve) Time the valve is on. Main control of dispensed volume.

### MicroValve Steps

(for Micro-Dot valve) The number of motor counts. Main control of dispensed volume.

### Dispense Velocity

Speed at which the needle travels from one location to the next. Dispense Velocity is the speed between segments of a coordinated move. The move between locations (dot-to-dot) is controlled by the Move Velocity. Used to achieve smooth, consistent material flow for line dispenses and area fills.

### End Z

Upward dispense motion of only the Z axis above Start Z. Used to create taller dot profiles (pillars). Also used with Start Delay for puddled or angled (ramped) lines.

### Valve Off

The distance before reaching the end of the dispense (End Z) at which the valve turns off. Used to prevent material tailing by turning the valve off before the dispense is complete. The final portion of the dispense action relies on dissipation of material pressure inside the needle.

**Snap Off Z**

Distance the needle moves from the last dispense height after dispense is completed. Used to separate the needle from the material.

**Snap Off Velocity****Snap Off Acceleration**

Speed at which the needle performs snap off. Used to control material tailing.

**Pinch Delay**

**IN EFFECT AS OF FLOWare software version 2.9.3P**

The value of the Pinch Delay parameter determines whether normal pump operation or **deferred pump reverse** operation will occur. The difference between the two operations occurs immediately after the servo pump is turned OFF at or near the end of a Line/Arc/Move operation. Refer to the *Programming - Keys to Success* section of *Using FLOWare Software*.

**Pre Snap-Off Delay**

Delay time after the dispense that the needle remains at dispense height prior to performing snap off. Used to allow material to fall away from the needle prior to leaving the current position.

**Post Delay**

Delay after Snap Off Z is performed. Used to allow materials to cleanly separate from the needle before proceeding to the next operation.

**IN EFFECT AS OF FLOWare software version 2.9.1**

All operations using a PostDelay value greater than zero will await completion of the SnapOffZ motion and then begin the Post Delay delay. If Post Delay is less than or equal to zero, the wait for motion complete will not occur.

**IN EFFECT PRIOR TO FLOWare software version 2.9.1**

All operations using a Post Delay value wait for SnapOffZ position to be achieved before beginning Post Delay time ONLY when the head type is an Etch, Rout, Drill, or Pickup tool. All other head types do not wait for SnapOffZ to be achieved. The Post Delay is the sum of the Pinch Delay value and the Post Delay value beginning near the beginning of the SnapOffZ motion. Operation sequence is as follows:

- 1 - Move to SnapOffZ.
- 2 - If head type is Etch/Rout/Drill/Pickup, wait for motion complete.
- 3 - Operate SuckBack, if appropriate.
- 4 - Delay - PinchDelay (from Mount info).
- 5 - Delay by one of following (controlled by ValveControlFromDetail):
  - \* PostDelay (from detail line).
  - \* PostDelay (from mount info).

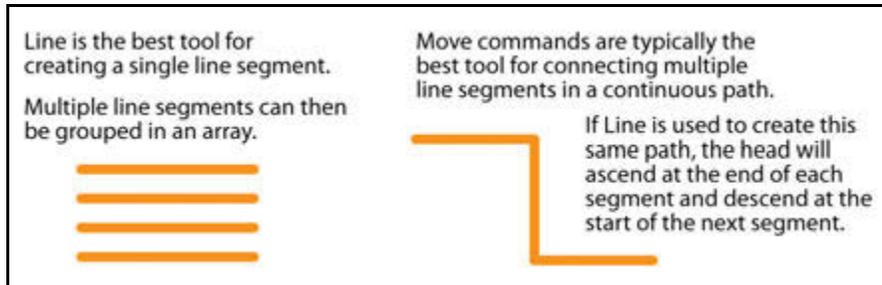
**Operation Stages**

A dispense operation is always composed of the following three basic stages. See illustrated examples at [Sample Dispense Operations](#) (pg 3.18). For details, refer to [Move Controls](#) (pg 3.46).

Start	moving the needle into position and turning on the valve
Middle	performing the dispense function
End	turning the valve off and moving the needle to achieve material snap off

## What are the Differences between a Line and a Move?

When it comes to creating a series of lines, is the best tool for the job *lines* or *moves*? How do you choose? The following is a quick guide:



- [Lines](#) (pg 3.22) are simpler to use when you want to create a single motion, single line segment dispensed in a straight line from point A to point B.
- [Move Commands](#) (pg 3.23) are the better choice when you want to connect multiple line segments in a continuous path without raising the head.

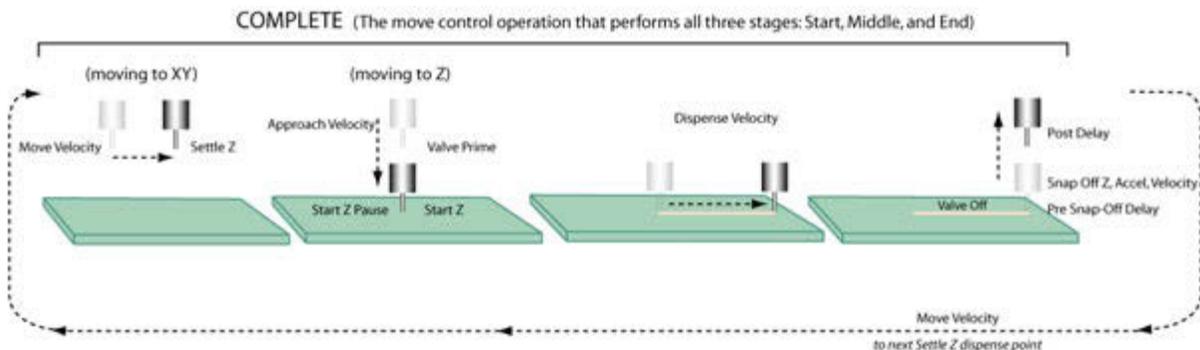
## Lines

A line dispense is a *single* complete dispense motion. A line begins at the coordinate point and ends at a point you specify in the Size X, Size Y fields. A line automatically turns off the valve at line completion; (you can override this timing and shut the valve off earlier using the Valve Off field).

The following is what occurs during a line dispense:

1. The gantry moves over the line coordinates and lowers the head to Settle Z height.
2. At Approach Velocity, the gantry moves down to Start Z height, dispenses to the point specified in Size X, Size Y, and also to [End Z](#) (pg 3.20) height if greater or less than 0.00.
3. Once the gantry reaches the point specified by Size X and Size Y, it shuts off the valve and snaps off to Snap Off Z height at Snap Off Z Acceleration and Snap Off Velocity.

**Figure 7: Sample of a Single Line Segment**



## Move Commands

---

Move commands are used to perform a continuous dispensing motion. The valve can be turned on and off at any time during any of the intermediate moves.

**HINT:** Each move command is a single-part operation (Start, Middle, End). When used in sequence, you can build a connected motion. The sequence of move commands determines the path and valve behavior that occurs during the continuous motion.

Refer to [Move Controls](#) (pg 3.46) for a more in depth discussion of all of the move operation parameters (Complete, Start, Middle, End, and No Operation).

The following [Operation Stages](#) (pg 3.21) help illustrate further differences between [Lines](#) (pg 3.22) and the use of move commands:

1. **The beginning** - You specify a starting point (point A) set to START using the MOVE CTRL button.
2. **The middle** - Then you can add a series of moves, arcs, rectangles, and circles for one continuous motion that moves to all new coordinate points (point B, C, D, etc.). All of these intermediate moves are set to MIDDLE using the MOVE CTRL button.

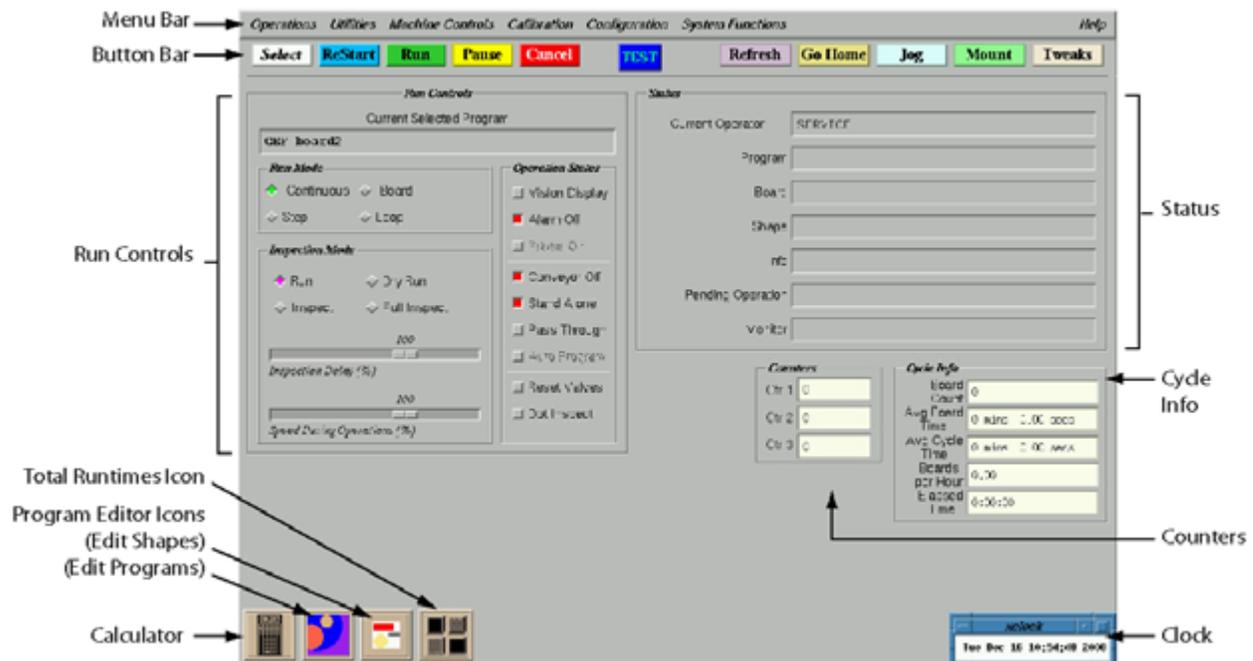
[Start Z](#) (pg 3.20) or [End Z](#) (pg 3.20) can be used to change Z height during these moves. Start Z and End Z accomplish the same result when applied to an intermediate operation.

The valve can be set to turn on and off at any time during any of these intermediate moves. Use the ON/OFF CTRL button to implement these actions.

3. **The end** - Set the final move to END using the MOVE CTRL button so it will snap off to Snap Off height and proceed to the next command in the program.

## Main Window

The main control window displays when the system is ready to run and is the site where all user interaction with the FLOWare control software begins. Whether or not all menu bar and button bar choices are displayed depends on the current access rights. All choices are displayed here.



## Main Menu Bar

Each item in the main menu bar has a drop-down menu. Current access rights control which of the main menu bar items are available for use. Typically, an operator will have access to Operations and some or all of the Utilities drop-down menu items.

### Operations

Displays a drop-down menu of basic operations such as [Enter a Password](#) (pg 5.13), [Clear a Password](#) (pg 5.13), [Material Expiration \(Pot Life\)](#) (pg 4.59), [Shutdown](#) (pg 2.2) of the system, [Boot with Reboot](#) (pg 6.30), exiting the main control window, and displaying the [Icons](#) (pg 3.29) that appear along the bottom edge of the main control window.

Exit Main should not be used. If this operation is activated inadvertently, restart the machine to re-display the main window.

### Utilities

Displays a drop-down menu of utility functions. For details about backups, see [Routine Backups](#) (pg 6.14); for data import, export, and conversion topics, see [Using Existing Programs](#) (pg 3.2); for installing and upgrading software, see [Installing & Upgrading Software](#) (pg 6.13); for using a USB device, see [USB Port](#) (pg 2.9); and for data management, see [Account Management](#) (pg 6.3).

**Machine Controls**

Displays a drop-down menu of manual [Machine Controls](#) (pg 7.4) choices which are not intended for typical customer use.

**Calibration**

Displays a drop-down menu of [Calibration](#) (pg 3.125) choices for conveyor speed and width, mapping, camera vision, the precision scale, and more.

**Configuration**

Displays a drop-down menu of [Configuration](#) (pg 3.136) choices. Of particular interest is the [Option Settings](#) (pg 3.136) choice; the other choices are not intended for typical customer use.

**System Functions**

Displays a drop-down menu of various [System Functions](#) (pg 7.7) which are not intended for typical customer use.

**Help**

Click on Help > About to determine which version of the FLOWare software is currently installed on the system.

**Main Button Bar****CANCEL**

Ends program execution. Once a program is canceled, it can only be restarted from the beginning with the normal Run procedure. Occasionally, a program will not abort immediately because the current operation has to execute fully.

**GO HOME**

Moves the gantry **quickly** out of the way (to coordinates taught during configuration of base locations).

**JOG**

Enables manual control of camera/gantry movement and position. Refer to [Jogging the Gantry](#) (pg 2.7).

**MOUNT**

Opens the [Mounts Table](#) (pg 5.57) window in preparation for product to be mounted in the dispenser manually. On conveyor systems, the lift plate rises to support product. On stand-alone systems, the board crowders will lock.

**PAUSE**

Stops the current operation at a convenient place in the program; that is, gantry motion may not stop immediately after you click PAUSE. This is a non-destructive command; the system will not stop in the middle of a dispense of any kind. Operations may be resumed when convenient by clicking the RUN button.

**REFRESH**

Moves the gantry to the front of the machine (to coordinates taught during configuration of base locations) for easy access to the valves.

**RESTART**

Functions the same as the RUN button except none of the setup parameters are changed. RESTART will not prompt for the lifter pins to be repositioned, and, if pallets or feeders are being used, the program will continue where it left off without resetting the pallets or feeders (where using the RUN button will start the program at the beginning of the pallet or feeder).

**RUN**

Starts the currently selected program in the current program mode after prompting the operator to calibrate the heads and load the product.

**SELECT**

Lets you choose a program to run. The dispenser will always run the currently selected program.

**TEST**

This button is for software development purposes only.

**TWEAKS**

Opens the [Live Program Adjustment](#) (pg 5.46) window. Intended as an on-the-fly program adjustment feature for use during program development, [Tweaks for Valves/Tools](#) (pg 3.120) can be used during a program run to adjust machine parameters per valve mount station. All listed parameters can be changed by a percentage based on the original program.

**Run Controls**

In addition to displaying the name of the currently selected program in Current Selected Program, the Run Controls panel includes:

**Operating Modes**

The user can select one of two operating modes, Run mode or Inspect mode; each with a variety of operation patterns. These modes determine whether the current program runs as designed or allows for inspection of the program without executing its operations.

**NOTE:** Mode settings are independent of programs, with the default mode being the mode of the previously selected program.

**Run Mode**

The run mode determines how the currently selected program will execute. Of the four available operation patterns, the Continuous choice is generally used for normal production patterns and Loop is typically used as a demonstration or test mode.

**Table 12: Run Mode Operating Patterns**

Pattern	Description
Continuous	Program execution continues without pause except for required operator intervention.
Board	Processes a subboard on a panel without pause, except for required operator intervention, and then prompts the operator before processing the next panel. The operator can either continue with the next subboard or skip it.
Step	Processes a single program step and then prompts the operator to continue.
Loop	Processes the same board repeatedly without pause except for required operator intervention.

## Inspection Mode

The inspect mode determines how the currently selected program will be processed - either in full or in one of the various inspection modes. This mode is typically used for [Testing & Inspecting](#) (pg 3.118) and visually inspecting program execution.

**Table 13: Inspection Mode Operation Patterns**

Pattern	Description
Run	The program executes as designed; use for normal activities.
Dry Run	Same as the Run pattern except no head operation or material dispensing occurs and no movement below the board surface (trace cutting) is made.  Use to research such concerns as whether or not the dispense needle heights in a program are set properly, or to verify whether or not all program locations have been taught.
Inspect	The camera, not the heads, moves to the coordinates of each program line providing visual inspection of the program. The gantry pauses for a specified time at each location to allow inspection. To adjust pause duration, use the Inspection Delay slider.  Use to show the first XY coordinate for the start of a primitive shape and show that point, and to skip all calculated points and then go to the next shape.
Full Inspect	Same as the Inspect pattern except the camera moves along the path intended for the head(s), showing all calculated points.  Use to research such concerns as if the correct locations have been taught, if the offset dot locations are repeatable, and if the valve moves to the correct location. To adjust speed, use the Speed During Operations slider.

## Inspection Sliders

In addition to clicking on the desired inspection operation pattern, use the slider bars (also located in the Inspection Mode panel) to set operation parameters:.

**Table 14: Operation Parameters set with Sliders**

Slider	Description
Inspection Delay	Length of time the camera will wait over a coordinate.
Speed During Operations	The relative speed, either faster or slower than the current setting, at which the camera moves over moves, fills, lines, and arcs during a Full Inspect.

## Operation States

---

Operation States control conveyor and camera operations. One or more states can function at a time. To select an operation state for the camera, alarm, conveyor, printer, etc., click on the toggle box of each state you wish to activate/disable.

Operation states are independent of program modes, but like program modes, the previously selected state is the default state; that is, operation states are independent of programs. One or more states can function at a time. Click on the box of each state you wish to activate.

### Vision Display

Displays the camera image whenever the camera is located over a significant feature.

### Alarm Off

Toggle control for enabling or preventing the audible alarm from operating. When set to ON, the alarm will sound under these conditions:

- a head requires attention,
- a manually mounted item requires attention, or
- the machine times out.

State	Appearance & Behavior
On	alarm is on when the Alarm Off toggle box appears gray and raised. When an alarm condition occurs, the alarm continues beeping until the user either clicks OK on the message prompt or turns the alarm off.
Off	alarm is off when the Alarm Off toggle box appears red and recessed. The alarm will not beep when an alarm condition occurs. There are no messages that override the Alarm Off condition.

### Silencing the Alarm

To silence a beeping alarm, click Alarm Off and then click it once more to reactivate the alarm in case an additional alarm condition occurs.

### Printer On

Activate this toggle box to use a printer attached to the dispenser parallel port. For details, refer to [Print a Program](#) (pg 3.48). Various other system print controls (such as Print Scale Values) can also be set to print and then be globally controlled here.

### Conveyor Off

Turns on the conveyor belt briefly in order to seat a board against the nest stop pin, making this a convenient conveyor state control when developing or testing a program. To use this operation state to emulate a manual dispenser with no conveyor, see [Emulate Stand-Alone Dispenser](#) (pg 3.119).

### Stand Alone

Causes the conveyor to ignore upstream and downstream signals, thus requiring manual product placement and removal, providing a convenient method of conveyor state control for program development and testing. To use this operation state to emulate a stand-alone conveyor dispenser or a manual dispenser with no conveyor, see [Emulate Stand-Alone Dispenser](#) (pg 3.119).

### Pass Through

Inhibits all machine processes except that of passing product through the machine on the conveyor. Use this in an inline environment when a product requires no functions

from the dispenser but you want to move boards from the upstream unit to the downstream unit.

The pass through state controls the program rather than the machine; you can select and activate a program and the machine will still look for board information but will not act on it. The board will not be processed but the machine will read SMEMA signals and operate conveyor width, conveyor pins, board width, and stop pin timing.

To:	Do this:
turn ON	1 - In the main button bar, click SELECT and select a program. 2 - Click the Pass Through toggle box to turn ON. 3 - In the main button bar, click RUN.
turn OFF	1 - In the main button bar, click CANCEL. 2 - Click the Pass Through toggle box to turn OFF.

### Auto Program

(Also referred to informally as Auto Mode.) Enables a device outside the dispenser, such as a matrix reader, to scan information, such as a barcode, from incoming product and then dictate various instructions to the dispenser, such as which program to run, the number of boards to run before the next program, etc.

### Reset Valves

Provides a quick reset of the valve controller for a Micro-Dot valve, causing the system to recognize the head in cases where the valve is installed on the system after the system has already been powered on.

### Dot Inspect

Not currently functional; it has no effect on anything in either the On or Off state.

## Icons

Several icons are located in the bottom corners of the main menu window:

### Calculator

Double-clicking the calculator icon displays a fully operational, standard X-Windows feature calculator. Functions can be performed with the trackball or with the keyboard. To remove the calculator, double-click the button in the upper left corner of the calculator. To restore the calculator, click on Operations > Calculator.

### Clock

The clock icon displays the system date and time. To remove the clock, double-click the button in the upper left corner of the clock. To restore the clock, click on Operations > Clock.

### Program Editor Icons

The Program Editor icon is displayed as one of two variations. Either the Edit Programs or Edit Shapes icon will display depending on which selection tool is active in the Program Detail window. To restore a Program Editor icon, click on Operations > Edit.

### Total Runtimes

Total Runtimes is an add on application that displays current accumulated "run times" in its own window. For details, refer to *FLOWare Software Guide Addendum Total Runtimes*.

## Status

In addition to displaying the name of the current user and the names of the program, board, and shape currently being processed, status fields also provide the following data:

### Info

Displays information when a process is waiting, such as *loading a program*, *operating in pass-through mode*, or *waiting to release the exit board*. When in Inspect Mode, the operation being executed displays.

### Pending Operation

Displays the pending operation when a pallet is at a fixed location and the pallet needs to be changed.

### Monitor

Data is only displayed in the Monitor field while a program is active. When the program ends, the Monitor field resets to empty. For details, refer to [Monitoring Program Details](#) (pg 3.139).

### Material

When the [Material Expiration \(Pot Life\)](#) (pg 4.59) feature is enabled, this status field displays and presents either the time remaining for the current material or an indication that the material is expired. If this feature is disabled, the field does not display.

## Cycle Info

Tracks cyclic aspects of a program run. All fields reset to zero when a program run is initiated.

### Board Count

The number of boards processed through the dispenser during the current program run. When applied to pallets, the complete board, not the individual pallets, are counted.

### Avg Board Time

The average time per board spent executing program commands. The first board in a program typically takes longer to run due to the calibration process that occurs at the beginning of a program run.

### Avg Cycle Time

The average time per board to complete a cycle includes Avg Board Time plus all other events that occur within the cycle, such as pausing for operator intervention, waiting for upstream/downstream equipment, etc.

### Boards per Hour

The number of boards processed during an hour based on the value of Avg Board Time.

### Elapsed Time

Time elapsed since the current program run began.

## Counters

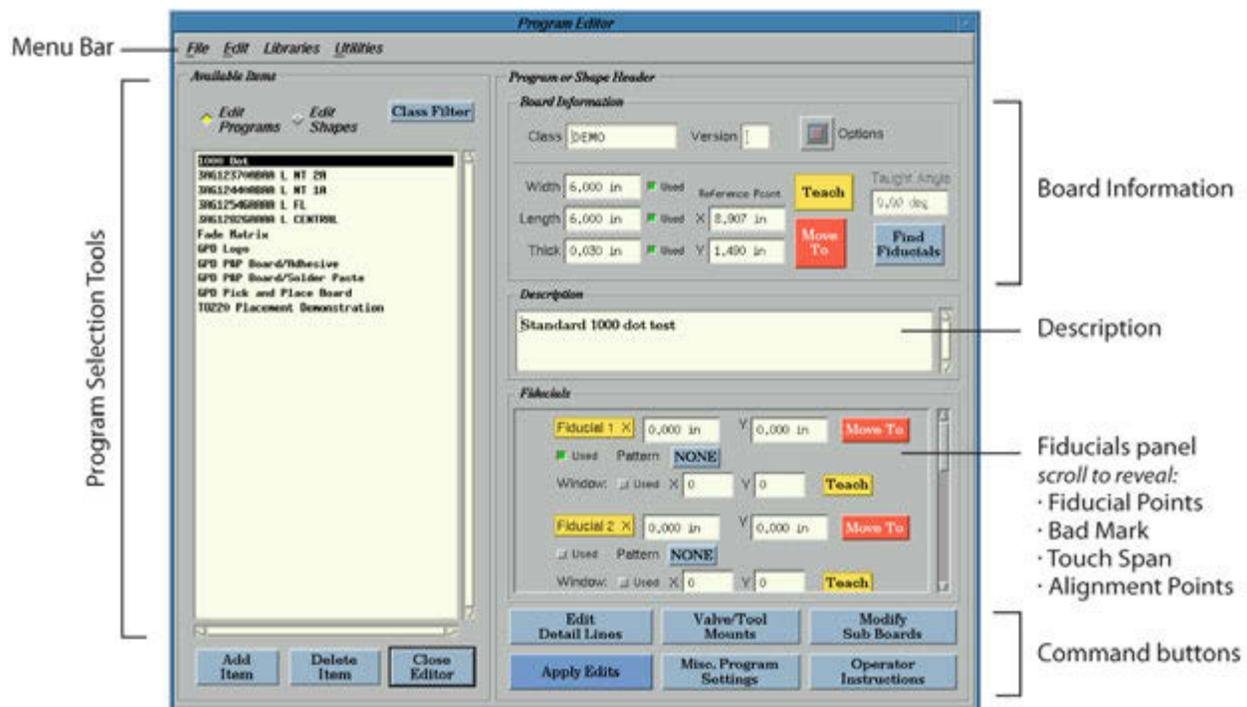
Various types of counters are available - those that increment or decrement, those that test one counter against another, and those that test a counter against a fixed value. Counter values display only during a program run when counters are used in the active program. Counters are added to a program as an OPERATE line with a SubOp. For more details, refer to [Counter Usage](#) (pg 4.55).

## Program Editor

Program Editor provides access to the creation, modification, and selection of programs in addition to the libraries and tools that directly affect program characteristics.

Elements key to program creation are administered within the Program Editor. While accurate board information is critical for conveyor operations, using the class filter and shape version features can simplify your programming efforts; understanding the reference and fiducial points will help you avoid unexpected dispense results; the touch span feature is useful for close tolerance dispensing; and bad mark expands your programming strategy options.

To access Program Editor, click on the Program Editor icon on the main control window.



### Menu Bar

Each item in the menu bar has a drop-down menu.

#### File

Displays a drop-down menu for Print and Exit.

The Print choice prints the currently selected program with the option of reducing details by category if a printer is attached. Refer to [Print a Program](#) (pg 3.48).

The Exit choice, in addition to closing the Program Editor, also deletes the Program Editor icon from the main control window. Refer to [Program Editor Icons](#) (pg 3.29).

#### Edit

Displays a drop-down menu of tools for copying or renaming an existing program before making any necessary changes to make the new program unique. Refer to [Update a Program](#) (pg 3.13). Several menu items (Cut, Paste, Clear) are not currently functional.

## Libraries

Displays a drop-down menu of [Libraries](#) (pg 5.1) that pertain to the machine configuration. Each library is accessible with the proper access rights via the Program Editor.

## Utilities

Displays a drop-down menu for Optimize which reorganizes the current program to minimize execution time with either point-to-point, fixed divisions (number of divisions), or a floating square (size of square). Refer to [Optimize a Program](#) (pg 3.12).

## Program Selection Tools

### Edit Programs / Edit Shapes

This toggling selection tool determines whether the **Edit Programs** version or the **Edit Shapes** version of the Program Editor displays. The difference is most noticeable by which program names display in the Available Items panel.

### Available Items panel

The names of the currently available program or shape names as determined by the program selection tools (Edit Programs, Edit Shapes, and Class Filter) are displayed here.

### Classes

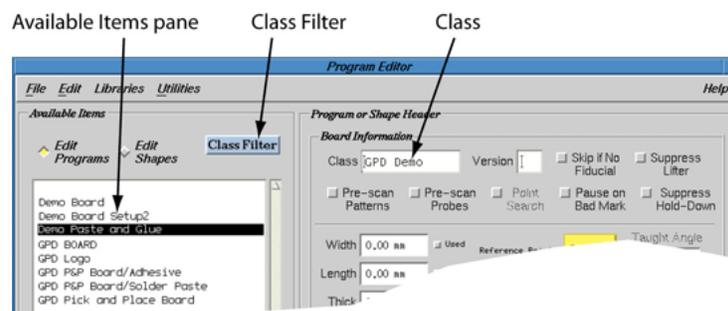
Classes are used to isolate programs for different product lines from each other.

**EXAMPLE:** For example, when working with product line ABC, you would create a class of ABC and then assign every shape and vision pattern used in the programming for this product line to the ABC class. One advantage to using classes is the ability it provides to limit operator access to only those classes of program to which they need access. Classes also enable program developers working with multiple products to restrict the display of programs and shapes to only those with which they are currently working.

### CLASS FILTER

Opens the Classes window where you can select a class of program or shape to display in the Program Editor list of programs. Use class filters to expand or restrict the combination of program or shape names displayed in the lists of program (or shape) names you see in the Available Programs window and the Available Items panel of the Program Editor window.

The class filter assigned to the current program is both displayed in and entered in the [Class](#) (pg 3.35) field.



Class filter follows these basic rules:

- Each program can have a single class.
- Each shape can have a single class.
- A *blank* is a significant class.



The "blank" at the beginning of the list signifies "no class"

Class filter can be used to accomplish the following:

- Expand the list of names to include ALL programs (or shapes).
- Expand or restrict the name list to ANY COMBINATION of programs (or shapes) you want to display.
- Restrict the list of names to ONLY programs (or shapes) with no class filter.

### ***Display by Class Filter***

To determine which programs or shapes display in the Available Items pane:

1 - In Program Editor, click CLASS FILTER. The Classes window displays. Illustrated here is the selection of only those programs with no class filter plus those with an Adhesive or Solder paste class filter.



2 - Select each class filter name of the programs or shapes you want displayed. The selected items will be the ONLY items displayed on ANY list of programs or shapes.

**Table 15: Selecting Class Filters**

To Select:	Do this:
All classes	click ALL.
No class	click the <i>blank</i> for none.
A single class	click on the class you want to select.
A combination of classes	hold down <Ctrl> and click each class you want to select/deselect.
To accept displayed selection as is	click CANCEL.

3 - Click OK. Only those programs with a selected class filter will now display.

### **Assign a Class Filter**

To assign a class filter to a program or shape:

1 - In Program Editor, either click on Edit Programs or Edit Shapes (to display programs or shapes) or else create a program or shape.

2 - Position the cursor so it highlights the program or shape to which you want to assign a class filter.

3 - Enter a class filter name in the Class field.

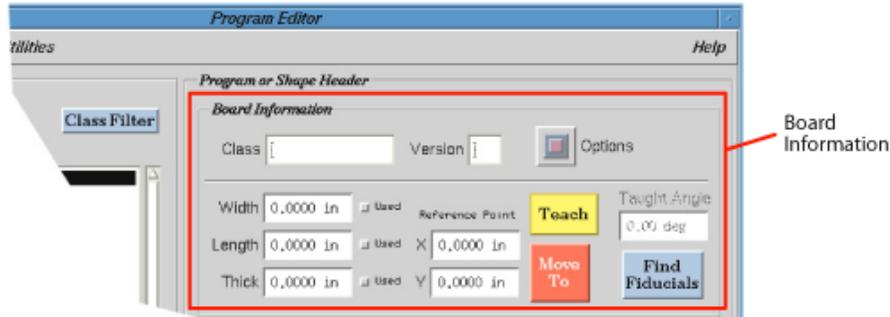
**NOTE:** When adding class names for **Shapes** only - When you click in the Class field in the Shapes version of Program Editor, a blank character is automatically entered. Use the BACKSPACE key to delete this blank character and then enter desired class name text. Do not use the back arrow key; if you do, the blank character becomes the last character in the new class name.

4 - Click APPLY EDITS to establish the entry.

5 - As needed, assign a class filter to more programs or shapes by repeating this procedure.

## Board Information

Board Information is a collection of board reference data and board processing options located in the Program Editor. While the numerous board processing options are indeed optional, Reference Point coordinates are essential data for all programs and the board dimension values directly affect conveyor operations.



### Class

The class filter assigned to the current program is entered and displayed here.

Use class filters to expand or restrict the combination of program or shape names displayed in the lists of program (or shape) names you see in the Available Programs window and the Available Items panel of the Program Editor window. For details, refer to [CLASS FILTER](#) (pg 3.32).

### Version

Any single character or number value may be entered in the Version field to control which version of a shape is used by a program. Version provides you with a quick way to switch between one set of shapes and another, and eliminates having to set up another program that is a duplicate except for the use of a different shape. Entering a prefix code in the Version field tells the program to use the shape name with that version prefix instead of using the shape name actually specified in the program.

For example, suppose you have two processes to run on an identical board. Create a base program using a “generic” shape of 0805. Before running process A, enter an A in Version so the system will look in the component library for an A/0805 shape and use those parameters to complete the process. For the second process, enter an S in Version so the system will search the component library for an S/0805 shape and use those parameters for the process. Using Version allows you to have one base program and easily change between processes by selecting the process type, i.e., the version prefix, such as A and S used in the preceding example.

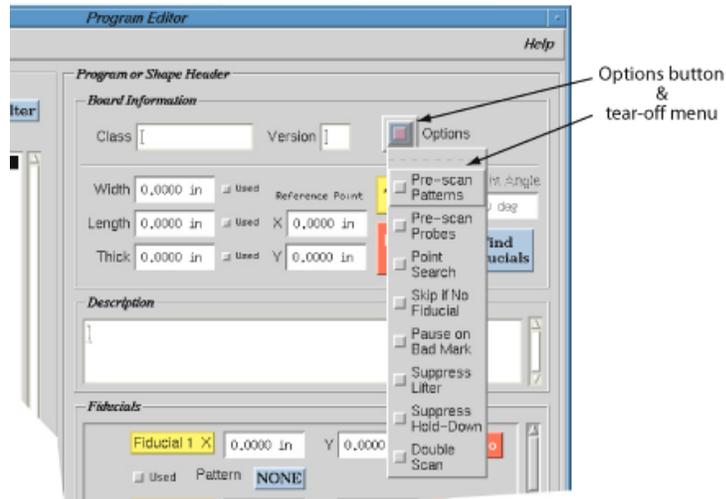
### **Changing Versions**

To change the shape version used by a program:

- 1 - In the Program Editor, position the cursor so it highlights the current program.
- 2 - Enter the shape prefix you want used by the program in the Version field.
- 3 - Click APPLY EDITS to save the entry.

## Board Options

A drop-down menu of options affecting how boards are processed. These options can be toggled on/off in any combination as needed. When turned on, each option performs as described in the following table.



**Table 16: Effect of Active Options**

Option	Results
Skip if No Fiducial	If a fiducial is missing, rather than stopping for operator intervention, the program will skip the board, subboard, or shape.
Suppress Lifter	Suppresses lifter plate operations.
Pre-scan Patterns	Requires a complete vision scan be performed before the program runs.
Pre-scan Probes	Requires a complete probe be performed before the program runs.
Point Search	Limits the search area for the vision system.
Pause on Bad Mark	Program will pause for operator intervention if a bad mark is detected.
Suppress Hold-Down	Hold-down vacuum on the board will be suppressed.
Double Scan	Performs a second fiducial search (thus slowing the fiducial scanning process). After the standard process of looking for a fiducial and moving the gantry based on search results is performed, a second fiducial search is performed and the gantry is again moved if a position correction is deemed necessary by the second search.

## Board Dimensions

The product reference data in Width, Length, and Thick are required by SMEMA and automatic adjust conveyor systems. Width may be used to set the width of an automatic conveyor; Length is used to improve conveyor operations; and Thick may be used to adjust camera calibration.

Successful conveyor operations require a value be entered in Length. Length works in conjunction with conveyor speed to successfully transfer boards between conveyor stop positions. If the boards have slots or holes, a Length value must be entered in the currently selected program to successfully convey these types of boards.

- When a value is entered in Length, the software can calculate when to expect the tail end of the board to pass the sensors.

- If no value is entered in Length, board detection is limited to the sensors which, if the boards have slots or holes, might lead to failure to detect board presence.

### Reference Point

This is the point upon which all other points in the program are dependent, including data points on the product and all values and defaults (except those defined as absolute). The reference point is used in conjunction with fiducial points to locate product in relation to the gantry. The reference point is measured in relation to the machine, while fiducial points are measured in relation to the reference point.



**IMPORTANT:** It is important to teach the reference point prior to teaching the fiducial points or unexpected fiducial point positions will result.

If the same location is to be used for both the reference point and the first fiducial point, then a zero value must be entered in the first fiducial coordinates. If you use the same coordinate values in the first fiducial as are used for the reference point, the location of the first fiducial will be offset from the reference point by the values entered in the first fiducial coordinates. For further discussion, refer to [Relation of Reference Point to Fiducial Points](#) (pg 3.15).

Reference point coordinate values are taught in the Program Editor by either entering the X and Y values manually or using the TEACH button. The MOVE TO button can then be used to visually verify the taught coordinates; it will move the gantry to the coordinates designated in the X and Y fields. Refer to [Buttons for Teaching Coordinates](#) (pg 2.17) for details.

### Description

Up to 250 characters of optional text can be entered in the Description field to describe the currently selected program or shape.

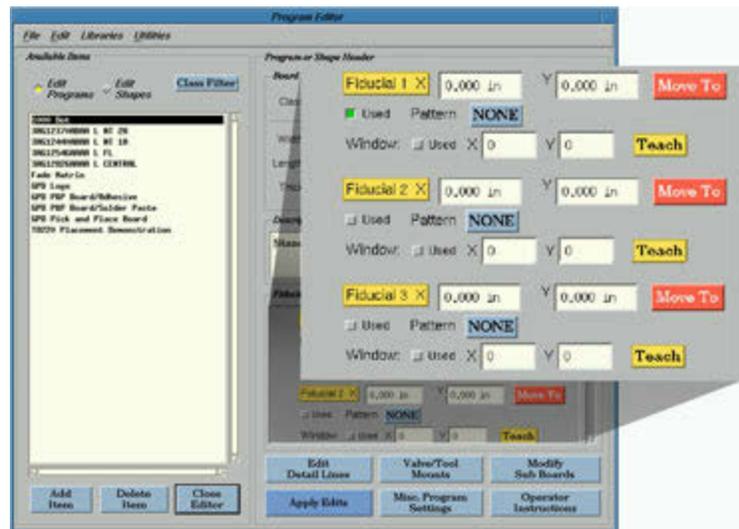
## Fiducials panel

### Fiducial Points

Fiducials are product orientation points and their use is optional but recommended for accuracy. Fiducial point locations must be defined if you want program adjustments to be made for product orientation. Three-point fiducial point correction is used to compensate for product stretch and rotation.

Patterns are used to define fiducials on dispensers equipped with automatic vision. Standard fiducial patterns are supplied, however, custom patterns can be taught. For details, refer to [Patterns Library](#) (pg 5.16).

Current fiducial coordinates display next to the FIDUCIAL X button which, when clicked, opens the Jog window for teaching fiducial coordinates. Editing fiducial values is accomplished by clicking the fiducial field and manually entering a new value.



### Rules of Fiducial Use

- Fiducial points can be set up in any order, however, if at least a single fiducial is defined and Fiducial 1 is left undefined, the program will default to the work area origin point (0,0) resulting in the use of the same location by both the first fiducial point and work area origin point.
- If the first fiducial point is to use a location different than that of the work area origin point, most commonly referred to as Reference Point, be sure to teach the Reference Point first; always teach the Reference Point before teaching fiducial points. For more information about machine and product origin points, refer to [Relation of Reference Point to Fiducial Points](#) (pg 3.15).

### Using Multiple Fiducials

When teaching multiple fiducials, you are advised to use the CAD print data diagram of the product. The XY data from the CAD print represents ideal orientation. Teaching multiple fiducials with the camera and a sample product can easily lead to skewed results.

For the most consistently accurate results, use consecutive fiducial points. For example, use Fiducial 1 only, or Fiducials 1 and 2, or Fiducials 1 and 2 and 3. Use the following guide when deciding how many fiducials to define.

**Table 17: Three-point Fiducial Point Correction**

Define:	To adjust for:
1 fiducial	(x,y) position only
2 fiducials	(x,y) position, adjust for product rotation, and <i>uniform</i> stretch in (x,y) directions For example, using 2 fiducials assumes that the product is square but will compensate for rotation.
3 fiducials	(x,y) position, adjust for product rotation, and independent stretch in (x,y) directions For example, using a 3rd fiducial will compensate for skew (out of parallelism). If the product is supposed to be square but happens to be a parallelogram, the system will adjust accordingly.

### Bad Marks

A bad mark is a pattern detected by the vision system at the board or shape level of a program. When a program executes, the control software searches for the bad mark pattern prior to searching for fiducials and performing dispense operations. Bad mark coordinates are relative to the [Reference Point](#) (pg 3.37).

A bad mark can be detected at either the board or shape level of a program for a board or subboard. When detected, a bad mark triggers one of three actions.

#### Using Bad Marks

When processing palletized (panelized) boards where the bad mark location may vary from board to board, use shapes with bad marks instead of subboards with bad marks.

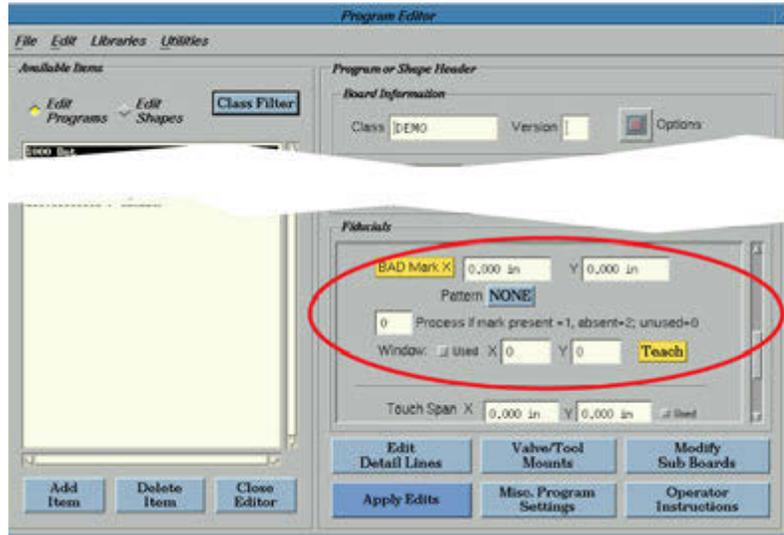
Bad marks can be used during several different programming strategies:

- To teach or select a **pattern** for a bad mark, refer to [Patterns Library](#) (pg 5.16).
- To teach or select a **shape** for a bad mark, refer to the step within [3. Teach Program Parameters](#) (pg 4.2) that addresses bad marks.
- To teach locations for a bad mark pattern, refer to [Jogging the Gantry](#) (pg 2.7).
- To teach the bad mark location on a subboard and select the bad mark pattern to be used, refer to [Subboard Bad Mark](#) (pg 4.39).
- Bad marks can also be used as a process inspection tool. Refer to [Inspecting with Bad Marks](#) (pg 3.105).

### **Bad Marks for Programs & Shapes**

To teach and edit bad marks for programs and shapes, use the bad mark controls located in the Fiducial panel of the Program Editor to choose one of three actions:

- process board if a bad mark is *present* (enter 1 in Flag)
- process board if a bad mark is *absent* (enter 2 in Flag)
- process board whether or not a bad mark is present - the program ignores the presence of bad marks (enter 0 in Flag).



Bad Mark controls - use the slider in the Fiducials panel to locate Bad Mark fields and buttons

### **Bad Marks for Subboards**

To teach and edit a [Subboard Bad Mark](#) (pg 4.39), use the controls located in the Bad Marks panel of the SubBoard Editor window to choose one of three actions:

- skip a board with a bad mark.
- process board if a bad mark is present.
- process board if a bad mark is absent.

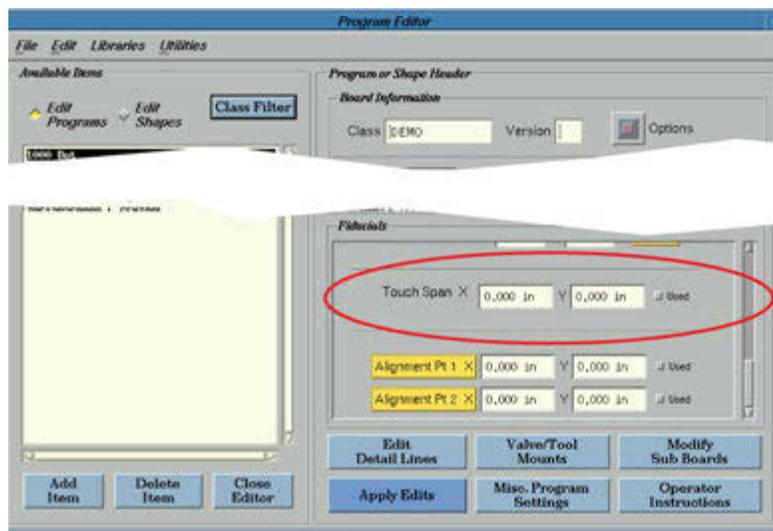
## Touch Span

This feature is particularly helpful when crucial close-tolerance dispensing requires high precision on non-flat boards. The Touch Span values can change the frequency of level detects performed on a board by establishing the XY boundary parameters around the point of the last height sense beyond which the program will perform another height sense. The Touch Span values then apply to the new height sense point.

### **Touch Span for Programs & Shapes**

To assign Touch Span boundary parameters:

- 1 - Select a program in the Program Editor.
- 2 - In the Fiducials pane, scroll down until the Touch Span parameters are visible.



Touch Span - use the slider in the Fiducials panel to locate Touch Span parameters.

- 3 - Enter a value in X and Y. These values represent the distance you want the dispenser to travel in each axis before it performs a board height sense.

- 4 - Click APPLY EDITS.

### **Touch Span for Subboards**

You can choose whether the touch probe touches down on every subboard or just the first subboard. Refer to [Subboard Touch Probe Frequency](#) (pg 4.40).

## Alignment Points

For a program that uses arrays, alignment points can be used as an aid for array-to-board edge alignment. For details, refer [Arrays & Alignment Points](#) (pg 3.100).

## Command Buttons

### **ADD ITEM**

Begins the process for adding a new program or shape.

### **DELETE ITEM**

Begins the process of deleting the program or shape currently selected.

### **CLOSE EDITOR**

Closes the Program Editor to an icon on the main window.

### **EDIT DETAIL LINES**

Opens [Program Detail](#) (pg 5.86). Modify, save, or delete program detail line(s).

### **VALVE/TOOL MOUNTS**

Opens the [MOUNT](#) (pg 3.71) version of the Mounts/Material Editor. Used to define the position and type of valve/tool, material, and needle gauge for each mount position to be used in the current program (not applicable to shapes).

### **MODIFY SUB BOARDS**

Opens the [SubBoard Editor](#) (pg 5.101). Define the location and orientation of each subboard in a program (not applicable to shapes). Refer also to [Creating Subboards](#) (pg 4.38).

### **APPLY EDITS**

Implements any changes currently displayed in the Program Editor window and any program line modifications made in the Program Detail window.

### **MISC PROGRAM SETTINGS**

Opens [Miscellaneous Program Settings](#) (pg 5.55) for defining and refining program settings for various purposes, e.g., vision calibration, temperature, pressure, or rotation relative to bad marks.

### **OPERATOR INSTRUCTIONS**

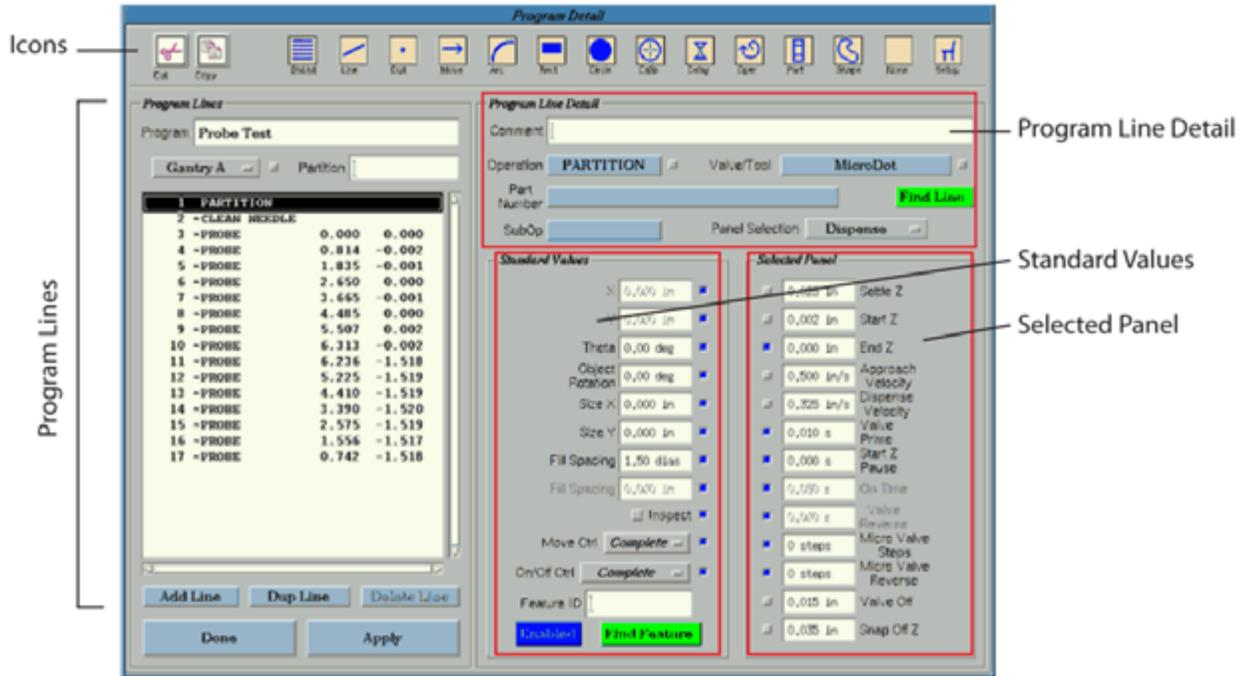
Opens [Enter Operator Instructions](#) (pg 5.29) where you can add, modify, or delete instructions associated with the currently selected program (not applicable to shapes). These instructions display in the Mounts Table window.

## Program Detail

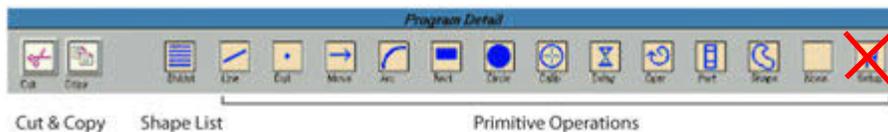
The user can establish or modify operation detail parameters of any program line for the currently selected program using elements in the Program Detail window.

Program detail records describe each operation performed for the program. One record is required for each operation, although a record may generate multiple operations if it refers to a shape or defines an array.

To access Program Detail, click on the EDIT DETAIL LINES button in the Program Editor.



## Icons



Clicking the Cut icon or the Copy icon serves to delete or copy the currently selected program line.

Clicking the ShList icon displays a list of all currently available (non-class filtered) shapes.



**IMPORTANT:** Use the ShList icon rather than the Shape icon to call a shape for a program. Using ShList presents you with all the available shapes within the class you have selected. (The Shape icon is reserved for future use and does not currently function properly.)

The remaining icons (Line, Dot, Move, Arc, Rectangle, Circle, Calibrate, Delay, Operate, Partition, Shape, None, and Setup) represent primitive operations. Use these to insert a preprogrammed primitive operation below the currently selected program line.

## Program Lines

### Program

The name of the currently selected program displays here.

### Gantry

The gantry identification code for the currently selected program displays here. When clicked, a menu of gantry choices displays.

### Partition

The name of a partition or shape displays here. This field is typically allowed to default for program lines subsequent to a partition or shape line. For details, refer to [Partition Line](#) (pg 3.91).

### program lines

A sequential display of the partition and shape lines comprising the currently selected program.

### ADD LINE

Inserts a new program line below the currently selected one after opening a list of operation types from which to select for the new program line.

### DUP LINE

Duplicates a program line by copying the currently selected program line and then pasting it directly below the original.

### DELETE LINE

Deletes the currently selected program line.

## Program Line Detail

### Comment

Text describing the currently selected line for documentation purposes. Often used when converting pick-and-place data to the dispenser input format.

### Operation

Determines which operation is used to perform the current program or shape line. When clicked, a list of all currently available (non-class filtered) [Operations \(Primitives\)](#) (pg 5.108) displays (unless the currently selected line is a partition line).

Operation may be the name of one of the primitive operations or the name of a shape. (Prior to using a shape in a program run, the shape must be created.)

### Valve/Tool

Dictates which head (valve or tool) will be used during the operation for the current program line. Typically, a selection for Valve/Tool is made in the partition line with the Valve/Tool field in all subsequent program detail lines set to default to the partition line; otherwise, either a head must be selected for each program line or else Valve/Tool will default to NONE.

Clicking on Valve/Tool opens a list of currently available heads. The name in Valve/Tool must match the name of the valve/tool in the Mounts/Material Editor-[MOUNT](#) (pg 3.71) library; if it does not, the program will not run. (Prior to using a head in a program, a valve or tool must be defined.)

### Part Number

This is an optional part number of up to 36 characters. This field is usually filled in when converting pick-and-place data to dispenser input format. The [Import Data](#)

(pg 3.2) feature uses this field to determine the operation type from the cross reference library.

Clicking on Part Number opens a list of currently available part numbers from which to choose.

### FIND LINE

Allows you to find a specific program detail line within the current program by first jogging the camera over a physical location, and then when FIND LINE is clicked, the system finds and highlights the program line associated with the point nearest to the current camera coordinates.

When FIND LINE is used with a program containing subboards, an additional prompt for subboard selection displays. You can position the camera over a location on **ANY** one of the subboards, click FIND LINE, and select a particular subboard from a list of all subboards in the program. Then the system finds and highlights the program detail line associated with that particular location in the subboard you selected.

### SubOp

Clicking SubOp opens a list of currently available operation subtypes from which to choose. The choices displayed are dependent upon the operation used in the Operation field.

### Panel Selection

A pull-down menu of choices, each of which will display a different set of fields in the [Selected Panel](#) (pg 3.46).

## Standard Values

X  
Y

Location where the current operation is to occur relative to the board reference point.

### Theta

Rotation (radians) of the fourth axis for this head.

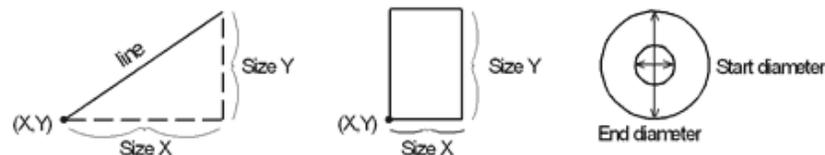
### Object Rotation

Object Rotation is the rotation of a single object about X, Y (as opposed to *Rotation* which is used to rotate an entire array). Refer to [Rotation Guidelines](#) (pg 3.97).

### Size X

### Size Y

The X-size and Y-size of a line or rectangle or the start diameters of a circle.



### Fill Spacing

### Fill Spacing

For filled features such as circles and rectangles, this field defines spacing between successive lines of the fill in units of needle diameters. A typical value is 1.5 needle diameters. The second Fill Spacing field in millimeters is an alternate value to the first Fill Spacing field in needle diameters.

## Move Controls

Gantry motion and valve control can each be exercised independently for continuous operation across several program lines with these two move control buttons:

**MOVE CTRL** enables gantry motion.

**ON/OFF CTRL** enables valve control.

Each of these buttons provides the ability to perform only a single part (Start, Middle, or End) of the operation for the current program line. Refer to [Move Commands](#) (pg 3.23) for additional details and [Sample Dispense Operations](#) (pg 3.18) for illustrated examples.

This control is particularly useful for continuous valve or tool operations. This single part operation control also allows the preservation of Z coordinates (gantry motion) through several lines of a program.

**Table 18: Move Operation Parameters**

Operation Part	Explanation
Complete	all three stages of the operation (Start, Middle, and End) are performed.
Start	only the start and middle stages are performed. The beginning of an operation consists of moving to (X, Y) at Move Velocity, then moving downward at Approach Velocity to Start Z, starting valve operation at the appropriate time.
Middle	only the middle stage is performed. The middle stage (the heart of an operation) is always performed. The middle of an operation consists of activities unique to the operation, such as the delay for a dot or the fill motion for a rectangle or circle. Height is unaffected.
End	only the middle and end stages are performed. The end of an operation can ensure the valve is off and perform the snap-off motion to SnapOff Z at SnapOff Velocity and SnapOff Acceleration.
No Operation	behaves the same as Middle.

## Feature ID

Use the feature ID function as an alternative to the default of processing all program lines. With feature ID, you can define and run a select subset of program lines. A feature ID can be assigned to any program line; any program line without a feature ID (a blank) will always run. For details, refer to [Feature ID](#) (pg 3.102).

## FIND FEATURE

Used to easily locate previously assigned feature IDs within a program. For details, refer to [Finding a Feature ID](#) (pg 3.103).

## ENABLED / DISABLED

This toggle button indicates whether or not the currently selected program line will be used or not. Any program line can be easily enabled or disabled.

## Selected Panel

Numerous subsets of related fields are organized into a set of [Selectable Panels](#) (pg 2.12). Click on the Panel Selection button to select and display each panel from a drop-down menu of choices.

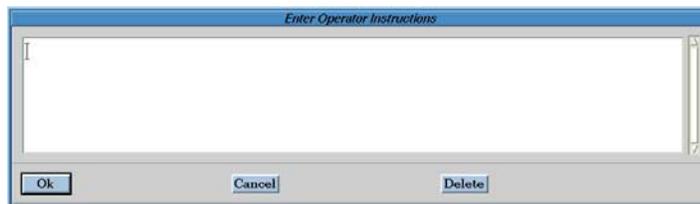
## Operator Instructions

Instructions may be associated with any program and then the system will automatically present the operator with the instructions just prior to running that program. Optional text entered in the Enter Operator Instructions pane of the Program Editor displays in the Mounts Table for the operator to see during the initial step of a program run.

### Modify Operator Instructions

To add, change, or delete operator instructions:

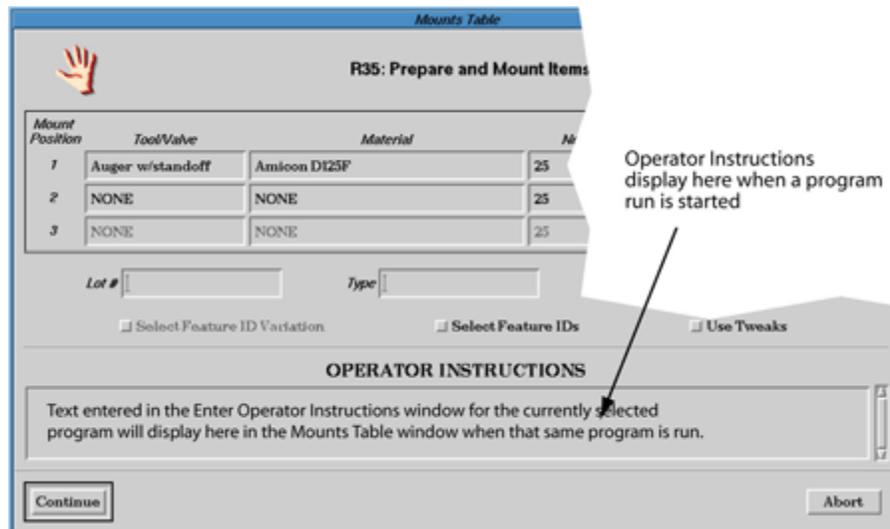
1. In the Program Editor, select the program to which you wish to associate operator instructions text.
2. While still in the Program Editor, click on the OPERATOR INSTRUCTIONS button. The Enter Operator Instructions window displays.



3. Click anywhere in the text pane to activate it and enter or change the text you want associated with the currently selected program.
4. Click OK to save your entry or, to delete the text, click DELETE.

### View Operator Instructions

Whenever the program to which you have added operator instruction text is run, the operator instructions will display in the lower portion of the Mounts Table.



## Print a Program

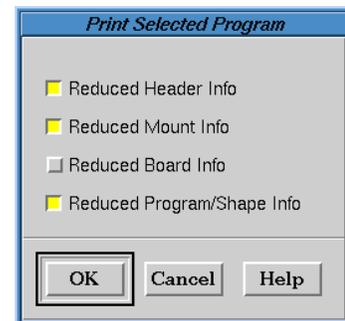
A program may be printed in full or in part to a printer. The print options available in the Print Selected Program window allow you to print the currently selected program, optionally reducing detail with the use of one or more filters.

In order for reports to print, both of these conditions must be met:

- a dot matrix printer must be connected to the dispenser via a serial port (on the machine rear panel or on the dispenser computer) and
- the [Printer On](#) (pg 3.28) operation state must be turned on.

To print a selected program:

1. Connect a printer to the dispenser.
2. Open the Program Editor and select the program to be printed.
3. Open the Print Selected Program window by clicking on File > Print Options.
4. Activate one, all, none, or any combination of the reduction filters. A yellow, pushed-in box indicates an active (on) filter. A gray, pushed-out box indicates an inactive (off) filter. An activated reduction filter will print only minimally identifiable detail for its section of the report. Compare the following sample reports to see what each filter generates when turned on and off.
5. Click OK to print the report, or CANCEL to exit without printing the report.



## Sample Reports - Reduced Detail

The following sample report illustrates the minimally identifiable detail that prints for each print filter (Header, Mount, Board, and Program/Shape) when *Reduced* is activated for each filter. One, none, or any combination of the reduction filters can be activated when generating a report.

```

Program Kester Type6 .0065"                2004/11/30 12:21:32   Page   1
Name: Kester Type6 .0065"                Class: Solder Paste  Version:
Prior scan & probe used for paste @ 18,500 DPH.
Entered By: SERVICE      2002-10-15 12:34:56.458
Changed By: SERVICE      2004-11-30 12:18:10.790

----- MOUNTS -----
Head A0: Micro Valve          Material: Kester R276 NC Type6

----- BOARDS -----
Array: 0 X 0      Spacing: 0.0000 in X 0.0000 in   Probe Suppress: N

----- PARTITION (No Name) -----
Gan SeqNo Operation          Coords          Angle   Array      Rot
A      1 PARTITION          ( 0.0000, 0.0000)  0.0
A      2 OPERATE            ( 0.1772, 0.1772)  0.0
A      3 OPERATE            ( 0.0000, 0.0000)  0.0
A      4 DDT                 ( 0.0000, 0.0000)  0.0  36 X 37  0.0

```

## Sample Report - Full Detail

The following sample report illustrates the full detail that prints for each print filter (Header, Mount, Board, and Program/Shape) when *Reduced* is left inactive for each filter. One, none, or any combination of the reduction filters can be activated when generating a report.

```

Program Kester Type6 .0065"                2004/11/30 13:04:41    Page 1
Name: Kester Type6 .0065"                  Class: Solder Paste  Version:
Prior scan & probe used for paste @ 18,500 DPH.

Entered By: SERVICE      2002-10-15 12:34:56.458
Changed By: SERVICE      2004-11-30 13:03:43.018
Reference: ( 0.9265, 0.6205) Board Size: ( 3.2500, 5.5000, 0.2500)
Fiducial 1: ( 0.0000, 0.0000) Pattern: Setup @ 26% Focus
Fiducial 2: ( 0.3543, 0.0000) Pattern: Setup @ 26% Focus
Fiducial 3: ( 0.3543, 0.3543) Pattern: Setup @ 26% Focus
Bad Mark (0): ( 0.3543, 0.3543) Pattern: NONE

----- MOUNTS -----
Head A0: Micro Valve          Material: Kester R276 NC Type6
Feature ID:
*Settle Z 0.0750 in          *Snap Off Velocity 10.00 in/sec
*Suckback Dead Time 2 ms    *Snap Off Acceleration 100.0 in/s
*Suckback Reverse 2 ms     *Air Pressure 17.0 lb/sq in
*Warning Count 2000000000 dots *OnTime Warning 2000000000 secs
*Idle Warning 2000000000 secs *Total Time Limit 2000000000 secs
*Standard Accel 150.0 in/sec/sec
*Start Z 0.0080 in          *Valve Prime 15 ms
  On Time 75 ms             *Move Velocity 10.00 in/sec
*Snap Off Z 0.1100 in      *Approach Velocity 10.00 in/sec

----- BOARDS -----
Array: 0 X 0      Spacing: 0.0000 in X 0.0000 in      Probe Suppress: N
Fiducial 1: ( 0.1000, 0.1000) Pattern: Circle
Fiducial 2: ( 4.0250, 3.9250) Pattern: Circle
Fiducial 3: ( 0.0000, 0.0000) Pattern: NONE
Bad Mark (0): ( 0.0000, 0.0000) Pattern: NONE

Number: 1 Name: Board 1      FeatureID:
  Position (in): ( 0.0000, 0.0000) Angle: 0.0 deg
Number: 2 Name: Board 2      FeatureID:
  Position (in): ( -4.1353, -0.0042) Angle: 0.0 deg

----- PARTITION (No Name) -----
Sequence Number: 1      Operation: PARTITION ( )
Coordinates (in): ( 0.0000, 0.0000) Object Rotation: 0.0 deg
Head: Micro Valve 10k      Feature ID:      Gantry: A

  Start Z 0.0022 in          *Fill Width 0.0000 in
  End Z 0.0070 in           *Fill Spacing 0.00 Needle Dias
  Valve Prime 0 ms          *Size X/Start Dia 0.0000 in
  Start Z Pause 5 ms       *Size Y/End Dia 0.0000 in
  *On Time 50 ms           *Move Velocity 20.00 in/sec
  Snap Off Z 0.1000 in     Approach Velocity 5.00 in/sec
  Valve Off 0.0050 in      Dispense Velocity 2.00 in/sec
  *Scale Factor 1.00 %     Moves: NONE DnOffs: NONE

Sequence Number: 2      Operation: OPERATE (PROBE)
Coordinates (in): ( 0.1772, 0.1772) Object Rotation: 0.0 deg
Head: Micro Valve 10k      Feature ID:      Gantry: A

  *Start Z 0.0022 in          *Fill Width 0.0000 in
  *End Z 0.0070 in           *Fill Spacing 0.00 Needle Dias
  *Valve Prime 0 ms          *Size X/Start Dia 0.0000 in
  *Start Z Pause 5 ms       *Size Y/End Dia 0.0000 in
  *On Time 50 ms           *Move Velocity 20.00 in/sec
  *Snap Off Z 0.1000 in     *Approach Velocity 5.00 in/sec
  *Valve Off 0.0050 in      *Dispense Velocity 2.00 in/sec
  *Scale Factor 1.00 %     Moves: NONE DnOffs: NONE

```

## Programming with Shapes

A shape is a block of program lines that can be referenced with a single line in a program. Shapes can be extremely useful for eliminating repetitive entry of program parameter definitions and simplifying program creation by enabling you define a package just once as a shape.

### Why Use Shapes?

Use shapes to your advantage by defining a package as a shape once, or defining often-used dispensing properties once, and then using the new shape as often as needed.

#### Package as a Shape

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Rather than recreating all the program lines used to generate a component package each time it is needed in a program, simplify program creation by teaching a package as a shape and then reusing the shape every time the package is to appear in a program.

Components may often look alike; they may be packaged the same way. When dispensing adhesive or solder paste for such components, the component package determines the pattern of dispensing. A robust library of shapes facilitates program creation.

The component package is also commonly referenced when converting pick-and-place data. To easily convert pick-and-place data into dispensing data, it is more convenient to define a package as a shape and use the shape in the dispense program. This replaces repeatedly having to define the dispense information everywhere the component package is placed in the program.

#### Often-Used Dispensing Properties

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Rather than re-entering all parameter definitions each time they are needed in a program, define a set of shapes once – one shape for each dispense pattern – and then refer to the appropriate shape whenever it is to occur in the program.

Product frequently has multiple components requiring identical dispensing properties. When manually teaching a program for such a product or when pick-and-place data is unavailable for a product, use shapes.

#### Shapes versus Subboards

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When dealing with complex programs, shapes are considered easier to work with than subboards. When using shapes, you retain control over certain aspects of programming such as defining feature IDs and process sequence. When using subboards, these aspects of programming are automated and may become viewed less as a benefit and more of a disadvantage as the complexity of a program increases.

- **Feature ID** - shapes allow more control over the naming of a Feature ID. Subboards automatically assign the Feature ID name. If a meaningful feature ID is preferred, such as matching the Feature ID to a label on a pallet, use shapes rather than subboards.
- **Sequence** - the sequence in which shapes are processed can be user-defined when using *shapes*. Alternatively, if you choose to *array subboards*, the sequence is automatically generated according to the most efficient single pass; however, automatic sequencing can be overridden by teaching individual subboard locations.

- **Orientation** - when shape orientation varies, either shapes or subboards can be used; however, many users find it easier to use shapes, especially when shape orientation varies by 180 degrees.
- **Complexity** - for more complex programs, users tend toward using shapes since feature ID and process sequence can be user-defined.
- **Touch Probe Action** - touch probe action must be programmed to occur when using shapes. When using subboards, touch probe action occurs automatically for each pallet unless suppressed.

## Shape Library

Shapes are stored in the shape editor, effectively separating them from programs in the program editor [refer to [Edit Programs / Edit Shapes](#) (pg 3.32) for details about editor versions]. This allows any program to reference any defined shape.

Each shape has a name referenced in a program as if it were an operation type, the same way as DOT, MOVE, or RECTANGLE are referenced.

## Shape Guidelines

All shapes follow these basic guidelines:

- Any shape defined in the shape library can be referenced by any program.
- Any number of shapes can be used multiple times within the same program.
- Shapes are created, modified, and deleted in the same manner as programs.
- With the exception of a [Partition Line](#) (pg 3.91) and a [Shape Partition Line](#) (pg 3.56), any type of program line, including other shapes and arrays, can be used to define a shape.
- A list of all available shapes will display in a [Select List](#) (pg 5.98) window during program creation and program editing.

## Shape Reference Point

Each shape is an independent program that requires a shape reference point. Each time a shape is added to a program or to another shape, the shape's reference point must be taught; this distinguishes the location of each shape from that of all other uses of the same shape.

### Reference Points - Program versus Shape

Because the location of a shape can be relative to multiple programs or shapes, a **shape reference point** must be identified (taught) each time a shape is created or edited.

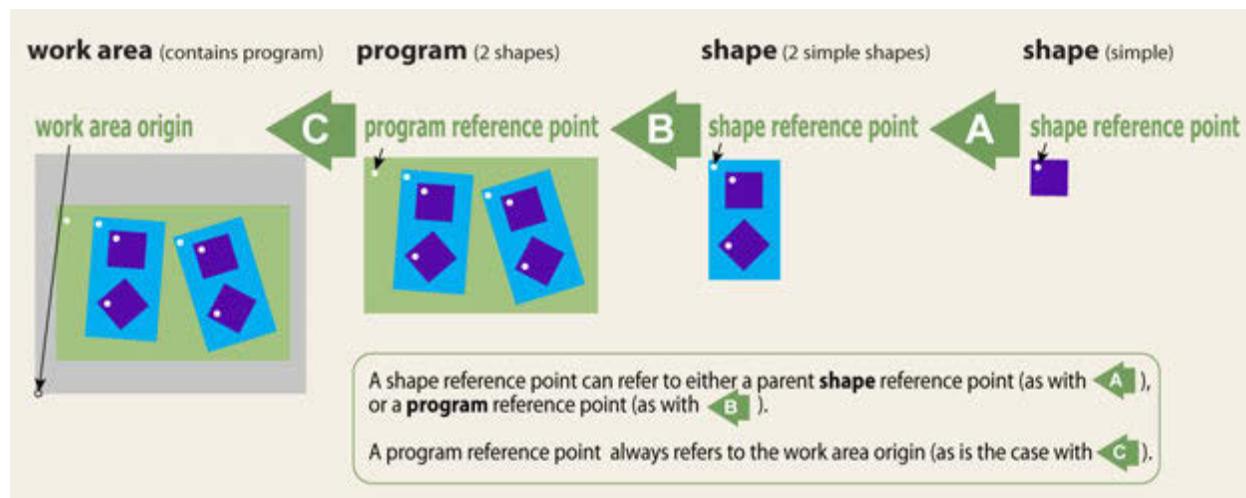
A **program reference point**, on the other hand, is taught once and preserved by the system.

## Frame of Reference

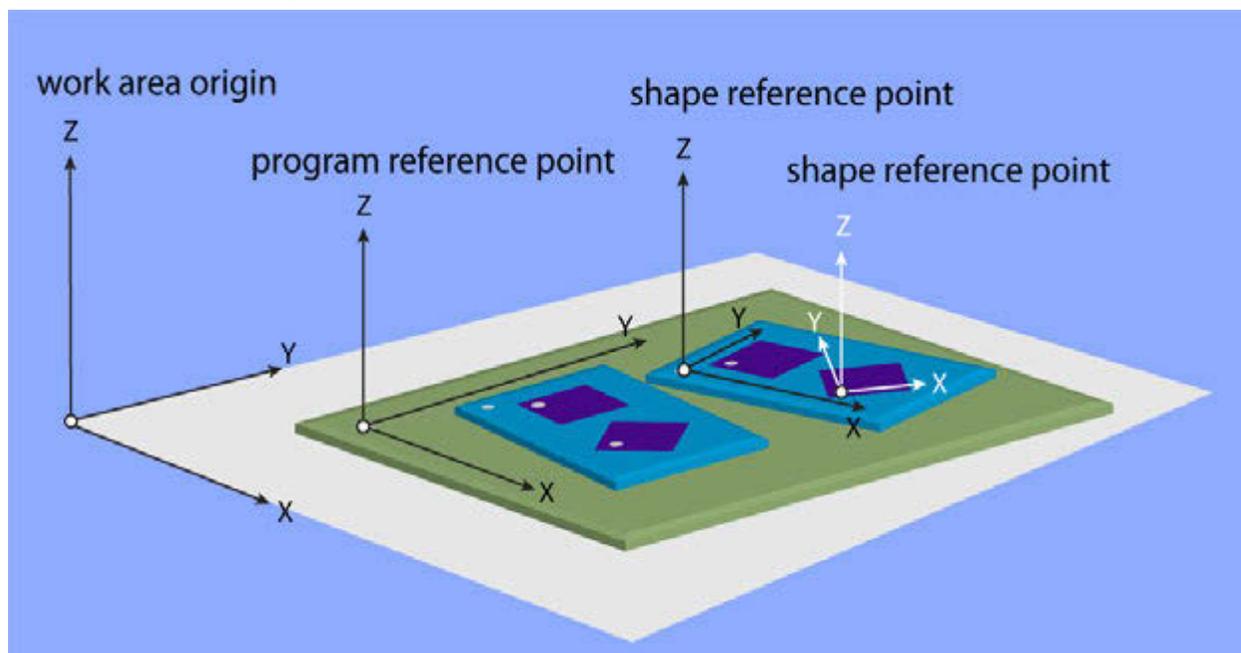
There are three distinct types of reference point: the work area origin, a program (board) reference point, and a shape reference point, with each referring to a different frame of reference or world origin.

A shape reference point is measured in relation to either a parent shape or program, while a program reference point is always measured in relation to the work area origin.

**Figure 8:** Each type of reference point has a different world origin.



**Figure 9:** Relationship of the three different types of reference point.



## Types of Shape Reference Points

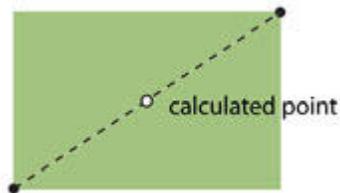
---

Only one type of reference point can be set at a time using the [Set Shape Reference Point](#) (pg 5.100) window: a calculated center, a single point, or a fixed location. Activating any of these choices deactivates the other two. (Currently, you have two choices: setting a single point or calculating a center point; the fixed location option is not currently functional.)

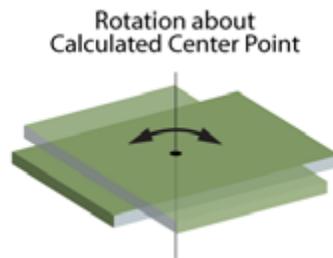
### Calculated Center

Often used for importing CAD data. Use the calculated center option when:

- an exactly centered shape reference point is acceptable (*calculated at the center between two points*), and



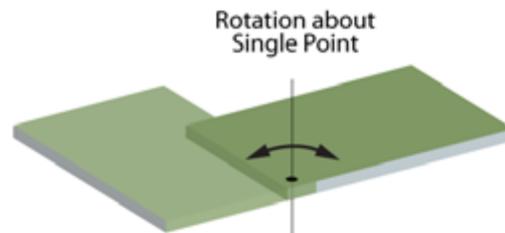
- it is desirable for any rotation command from the program to cause the shape to *rotate about its center*.



- Calculated Center is also a good choice if shape size exceeds the camera field of view.

### Single Point

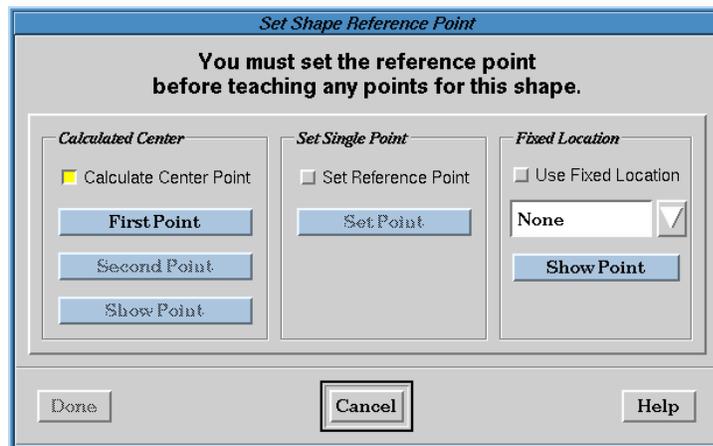
Often used to indicate the corner of a shape. Use the single point option when (1) the shape reference point is a *known point* or an approximate point is acceptable, and (2) it is desirable for any rotation command in the program to cause the shape to *rotate about the shape reference point*.



## Teach a Shape Reference Point

The system will prompt for a shape reference point each time a shape is added or edited. Once taught, the system will maintain the shape reference point data until you exit the shape.

1. [Set Shape Reference Point](#) (pg 5.100) displays whenever the system recognizes that a shape reference point needs to be established. This can occur while you are looking at a point using a MOVE TO button, teaching a point using a TEACH button, or searching for fiducials using the FIND FIDUCIALS button.



2. Identify a common feature within the shape that can be used as the shape reference point, assuming a shape is to be used multiple times in a program.

**NOTE:** The feature you choose must be present at the same location within the shape for each occurrence of the shape.

3. Decide which of the [Types of Shape Reference Points](#) (pg 3.53) you want to use to refer to the chosen feature that is to become the reference point and follow the associated instructions:

### **Set Single Point**

- a. To set a [Single Point](#) (pg 3.53), click Set Reference Point.
- b. Click SET POINT. Jog (J04) displays.
- c. Jog the gantry to the desired location and click CLOSE.
- d. Set Shape Reference Point re-displays. Click DONE. The shape reference point has been taught.



**CAUTION:** The gantry may move when you click DONE.

- e. Jog re-displays, returning you to what you were doing (looking at or teaching a point, or searching for a fiducial) prior to the process of teaching a shape reference point. Click CLOSE.

### **Calculated Center Point**

- a. To set a [Calculated Center](#) (pg 3.53) point, click Calculate Center Point.
- b. Click FIRST POINT. Jog (J00) displays.
- c. Jog the gantry to the **first** desired location and then click CLOSE. Set Shape Reference Point re-displays.
- d. Click SECOND POINT. Jog (J00) displays again.
- e. Jog the gantry to the **second** desired location and then click CLOSE. Set Shape Reference Point re-displays.
- f. Click SHOW POINT. The system calculates and moves to the center point between the first and second points. Jog (J00) displays again.



**IMPORTANT:** Do not skip the SHOW POINT step or else the final shape reference point will use SECOND POINT coordinates.

- g. Visually verify that the calculated center point meets expectations, and then click CLOSE.
- h. Set Shape Reference Point re-displays. Click DONE. The shape reference point has been taught.



**CAUTION:** The gantry may move when you click DONE.

- i. Jog re-displays, returning you to what you were doing (looking at or teaching a point, or searching for a fiducial) prior to the process of teaching a shape reference point. Click CLOSE.

4. Enter either a description or the coordinates for the shape reference point in the [Description](#) (pg 3.37) field of the Program Editor.



**IMPORTANT:** Because the system prompts for the shape reference point each time a shape is added or edited, you should keep a record of the location. The Description field in Program Editor is the only place where this information is kept and you must enter it manually; it will not be entered automatically for you.

### **Change a Shape Reference Point**

A shape reference point can be changed at any time.

To change an established shape reference point:

1. In the Edit Shapes version of the Program Editor, highlight a random shape, then highlight the shape to be modified.
2. In the Fiducials panel, click MOVE TO for Fiducial 1. [Set Shape Reference Point](#) (pg 5.100) displays.
3. Perform [Step 3](#) through [Step 4](#) of [Teach a Shape Reference Point](#) (pg 3.54) to teach and record new coordinates for the shape reference point.

## Shape Partition Line

The main difference between a shape partition line and a standard [Partition Line](#) (pg 3.91) is that a shape partition line is used within a shape and can be used only once. It displays as Shape and is the first line in the shape program.

All Gantries		Partition
1	SHAPE	
2	DOT	0.00

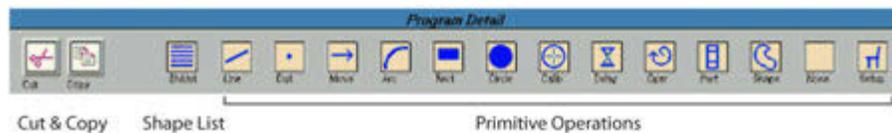
## Shape Name Default

Assuming all levels are fully defaulted, a shape partition defaults not to the 12 *PARTITION* line of the [..Default.. Program](#) (pg 3.93), but to the 13 *SHAPE* detail line (as illustrated in Figure 15 on page 3-93).

## Pre-Programmed Shapes

In addition to any custom shapes created by the user, a set of unalterable, preprogrammed shapes reside in the shape library for use as initial building blocks.

[Icons](#) (pg 3.43) across the top of the Program Detail window provide a shortcut to each of these unalterable shapes.



## Custom Shapes

When you need a shape that differs from the [Pre-Programmed Shapes](#) (pg 3.56), you can [Create a Custom Shape](#) (pg 3.56) and then [Add a Custom Shape to a Program](#) (pg 3.59).

### Create a Custom Shape

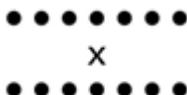
The following instructions guide you through the process of creating a custom shape and saving it to the shape library. A custom shape named Socket is used as an example and the following assumptions are made:

#### Assumption 1

We will be creating a shape name of *Socket*.

#### Assumption 2

*Socket* represents a chip socket pattern with a form where x marks the center of the package and the dots are dispense points spaced 0.3" vertically and 0.1" horizontally. It will look like this figure:



**Assumption 3**

The program lines that will define *Socket* can look like either of the following sets of defined parameters:

**METHOD A**

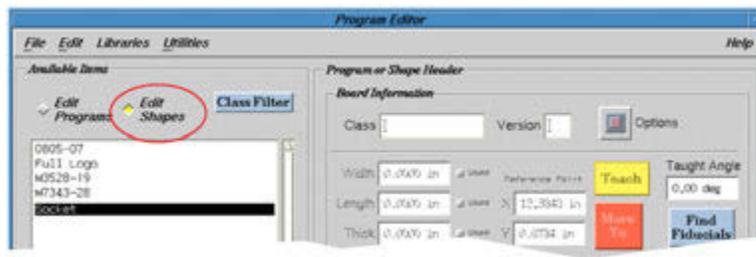
Operation	X	Y
DOT	-0.3	-0.15
DOT	-0.2	-0.15
DOT	-0.1	-0.15
DOT	0.0	-0.15
DOT	0.1	-0.15
DOT	0.2	-0.15
DOT	0.3	-0.15
DOT	0.3	0.15
DOT	0.2	0.15
DOT	0.1	0.15
DOT	0.0	0.15
DOT	-0.1	0.15
DOT	-0.2	0.15
DOT	-0.3	0.15

**METHOD B**

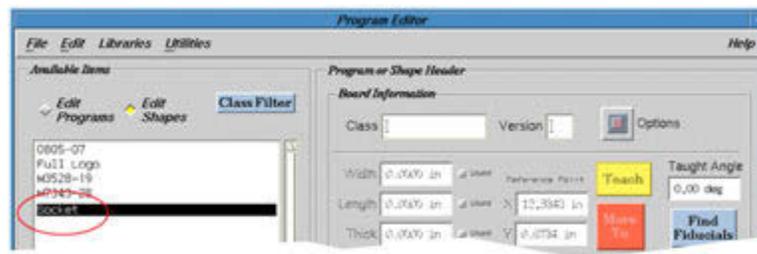
Operation	X	Y	X Count	Y Count	X Space	Y Space
DOT	-0.3	-0.15	7	2	0.1	0.3

To create a shape (based on the above assumptions):

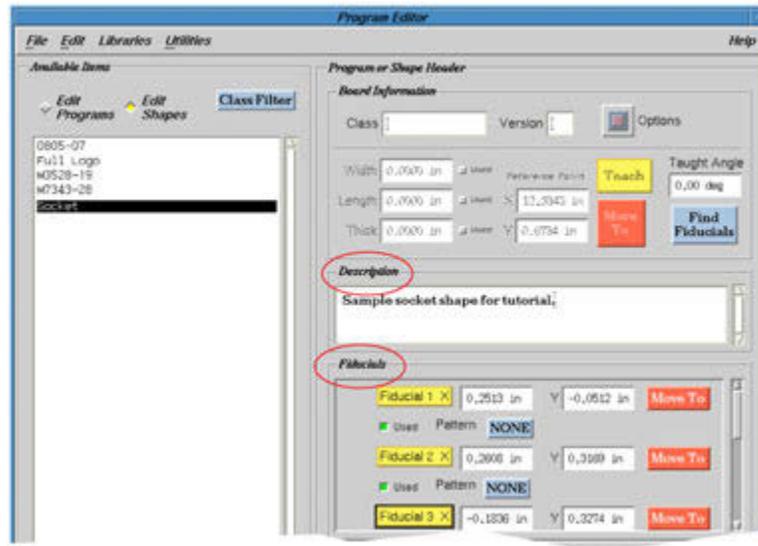
1. In the Program Editor, select the Edit Shapes option.



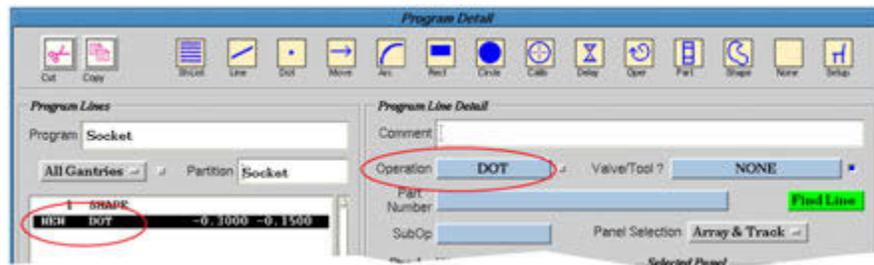
2. When creating a shape, you can either type in a shape program name or select a shape from the shapes library. For purposes of this example, click ADD ITEM, type in the name *Socket*, and click OK. The SOCKET name displays.



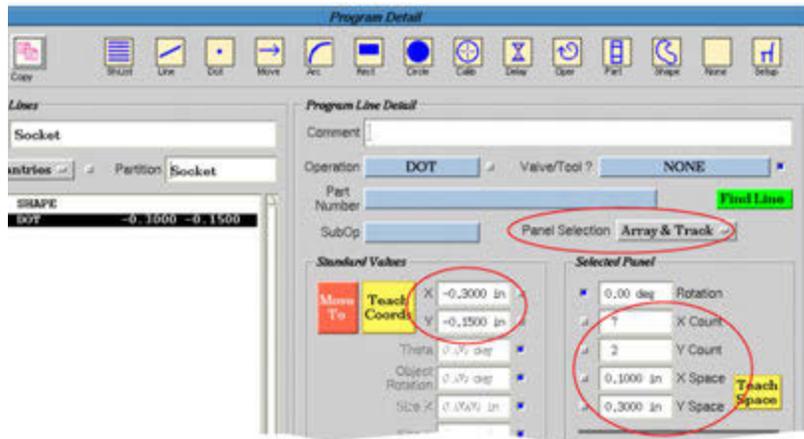
3. When creating a shape for a real program, you would now define the optional program description in the Description pane and the optional fiducial point(s) in the Fiducials pane.



4. Create shape details by adding program lines and establishing the parameters for each new line:
  - a. Click on EDIT DETAIL LINES to open the Program Detail window.
  - b. Click on ADD LINE.
  - c. Select an existing shape from Operation – use DOT for our example – and then click ACCEPT.



- d. Modify the parameters, as needed, for the new program line. For our example, make the appropriate entries in X, Y, etc., as shown in [Assumption 3](#) (pg 3.57). To access the X Count, Y Count, X Space, and Y Space fields, select the Array & Track option from the Panel Selection option menu.



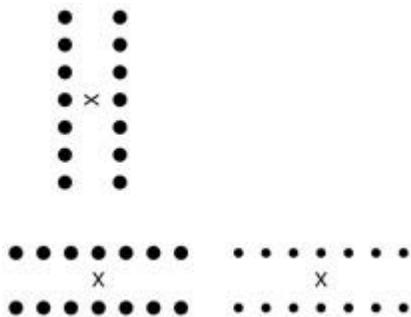
- e. Continue adding new program lines and entering parameter values as needed. For our example, this step is unnecessary if you chose to enter a single program line like Method B shown in [Assumption 3](#) (pg 3.57).
5. Save the program by clicking APPLY and then exit Program Detail by clicking DONE.

### Add a Custom Shape to a Program

The following instructions guide you through the process of using an existing shape in a program. For the following example, we will use the shape created in [Create a Custom Shape](#) (pg 3.56) and the following assumptions:

#### Assumption 1

We will use a single shape to create several chip socket shapes on a board. It will look like this



#### Assumption 2

The program lines will be based on the *Socket* program created in [Create a Custom Shape](#) (pg 3.56). The program will look like this:

Operation	X	Y	Object Rotation	On Time
SOCKET	1.0	1.0	0	35
SOCKET	1.0	2.0	90	35
SOCKET	2.0	1.0	0	25

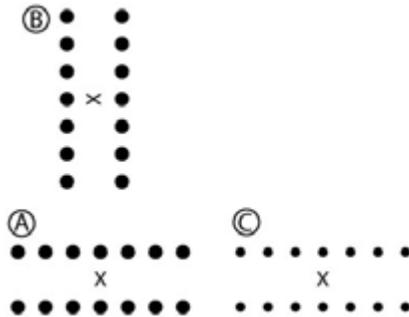
**Assumption 3**

The new program will dispense a set of shapes that looks like the figure below and where:

A = is the set of 14 dots centered at coordinates (1.0,1.0).

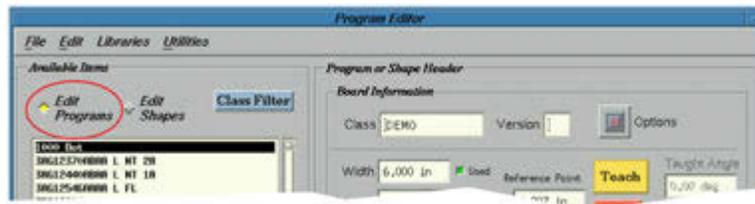
B = is another set of 14 dots centered (1.0,2.0) but rotated 90 degree, i.e. the socket image is vertically oriented.

C = is a third set of 14 dots centered at (2.0,1.0). The dots in the first two socket shapes, A and B, will be larger than those in socket shape C as a result of the different On Time values (35 ms for the first two shapes, and 25 ms for the third).

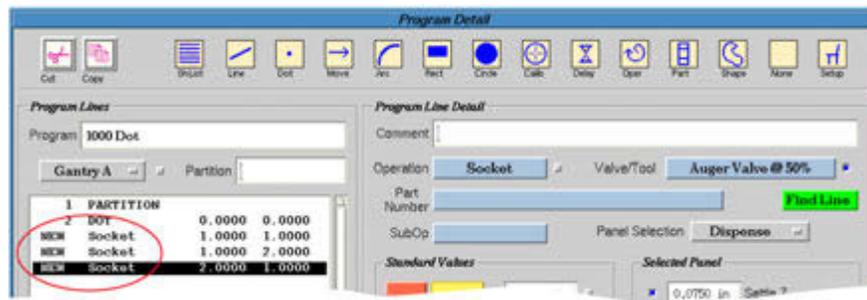


To add an existing shape to a program (based on the above assumptions):

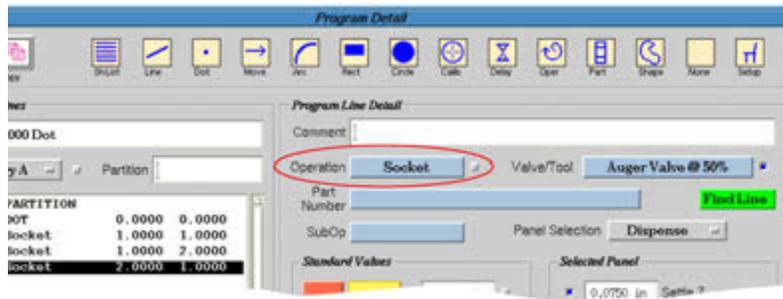
1. In the Program Editor, select the EDIT PROGRAMS option.



2. Select the program to which you want to add a shape, then click EDIT DETAIL LINES to open Program Detail.
3. To add new program lines using an established shape and then enter parameters for each new program line:
  - a. Highlight the program line that will precede your new program line and then click ADD LINE. A new program line is added to the program.

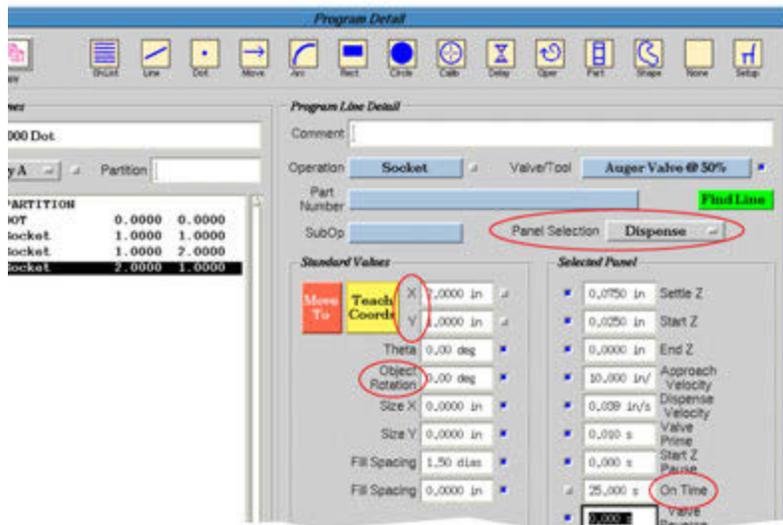


- b. Select an existing shape from Operation – choose SOCKET, the shape created in [Create a Custom Shape](#) (pg 3.56) – and then click ACCEPT.



- c. Modify the parameters, as needed, for the new program line. For our example, enter values for X, Y, [Object Rotation](#) (pg 3.45), and On Time as shown in [Assumption 2](#) (pg 3.59).

Some fields will only display if you select the Dispense option from the Panel Selection option menu.line.



**NOTE:** By overriding the On Time value for the third usage of Socket, the dot size is changed to meet the description in [Assumption 3](#) (pg 3.60).

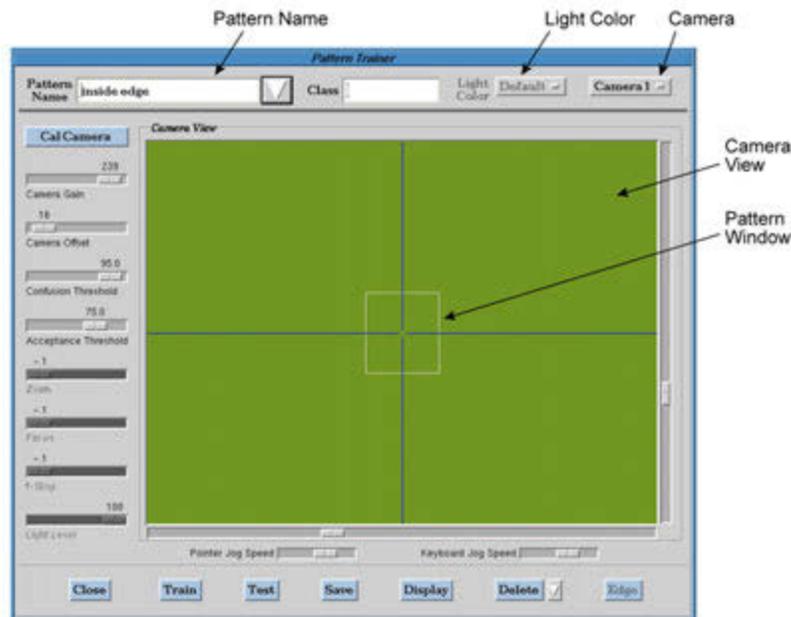
- d. Continue adding new program lines and entering parameter values as needed. For our example, this means creating the second and third SOCKET program lines as shown in [Assumption 2](#) (pg 3.59).
4. Save the program and exit Program Detail by first clicking APPLY and then DONE.

## Teaching a Pattern

Create or modify vision patterns used during fiducial or bad mark pattern recognition by the (optional) automatic vision system to locate a product and adjust for its orientation. For details about pattern usage and management, refer to [Patterns Library](#) (pg 5.16).

To create a new pattern:

1. From the Program Editor menu bar, click on Libraries > Patterns. Pattern Trainer displays.
2. Either type a name of up to 36 characters in the Pattern Name field, or select an existing pattern similar to the one you want to create by clicking the ▼ button next to the Pattern Name field and typing the new name in the Pattern Name field. When teaching a new pattern, you must enter an original name.



### 3. Class Filter

(Optional) To assign a class filter, either the name of a new or existing class filter in the Class field. For details, refer to [Assign a Class Filter](#) (pg 3.34).

4. In most cases, you may use the default parameters that display. To do so, click OK and skip to [Set Camera Thresholds](#) (pg 3.63); otherwise, continue with the following steps.
5. **Illumination Color & Axis**  
If optional illumination hardware is installed, click the LIGHT COLOR button and select the illumination color or axis that applies.
6. **Multiple Cameras**  
If multiple cameras are installed, click the CAMERA button and select the number of the camera that will be used to search for the new pattern.

## 7. Adjust Camera Focus

If the camera is out of focus, adjust the focus per the following procedure; otherwise, skip to the next step.

- a. If the dispenser is configured with a lifter plate, verify that the lifter plate is in the UP position prior to performing the camera focusing steps. For instructions on how to raise the lifter plate, refer to the *Lifter Controls* under *Machine Controls* in the *Operating Detail* section of the *Dispenser Operator Guide*.
- b. Jog the camera so the cross hairs in the Pattern Window align over the image you wish to teach as a pattern.
- c. As necessary, adjust Focus, Zoom, f-stop, Lighting Level, and Lighting Color in the Live Video Parameters window. For details about these elements, refer to [Lens Focus](#) (pg 3.77).

## 8. Set Camera Thresholds

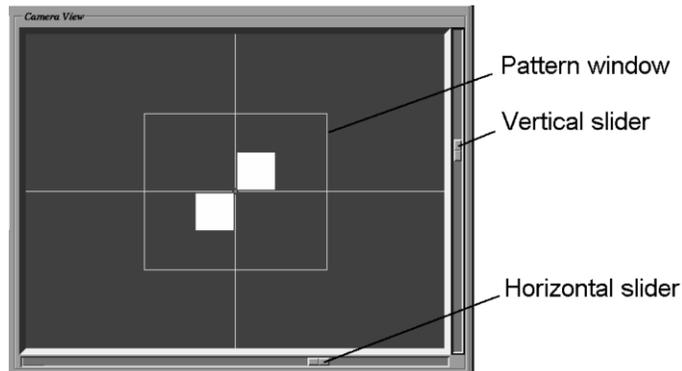
Set the Confusion Threshold and Acceptance Threshold as needed, or use the existing threshold settings as a starting place. Both thresholds affect search speed and the success rate of finding the trained pattern.

## 9. Pattern Parameters

To train pattern parameters:

- a. Define the Pattern Window area by clicking and dragging the horizontal and vertical Pattern Window slider bars. Everything displayed inside the defined Pattern Window is considered the pattern being taught. Include the complete image plus any distinctive features in the vicinity. A more distinct pattern will be easier to find.

Capture the complete shape image and a generous area around it. Capturing approximately 1/4 of the total Camera View panel will help decrease search time. A relatively small pattern will require increased search time.

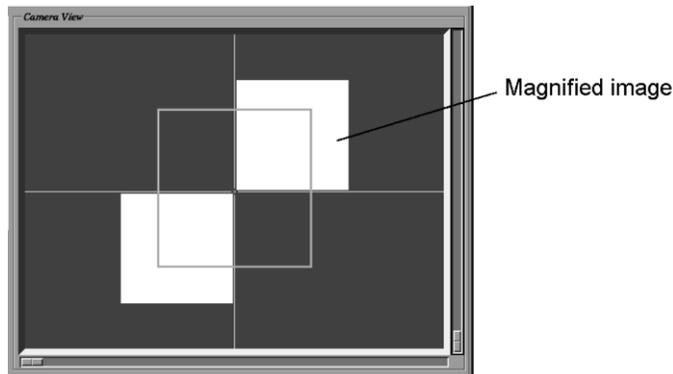


- b. Click the TRAIN button to teach the Pattern Window. Wait for the clock cursor to disappear.

## 10. Examine the Pattern

Examine the pattern for distinctive details:

- a. Click the DISPLAY button. The currently selected image is magnified (in a frozen image mode). The position of the displayed image in the Camera View panel is arbitrary with respect to the cross hairs that cross at the midpoint of the trained pattern.



- b. Return to live video mode by clicking the LIVE toggle button or click within the Camera View panel.

## 11. Test Pattern

To test the pattern:

- a. Click the TEST button. The automatic vision system searches for the pattern and displays an *Acceptance* score. *Acceptance%* is the percentage of match between the pattern taught and the pattern found. *Times ms* is the length of time the vision system takes to find the pattern.
- b. Jog the gantry away from the image coordinates while keeping the complete pattern within the field of view of the Camera View panel.
- c. Click TEST again and take note of the acceptance value test results.
- d. Repeat the test process two or three times, moving the gantry to a different position each time. Take note of the acceptance values each time you click TEST.

## 12. Adjust Threshold Settings

Adjust the threshold settings based on the test score results. The following settings are initial recommendations only.

- a. Calculate the Acceptance Threshold (AT) setting:

$$\text{ACCEPTANCE} - 10 = \text{AT}$$

where ACCEPTANCE is the lowest score gathered during [Adjust Threshold Settings](#) (pg 3.64) and AT is Acceptance Threshold.

- b. Calculate the Confusion Threshold setting:

$$\text{AT} + 10 = \text{CT}$$

where AT is Acceptance Threshold and CT is Confusion Threshold.

**13. Save Pattern**

To save the trained pattern parameters, click SAVE to save the parameters, and then click CLOSE to exit the Pattern Trainer.

## Setting Up Valves & Tools

Even though the same basic process can be used to set up most valves and tools, some specific parameter differences can impact the performance of each head.

Valve data must be defined before working with program lines or program parameters because the program must know which valve or tool to use, plus these factors determine some of the default values used by the program.

### Micro-Dot Valve Setup

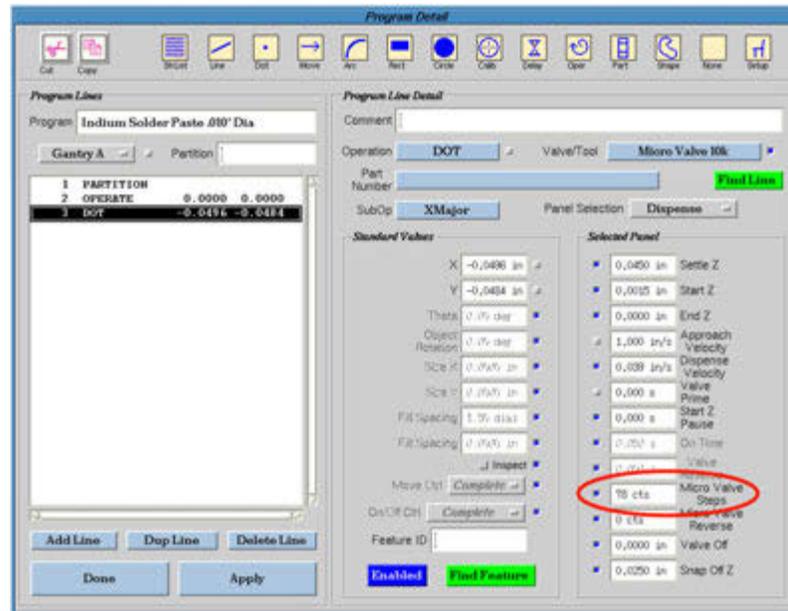
To set up a Micro-Dot valve in a program:

1. Install a Micro-Dot valve on the dispenser in the desired mount position.
2. Make selections and entries for the Micro-Dot valve in the Valve/Tool Editor:
  - a. In the Program Editor menu bar, click on Libraries > Head to open the Valve/Tool Editor window.
  - b. Either select an existing Micro-Dot valve from the Valve/Tool Name field or create a new valve record.

The screenshot shows the 'Valve/Tool Editor' window. The 'Valve/Tool Name' field is set to 'MicroDot Valve' and the 'Type' dropdown is set to 'MicroValve'. The 'MicroValve Velocity' field is set to '5000 cts/s'. Other fields include X, Y, and Z Offsets, Standoff Z Offset, Valve Speed, Micro Feed Rate, Micro Valve Reverse, Micro Valve Acceleration, Hold Time, Open Time, and Seating Force.

- c. Select the MicroValve choice from the Type option menu.
  - d. Enter a value in the MicroValve Velocity field. Both the type of material and needle gauge to be used will factor into the value you choose to enter here.
  - e. To save your entries, click APPLY and then CLOSE.
3. Add Micro-Dot valve parameters to a program or shape:
    - a. In the Program Editor, select the program to which you want the Micro-Dot valve added.
    - b. Click on EDIT DETAIL LINES to open the Program Detail window.
    - c. If the Micro Valve Steps field is not already visible, select the Dispense choice from the Panel Selection option menu.

- d. Enter a value in the Micro Valve Steps field based on one of the following choices:



If dispensing:	The value in Micro Valve Steps will control:
Dots	Dispense shot size. This value determines how long the valve will remain on during dot dispense.
Any shape other than dots	Length of time required by the program to dispense the shape.

- e. To save entries, click APPLY and then click DONE to exit the window.

## Auger Valve Setup

To set up a variable speed auger valve in a program:

1. Install a variable speed auger valve on the dispenser in the desired mount position.
2. Make selections and entries for the auger valve in the Valve/Tool Editor:
  - a. In the Program Editor menu bar, click on Libraries > Head to open the Valve/Tool Editor window.

- b. Select an existing auger valve from the Valve/Tool Name field or else create a new valve record.

- c. Select the Variable Auger choice from the Type option menu.

**NOTE:** Be sure to choose *Variable Auger* and not *Auger* or else the variable speed auger valve will not function.

- d. Enter a value in the Valve Speed and Valve Ramp fields. Both the type of material and needle gauge to be used will factor into the value you choose to enter here. If these values are set too low for the material being used, the valve will stall.
- e. To save your entries, click APPLY and then CLOSE.

## Pressure Sense Tool Setup

To set up a Pressure Sense tool in a program:

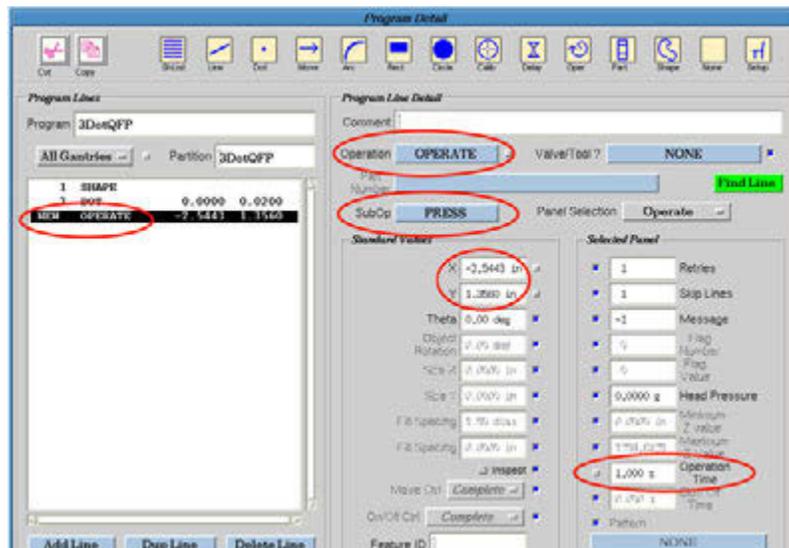
1. Install a Pressure Sense tool on the dispenser.
2. Make selections and entries for the Pressure Sense tool in the Valve/Tool Editor:
  - a. In the Program Editor menu bar, click on Libraries > Head to open the Valve/Tool Editor window.
  - b. Select an existing Pressure Sense tool from the Valve/Tool Name field or else create a new tool record.

**SUGGESTION:** Set up a new tool record (with tool name, pressure, etc.) for each different pressure value you will be using. This will help prevent damaging the tool as a result of inadvertently running operations not meant for that particular tool. For example, set up one tool named *2.5 kg Tool* with an assigned value of 2500 grams seating

pressure, and a different tool named *3.0 kg Tool* with an assigned value of 3000 grams seating pressure.



- c. Select the Pickup choice from the Type option menu.
  - d. Enter a value in the Seating Force field.
  - e. To save your entries, click APPLY and then CLOSE.
3. Add Pressure Sense tool parameters to a program or shape:
    - a. In the Program Editor, select the program to which you want the Pressure Sense tool added.
    - b. Click on EDIT DETAIL LINES to open the Program Detail window.
    - c. Create an OPERATE program line to seat a part by first highlighting the program line that will precede your new program line and clicking ADD LINE. A new program line is added to the program. Then select the OPERATE choice from the Operation option menu.



- d. Select the PRESS choice from the SubOp option menu.
- e. If the Operation Time field is not already visible, select the Operate choice from the Panel Selection option menu.
- f. Enter a value in the Operation Time field for the desired length of press time. *Press time* begins when the Pressure Sense tool achieves the Seating Force value (previously entered in the Valve/Tool Editor). Tool descent time is not factored into press time and the tool will retract automatically (Snap Off Z in the Dispense panel) when the Operation Time value expires.
- g. Teach the X and Y coordinates for the new program line.
- h. To save your entries, click APPLY and then DONE to exit the window.

### **Monitoring Pressure Data**

---

The amount of pressure exerted by the Pressure Sense tool can be monitored as it continuously displays in the Monitor field on the main window. For details, refer to [Monitoring Program Details](#) (pg 3.139).

## Programming - Keys to Success

Topics important to your programming success are included in this section.

- [MOUNT](#) (pg 3.71)
- [Material Parameters](#) (pg 3.73)
- [Vision Lighting & Focus](#) (pg 3.74)
- [Operations](#) (pg 3.86)
- [Defaults](#) (pg 3.89)
- [Arrays & Alignment Points](#) (pg 3.100)
- [Feature ID](#) (pg 3.102)
- [Process Inspection Tools](#) (pg 3.105)
- [Testing & Inspecting](#) (pg 3.118)
- [Tweaks for Valves/Tools](#) (pg 3.120)
- [Conveyor Auto-Width](#) (pg 3.124)

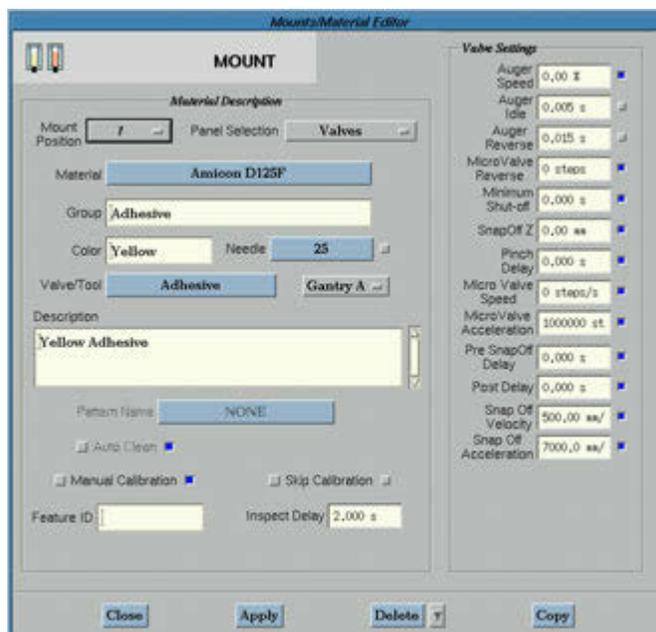
### MOUNT

Values displayed in Mounts/Material Editor - MOUNT are program specific. They define the following to be used by the selected program:

- head station position,
- type of head (valve or tool), and
- type of material.

MOUNT also performs the critical function of defining the following for a program:

- needle gauge,
- setup parameters for the calibration dot,
- process parameters (air pressure, etc.)
- settings for vision parameters for inspection mode,
- limit parameters,
- material weight for scale (if present),
- valve settings, and
- gantry.



## MOUNT Rules

The following rules apply to all uses of Mount/Material - MOUNT:

- Head and material data must be defined before working with program lines or program parameters because these factors determine some of the default values used by the program.
- If a program uses valve/tools in multiple mount positions (for example: Head 1 to dispense material A and Head 2 to dispense material B), the name for each valve/tool must be unique.

## MOUNT & Defaults

Parameters set to default in Mount/Material Editor - **MOUNT** are operating at the program level and default to Mount/Material Editor - **MATERIAL**. So, when a material is selected using Mount/Material - MOUNT, all the parameter, setup, and valve information associated with that material will display in the MOUNT window.

For complete details about the defaulting hierarchy of the Mount/Material Editor windows, refer to [Mounts & Material Defaults](#) (pg 3.94).

## Location of Valve Parameters

Valve control and valve speed parameters are typically controlled from the detail lines of the program. Alternatively, the level of control can be relocated to Mount/Material - MOUNT.

The valve parameters usually display in the Dispense and Extra Control [Selectable Panels](#) (pg 2.12) of Program Detail, but can be re-configured by GPD Global Service personnel to display instead in Mount/Material - MOUNT.

## Material Parameters

Material data must be defined before working with program lines or program parameters because these factors determine some of the default values used by the program.

A set of standard materials and associated parameters are included in the control software. The material parameters for each material are stored in the [Materials Library](#) (pg 5.7).

To view the default parameters associated with any of these materials, open the Mount/ Material Editor MATERIAL window by selecting Libraries > Material from the Program Editor menu bar, and then select the desired Material ID from the Material field.

**Table 19: Examples from Material Library**

Material Group	Material ID	Material Color	Recommended Valve	Material Info
2-Part	3-M DP 190	Black	MV-50	2-Part / 1-to-1 mix ratio in duo-pack design cartridge. Very high snap-off required.
Adhesive	Amicon D124F	Pale Yellow	Auger Valve	Dots have a very rounded profile. For high speed surface mount adhesive.
	Loctite 3106 UV	Clear	Auger Valve @ 75%	UV cure adhesive. Stringy material requiring higher snap-off heights.
Conductive Adhesive/Epoxy	Namics H9628D	Silver	Micro Valve 50K	Conductive material that must be kept at -40 degrees C/F. Excellent material for small, low profile dots @ high speed dispense rates.
Dielectric Epoxy	MS (Ablestik 84-3)	White	LX Auger Valve with Delrin cartridge	Ablestik 84-3. Non-conductive material that must be kept at -40 degrees C/F. Material is discolored with carbide; use Delrin/plastic cartridge assembly.
Damming Material	Hysol FP4451	Black	LX Valve	Damming material for use with Hysol FP4450. Viscosity is too thick for 8-pitch deep auger. Recommend using 0.125" 16-pitch w/19:1 motor ratio.
Fill Material	Hysol FP4450	Black	Auger Valve with shutoff	Fill material for use with Hysol FP4451. Requires shut-off to prevent needle drip.
RTV Silicone	NuSil MED-2000	Clear	Spool Valve	RTV silicone adhesive. Requires a high snap-off, slow dispense rate, and a longer Start Z pause.
Solder Paste	Indium NC-SMQ90	Grey	Micro Valve 20K	Solder paste Type 4 mesh. 86% Metal Content and No-Clean flux.
None	Vacuum Material	None	Vacuum Tool	This is used to define running parameters for the vacuum tool only; it is not to be used with dispensing valves.

## Vision Lighting & Focus

Adjust vision lighting and focus as necessary to heighten camera capabilities.

- [Lighting Controls](#)
- [Lens Focus](#)
- [Automatic Vision System Set Up](#)

### Lighting Controls

Defining various elements for the camera such as the level of light intensity, lighting color, and the type of illumination can heighten camera vision capabilities.

Software lighting controls, available when the dispenser is equipped with the applicable options, can be found on the following windows: Jog, Lens Adjust, and Pattern Trainer.

Parameters for light level, light color, and type of illumination can be set up for specific materials in the materials library.

Lighting controls available in the Program Detail window provide the ability to change lighting parameters either globally (by modifying the partition line) or for a single program line.

### Intensity

---

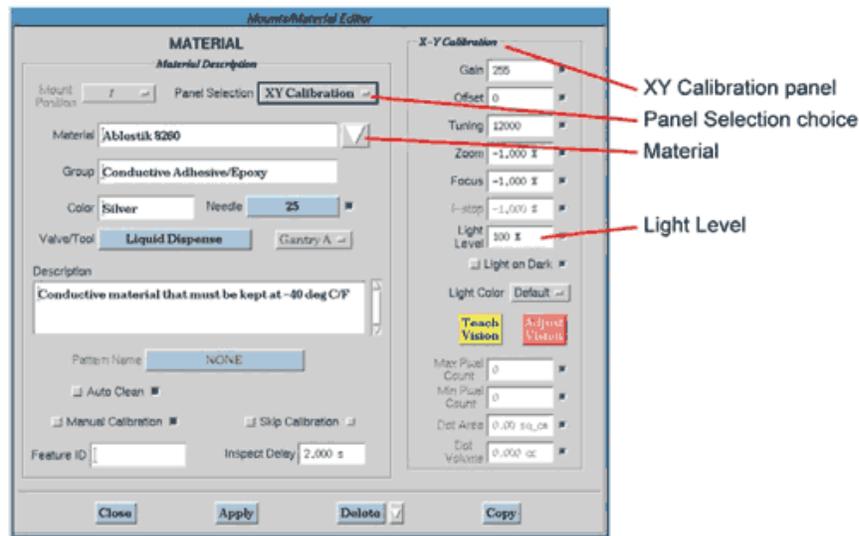
**NOTE:** *The optional Light Intensity hardware has been discontinued; the same functions can now be accomplished using the gain and offset lighting features discussed in [Program Set Up](#) (pg 3.82).*

When a machine is equipped with the Illuminator Intensity Control option, the intensity of the light illuminating the camera field of view can be controlled either manually by the operator or automatically through the software. A specific light level can be defined to enhance fiducial and pattern identification.

To enter a value for intensity control:

1. From the Program Editor menu bar, click on Libraries > Materials. The Mounts/Material Editor- MATERIAL window displays.
2. Select the material to which you wish to assign a light level parameter. The material name should be displayed in the Material field.
3. From the Panel Selector pull-down menu, select XY Calibration. The XY Calibration panel displays in the right-hand side of the window.
4. Enter desired value in the Light Level field.

- Click APPLY to save your entry. You have completed setting a light level for the selected material.



## Color & Type

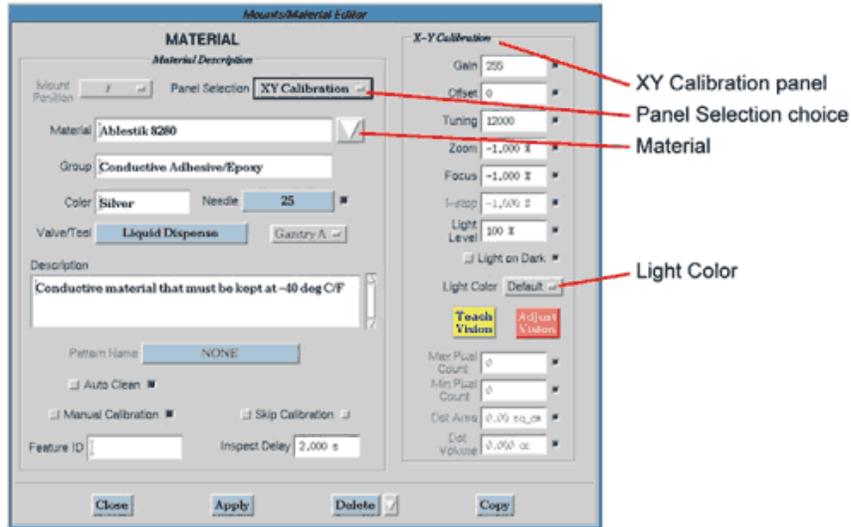
You may select the [Camera Light Color](#) (pg 3.77) and type of illumination best suited for your process provided the applicable options are installed on your machine. The selected lighting elements become associated with a specific fiducial or pattern image within a program.

To enhance fiducial or pattern identification when vision is affected by surface colors or textures, you may define a specific color (typically red or blue) with the Illuminator Intensity Control option, and a choice of ring light or diffuse on-axis light is available with the Multi-Axis Illumination option.

To select a color or type of light:

- From the Program Editor menu bar, click on Libraries > Materials. The Mounts/Material Editor- MATERIAL window displays.
- Select the material for which you wish to select a color or type of light. The material name should be displayed in the Material field.
- From the Panel Selector pull-down menu, select XY Calibration. The XY Calibration panel displays in the right-hand side of the window.
- Click the Light Color DEFAULT button and make desired selection from the pop-up menu.

5. Click APPLY to save your selection. You have now completed selecting a color and/or type of light for the selected material.



## Camera Light Color

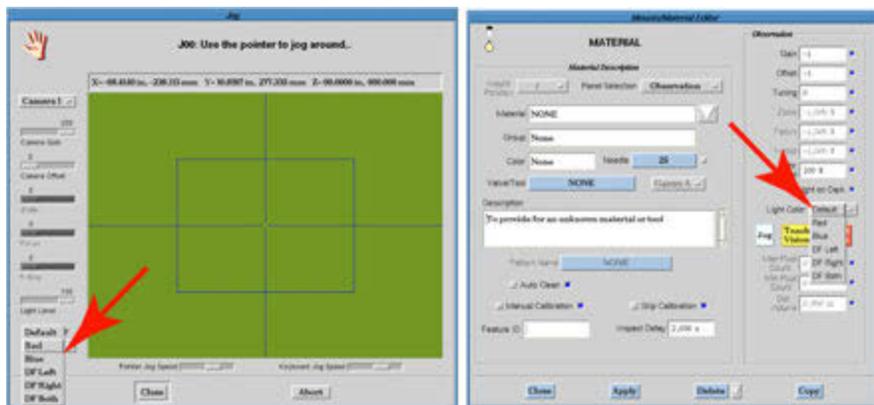
Use the Dark Field camera light colors with the low angle ring light for improved edge detection. The Dark Field options (DF Left, DF Right, DF Both) can be used alone or in conjunction with the overhead lighting options (Red, Blue).

**Figure 10:** Relative locations of DF Left & DF Right areas of illumination



To turn off the overhead lighting options, be sure the Light Level field (or slider in the Jog window) is set to 0%.

**Figure 11:** Location of camera light color controls



## Lens Focus

The camera lens focusing instructions differ depending on whether your system uses a fixed, manually adjusted camera or an automatic, programmable focus camera.



**IMPORTANT** Making adjustments to camera focus or lighting conditions may affect all patterns used by your programs and thus require you to modify your patterns accordingly.

<b>IMPORTANT</b> <a href="#">Tout changement de</a>	<b>WICHTIG</b> <a href="#">Jegliche Justierungen</a>	<b>IMPORTANTE</b> <a href="#">Regolazioni al fuoco</a>	<b>IMPORTANTE</b> <a href="#">Los ajustes al enfoque</a>
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## Fixed Camera

If your dispenser is configured with a fixed (passive) vision system, use these steps to adjust the aperture and focus for a manually adjusted camera lens:

1. Jog the camera to a position over the calibration dot on the calibration station.
2. Manually adjust the aperture (f-stop) to wash out unimportant features (paper grain) and increase contrast. The background should be as white as possible while maintaining dot blackness. Be sure not to introduce distortion such as blooming (indicates the f-stop is open too far).

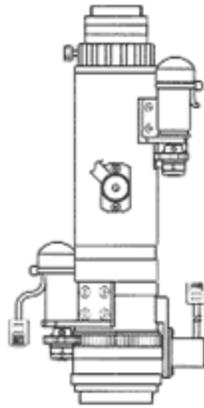
3. Manually adjust the focus ring so the dot is distinct (black versus white). There should be no shades of gray between the dot and the background.

### Programmable Focus Camera

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If your dispenser is configured with an Automatic Vision System, the camera (mounted next to the heads) works with the vision system to verify product alignment and the XY location of the valve tip prior to the dispensing process. An automatic vision system locates images automatically as opposed to requiring an operator to manually align the camera over parts. More specifically, the automatic Total Runtimes system uses a video camera and a programmable zoom/focus lens.

**NOTE:** The programmable zoom and focus is specific to a fiducial/pattern image and program.



ClearVu Vision  
Programmable Optem Lens

The Programmable Focus Lens Camera is a part of the Total Runtimes option. This automatic vision alignment system automatically performs the functions of alignment, locating, and pattern-recognition training with a software-controlled, programmable focus lens camera.

This camera must be adjusted through the software - it cannot be manually adjusted. Lens focus, zoom, and f-stop (camera iris) adjustments are controlled through the software rather than by means of mechanical adjustments - refer to [Automatic Vision System Set Up](#) (pg 3.78). Live video provides immediate feedback as these software camera control adjustments are made.

### Automatic Vision System Set Up

**NOTE:** This section applies only to dispensers configured with a Total Runtimes programmable focus camera.

With the (optional) automatic vision feature, there is no need to manually align the camera during calibration or during a program run. Alignment is performed automatically with no operator intervention.

The automatic vision feature locates fiducial points by means of a pattern search. The user teaches a fiducial pattern (model) and stores the pattern for later use in a program (where the system looks for the fiducial).

During the needle calibration procedure, a dot of material is dispensed on the calibration station at the dispense pad. In place of manually aligning the camera over the dot, the automatic vision locates the roundest object on the pad and makes positional adjustments based on what it finds.

Camera calibration looks at the calibration dot (on the calibration station) from two different positions. The difference in positions is used to (1) calculate the size and aspect ratio (width to

height) of the camera pixels, and (2) determine the ratio transformation of the camera pixels to encode counts.

The following topics are discussed in this section:

- [Total Runtimes Sequence of Operation](#) (pg 3.79)
- [Material Set Up](#) (pg 3.80)
- [Program Set Up](#) (pg 3.82)
- [Calibration Chip Use](#) (pg 3.83)
- [Parameters & I/Os](#) (pg 3.83)
- [Adjust Lens Focus Settings](#) (pg 3.84)

## Total Runtimes Sequence of Operation

The following is a typical sequence of events for the Total Runtimes system:

1. The surface sensor probe moves to the touch pad to establish pad height.
2. The camera adjusts to the values set in the Vision Calibration panel [refer to [Vision Calibration](#) (pg 3.129)]. If defaulted, the camera uses the settings from the ..Default.. program [refer to [Program Set Up](#) (pg 3.82)].

The screenshot shows the 'Miscellaneous Program Settings' dialog box. It is divided into three main sections: Vision Calibration, Temperatures, and Other.

- Vision Calibration:** Includes fields for Gain (100), Offset (21), Tuning (0), Zoom (30,000 %), Focus (20,000 %), f-stop (0,000 %), Light Level (0 %), and a checkbox for Light on Dark. There is a dropdown for Light Color (Red) and three buttons: Teach Vision, Adjust Vision, and Jog. At the bottom are fields for Max Pixel Count (0), Min Pixel Count (0), and Dot Volume (0,000 cc).
- Temperatures:** Contains checkboxes for Pre-Heat Heater On and Post-Heat Heater On. Below each is a Temperature field (0 C) and a Range field (0 C), followed by a Pre-Heat PID and Post-Heat PID field.
- Other:** Includes a checkbox for Work Area Heater On, a Temperature field (0 C), a Range field (0 C), and a Work Area PID field. At the bottom right are fields for Bad Mark Count (0), Post Press (0,000 g), Post Press Range (0,000 g), and Post Press Time (0,000 s).

Buttons for 'Done' and 'Apply' are located at the bottom of the dialog.

3. The camera moves to a dot on the calibration station glass chip. The dot selected depends on the Zoom value and the settings for CamCalZoom1 and CamCalZoom2 [refer to [Configuration Parameters](#) (pg 3.83)].

### Example

- If CamCalZoom1 = 30 and Zoom < 30, the camera moves to the largest dot for calibration.
- If CamCalZoom2 = 60 and Zoom > 30 but < 60, the camera moves to the medium sized dot for calibration.
- If Zoom > 60, the camera moves to the smallest dot for calibration.

For additional details about proper set up of the camera calibration locations, refer to *Teaching Base Locations* in the *Dispenser Service Guide*.

4. The surface sensor probe touches either the ceramic chip or the paper pad on the calibration station.
5. The valve needle moves to the touch pad to establish needle tip height.
6. The valve purges.
7. The valve dispenses a dot on the ceramic chip or paper pad.
8. The camera adjusts to the Zoom value of XY\_Calibration only if it is different than the value set in the Vision Calibration panel, and then moves to the glass chip to re-calibrate.
9. The camera adjusts to the focus and light settings of the XY\_Calibration and centers on the dispensed calibration dot to establish the XY coordinate relationship between the camera and needle.
10. The gantry moves to park location for program start.
11. The gantry adjusts to the Zoom value of the pattern used at the first fiducial point, adjusts the focus and light settings to those defined in the Vision Calibration panel of the Miscellaneous Program Settings window, and moves to the glass calibration chip to re-calibrate (only if Zoom value differs).
12. After calibrating, the camera now adjusts to the focus and light settings of the pattern used at the first fiducial point and finds the point.
13. After finding fiducials and if in Full Inspect mode or Inspect mode, the camera will adjust to the settings defined in the Observation panel section of the Mounts/Materials Editor window. IF the zoom is different, it will re-calibrate once again.

## Material Set Up

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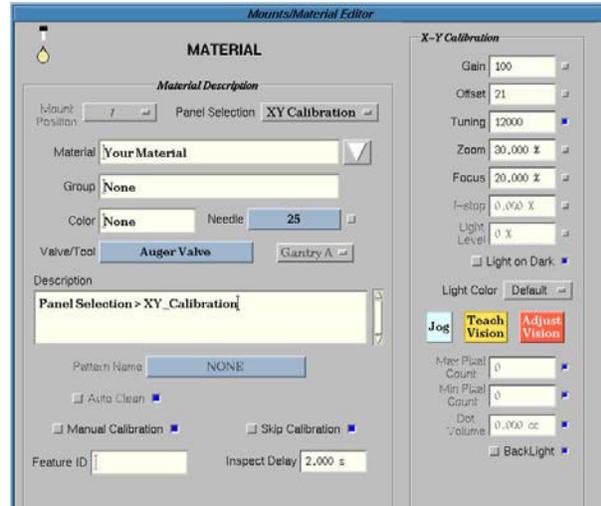
Process cycle time can be greatly reduced if consistent zoom settings are used. To keep process cycle time to a minimum, use the same zoom and focus settings in all areas where vision is used:

- patterns used at fiducial points
- in the program Vision Calibration panel
- in the Materials Library in XY\_Calibration settings and Observation settings

The XY\_Calibration settings establish the XY relationship between the needle and camera. The camera uses these settings to view and automatically center on the dispensed calibration dot located on the ceramic chip or paper pad.

To set up the material you will be using in your program in the material library, set up the XY\_Calibration and Observation settings:

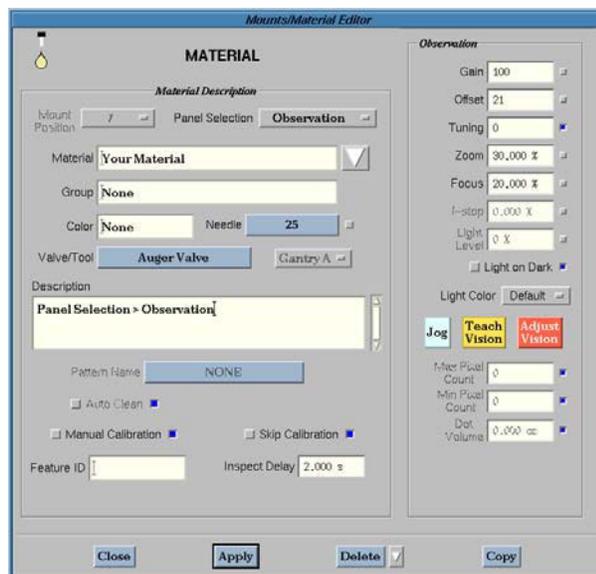
1. From the Program Editor, click on Libraries > Materials. From the Panel Selection button, select XY\_Calibration.
2. Click the JOG button, move the camera over the ceramic chip or paper pad, and view a dot of the material that will be used by the program.
3. Adjust the lighting for a dark dot on a light background. If the calibration station back light is used, turn off the top light and turn on the back light before adjusting Gain and Offset.



**IMPORTANT:** As much as possible, always teach Zoom and Focus values equal to the Zoom and Focus Settings used in the Vision Calibration panel.

4. Close the Jog window and click TEACH. This updates the data field settings in the XY\_Calibration window.
5. In the Observation panel selection area of the Mounts/Material Editor - MATERIALS window, adjust the camera settings for use when in Inspect mode or Full Inspect mode. Adjust the camera settings with the camera positioned over the dispense area of your component and verify that the lifter plate is in its raised position.

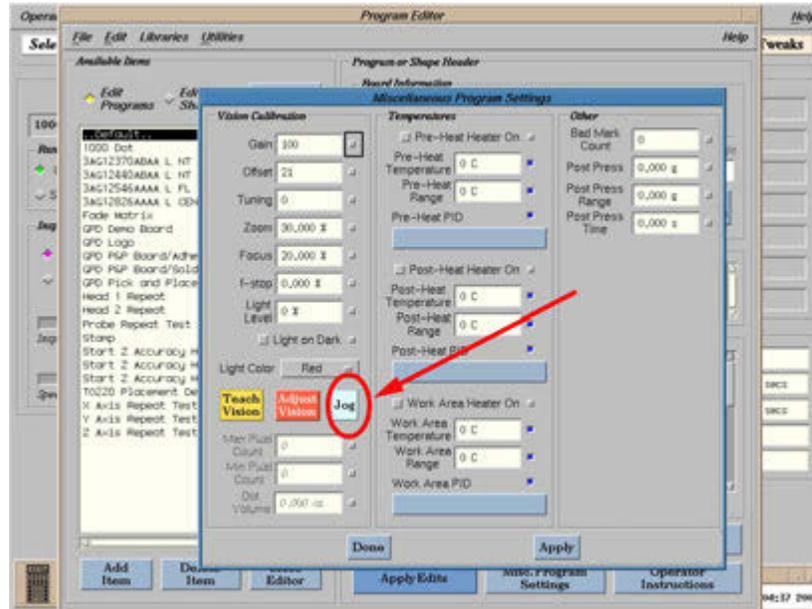
**IMPORTANT:** As much as possible, always teach Zoom and Focus values equal to the Zoom and Focus Settings used in the Vision Calibration panel.



## Program Set Up

To set up the vision calibration settings properly in the Misc Program Settings panel of the ..Default.. program:

1. Open the Program Editor and highlight the [..Default.. Program](#) (pg 3.93).
2. Click on MISC PROGRAM SETTINGS> JOG.



3. Move the camera over a calibration dot on the glass calibration chip and adjust the zoom to 100%.
4. Adjust the focus until the image is sharp and clear.
5. Move the zoom back to 0% and verify that the focus is good throughout the full range of the zoom. If the zoom is out of focus at 0%, refer to the ADJUST Camera/Lens Alignment section of the Dispenser Service Guide for setting the camera-to-focus height adjustment.



**CRITICAL: Sharp focus throughout the zoom range is critical.** When a new zoom value is called for, either from the XY\_Calibration of the Mounts/Material Editor - MOUNT window or from a pattern being used at a fiducial point, the camera needs to re-calibrate the pixel-to-gantry transformation. When doing so, it only adjusts the zoom. The focus, gain, and offset are gathered from the Vision Calibration panel of the Miscellaneous Program Settings window.

6. Adjust the Gain and offset lighting to a level that will maintain a dark dot with a light background throughout the zoom range. If this is not possible, manually adjust the Iris (f-stop).

Typically, the Iris will need to be opened slightly to allow more light for a brighter image at 100% zoom. This is also critical for the same reason as stated in the prior step. When the camera comes to calibrate at the glass chip at a new zoom level as called for from either the XY\_Calibration settings or a pattern used at a fiducial point, the **Gain, Offset, and Focus information will be gathered from the Vision Calibration panel. Only the Zoom will adjust to the new values as called.**

7. When the above-mentioned conditions are met, set the following:
  - a. Set Zoom to 50%
  - b. Adjust the Gain and Offset for a clear black dot and white background.
  - c. Set Zoom back to 0%.
8. Close the Jog window and click the TEACH button. This action updates the vision calibration settings.



**IMPORTANT:** Zoom is typically taught at 0% or at the typical zoom values used by the patterns; however, it can be taught at a different value of engineer's preference. Keep in mind that any new program and any existing program that is defaulted will use the vision settings of the ..Default.. program to calibrate at the glass chip. Again, **keeping zoom values consistent is the key to minimizing re-calibration.**

## Calibration Chip Use

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As the value of zoom increases, the viewing area decreases and the dot size will grow larger. For this reason, the camera must be able to calibrate on smaller dots at higher zoom levels. To properly teach the locations of the different calibration dots at higher zoom values, refer to *Teaching Base Locations* in the *Dispenser Service Guide*.

Keep in mind that there are [Configuration Parameters](#) (pg 3.83), CamCalZoom1 and CamCalZoom2, used in the Dispenser Configuration file that determine at what zoom level each dot is used.

## Parameters & I/Os

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The parameters and inputs/outputs (I/Os) listed below are used by the ClearVu programmable vision system and are located in the Edit Configuration file (for details, refer to [Dispenser Configuration](#) (pg 3.136)).

### **Configuration Parameters**

Unless otherwise noted below, the following displayed values may be changed as needed.

- CamCalZoom1 = 30
- CamCalZoom2 = 60
- GantrySettleDelay = 150
- HasVision = True      **< never change this value**
- LensType = 2      **< never change this value**
- LensPort = dev/ser3
- Reduce Flash = True
- DotCalibDlg = 1

### **Inputs/Outputs (I/O)**

- IO/Vision/LightBlue - 10003 - Hard Wired
- IO/Vision/LightRed - 10002 - Hard Wired
- IO/Vision/BackLight -10017 - Configurable
- IO/Vision/LensAdjust - Configurable

## Adjust Lens Focus Settings

**OBSOLETE AS OF FLOWare software version 2.1.**

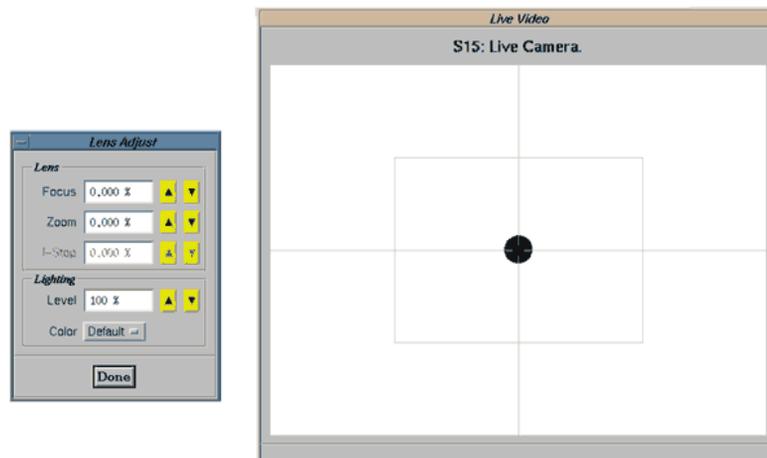
The software tools described in this section can be used in subsequent software versions, however, **all changes to vision values made using the Lens Adjust window are temporary and overridden** by the newer vision tools described in [Total Runtimes Sequence of Operation](#) (pg 3.79).

Prior to adjusting the lens focus settings for an automatic vision system, it is important to first understand the contents of [Automatic Vision System Set Up](#) (pg 3.78).

**! IMPORTANT:** Programmable zoom and focus values are specific to a fiducial/pattern image and program. Therefore, adjusting the camera and/or lighting may require changing all patterns used by your programs.

To adjust the lens focus settings:

1. If the dispenser is configured with a lifter plate, verify that the lifter plate is in its raised position prior to performing the following camera focusing steps.
2. Jog the camera to the point where it is to focus.
3. In the menu bar of the Main Control Panel, click on Machine Controls > Lens Adjust. Two different types of windows display – the lens adjust controls and a live camera video display.



4. Adjust camera focus as needed using the arrows in the Lens Adjust window to obtain a clear picture in the Live Video window. The contrast should be black and white, not shades of gray. If the contrast is gray, adjust the aperture and focus of the camera lens.

**NOTE:** Typically, you'll use the Focus and Zoom controls the most often. For camera lenses for which the f-stop field is active, set the desired level of brightness with the f-stop arrows. (Units can not be converted in the Lens Adjust window.)

5. As needed, adjust Lighting Level to obtain the optimum intensity for the current viewing situation. Also as needed, switch the Lighting Color for optimum contrast results. For further details about controlling light intensity and color, refer to [Lighting Controls](#) (pg 3.74).

**NOTE:** Lens and lighting controls are available in both the Jog window and the Lens Adjust window. Coarse adjustments can be made in the Jog window, while finer adjustments are more easily made using the controls in the Lens Adjust window.

6. If you will want to view dispense heights at a later time while in Inspection Mode, record the Focus and Zoom values displayed now; otherwise, skip to the next step.
7. Click DONE in Lens Adjust.

## Operations

Operations define how the dispenser is to perform. Basic software operations can be combined into a package called a *shape*.

### Operation Categories

Different types of operations are used to define the processes performed by program lines. All types of operations fall into one of two categories: they either function as an operation or as a shape.

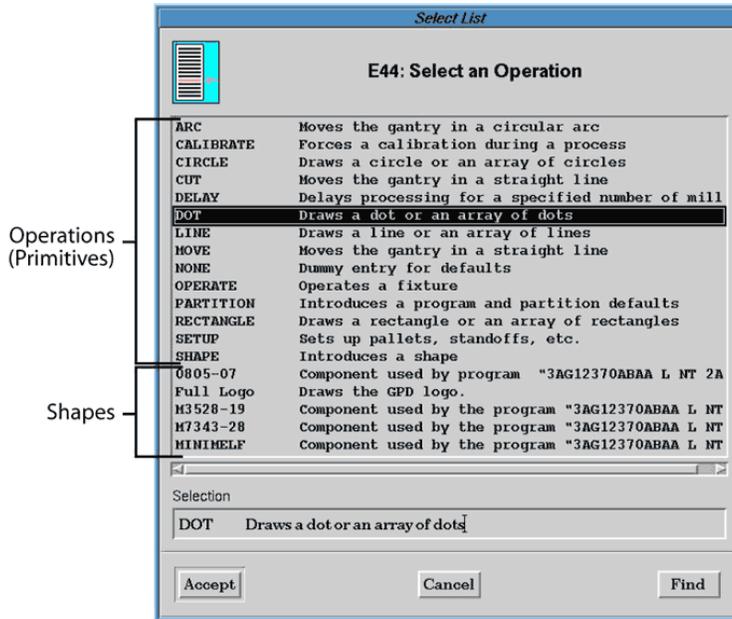
Operation Category	Explanation
operation	a preprogrammed, primitive shape provided by the control software. Each operation defines an often-used shape or action; e.g., dot, line, move, arc, delay, etc.
shape	a subroutine created by the user, incorporating primitive operations and other shapes.

All *operations*, or primitives, are always available. They can be accessed from the top of the Program Detail window where each operation appears as an icon, from the Select List window (discussed below), or with the Program Detail OPERATION button.

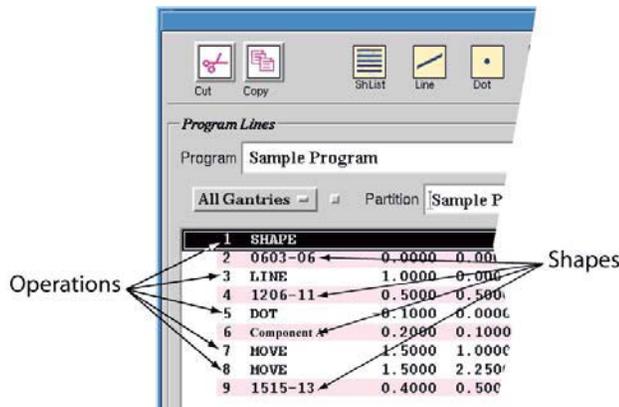


All *shapes* are also always available unless filtered by class. A list of all currently available (non-class filtered) shapes can be accessed with the ShList icon located at the left of the icon group (shown above), from the Select List window (shown below), or with the Program Detail OPERATION button.

All operations from both category types – *operation* and *shape* – are listed in the Select List window that displays when you click on the ADD LINE button in the Program Detail window. Primitives are always listed first.



Examples from both operation categories – operation and shape – are shown below in a sample program (in the Program Detail window).



## Summary of Operations (Primitives)

The table below lists and briefly explains the preprogrammed, primitive operations available in the dispenser control software. For further, detailed information about each operation/primitive, refer to [Operations \(Primitives\)](#) (pg 5.108).

<b>Operation (Primitive)</b>	<b>Brief Explanation</b>
Arc	moves the gantry in a circular arc
Calibrate	forces a calibration during a process
Circle	draws a circle or an array of circles.
Cut	synonym for the Move operation; moves the gantry from point to point.
Delay	delays processing for a specified number of milliseconds.
Dot	draws a dot or an array of dots.
Line	draws a line or an array of lines.
Move	moves the gantry from point to point.
None	dummy entry for defaults or comments.
Operate	operates a fixture; performs special functions not included in other primitives.
Partition	introduces a program and partition defaults.
Rectangle	draws a rectangle or an array of rectangles.
Setup	performs setup of pallets, standoffs, etc. prior to program execution.
Shape	introduces a shape and shape defaults.

## Defaults

The proper use of default and override values can save both programming time and program run time. Increased efficiency in both areas results from understanding and effectively using these toggling value controls.

### Default Values & Override Values

All value fields with a square blue or gray [Default Button](#) (pg 2.16) next to them can use the default value supplied by the system or an override value entered by the user.

You control whether a field uses the default value or an override value by turning the default button on or off. The displayed button color indicates which value is active for that field:



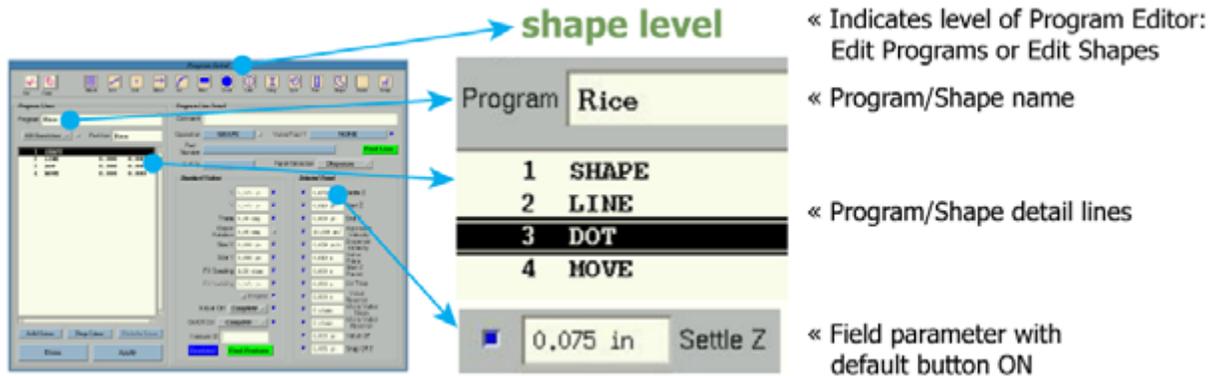
### Hierarchy of Defaults for Programs & Shapes

An understanding of default hierarchy is very important to the effective and proper use of default and override values.

#### Key to Illustrations

For simplicity, the illustrations used to explain default hierarchy in [Hierarchy of Programs & Shapes](#) (pg 3.90) show only window snippets (program name, program/shape detail lines, and a representative value field) to convey the hierarchical relationship between elements in both versions [[Edit Programs / Edit Shapes](#) (pg 3.32)] of the Program Editor.

**Figure 12:** Key to illustration format used to explain default hierarchy

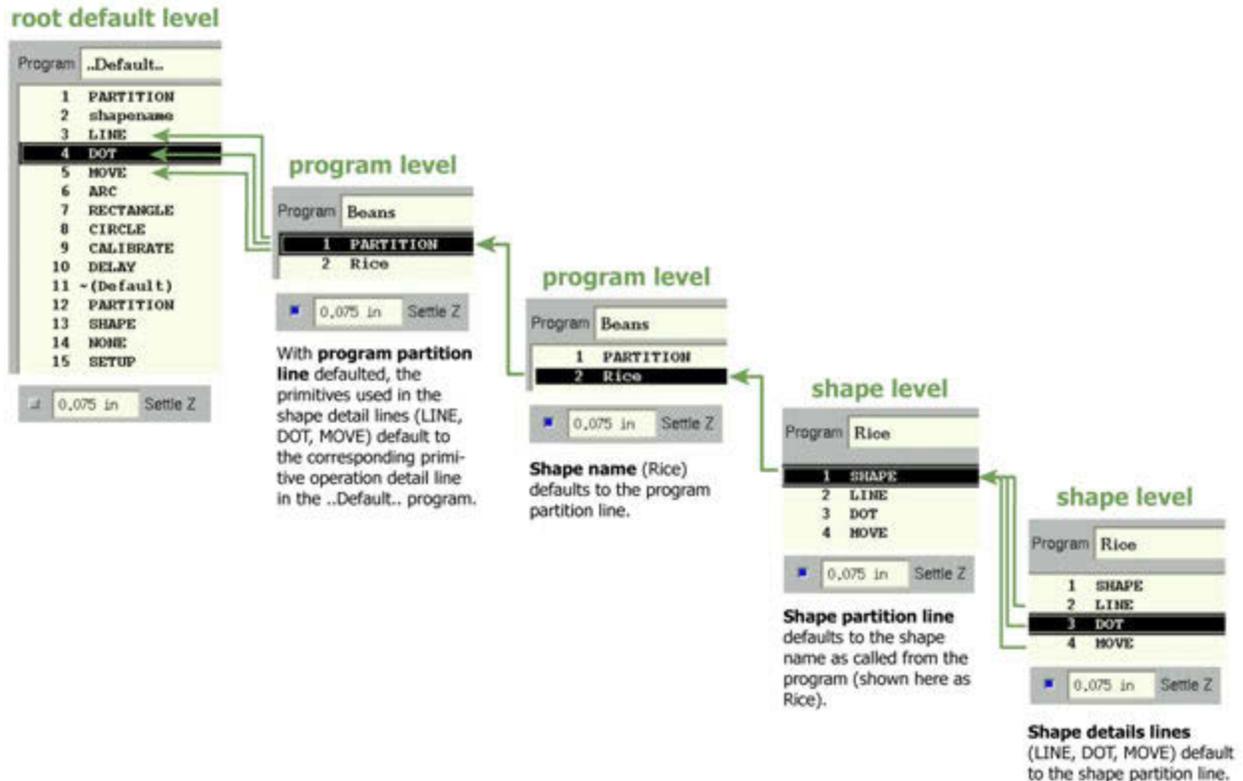


## Hierarchy of Programs & Shapes

If all program and shape levels are defaulted – if all Default buttons are blue as shown in Figure 13, the primitives used in a shape (like LINE, DOT, MOVE) follow the default hierarchy relationship shown here to the root [..Default.. Program](#) (pg 3.93) level where the most commonly used values are defined.

The example in Figure 13 shows a simple program named Beans that consists of a shape named Rice that consists of a line, dot, and move. This example follows the DOT shape detail line through the full hierarchy of defaults.

**Figure 13: Hierarchy of defaults: all program & shape levels are defaulted for DOT.**



### Additional Fully-Defaulted Hierarchy Tips

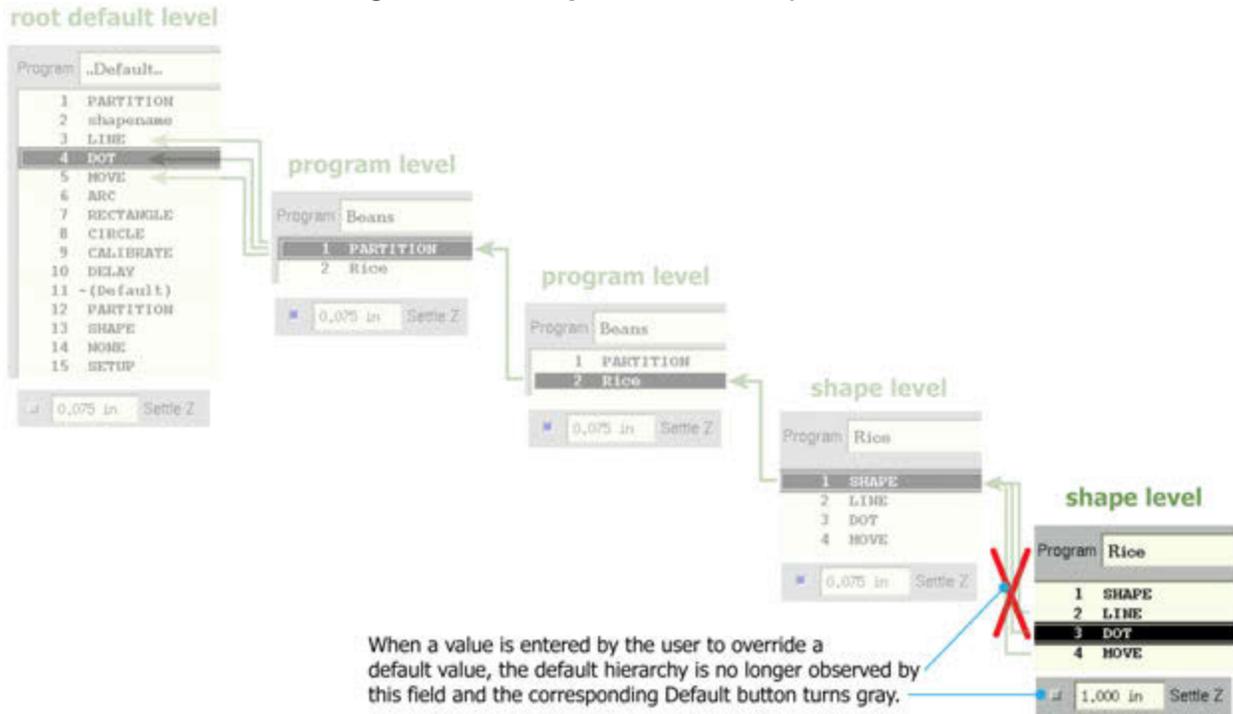
- Assuming all levels are defaulted, a shape in a program will default to the 2 *shapename* detail line in the `..Default..` program.
- Assuming all levels are defaulted, any value inside any shape, even when nested, comes from the corresponding primitive in the `..Default..` program.
- When a shape is embedded in a program, the shape values override the program values. In other words, a non-default value entered at the shape level will override a non-default value entered at the program level.
- Also see [Shape Partition Line](#) (pg 3.56).

## How Overriding a Default Value Affects Hierarchy

When a field value is entered by the user, the default value is overridden, the default hierarchy is no longer observed by this field, and the corresponding Default button turn gray.

The example in Figure 14 shows how an override value entered in the DOT shape detail line breaks the defaulting progression.

**Figure 14:** Overriding the default hierarchy for DOT.



## Using Overrides

Overriding default values can, if done at the proper level in the default hierarchy, impact program efficiency.

**RECOMMENDATION:** Overriding a value at the lowest level of defaults, as illustrated in Figure 14 on page 3-91, is the best choice in most cases.

## Partition Line

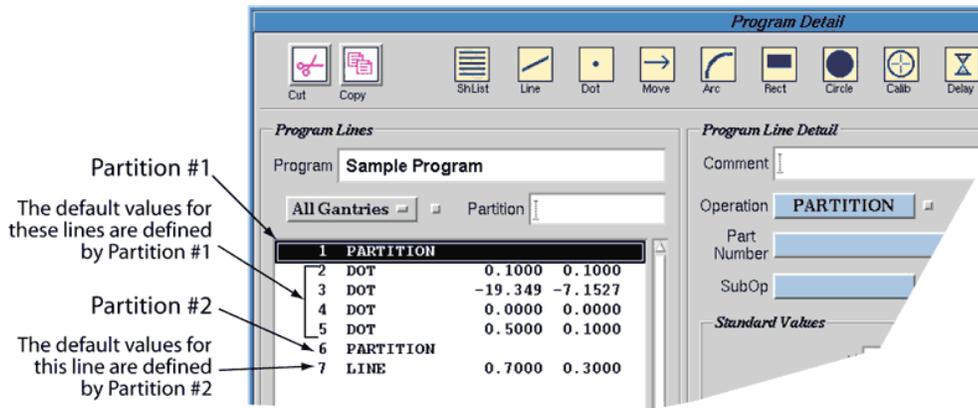
A partition line is a type of program line that appears automatically at the beginning of every new program and defines the default values for all program detail lines that follow it. A partition line saves you from having to enter the bulk of the values in each program line.

Multiple partition lines can be used in a program. (A [Shape Partition Line](#) (pg 3.56) is a different matter; it can be used only once in a shape).

## Using Partition Lines

Additional partition lines can be added to divide a program into discrete sections. Each new partition line defines the default values for all program lines that follow it until overridden by a subsequent partition line.

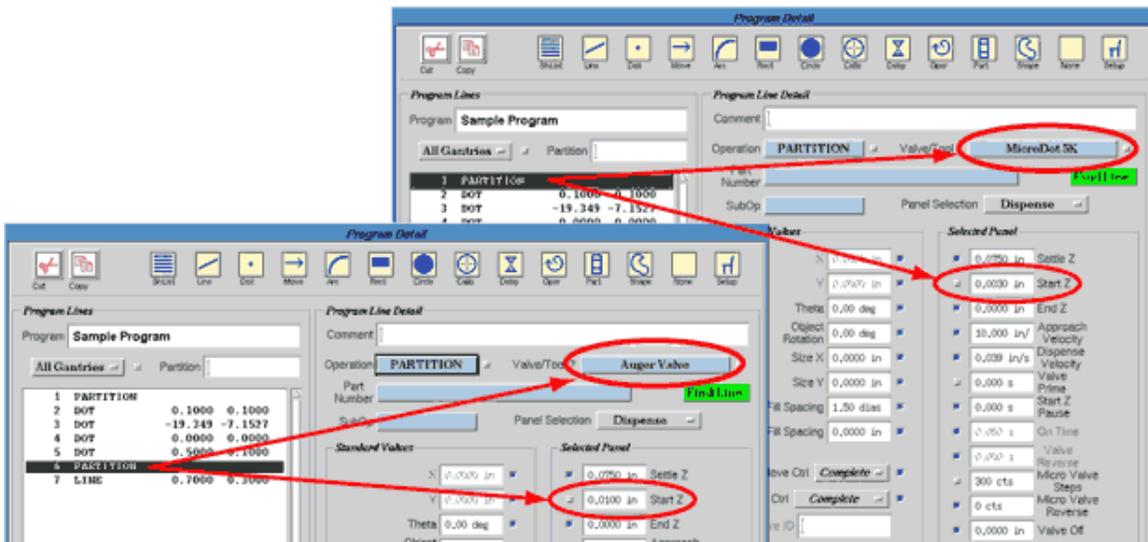
For example, in the sample program shown below, the initial partition line defines values for all of the DOT program lines, and the second partition line defines the values for the LINE program line.



### Partition Line Parameters

The initial default parameters for a partition line are automatically set to a reasonable value by the system; these parameters can be modified as needed. If an additional set of default parameters with different values are needed in a program [as discussed in [Using Partition Lines](#) (pg 3.91)], the use of additional partition lines is suggested.

For example, all DOT program lines in the sample program shown below use a Micro-Dot valve and a Start Z value of 0.0030 inches, but when the program arrives at the LINE program line, it needs to use an Auger valve and a Start Z value of 0.0100 inches.



## ..Default.. Program

..Default.. is the name of the foundation program in the FLOWare software. Access to the ..Default.. program requires appropriate access rights plus class filtering for the blank filter. Modification of the ..Default.. program is limited to changing parameter values. This program cannot be deleted.

If the **..Default.. program is not visible** at the top of the available programs list in the Program Editor, it will reappear if you click in the menu bar on Edit > Refresh Programs List (assuming the appropriate access rights are active).



**WARNING** The content of this section is NOT recommended for use by anyone besides GPD Global personnel or those working under the direct guidance of GPD Global personnel. Improper application of this information can lead to serious complications in FLOWare Software operations. Any non-GPD Global employee who uses this information beyond the stated application specified by GPD Global Service Department personnel is in danger of causing personal injury and invalidating their machine warranty.

<b>ATTENTION</b> <a href="#">Le contenu de cette</a>	<b>WARNUNG</b> <a href="#">Der Inhalt dieses</a>	<b>ATTENZIONE</b> <a href="#">Il contenuto</a>	<b>ADVERTENCIA</b> <a href="#">NO SE RECOMIENDA</a>
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Modification of the ..Default.. program is limited to changing parameter values. This program cannot be deleted.

The ..Default.. program consists of a program detail line for each of the often-used primitive operations [[Operations \(Primitives\)](#) (pg 5.108)], each of which are already populated with reasonable starting values.

**Figure 15:** Program detail lines in the ..Default.. program.

Program	..Default..	
1	PARTITION	0.000
2	shapename	0.000
3	LINE	0.000
4	DOT	0.000
5	MOVE	0.000
6	ARC	0.000
7	RECTANGLE	0.000
8	CIRCLE	0.000
9	CALIBRATE	0.000
10	DELAY	0.000
11	~(Default)	0.000
12	PARTITION	0.000
13	SHAPE	0.000
14	NONE	0.000
15	SETUP	0.000

**Table 20: Purpose of each detail line in ..Default.. program**

Program Detail Line	Purpose
1 PARTITION	This is merely a partition line for the ..Default.. program, as is the rule for all programs – the first program detail line in every program must be a partition.
12 PARTITION	This is the primitive partition operation used by all programs. The first program detail line in every program must be a partition line - one is automatically inserted whenever a program is created and populated using the values in this partition.  This is the partition that populates any newly created program.
2 shapename	All newly created shapes are given a name of the programming engineer's preference. When writing a program, the engineer will call out these shapes to run in the process.  This is the line that populates the parameters for the shape when called out from the program, assuming all program and shape levels are defaulted.
13 SHAPE	This is a shape partition line. Just as PARTITION defines parameters for subsequent detail lines in a program, the shape partition line defines parameters for subsequent detail lines in the shape.  This is the shape line that populates any newly created shape.
11 ~(Default)	Defines the parameter values for any <a href="#">Operate</a> (pg 5.112) operation in programs or shapes, assuming all program levels are defaulted.
remaining lines 3-10, 14-15	The remaining program detail lines in the ..Default.. program (LINE, DOT, MOVE, etc) populate any newly created program line using a corresponding primitive operation, assuming all program levels are defaulted.

## Mounts & Material Defaults

There are three versions of the [Mounts/Material Editor](#) (pg 5.59), each with a different purpose directly affected by the hierarchy of defaults.

### Purpose of Each Editor

In addition to representing different levels of the default hierarchy, the different purpose of each Mounts/Material Editor window is affected by the default hierarchy.

Parameter definitions remain the same across all three versions of the editor, although not all fields are active in all three windows.

- **DEFAULTS**  
Library of material parameter (needle, valve speed, head type, etc.) values affecting the **most commonly used materials**. Define the defaults for materials with the [Material Defaults Library](#) (pg 5.9) according to head mount position.
- **MATERIAL**  
Library of material parameter values affecting a **particular material**. Details at [Materials Library](#) (pg 5.7).

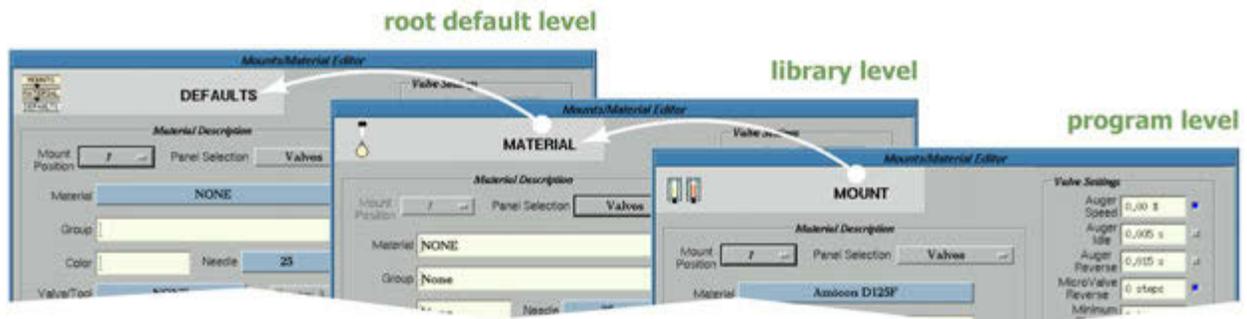
- MOUNT  
Table of values affecting a **specific program**. Details at [MOUNT](#) (pg 3.71).

## Editor Versions & Hierarchy of Defaults

Each version of the Mounts/Material Editor has a distinct heading and icon to help identify it from the others and follows a straightforward hierarchy of defaults:

- MOUNT operates at the program level and defaults to MATERIAL.
- MATERIAL operates at the library level and defaults to DEFAULTS.
- DEFAULTS operates at the root default level.

**Figure 16:** Basic default hierarchy of the three Mounts/Material Editors



### Using Overrides

For increased efficiency, values are most commonly overridden at the library level because any change made here apply to all programs using the selected material.

Overriding a value at the program level is typically done only if the value applies to a single program.

### Additional Info You Probably Won't Need

Confusion can occur when library level MATERIAL is defaulted and the user happens to notice an unexpected value displayed in program level MOUNTS. Although rarely observed because it deals with defaults at the level of the various Mount Position choices (1 through 6), this situation bears some explanation.

Everything displays normally when there is an *override* in library level MATERIAL because program level MOUNTS defaults to library level MATERIAL and the defaulting cascade stops there due to the override.

If, however, library level MATERIAL is *defaulted*, then an additional detail about the default hierarchy involving the Mount Position becomes involved. Assuming all levels are defaulted, values at Mount Position X at program level default to the corresponding Mount Position X at root default level.

For example, defaulted values in program level MOUNTS for Mount Position 2 actually default to the corresponding Mount Position, which in this case would be Mount Position 2, in the root default level DEFAULTS.

## Miscellaneous Program Settings Defaults

Values in the [Miscellaneous Program Settings](#) (pg 5.55) window default from the [..Default.. Program](#) (pg 3.93).

**RECOMMENDATION:** All default buttons in the [Vision Calibration](#) (pg 3.129) pane of the Miscellaneous Program Settings window should be turned ON (they should appear blue). This forces the program to use the default vision values established in the [..Default..](#) program.

## Offline Head Defaults

All parameters in the [Offline Operations](#) (pg 5.67) window, except valve type, default from the [Materials Library](#) (pg 5.7).

## Rotation

Two types of items (in a program or shape line) can be rotated: a single object and an array. Because both an entire array and an individual item within an array can be treated as a single object, there are two different ways to implement rotation:

### Object Rotation

Used for [Single Object Rotation](#) (pg 3.98).

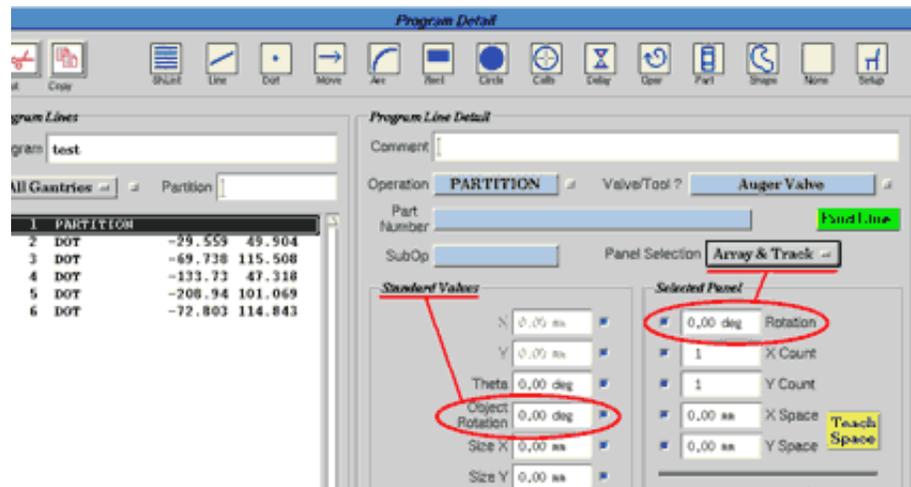
### Rotation

Used for [Array Rotation](#) (pg 3.98).

## Rotation Guidelines

Either parameter will rotate a single object a specified number of degrees about a coordinates-defined point, however, these parameters behave differently when applied to an array. For this reason, it is strongly recommended that you consistently follow these guidelines:

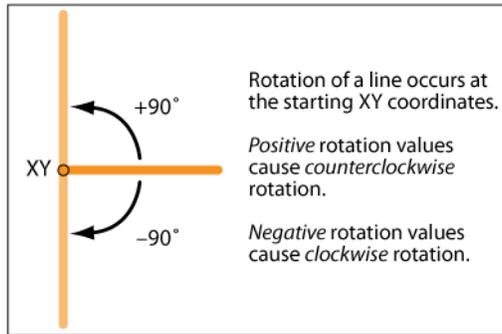
- Use **Rotation** to rotate an *entire array*, and **Object Rotation** to rotate a *single object*.
- All rotation occurs about the point defined in the X,Y fields (located in Program Detail in close proximity to the rotation parameter fields).
- The entry of positive rotation values results in counterclockwise rotation for both Rotation and Object Rotation. Clockwise rotation requires the entry of negative values.
- Rotation is independent of Object Rotation, so both parameters may be applied to the same item if necessary.
- Rotation is applied by entering a value in Program Detail in either the **Rotation** parameter or the **Object Rotation** parameter.



### Single Object Rotation

A sample of how Object Rotation influences a single object (line, rectangle, or created shape) is shown in Figure 17. The sample line in the X axis is shown rotated +90 degrees and -90 degrees to become a line in the Y axis. The point of rotation is always the starting XY coordinate for the line. Counterclockwise rotation results from a positive value. Refer to [Rotation Guidelines](#) (pg 3.97). An array can also be rotated as a single object. See example shown in [Array Rotation](#) (pg 3.98).

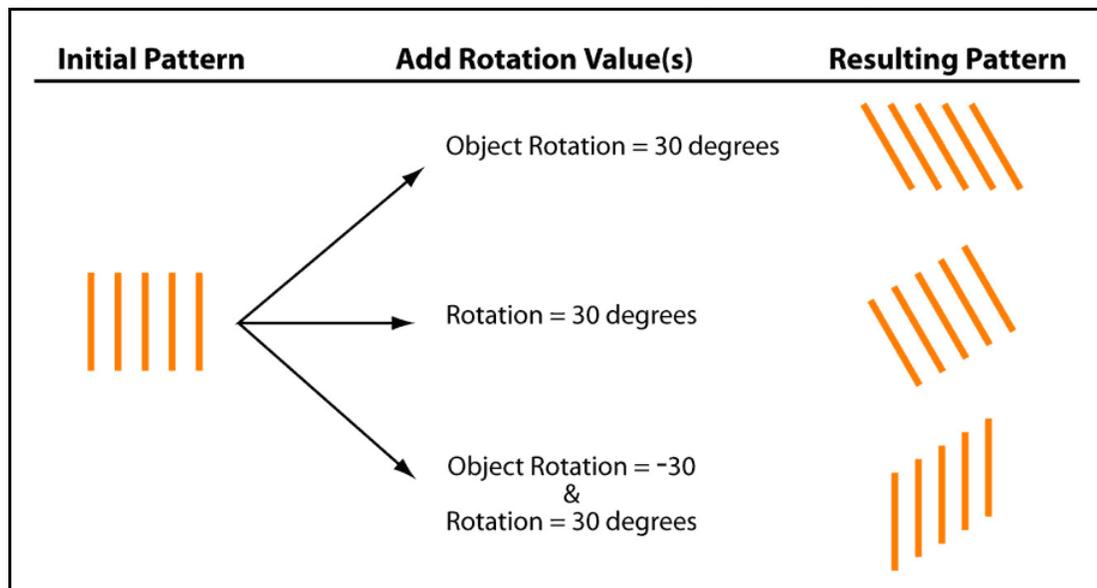
**Figure 17:** Example of using Object Rotation to rotate a single object (line)



### Array Rotation

To illustrate how the different rotation parameters (Rotation and Object Rotation) influence an array, a sample array of five vertical lines is shown in Figure 18, before and after each rotation parameter is applied. Note how applying *both* rotation parameters (Rotation and Object Rotation) to the array affects the resulting pattern. Refer to [Rotation Guidelines](#) (pg 3.97).

**Figure 18:** Different Rotation Parameters Can Produce Dramatically Different Array Patterns



The following values were used to produce the **initial pattern** in Figure 18.

OpType	XCoord	YCoord	SizeX	SizeY	XCount	YCount	XSpace
LINE	0	0	0.0	1.0	5	1	1.0

## Theta Rotation

*Not currently functional.* Theta rotation acts on the valve/tool head, rotating the head around the component. Theta rotation is used in conjunction with an upward-looking camera for pick-and-place applications or for applications utilizing a pre-formed needle where the end is angled to dispense on the side of a component.

## Arrays & Alignment Points

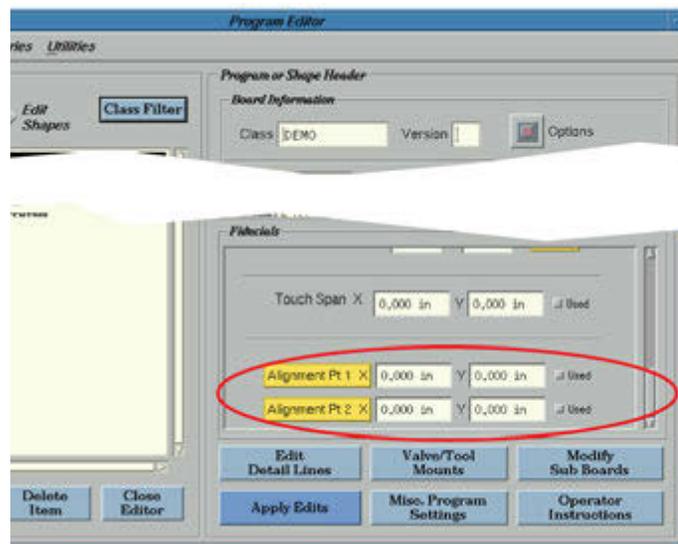
Alignment points are used to remedy situations in which arrays do not stay properly aligned (otherwise, using alignment points is unnecessary). When programming with arrays, consider using alignment points when any of the following scenarios exist:

- horizontal (0 degrees) is not parallel to the board edge,
- a constant board feature indicating 0 degrees is unavailable,
- inconsistent board positioning is common, or
- no fiducials or manually taught fiducials are present.

### Using Alignment Points

Alignment points are used to remedy situations in which arrays do not stay properly aligned; otherwise, using alignment points is unnecessary. Alignment points define horizontal (0 degrees) and vertical (90 degrees) on a board. These angles, which are not established by fiducials alone, become the reference points upon which array rotation is based.

Alignment points apply only to arrays and are typically used when arrays have been programmed along an absolute x or y path but actually dispense at an unexpected angle. Teaching an alignment point at either end of a array pattern establishes a straight path along which the arrays will align. Accuracy increases with an increased distance between the two alignment points.



Alignment Points - use the slider in the Fiducials panel to locate the Alignment Point parameters.

To use alignment points:

1. Locate the Alignment Point fields in the Fiducials pane of the Program Editor.
2. Enter coordinates in Alignment Point 1 for a point on the product.
3. Enter coordinates in Alignment Point 2 for the other end of the horizontal or vertical path.

## Creating Arrays

When creating arrays using particular operations, namely Circle, Dot, Line, and Rectangle, apply the following rules:

1. Assign values to the array parameters.
  2. The array is formed by X Count items in the x-direction spaced X Space apart with Y Count items in the y-direction spaced Y Space apart for a total of (X Count x Y Count) items. Items equate to circles, dots, lines, and rectangles.
  3. The entire array is then rotated about the first reference point Rotation degrees.
- For details about rotating arrays, refer to [Array Rotation](#) (pg 3.98).

## Feature ID

The feature ID function provides an alternative to the default of processing all program lines by enabling you to define and run a select subset of program lines. A feature ID can be assigned to any program line. Any program line without a feature ID (blank) will always run.

### Using Feature ID

One way to use feature ID is to choose to run all program lines except those applicable to pick-and-place. Another way to use this function would be to limit a program run to only the lines applicable to a particular type of component location on a board.

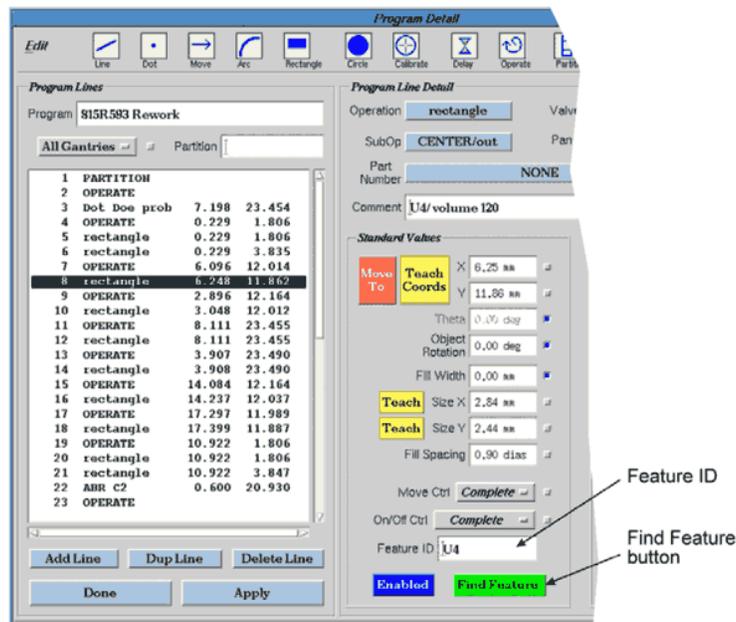
Feature IDs are typically created during program development as names for product features and may be used to represent any feature on a product. Typically they are used to designate component board locations (e.g., C15, R23, etc.).

When you activate the feature ID function for a program run, you will be prompted to select the feature IDs you want recognized during the program run. You may choose any combination of feature IDs ranging from none to all or any combination in between.

A program will run only the set of program lines containing the feature IDs you select and that set is only in effect while the program is running. If the program is stopped and restarted, the system reverts to the default of processing all IDs unless you reselect a subset of feature IDs.

### Assigning a Feature ID

If you want to execute only select program (shape) lines, assign a Feature ID to the program (shape) lines you want to include when the program runs.



To assign a feature ID to a program (or shape) line:

1. Select or create a program (or shape) and open the Program Detail window.
2. Highlight the program line to which you want to assign a feature ID.
3. Type a name in the Feature ID field.
4. Click the APPLY button. This assigns the feature ID name to the selected program line.

## Finding a Feature ID

Previously assigned feature IDs can be easily located within a program. The FIND FEATURE button helps you locate the first occurrence of a Feature ID in a program by highlighting the program line in which the feature ID was found.

To find a specific feature ID within a program:

1. In the Program Detail window, click the FIND FEATURE button. An input request displays.
2. Type the name of the feature ID you want to locate.
3. Click OK. The system finds and highlights the first program line assigned using the specified feature ID.

## Activating Feature ID Function

To activate and select feature IDs for a program run:

1. Select and start a program.
2. When the Mounts Table window displays, be sure to click the Select Feature IDs box before clicking CONTINUE.

Mount Position	Tool/Valve	Material	Needle	Air Pressure	Skip Calibration
1	Micro Valve 20k	Indium T5 SMQ51	27	16 psi	<input type="checkbox"/>
2	NONE	NONE	25	0 psi	<input type="checkbox"/>
3	NONE	NONE	25	0 psi	<input type="checkbox"/>

Lot #  Type  Category

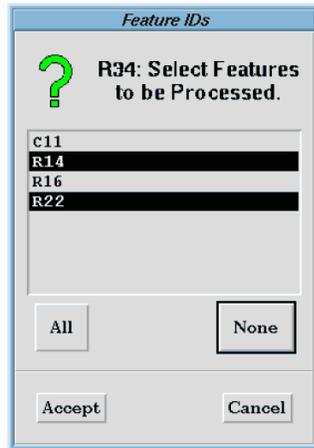
Select Feature ID Variation  Select Feature IDs  Use Tweaks

OPERATOR INSTRUCTIONS

3. The Feature IDs window will display unless the selected program contains no feature IDs. From this window select any combination of the feature IDs listed and then click ACCEPT.

The <Ctrl> button acts as a toggle button, allowing you to quickly change the selection state of a feature ID. For example, you can easily select the majority of feature IDs by first

clicking on the ALL button and then, while holding down the <Ctrl> button, clicking just those feature IDs you wish to deselect.



To select:	Do this:
All names	Click ALL.
No names	Click NONE.
A single name	Click the name you want to select.
A combination of names	Hold down <Ctrl> and click each name you want to select. OR Click ALL and then, while holding down <Ctrl>, click each name you want to deselect.
To accept the displayed selection as it is	Click ACCEPT.

After making any other pertinent entries to the Mounts Table window, click CONTINUE. The program will run only those lines with an enabled and selected feature ID.



**IMPORTANT** Only program (or shape) lines with no feature ID or with selected feature ID will run.

<b>IMPORTANT</b> <a href="#">Seules les lignes</a>	<b>WICHTIG</b> <a href="#">Nur Programmzeilen</a>	<b>IMPORTANTE</b> <a href="#">Si eseguiranno solo</a>	<b>IMPORTANTE</b> <a href="#">Sólo se ejecutarán</a>
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## Process Inspection Tools

The process inspection tools, Bad Marks and Dot Inspection, are integral to a program and perform process quality inspection during every production run process in contrast to the [Testing & Inspecting](#) (pg 3.118) choices that are typically used only during program development.

While [Dot Inspection](#) (pg 3.106) is limited to the inspection of dots, [Inspecting with Bad Marks](#) (pg 3.105) is a more flexible process inspection tool that can inspect a broad spectrum of shapes and primitive operations.

### Inspecting with Bad Marks

When applied to process inspection, bad marks can be set up to verify process conformity and/or material presence (a shape dispense actually occurred). The sole purpose of the bad mark in this scenario is to display a user message as needed informing the operator of the problem.

**NOTE:** When not used for inspection, [Bad Marks](#) (pg 3.39) are typically used in conjunction with fiducials.

After a pattern is dispensed in a program run, a bad mark shape in the program evaluates the pattern. If the process fails (the pattern is missing), the bad mark shape causes a custom user message to display. If the process passes (the pattern is good), the program skips the bad mark shape so no message is generated and continues on with the rest of the program.

Some of the advantages to using bad marks for process inspection are:

- Bad marks can be used to inspect a process at any point in a program.
- Bad marks find a pattern and then evaluate the pattern against an acceptance threshold:
  - If the pattern passes evaluation, the program continues.
  - If the pattern fails evaluation, the system displays a message.
- The text and buttons displayed in the message (that displays if the pattern fails evaluation) are determined by the user.

### Using Bad Marks with Custom User Message

---

Create a user message that will display if a pattern fails process inspection. You can customize the text content and the buttons (Ignore, Retry, Abort, etc.) displayed in the message.

To create a customized user message:

**EXAMPLE:** For the purposes of this procedure, we'll create a user message for a program of dispensed lines that we want inspected to verify that each line is actually dispensed.

1. Train the part of your process that you want inspected as a vision pattern. For example, teach a dispensed line in Pattern Trainer.
2. Create a custom user message:
  - a. From the Program Editor menu bar, click Library > SubTypes.
  - b. In SubType Editor [refer to [SubTypes Library](#) (pg 5.18)], create a subtype using *Message Type* that will display a user message edited to convey to the operator the fact that the process failed (material not present, dispense pattern missing, etc.).
  - c. From the main window menu bar, click System Functions > Edit Any File.

- d. User messages are edited in /appl/etc/config/ds.user.msgs
  - e. In the Subtype, test a pseudoIO to force the message to display.
  - f. Type the text you want to display on the message.
  - g. Select the buttons you want to display on the message using Edit Misc Resource.
3. Create the shape in your program that will inspect the process. For example, in a program of Shape (partition), add a program detail line using the InspectTest created during the prior step.

The shape is what contains both the bad mark pattern and the InspectTest program line. If it passes the bad mark it skips the execution of the InspectTest. If it fails the bad mark, it executes the Inspect test and displays a message.

4. Use the vision pattern created in step 1 in the Bad Mark Pattern, teach the location, and select Process if Absent.
5. In the detail lines of the shape, add the SubType that you created.

## Dot Inspection

Dot Inspection can be used when inspection needs are limited to the inspection of dots created with opaque material. After the initial setup, this inspection method is easier to implement in a program and can be used to inspect individual dots or arrays of dots.

Dot inspection is a process during which the camera compares a dispensed dot to a calibration dot for the purpose of identifying whether or not the dispensed dot falls within chosen parameters. Dot inspection can be set up to inspect any arrangement of dots:

- all dots on all parts,
- all dots on every nth part,
- particular dot(s) on all or every nth part, or
- only those dots which are specifically programmed to be inspected.

The user must configure the software to use one of two calibration dot modes. One mode measures the dispensed dot and then compares it to a user-defined dot size within a user-defined range; the other mode compares the dispensed dot to a set of dots of predefined sizes. While setting up a mode of dot inspection, the user may choose a time interval at which dot inspection occurs: inspect dots every n seconds or inspect dots on all parts. Further refinements to inspection location and timing are made during the creation of dot inspect program lines.

### 1. Work Area Set Up

---

Physically set the height of the work area to match the height of the calibration chip (located on the calibration station). Because the same vision settings for zoom and focal length will be used at both of these locations, a common physical height must exist.

## 2. Software Configuration

Choosing a mode of dot inspection determines which calibration dot will be used during the inspection process. Two modes are available:

- A - Measure dispensed dot and then compare it to a user-defined dot size within a user-defined range.
- B - Compare the dispensed dot to a set of dots of predefined sizes. (These dot sizes are typically defined by, but are not limited to, the preprinted, precision, calibration dot chip available from GPD Global.)

To implement the desired mode of dot inspection, select the mode appropriate for your process from the chart below and then proceed to the indicated page for detailed procedural instructions:

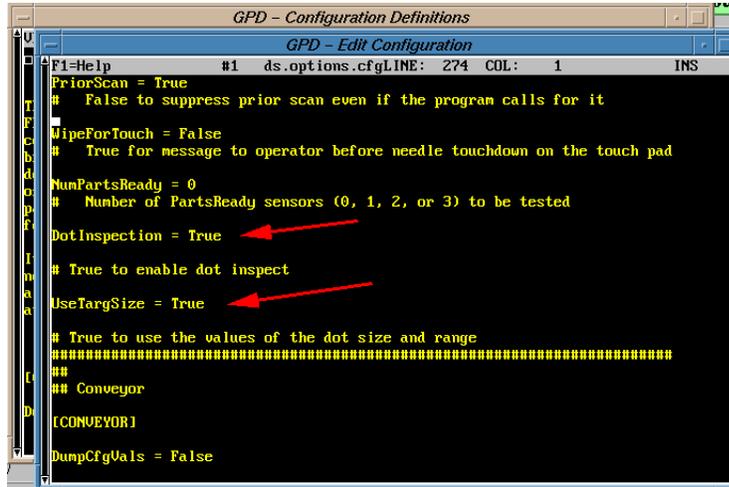
**Table 21: Modes of Dot Inspection**

Mode	Theory of Operation	Advantages	Go to:
- A - Verifies dispensed dot size based on values entered by the user.	Camera measures dispensed dot and then compares it to Target Size and Target Range: 1. System dispenses a dot. 2. Camera calibrates at the calibration chip dot size determined by the zoom value set in the program Vision Calibration panel (Miscellaneous Program Settings window) using the dot size value from the middle Cal Dot Sizes field (Option Settings window). 3. Camera looks at dispensed dot and decides pass/fail based on Target Size and Target Range set in Blobs panel (Program Detail window).	Time saving aspect - only a single calibration operation is performed, even if the program dispenses a range of dot sizes. Any size target may be set.	<a href="#">Mode A: User-Defined Calibration Dot Size</a> (pg 3.108)
- B - Verifies dispensed dot size based on the fixed size range of the calibration chip dots.	Camera uses pre-established calibration chip dots to establish acceptable range of dot sizes: 1. System dispenses a dot. 2. Camera views the three calibration chip dots using particular base locations (Camera to Camera Calibration A1, A2, B1, B2, C1, and C2). 3. Camera calibrates to the values set in Cal Dot Sizes fields (Option Settings window) and establishes the acceptable minimum/maximum size range for dispensed dots. 4. Camera looks at dispensed dot and decides pass/fail based on the acceptable range established during the prior step.	Can be used as a dot presence test (assuming the sizes of the calibration chip dots establish a wide size range when compared to the dispensed dot size).	<a href="#">Mode B: Fixed Calibration Dot Size</a> (pg 3.112)

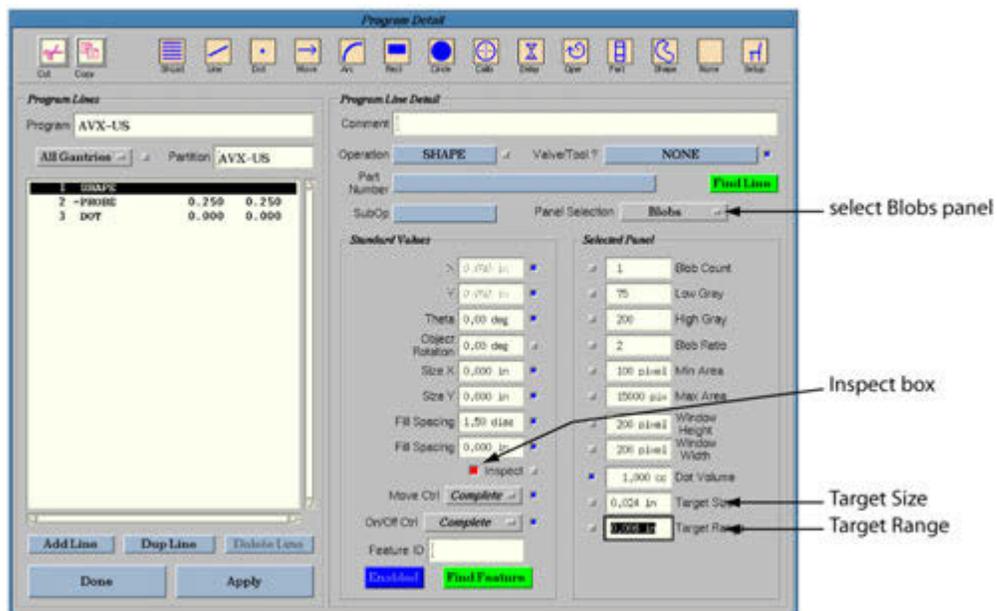
**Mode A: User-Defined Calibration Dot Size**

To select a calibration dot that verifies dispensed dot size based on values entered by the user:

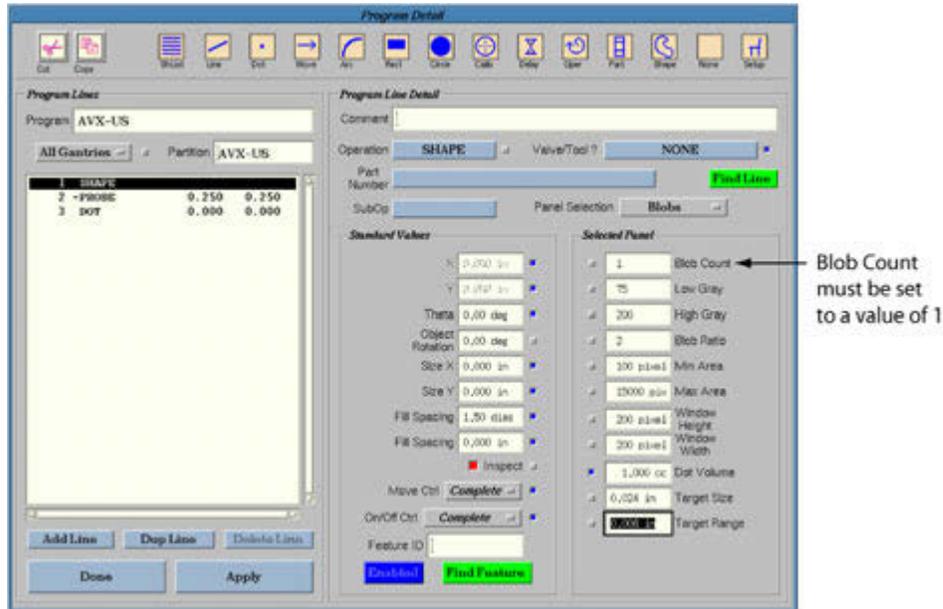
1. Open the Edit Configuration screen [Configuration > [Dispenser Configuration](#) (pg 3.136)] and enter a value of True for both Dot Inspection and UseTargSize.



2. If the values noted in the prior step were already set to True, skip to the next step; otherwise, reboot the system to implement the changed values before continuing.
3. Now that Dot Inspection has been configured to True:
  - a. Open Program Detail.
  - b. Turn on the Inspect box.
  - c. Select the Blobs panel.
  - d. Enter desired dot size and tolerance values in Target Size and Target Range.

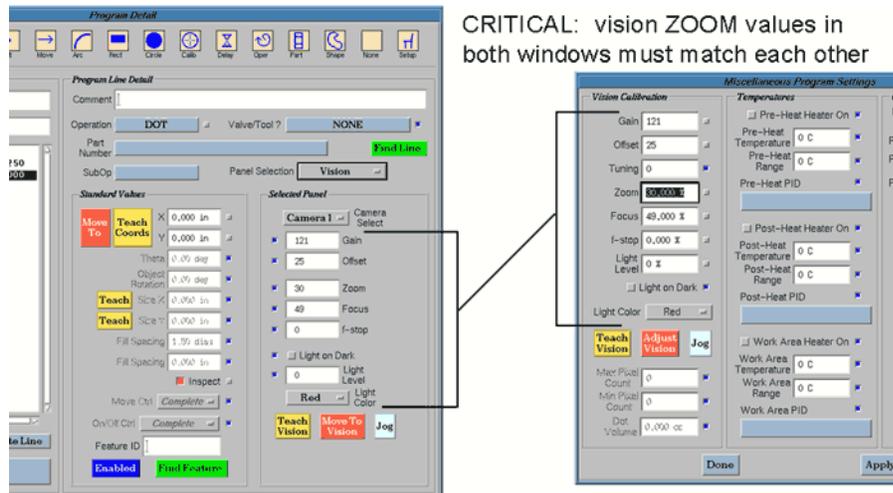


- In the Blobs panel, enter a value of 1 in the Blob Count field. (For purposes of the current procedure, only a 1 will work.) Establishing the correct value for blob parameters is critical to the success of finding dots dispensed by the dot program.

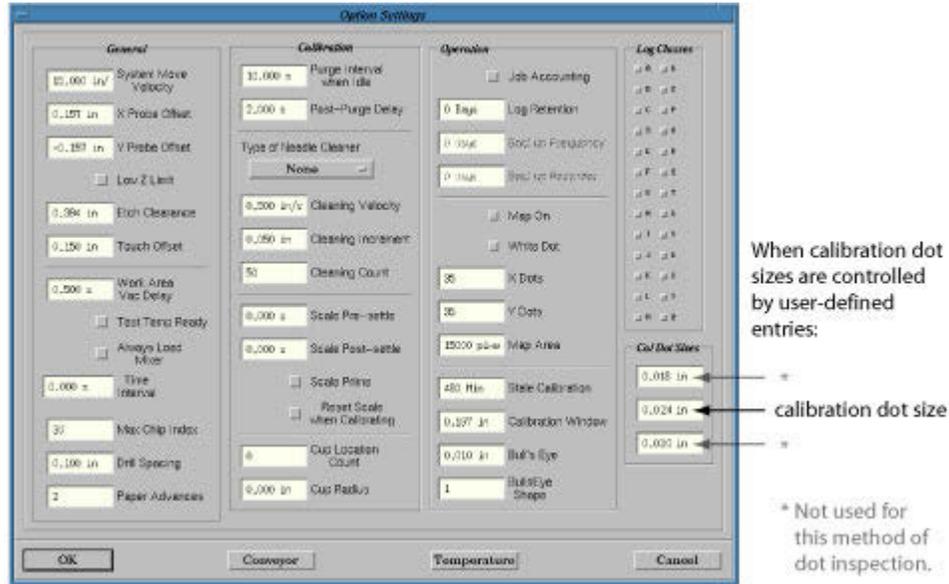


- Be sure identical values exist in the vision fields common to both the Vision panel (in Program Detail) and the Vision Calibration panel (in Miscellaneous Program Settings).

**NOTE:** The same value for Zoom **MUST** be used in both vision panels. The value for Focus will be the same if the work area surface is at the correct height. Gain and Offset values may need to be changed depending on the work surface, material, and lighting.



- In the Option Settings window, set the middle Cal Dot Sizes field to the diameter of calibration dot you want used.



The value used in this step to represent calibration dot size, along with the value entered in Zoom during the prior step, will affect which base locations are used for the calibration dot, thereby affecting the location of the calibration dot - refer to the chart below.

**Table 22: Relating Calibration Dot Size and Base Location**

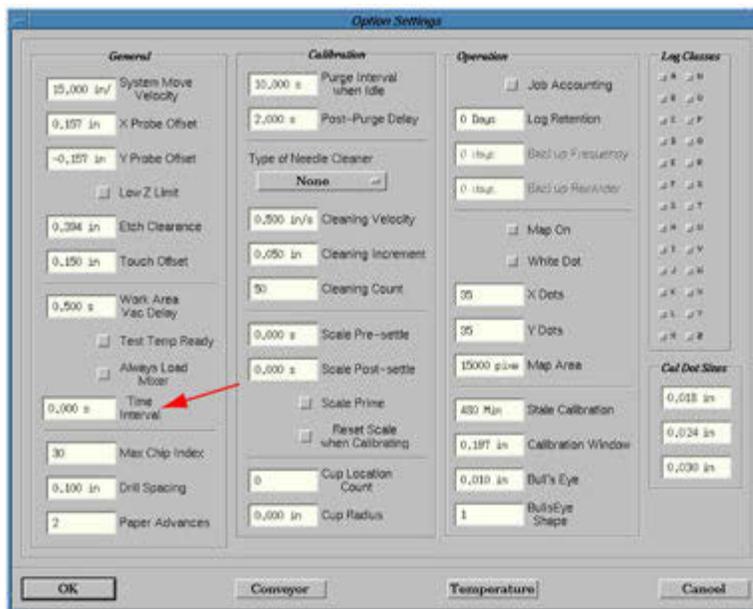
<b>If Zoom value in Vision Calibration is:</b>	<b>then the system will automatically use these Base Locations:</b>	<b>Abbreviation for Base Location Name:</b>
less than 30	Camera to Camera Calibration A1 (XY) Camera to Camera Calibration A2 (XY)	A1 A2
more than 30, but less than 60	Camera to Camera Calibration B1 (XY) Camera to Camera Calibration B2 (XY)	B1 B2
more than 60	Camera to Camera Calibration C1 (XY) Camera to Camera Calibration C2 (XY)	C1 C2

7. Enter a value in Time Interval for the amount of time to elapse between dot inspection sessions. Time Interval tracks process time, disabling dot inspection for the duration entered. For example, if a program can process 10 parts per minute and Time Interval is set to 1 minute, the system will inspect every tenth part.

Use the following chart when determining the value to enter in Time Interval.

**Table 23: Controlling Frequency of Dot Inspection**

To inspect:	enter this value in Time Interval:
dots on all parts	0
dots on every nth part	Multiply the process time per single part by the number of parts for which inspection is to be skipped.

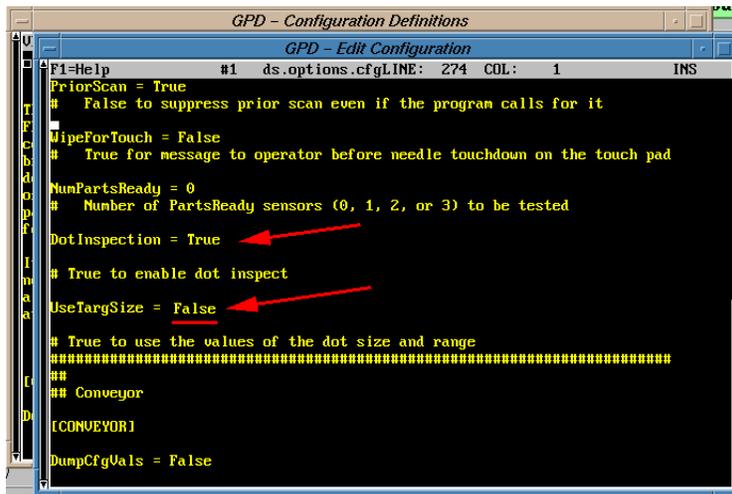


8. Go to [3. Programming for Dot Inspection](#) (pg 3.114).

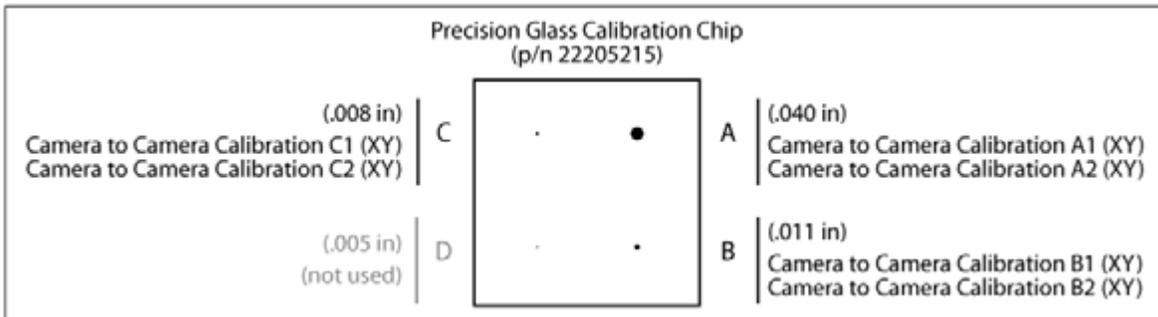
**Mode B: Fixed Calibration Dot Size**

To select a calibration dot that verifies dispensed dot size based on a fixed size range controlled by predefined calibration chip dots:

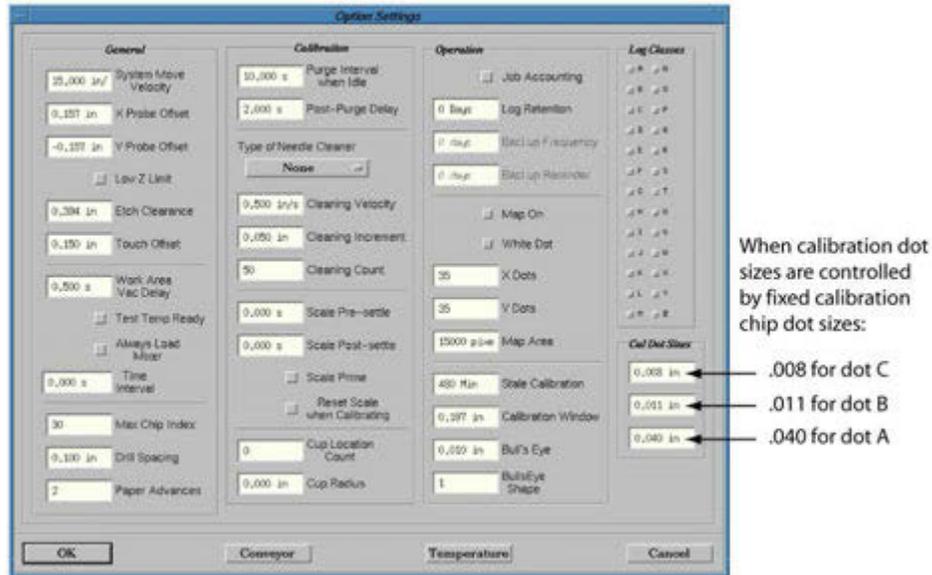
1. Open the Edit Configuration screen [Configuration > [Dispenser Configuration](#) (pg 3.136)] and enter these values:
  - a. Enter a value of True for Dot Inspection.
  - b. Enter a value of False for UseTargSize. An entry of False directs the system to calibrate using the three official calibration chip dot sizes established in base locations.



2. If the values noted in the prior step were already set, skip to the next step; otherwise, reboot the system to implement the changed values before continuing.
3. Verify the location taught for each base location shown below (A1, A2, B1, B2, C1, C2) correlates with the correct dot size (A, B, or C) on the calibration chip as indicated here:

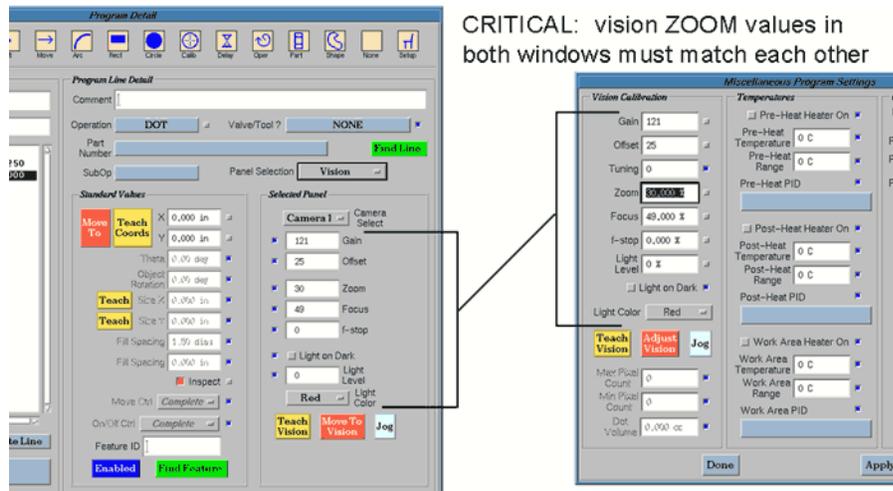


- In the Option Settings window, set the Cal Dot Sizes fields to match the base location values noted in the prior step.



- Be sure identical values exist in the vision fields common to both the Vision panel (Program Detail) and the Vision Calibration panel (Miscellaneous Program Settings).

**NOTE** The same value for Zoom MUST be used in both vision panels. The value for Focus will be the same if the work area surface is at the correct height. Gain and Offset values may need to be changed depending on the work surface, material, and lighting.



- Go to [3. Programming for Dot Inspection](#) (pg 3.114).

### 3. Programming for Dot Inspection

---

Dot inspection program lines must now be created or modified to incorporate dot inspection into a program. At the same time, further refinement can be made as to which dots will be inspected.

#### Add Dot Inspection to Program

- 1 - Select the program to be modified and open Program Detail.
- 2 - Choose one:
  - To inspect one or more new or existing dots of your choosing, go to [Inspect as Programmed](#) (pg 3.114).
  - To inspect each new dot after it is dispensed, go to [Inspect After Every Dot](#) (pg 3.116).

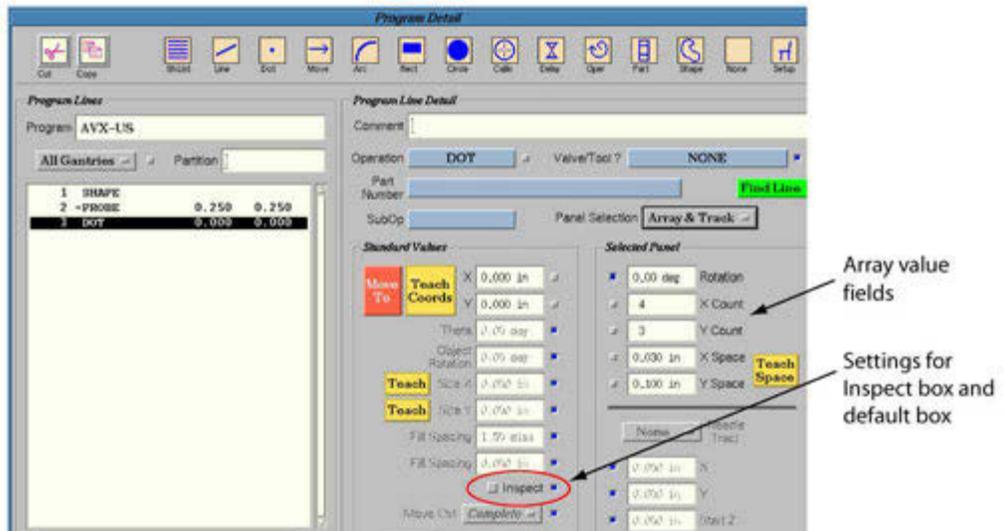
#### Inspect as Programmed

Consider the following guidelines when programming one or more new or existing dots to be inspected with a Dot Inspect operate:

- Typically, a DOT program line does not have to precede a Dot Inspect program line.
- The coordinates of a Dot Inspect program line determine both where the first dot in an array is dispensed and where dot inspection occurs.
- Any value greater than 0 in Time Interval (in Option Settings) will be overridden by a Dot Inspect program line when the Inspect box is turned on. If, however, the Inspect box is turned off, the Time Interval value becomes active.

- 1 - Prepare a DOT program line:
  - 1A - Create or select a DOT program line for which you want a dot inspected.
  - 1B - Verify the Inspect box is turned OFF (gray).
  - 1C - Verify the default button next to the Inspect box is turned ON (blue).

1C - Verify array values are entered in the X Count and Y Count fields of the Array & Track panel.

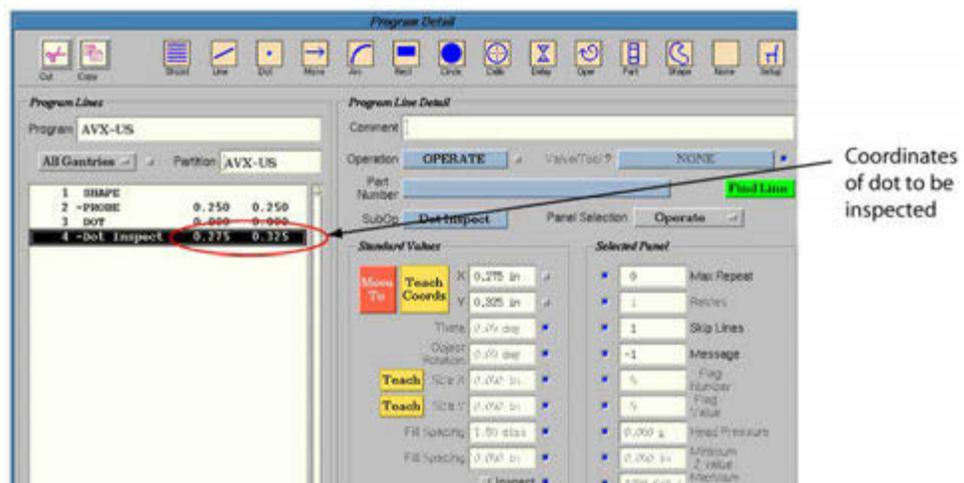


2 - Create a Dot Inspect program line:

2A - With the DOT program line from the previous step still selected, create a DOT program line by either clicking the Operation icon or clicking the Operation button and selecting OPERATE.

2B - With the new Dot Inspect program line selected, click the SubOp button and select DOTINSPECT. This subop will cause inspection for dot size and/or dot presence to happen unconditionally regardless of dispenser configuration condition.

2C - Teach coordinates for the Dot Inspect program line - dot inspection will occur at these coordinates.

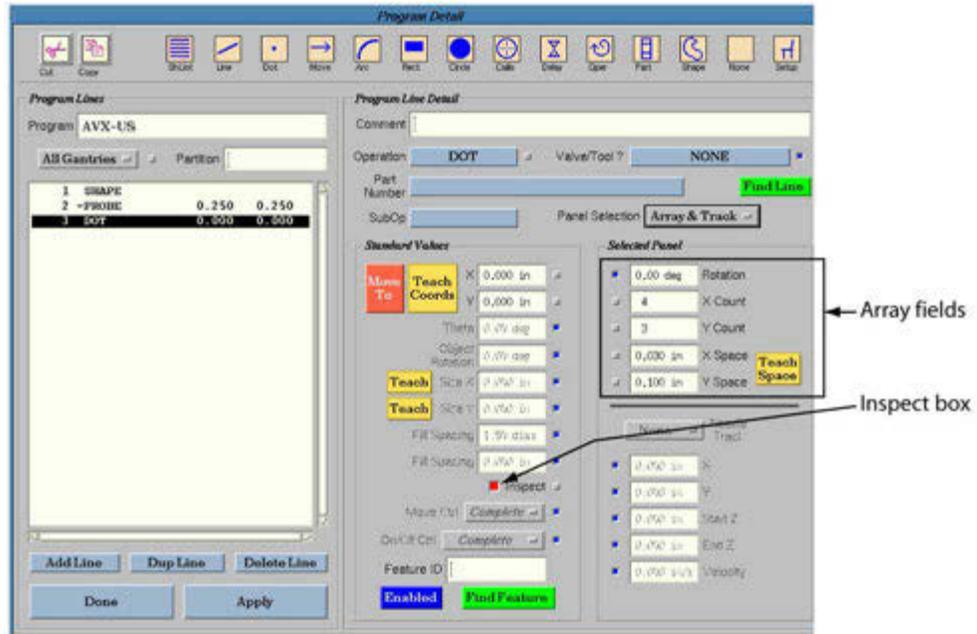


3 - Save and test the modified program. Any dot that does not meet the designated criteria will generate an error message indicating that dot size is out of range.

## Inspect After Every Dot

Inspection occurs after each new dot is dispensed as long as Inspect (on Program Detail) is turned on in a program line.

- 1 - Create or select a DOT program line.
- 2 - If desired, enter values in the array fields of the Array & Track panel.



3 - Turn on the Inspect box (it should be red). If array values were entered in the previous step, all dots in the array will now be set to be inspected.

4 - Repeat the above steps for each additional dot or dot array to be dispensed and inspected. All dot program lines with the Inspect button turned on will enable inspection as long as the value of Dot Inspection was set to True in the [Dispenser Configuration](#) (pg 3.136) file during Dot Inspection Set Up.

**OPTION:** Dot inspection can be set globally by turning on the Inspect button in the Partition line.

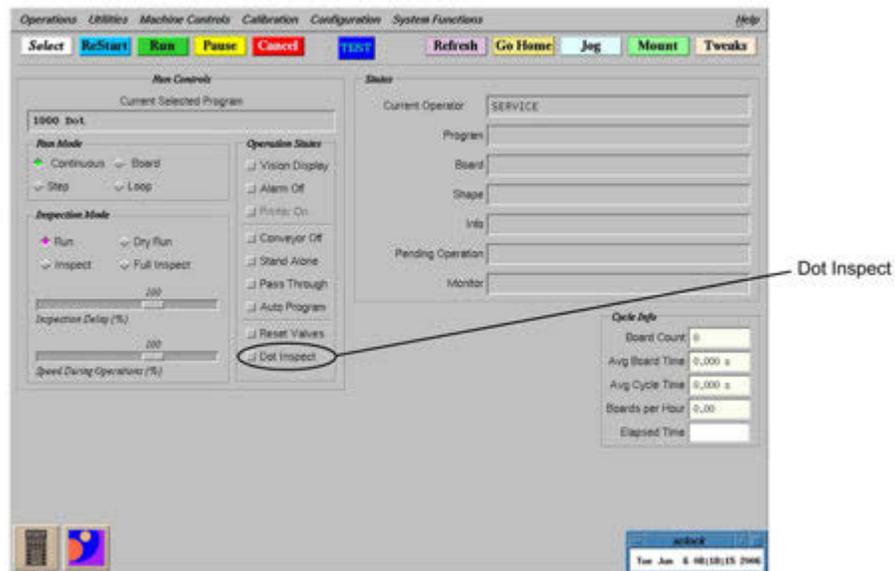
5 - Save and test the modified program. Any dot that does not meet the designated criteria will generate an error message indicating that dot size is out of range.

## Additional Notes

**NOTE:** The following items are currently inactive.

### Dot Inspect box on Main Window

Not currently functional. The Dot Inspect box located in the Operation States pane of the main window is currently not functional; it has no effect on anything in either the on or off state.



### OPERATE subops

**Dot Size** - Not currently functional. Computes dot size but does not currently display results.

**Dot Test** - Not currently functional. Compares dot with limits and if dot is found to be outside limits, an error message will display. If UseTargSize [[Dispenser Configuration](#) (pg 3.136) file] is set to TRUE, dot limits are based on the values in the Cal Dot Sizes fields (Options Settings). If UseTargSize is set to FALSE, dot limits are based on Target Size and Target Range (Program Detail - Blobs).

## Testing & Inspecting

The following test and inspection choices are typically used only during the process of program development, in contrast to [Process Inspection Tools](#) (pg 3.105) which are integral to a program and perform process quality inspection every time the program runs.

Program development testing and inspection can be handled in a variety of ways depending on your needs:

Testing Choices	Instructions
Test an entire program without dispensing material	<a href="#">Dry Run Test</a> (pg 3.118)
Visually inspect an entire program with the camera	<a href="#">Full Inspection</a> (pg 3.118)
Visually inspect only the general coordinates of a program with the camera, i.e., only the starting point of each shape or primitive in a program	<a href="#">General Inspection</a> (pg 3.119)
Test or run programs on a conveyORIZED dispenser as if it was a stand-alone machine, with or without the conveyor being operational	<a href="#">Emulate Stand-Alone Dispenser</a> (pg 3.119)

### Dry Run Test

During a program dry run, the needle performs the exact process it normally would during a program run except no material is dispensed.

To test a program using a dry run:

1. Select the program you want to test.
2. Click the Dry Run button located in the [Inspection Mode](#) (pg 3.27) panel of the main window.
3. Select one of the [Run Mode](#) (pg 3.26) options.
4. Click RUN in the main button bar. A dry run of the selected program executes.

### Full Inspection

During a full visual inspection of a program, the entire program is executed with the camera emulating the needle. (Obviously, no material is dispensed.)

To visually inspect an entire program:

1. Select the program you want to inspect.
2. Click the **Full Inspect** button located in the [Inspection Mode](#) (pg 3.27) panel of the main window.
3. Use the [Inspection Sliders](#) (pg 3.27) as needed.
4. Select one of the [Run Mode](#) (pg 3.26) options.
5. Click RUN in the main button bar. A full visual inspection of the selected program executes.

## General Inspection

During a general visual inspection of a program, an abbreviated version of the program is executed with the camera emulating the needle. The camera proceeds only to the starting point of each shape and/or primitive operation before skipping on to the next one in sequence.

To visually inspect only the general layout of a program:

1. Select the program you want to inspect.
2. Click the **Inspect** button located in the [Inspection Mode](#) (pg 3.27) panel of the main window.
3. Use the [Inspection Sliders](#) (pg 3.27) as needed.
4. Select one of the [Run Mode](#) (pg 3.26) options.
5. Click RUN in the main button bar. A general visual inspection of the selected program executes.

## Emulate Stand-Alone Dispenser

A dispenser with a conveyor can be made to emulate a stand-alone (manual) dispenser with or without the conveyor depending on which Operation States are selected.

### **Stand-Alone Dispenser - with Conveyor**

---

A conveyor unit can be made to emulate a stand-alone conveyor dispenser by bypassing the SMEMA controls:

1. Install SMEMA plugs in the SMEMA connector ports.
2. Click the [Stand Alone](#) (pg 3.28) operation state toggle box so it is turned ON. The conveyor will function normally except it will not communicate with upstream or downstream units.
3. Manually load product in the conveyor entry area and unload it from the conveyor exit area.
4. To return to normal conveyor operations, remove the SMEMA plugs and click the Stand Alone toggle box to turn it OFF.

### **Stand-Alone Dispenser - as if No Conveyor**

---

Turn the conveyor belt off to make a conveyor unit emulate a stand-alone (manual) dispenser with no conveyor:

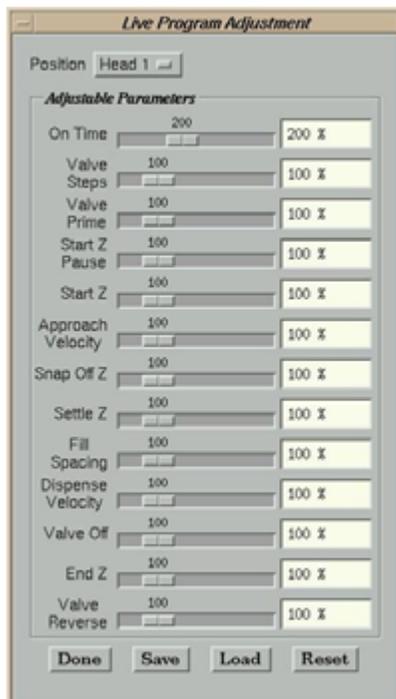
1. Click both the [Conveyor Off](#) (pg 3.28) and [Stand Alone](#) (pg 3.28) operation state toggle boxes so they are turned ON. The conveyor will cease to function.
2. Manually load and unload product from the dispenser area.
3. To return to normal conveyor operations, click the Conveyor Off and Stand Alone operation state toggle boxes again so they are turned OFF.

## Tweaks for Valves/Tools

Tweaks is an on-the-fly program development tool for discovering program adjustment values for a designated valve mount position. Tweaks (fine tuning adjustments) are implemented as soon as any tweak parameter is changed, providing you with immediate feedback.



**IMPORTANT:** Changes are only **temporary percentage changes** based on the original program and are only in effect while the program is actively running. Tweaks are multipliers, not actual values; they temporarily alter a parameter by a percentage. When desired adjustments are achieved, you must then calculate the new value by multiplying the original value by the tweak percentage and then manually entering the results in the corresponding field of the appropriate program detail line.



Clicking TWEAKS on the main menu button bar displays [Live Program Adjustment](#) (pg 5.46) which functions as the tweaks panel for making temporary adjustments to valve program parameters.

**NOTE:** Not all values listed in Live Program Adjustment apply to all valves.

## Tweak Controls

### RESET

All parameters in Live Program Adjustment can be reset to the default (100%) at any time using the RESET button.

### LOAD

The LOAD button loads previously saved tweak parameters to Live Program Adjustment.

### SAVE

The SAVE button saves tweak parameter values **ONLY** to Live Program Adjustment. Only one set of tweak values can be saved as each new save overwrites the previously saved values.

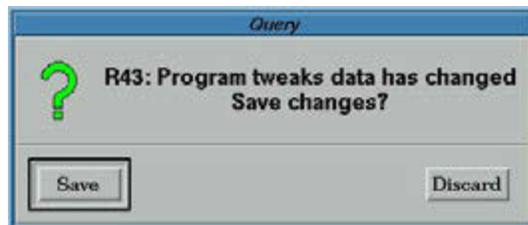


**IMPORTANT:** Tweak parameter values are **NOT** saved to the program being tweaked.

Tweaks does not permanently change parameters - it only implements value changes temporarily while the program is running and while Live Program Adjustment is open.

### Save after Program Cancel

If the running program is canceled at any time while Live Program Adjustment is open, a prompt displays giving you the option to save the current tweak parameters.



### Use Tweaks

The values displayed when the tweaks panel opens depends on whether or not *Use Tweaks* in Mounts Table is set to use tweak values in place of the program values:

- If Use Tweaks is ON, previously saved parameters will display in the tweaks panel.
- If Use Tweaks is OFF, the default parameter of 100% will display in all fields.

## Using Tweaks

Following are the two methods for applying tweaks.

### On-the-Fly Tweaks

---

To repeatedly adjust tweak parameters while observing how the program is affected:

1. From the main window button bar, click **TWEAKS** to open the tweaks panel, Live Program Adjust.
2. If previously used tweak values have been saved, they can be loaded now by clicking **LOAD**.
3. Run the program to be adjusted:
  - a. Select the program to be adjusted.
  - b. From the main window button bar, click **RUN**. Mounts Table displays.
  - c. Click **CONTINUE** to accept Mounts Table as is.
4. While the program runs:
  - a. In Live Program Adjust, select the applicable head from the Position option menu.
  - b. Adjust desired tweak parameters and observe how the program is affected. Continue making adjustments until desired results are observed.
5. When you are happy with the adjusted process and done using the tweaks feature:
  - a. Make a note of the tweak percentage for each field.
  - b. Click either **SAVE** to save the displayed multipliers or **DONE** to exit Live Program Adjust without saving them.
6. Implement the tweak adjustments in the program:
  - a. Navigate to Program Detail and the program detail line where the adjustments need to be implemented.
  - b. Based on the existing field values in Program Detail and the final tweak percentages, calculate the new values. You can use the on-screen [Calculator](#) (pg 3.29) to do the computing.

For example, if the program currently displays an original On Time of 0.010 and the final On Time in Live Program Adjust displayed 200%, then the program On Time value should be changed to 0.020.

- c. Manually enter the new values.

### Applying Saved Tweaks

---

To run a program with previously saved tweak values applied to it:

1. Select a program.
2. From the main window button bar, click **RUN**. Mounts Table displays.

3. In Mounts Table, activate Use Tweaks and then click CONTINUE.

**Mounts Table**

**R35: Prepare and Mount Items Specified.**

Mount Position	Tool/Valve	Material	Needle	Air Pressure	Skip Calibration	All	StandOff	Scale
1	125RPM Auger Valve	ESP 200-A	25	10 psi	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>
2	125RPM Auger Valve	Heraeus PD980002SP	25	10 psi	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>
3	NONE	NONE	25	0 psi	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>

Lot #  Type  Category

Select Feature ID Variation  Select Feature IDs  Use Tweaks

**OPERATOR INSTRUCTIONS**

4. Answer the various prompts that display; be sure to answer OK to the Click OK to continue? prompt.

The program runs with tweaks applied.

## Conveyor Auto-Width

### **IN EFFECT AS OF FLOWare software version 2.9**

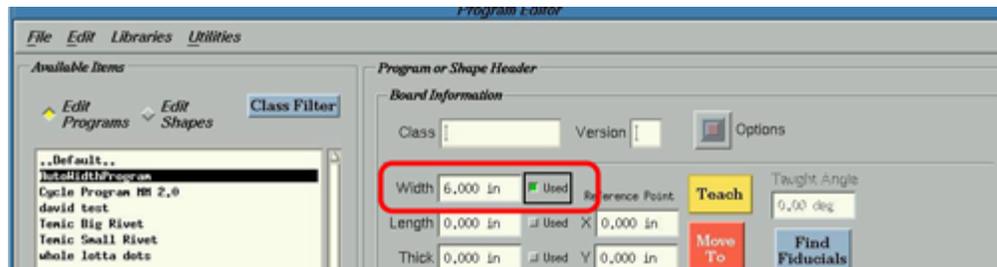
Dispensers configured at the factory with the automatic-width conveyor, will automatically adjust conveyor rail width to accommodate the current program. After the user enters a value in a program for board width and initiates a run for that program, a prompt to clear hardware from the lifter plate displays. As soon as the user responds to the prompt, the conveyor quickly opens or closes to the specified width.

The conveyor remains at the current width until either the width value is changed in the current program and the program is run again, or a different program with a different value is run.

### Programming for Auto-Width

For dispensers configured for the auto-width conveyor function:

1. Calibrate the conveyor if needed. The dispenser conveyor was calibrated at the factory, however, if you feel it should be re-calibrated, refer to [Conveyor Width Calibration](#) (pg 3.127).
2. Program the width of the conveyor:
  - a. Select the program for which you want to set a conveyor width.
  - b. Enter the desired width value in the Width field. Value must be greater than 1.00 inch (25.4 mm) or else manual width adjustment is assumed.



- c. Turn on the corresponding Used box (green indicates on).
3. Save the program.
4. Start a program run.
5. A prompt to `Clear Standoffs from Lifter Plate` will display. Remove any hardware from the work area that would otherwise be in the path of conveyor rail movement during the next step.



**CAUTION:** Prior to running a program on a dispenser configured with the automatic-width conveyor adjustment feature, **always verify that all boards, fixtures, and other hardware within the work area envelope** have been removed or repositioned to prevent damage to and by the conveyor rails. Potentially, every program can be set to a different conveyor width. The conveyor width setting for the program you want to run may not be set in accordance with current hardware positions.

6. Press CONTINUE. The conveyor rails will immediately adjust to the width set in the current program.

## Calibration

Calibration is important for keeping systems within specifications. Several dispenser features may need occasional attention:

- [Calibration Menu](#) (pg 3.125)
- [Conveyor Calibration](#) (pg 3.127)
- [Vision Calibration](#) (pg 3.129)
- [Scale Set Up within Software](#) (pg 3.130)

For shape calibration, refer to [Weight Calibrated Shapes](#) (pg 4.92).

## Calibration Menu

A drop-down menu of calibration choices is available by clicking on Calibration in the menu bar of the main window.

A brief explanation of each configuration choice follows:

### Calibrate Conveyor Speed

The conveyor must be calibrated any time a conveyor speed control is changed. Refer to [Conveyor Speed Calibration](#) (pg 3.127).

### Calibrate Conveyor Width

A conveyor equipped with automatic width adjust requires calibration to achieve proper processing results. Refer to [Conveyor Width Calibration](#) (pg 3.127).

### Map X-Y Surface

Mapping the dispenser work area for precise movement reduces the errors in positioning/placement caused by mechanical imperfections. For precision of less than 0.003" (0.076 mm), mapping is required. For high accuracy applications, mapping should be performed at least every six months (more often depending on usage) and every time the dispenser is moved.

Mapping is currently performed offline. **Do not use the Calibration > Map XY Surface sequence** from the main menu bar. Instead, follow the detailed instructions on how to map the system offline provided in the *Precision Contour Mapping Calibration* procedure (request the most current version of document part number 221MAPDOC).

### Plot X-Y Surface

DSPlot provides a two dimensional graphical representation of the mapping data. A visual representation of the Delta X and Delta Y offsets, normalized values, differences, and gantry coordinates of the mapping data are possible.

Plotting of the X-Y dispenser work area surface is currently performed offline. **Do not use the Calibration > Plot XY Surface sequence** from the main menu bar. Instead, refer to the DSPlot instructions in the *Precision Contour Mapping Calibration* procedure (request the most current version of document part number 221MAPDOC).

### Live Video Parameters

Used to align Cognex cross-hair generator with video capture. There is no reason for the typical user to use this feature.

### Test Serial ports

This function is for software development purposes only.

**Calibrate VCI Tilt  
Adjust VCI Z*****Tilt Adjust Fixture Controls***

Several styles of mechanical tilt adjust fixtures are available from GPD Global. Established operation sequences are used to calibrate and adjust a fixture tilt position. Use only the established setup sequence described in the document(s) listed below that are specific to the control fixture functions for your system. Using any other means can lead to damaged equipment and will void your warranty.

- *Vacuum Tilt Fixture Calibration* (Part No. 22150613CALIB) details calibration process instructions.
- *Vacuum Tilt Station* (Part No. 22150613) includes instructions for setup, position adjustment, and maintenance.
- *Dual Rotation Fixture Operations & Adjustments* (Part No. 22150250M) includes instructions for setup, adjustments, installation, and maintenance.

## Conveyor Calibration

To achieve the best operating results, systems equipped with a conveyor must be calibrated any time a conveyor speed control is changed. Systems equipped with the slow transit speed option and/or the automatic width adjust option require additional calibration procedures be performed.

### Conveyor Speed Calibration

In order to ensure the conveyor operates at the correct rate of speed, both single and three stop-pin conveyors must be calibrated any time a conveyor speed control is changed. Failure to calibrate changes to conveyor speeds is likely to result in time-out messages and improper stop-pin firing times.

Conveyor speed calibration uses the main menu bar Calibration > Calibrate Conveyor Speeds sequence. For complete, detailed instructions on how to calibrate both board transit speed and the optional slow transit speed, refer to *CALIBRATE Conveyor Speeds* in the *Dispenser Service Guide*.

### Conveyor Width Calibration

Calibrating the conveyor establishes the width between the conveyor rails for successful results when [Programming for Auto-Width](#) (pg 3.124). A conveyor equipped with automatic width adjust requires calibration to achieve proper processing results.

Typically, auto-width conveyor calibration is a one-time process performed at the factory. If, however, you want to re-calibrate the conveyor width, use the following procedure appropriate for your system.

#### Auto-width Conveyor Calibration

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Select the procedure appropriate for your system based on the version of operating software installed on your system.

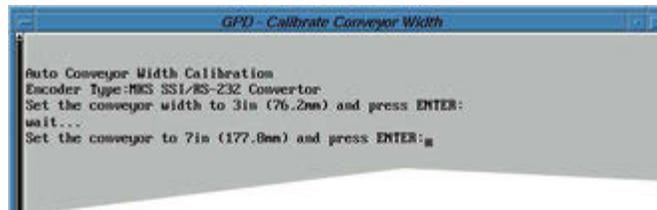
##### **IN EFFECT AS OF FLOWare software version 2.9**

Conveyor calibration is performed using a calibration tool (part number 22121463) and the following procedure.

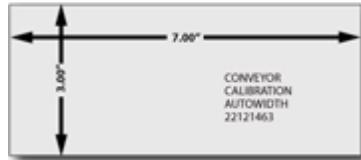
**NOTE:** The following calibration procedure supersedes earlier calibration procedures.

To calibrate an auto-width conveyor:

1. Verify that all boards are removed from the conveyor system.
2. From the main window menu bar, click on Calibration > Calibrate Conveyor Width. Calibration Conveyor Width displays.



3. Place the calibration plate in the conveyor at the nest position so it is seated against the nest stop pin. The conveyor should be snug against the calibration tool at a 3" (7.6 cm) opening.

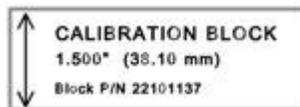


4. Press ENTER.
5. Place the calibration tool in the conveyor at the nest position so it is seated against the nest stop pin. The conveyor should be snug against the calibration tool at a 7" (17.8 cm) opening.
6. Press ENTER.
7. Remove the calibration plate. Calibration is complete.

#### **IN EFFECT PRIOR TO FLOWare software version 2.9**

To calibrate for auto conveyor width adjust:

1. Verify that all boards are removed from the conveyor system.
2. Position the Calibration Block on the conveyor by adjusting the conveyor rails to the approximate width of 1.50" (38.10 mm) using either the Conveyor Open/Close button (for MAX Series dispenser systems) or the Conveyor manual hand crank (for DS Series dispenser systems).



**NOTE:** For conveyor control locations, refer to *ADJUST Conveyor Width* in the *Periodic Operations* section of the *Dispenser Service Guide*.

3. Slide the Calibration Block into the conveyor nest position and seat it against the nest stop pin.
4. Adjust conveyor width so the Calibration Block is almost snug between the rails but will slide freely on the conveyor belts.
5. Calibration the conveyor:
  - a. From the main menu bar, click Calibration > Calibrate Conveyor Width.
  - b. Follow the directions that display:

Auto Conveyor Width Calibration

Set the conveyor width to 28.1 mm (1.5 inches) and press ENTER.

Conveyor width calibration occurs.

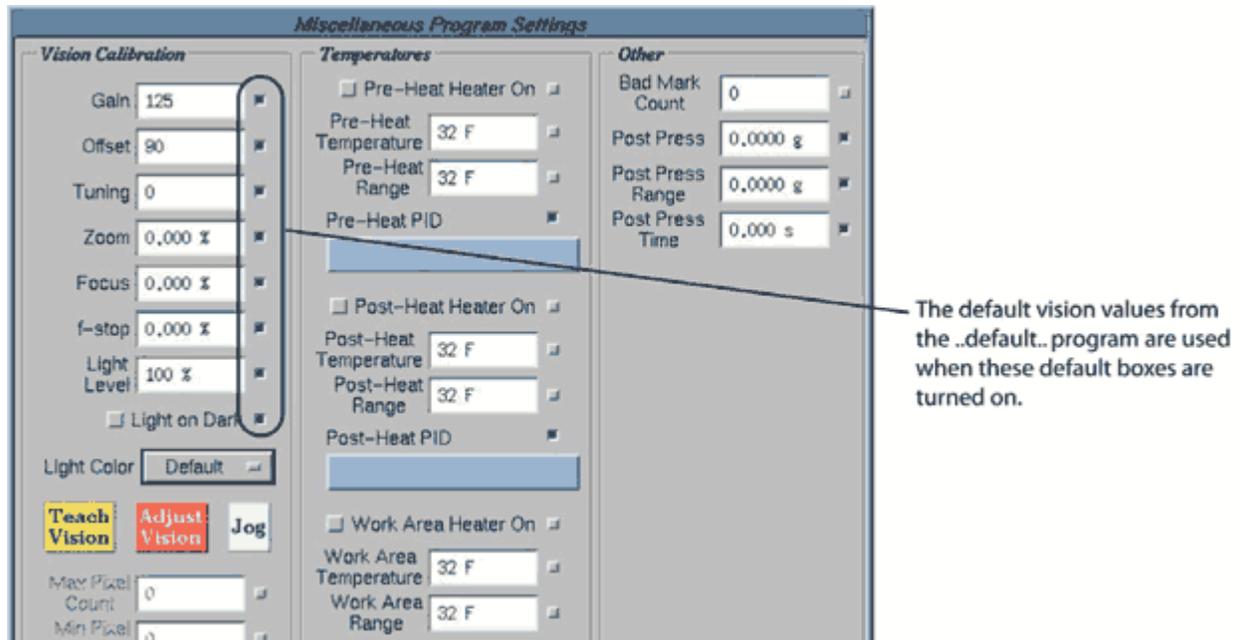
Calibration Complete - remove setup tool and then press ENTER.

Remove the Calibration Block from the conveyor. Calibration is complete.

## Vision Calibration

To verify that the vision system is properly calibrated:

1. In the Program Editor, click on the MISC PROGRAM SETTINGS button to open the Miscellaneous Program Settings window.
2. All default boxes in the Vision Calibration pane should be turned on (they should appear blue). If any of these boxes appear gray, click them to turn them on. Turning on the default boxes forces the program to use the default vision values established in the ..Default.. program.



3. Click on APPLY and then DONE.
4. Run your new program in Inspect mode to verify that the vision system is calibrated correctly — it should be able to locate the calibration dot on the calibration station. (If the camera cannot find the calibration dot, go to the ..Default.. program and examine the values in the vision calibration pane of the Miscellaneous Program Settings window.)

Your new program should now be ready to use in Run mode.

## Scale Set Up within Software

The first step in scale setup is to determine the flow rate of your valve material by using weight volume data. The next step is to apply the results as either material default values or as material values used by a single program.

After the initial power-up, depending on the model, the scale requires a minimum of 30 to 60 minutes to reach its required operating temperature. For further operating specifics, refer to *SETUP Scale* in the *Periodic Operations* section of the *Dispenser Service Guide*.

The following applies to all scale models.

- [Scale Software Operation Theory](#) (pg 3.130)
- [Determine Valve Flow Rate Using Weight Volume](#) (pg 3.130)
- [Scale Set Up Within Program](#) (pg 3.133)
- [Sustain Scale Adjustment Across Multiple Programs](#) (pg 3.134)

### Scale Software Operation Theory

Scale values can be set up as defaults for any program using a particular material by entering them in Mounts/Material Editor for the Material Library (Program Editor > Libraries > Materials). Another option is to apply scale values to a single program by entering them in Mounts/Material Editor for that program (Program Editor > Valve/Tool Mounts).

When the time value entered in Weight On Time expires, the system looks for Target Weight for On Time. If the actual weight is within Tolerance for Weight, the program runs. If the actual weight is outside Tolerance for Weight, the system displays the percentage of error in the Monitor field on the main window.

The system automatically increases/decreases Weight On Time by the percentage of error and then performs a weighing operation at the scale. The system repeats this cycle either until it reaches a value within Tolerance for Weight or until it exceeds Maximum Scale Retry.

The resulting percentage of change that the system used to increase/decrease Weight On Time is automatically used to compensate for actual material flow during program execution.

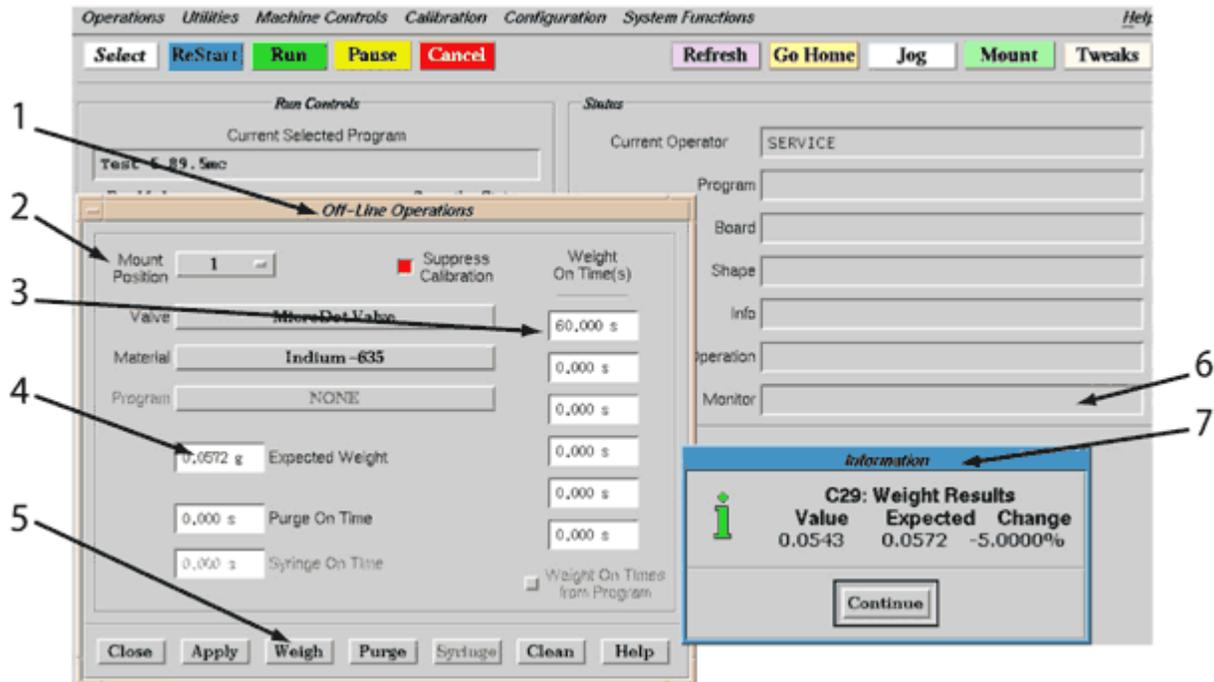
### Determine Valve Flow Rate Using Weight Volume

Use this procedure to determine the material weight volume values you will need later for scale setup within a program. Once you determine a weight volume value, you may alter the percentage error, but the most important aspect of the following procedure is to obtain consistent results. If you use a weight volume value from inconsistent results, you risk slowing down program runs due to scale retries for out of tolerance weight volumes.

To determine valve flow rate using weight volume:

1. Prepare a valve for dispensing with a clean needle and fresh material at room temperature.

- From the main menu bar, click Machine Controls > Offline Operations. The Offline Operations window (Item 1 in graphic below) displays.



- Select the Mount Position (Item 2) to be used during this procedure.
- Enter preliminary value in the top Weight On Time field (Item 3).
- Enter preliminary value, if desired, in the Expected Weight field (Item 4).
- Click on the WEIGH button (Item 5). The system will move to the scale and dispense for the length of time set in the Weight On Time field.
- After the dispense completes, verify that the needle snapped away cleanly leaving no material tail trailing from the needle tip. If needed, make adjustments to encourage the material to break away cleanly, i.e., to eliminate material trailing from the needle tip:

**Hardware** – to make adjustments so the material tail adheres to the side of the purge cup as the needle moves away, either adjust the position of the purge cup so the needle is positioned along the cup edge or adjust the dispense height at the cup. The dispense height at the purge cup is set up in Base Locations. A full discussion of *Base Locations* is located in the appendices of the *Dispenser Service Guide*.

**Software** – to adjust dispensing values such as Snap-off Velocity, Pre-Snap Delay, Post Snap Delay, or Auger Reverse, keep in mind that valve speed and syringe air pressure can drastically affect dispense accuracy.

- If you entered a value in the Expected Weight field, the scale weight value displays in an Information window (Item 6) with an error percentage. Note the values displayed. (During an actual program run, these values will display in the Monitor field (Item 7) of the main window instead of in the information window.) As needed, increase the Weight On Time

value to achieve enough volume for accurate results. A 3-position scale should be 15 mg or greater; a 4-position scale should be 10 mg or greater.

**Table 24:** EXAMPLE - Changing the Percentage of Error

Let's assume the desired shot weighs 0.0572 g (Expected Weight) and it takes 60 seconds (Weight On Time(s)) to dispense. When you test for the valve flow rate, the results display in the Information window as shown in the graphic below. Now, let's say you want to change the percentage error from -5% to 0%.

1. Add 5% of Weight On Times to Weight On Times:  $(.05 \times 60.000) + 60.000 = 63.000$
2. Enter 63.000 in Weight On Times.
3. Click the WEIGHT button.
4. Note the new values displayed in the Information window.

The screenshot shows the 'Off-Line Operations' window with the following settings:

- Mount Position: 1
- Valve: MicroDot Valve
- Material: Indium -635
- Program: NONE
- Expected Weight: 0.0572 g
- Purge On Time: 0.000 s
- Syringe On Time: 0.000 s
- Weight On Time(s): 60.000 s
- Buttons: Close, Apply, Weigh, Purge, Sprague, Clean, Help

The 'Information' window displays the following results:

C29: Weight Results		
Value	Expected	Change
0.0543	0.0572	-5.0000%

Annotations in the image explain the fields:

- Weight On Time(s):** The amount of time the valve is on at the scale to create a shot.
- Actual scale weight:** The 'Value' field in the Information window (0.0543).
- Weight expected from the given On Times:** The 'Expected' field in the Information window (0.0572).
- Percentage of error:** The 'Change' field in the Information window (-5.0000%). The text explains: "Percentage of error; the difference between actual weight and expected weight. If actual weight is short of expected weight, a negative value results; if actual weight is greater than expected weight, the value will be positive."

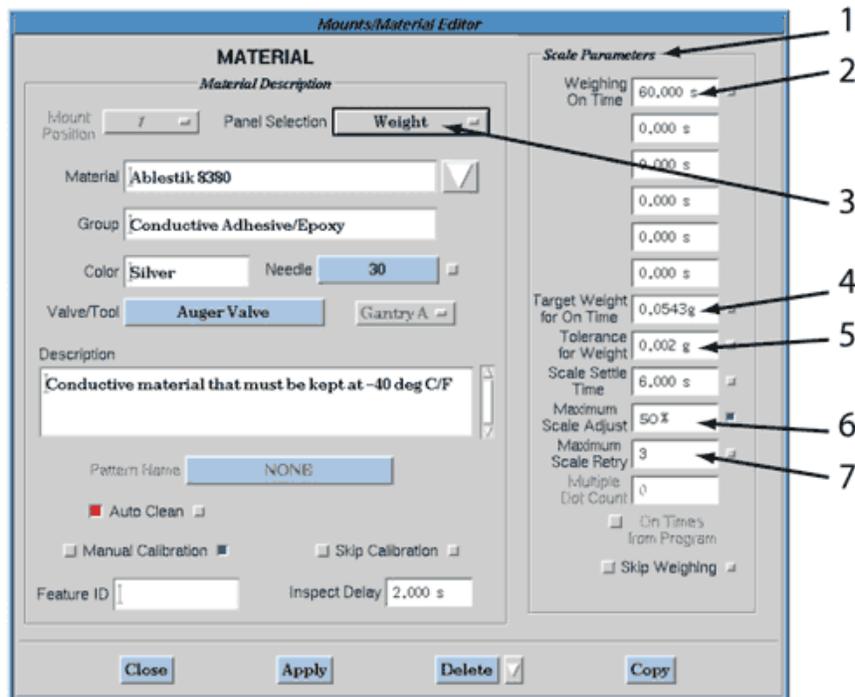
9. To verify dispense accuracy, run the test several times using the same values, repeating steps [Step 4](#) through [Step 8](#) until verification is complete.
10. Record the final weight results and the Weight On Time value for use in [Scale Set Up within Software](#) (pg 3.130).

## Scale Set Up Within Program

During a program run, the system will automatically compensate for actual material flow when you set up the scale values resulting from the [Determine Valve Flow Rate Using Weight Volume](#) (pg 3.130) procedure. You can set up these values in either the material library or in a specific program. We suggest entering them in the material library to simplify future programming.

To set up scale values in the material library:

1. Access the Scale Parameters in the material library:
  - a. Double click on the Program Editor icon. The Program Editor window displays.
  - b. From the Program Editor menu bar, click on Libraries > Materials. The Mounts/Material Editor - MATERIAL window displays.
2. Click on the Panel Selection button (Item 3 in the graphic below), scroll down the pop up menu, and select Weight. The Scale Parameters panel (Item 1) will display in the right-hand side of the Mounts/Material Editor - MATERIAL window.



3. Using the values recorded during [Step 10 \(pg 3-132\)](#), input values in Weighing On Time (Item 2) and Target Weight for On Time (Item 4).
4. Enter an allowable Tolerance for Weight (Item 5) value that will supply adequate coverage for the desired results without exceeding your coverage limit.

- Typically, you will want to enter a value in Maximum Scale Adjust (Item 6) between 50% and 70%.

**NOTE:** If you are mixing 2-part material on the machine, enter a value in Maximum Scale Adjust based on the following choices for handling material conditions:

**Automatic operations** – set the maximum scale adjust to 50% or greater.

**System attempts to make a single correction** before flagging the operator that scale adjustment has failed – set the maximum scale adjust to less than 50%. The smaller the tolerance value, the longer the scale compensation routine will take.

- If you want the system to keep adjusting until the set value is achieved, enter a value in Maximum Scale Retry (Item 7). Results depend upon whether or not the scale adjusts within the maximum number of scale retries:

**If the scale adjusts** to the value set in Maximum Scale, adjust before reaching the maximum number of retries. Then the program On-Times and Dispense Velocity will be adjusted according to the percentage that was required to match your Weighing On-Time to Target Weight.

**The scale fails to adjust** to the value set in Maximum Scale Adjust by the maximum number of retries. Then the system will flag the operator with the following options:

- Continue = continue with last correction attempt.
- Retry = start scale adjust over.
- Abort = abort program.

- Click APPLY to save your entries or click CLOSE to exit the window without saving the entries.

## Sustain Scale Adjustment Across Multiple Programs

If you set up material volume values using the Material Library, any adjustments you make to scale On- Time values in one program will carry across to all other programs using the same material for as long as the Stale Calibration function is active.

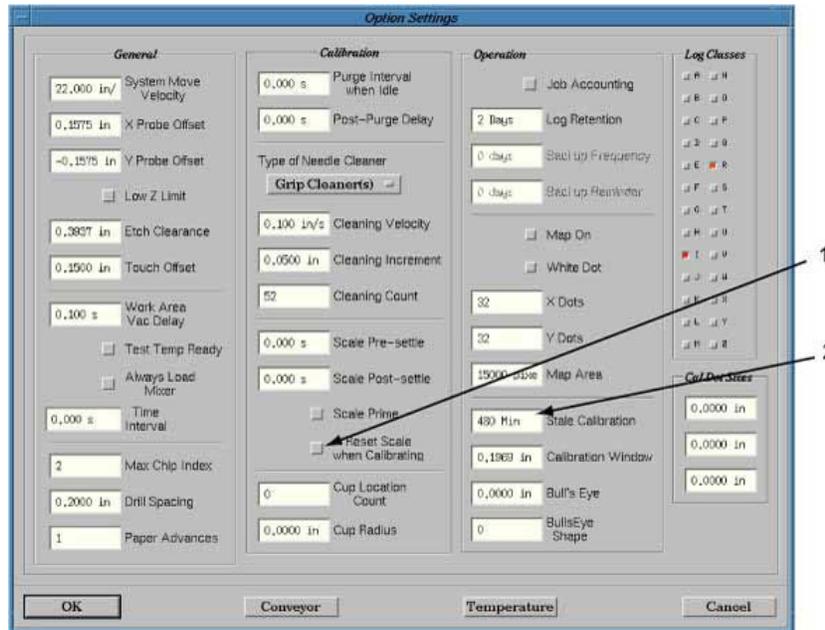
**Table 25:** EXAMPLE - Automatic Adjustment Across Multiple Programs

Let's assume you have set up material volume values in the Material Library for a particular material. Now let's also assume that Program A and Program B both use that same material. During machine calibration for Program A, material flow is calculated to be 30% less than the Target Weight for On Time; the system automatically corrects for this difference.

When machine calibration runs for Program B, the system will automatically apply the additional 30% of On Time at the start of the weigh routine to minimize calibration time. The system will continue to automatically apply an additional 30% of On Time to all programs run with this same material until the Stale Calibration value expires.

To sustain a scale adjustment setting across all programs using the same material:

1. Click on Configuration > Option Settings. Option Settings displays.



2. Verify that “Reset Scale when Calibrating” box (Item 1) is turned OFF.

Status of Reset Scale When Calibrating	How Weight Calibration is Affected
Turned Off (gray)	Begins with the value at the last calibration.
Turned On (red)	Begins with initial scale adjustment.

3. Verify that Stale Calibration (Item 2) is active. The scale adjustment setting remains valid until the Stale Calibration value expires.
4. Click OK to save your entries and exit the window.
5. Reboot the system.

## Configuration

Various configuration topics are included here. Because your machine is configured at the factory, re-configuration is typically only required if hardware is added or changed.

- [Configuration Menu](#) (pg 3.136)
- [Monitoring Program Details](#) (pg 3.139)
- [Temperature Control & Monitoring](#) (pg 3.142)
- [Needle Cleaner Setup](#) (pg 3.143)

## Configuration Menu

To create a custom dispenser system, certain selections are made at the factory to configure the machine before it ships. As needed, additional local changes can be made to the machine; a machine reboot is required for a configuration change to take effect.

A drop-down menu of configuration choices is available by clicking on Configuration in the menu bar of the main window. Of particular interest is the Option Settings choice; the other choices are not intended for typical customer use.

A brief explanation of each configuration choice follows:

Dispenser Configuration
Option Settings
I/O Definitions
Custom IO Definitions
Base Locations
TCP/IP Configuration
Servo Configuration
Print Config Files
Main Resource File
Editor Resource File
Misc Resource File
Temperature PID

### Dispenser Configuration

Brings up two panels, one to edit the current hardware configuration and one to display a fully detailed description of the current machine hardware configuration. Text is divided into categories such as General, Main, and Run\_Engine and resembles the \*.INI form used for Microsoft configuration files. Entries in this file are normally changed only if the machine hardware is changed.

For directions on how to change the global default settings for units, refer to [Global Default for Units](#) (pg 7.1).

For directions on how to configure the Monitor field to display program data on the main control window, refer to [Monitor Configuration Setup](#) (pg 3.139).

### Option Settings

Options Settings establish machine configuration for hardware on the dispenser. You can set parameters for the values that (may) affect your overall operation. For further details, refer to [Option Settings Features](#) (pg 3.137).

### I/O Definitions

Brings up two panels, one to edit the current I/O (input/output) configuration and one to display a fully detailed description of the current I/Os, the configuration file contents, and the associated text for how to add I/Os into the file. Entries in this file are manually changed only if machine wiring is changed.

### Custom I/O Definitions

Defines which items are displayed on the Custom Controls menu. Custom I/O names are defined here.

### Base Locations

Configuring the base locations enables the user to verify and teach all base locations and positions around the table for automatic adjustments. All base locations are

initially established at the factory, however, if any of the following conditions arise, a qualified engineer or maintenance person may use base locations to:

- teach the location of a newly installed device,
- change a location to increase process speed,
- verify the current coordinates of an existing location, or
- re-teach an existing location. For example, the camera calibration locations should be re-taught after adding a new calibration dot sticker to the calibration station.

A full discussion of base locations is located in *Base Locations* in the appendices of the *Dispenser Service Guide*.

### TCP/IP Configuration

For procedural details on how to set up TCP/IP communications between a GPD Global dispenser and a customer-supplied PC in order to establish the necessary communication to transfer data between the two systems, refer to [Interfacility Communications](#) (pg 7.15).

### Servo Configuration



**CAUTION:** DO NOT USE. This is a factory set calibration and is for GPD Global use only. Misuse of this file can cause the loss of all motor tuning, etc.

### Print Config Files

Used to print all configuration files to a printer hooked up to the back of the dispenser.

### Main Resource File

### Editor Resource File

### Misc Resource File

These files access X-Windows Resource Files which control all window displays and all window functions. Familiarity with X-Windows is required to work with these files. Changes installed at the site are removed with any software update.

### Temp PID

Not yet implemented. Determines PID loop parameters for temperature control (or anything else controlled by a PID loop).

## Option Settings Features

Options Settings are used to establish the machine configuration for hardware on the dispenser. You can set parameters for the values that (may) affect your overall operation. For a list of individual parameter descriptions, refer to [Option Settings](#) (pg 5.70).

A few of the Option Settings features are discussed below:

### Logging Files

Logging is an engineering tool that collects various types of system and user messages for purposes of analyzing machine performance, process results, failure rates, etc. Instructions on how to set up, retrieve, and format logging data can be found under [Message Logs](#) (pg 6.6).

### Monitor Temperature

The temperature ready signals from each temperature controller can be monitored. For instructions on how to set up temperature monitoring, refer to [Temperature Control & Monitoring](#) (pg 3.142).

**Needle Cleaner**

When the dispenser includes needle cleaner hardware, the system must be configured for the type of cleaner installed, various operational parameters must be established, and the coordinates for each point in the cleaning path must be taught. This set up has probably been done for you at the factory, however, most setup parameters may be modified, as needed, for process purposes. Instructions on how to configure a needle cleaner and set up its cleaning path can be found under [Needle Cleaner Setup](#) (pg 3.143).

**Scale Adjustment**

With material volume values set up for a particular material, any adjustment to scale On-Time values in one program can be made to carry across to all other programs using the same material (as long as certain conditions are met). Find detailed instructions under [Sustain Scale Adjustment Across Multiple Programs](#) (pg 3.134).

## Monitoring Program Details

The [Monitor](#) (pg 3.30) field, in the main window, displays a continually updated account of some program details only while a program is active.

This field can be configured to display several types of values: subboard count, board count (if subboards are not used), touch probe height, and tool foot pressure.

The rules that govern the monitor field:

- Subboard and board count represent the number of subboards (boards) processed by a program. This value increments by one when a subboard (board) has completed processing.
- Surface sensor height can be displayed in millimeters (with three decimal places) or in inches (with four decimal places).
- Pressure exerted by the Pressure Pick-up Tool is represented in grams. If the Monitor field is configured for the Pressure Pick-up Tool and the tool is not installed on the dispenser, then the Pressure value remains zero.

## Monitor Configuration Setup

When the Monitor field is configured to display on the main window, the real-time status of certain program data can be monitored by viewing this field.

There are several choices of display content from which to choose during configuration setup.



**WARNING** The content of this section is NOT recommended for use by anyone besides GPD Global personnel or those working under the direct guidance of GPD Global personnel. Improper application of this information can lead to serious complications in FLOWare Software operations. Any non-GPD Global employee who uses this information beyond the stated application specified by GPD Global Service Department personnel is in danger of causing personal injury and invalidating their machine warranty.

<b>ATTENTION</b> <a href="#">Le contenu de cette</a>	<b>WARNUNG</b> <a href="#">Der Inhalt dieses</a>	<b>ATTENZIONE</b> <a href="#">Il contenuto</a>	<b>ADVERTENCIA</b> <a href="#">NO SE RECOMIENDA</a>
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To configure the dispenser to display the Monitor field:

1. From the main window menu bar, click on Configuration > [Dispenser Configuration](#) (pg 3.136).
2. In the Edit Configuration window that displays, locate the [Run\_Engine] section and then set MonitorDisp to the appropriate value using the following choices:

MonitorDisp = n

where n defines whether or not the Monitor field displays on the main window.

0 = field content is not displayed (default setting)

1 = displays subboard count and tool foot pressure in grams (requires installation of Pressure Pick-up Tool hardware or else the pressure value will remain zero)

2 = displays subboard or board count and surface sensor height value (mm with 3 decimal places)

3 = displays subboard or board count and surface sensor height value (inches with 4 decimal places)

3. Press ESC to exit the Edit Configuration window, choose X to exit, and then choose Y for Yes to save the change.
4. Reboot the dispenser.

## Z Probe Limits

### **IN EFFECT AS OF FLOWare software version 2.9.3P**

The PROBE operation (Z height detection) will test the measured elevation against a set of limits and if the elevation is found to be outside of those limits, an error message indicating the Z Probe is out of range is presented, and the process is paused.

The limits are defined in the program PROBE step using the *Minimum Z Value* and *Maximum Z Value* fields.

- If both of these values are non-zero, then they define the range of the limits.
- If one or both these values are zero (0.000) then no limits checking is performed.

**NOTE:** The PROBE operation operates as expected in both pre and post scan modes.

**NOTE:** This testing/validation is not designed to be used to ensure a surface is within a very small tolerance for process precision. The purpose of this testing is to ensure that the measurements taken are not grossly outside the expected range which can happen if a height sensor is dirty, bent, or otherwise not operating properly.

### Z Probe Limits Operation

The Touch Pad surface elevation is used as a reference elevation. When a Z Probe operation is performed, the difference between the detected surface and the Touch Pad surface is calculated. This difference is checked against the range specified by the Minimum Z Value and Maximum Z Value values. If the difference between the detected surface and the Touch Pad surface falls within the defined limits, the operation is successful and the process continues.

If the difference is outside the defined limits, the process is paused with a warning dialog presented to the operator (plus, yellow light turns on and alarm sounds). The operator may at this point:

- ignore the warning and continue the process,
- retry the ZProbe (this will again measure the elevation of the surface and test it against the limits), or
- abort the process altogether.

#### **Example:**

Assume the following:

Touch Pad Elevation	10.550 mm
Minimum Z Value	-0.1 mm
Maximum Z Value	0.1 mm

A PROBE operation is performed which measures a surface at 10.503 mm. The difference between the measured surface and the Touch Pad elevation is 0.047 mm. This falls within the range -0.1 mm,0.1 mm and so the operation succeeds and the process continues.

A different PROBE operation is performed which measures a surface at 11.184 mm. The difference between the measured surface and the Touch Pad elevation is -0.634 mm which is well outside the defined range of -0.1 mm,0.1 mm. In this case, the process immediately stops and the operator is alerted with a message indicating the Z Probe is out of range. The operator may ignore the message, retry the measurement, or abort the process.

## Temperature Control & Monitoring

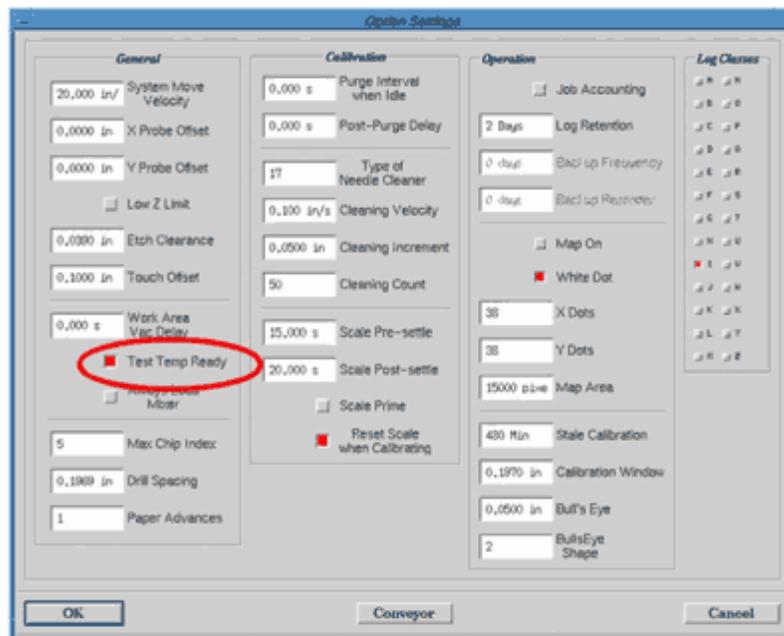
The FLOWare software temperature control function is currently limited to monitoring the temperature ready signals from each temperature controller. Temperature control for each heated device on the dispenser is maintained mechanically by a CAL 9900 temperature controller.

When temperature monitoring is set up in Option Settings, a program will test the temperature ready signal from each heated device prior to processing each product (board). If the temperature is within the set deviation range of the set temperature, the program continues. If the temperature falls outside this range, the program will wait until set temperature is achieved before proceeding.

### Monitoring Temperature

To set up temperature monitoring:

1. From the main menu bar, click Configuration > Option Settings. Option Settings displays.
2. Turn ON the Test Temp Ready default box. This activates the temperature monitoring function.

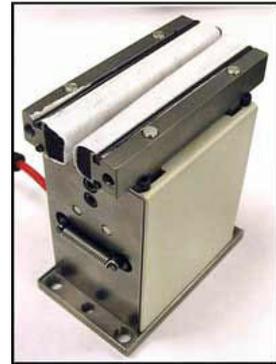


## Needle Cleaner Setup

The optional, software-controlled needle cleaner can be used to clean the needle on up to three heads, one at a time. This process is software controlled and can be used within a program to clean a needle during the calibration process or any time during a program run, or offline when the dispenser is not busy.

Needle cleaner setup involves these topics:

- [Cleaning Path](#) (pg 3.143)
- [Cleaner Setup Overview](#) (pg 3.143)
- [Configuring Cleaner](#) (pg 3.144)
- [Setting Cleaner Parameters](#) (pg 3.145)
- [Teaching Cleaning Path](#) (pg 3.147)



### Cleaning Path

Initially, coordinates for the start and end points of the needle cleaning path have to be taught. Then values for the number of increments the needle is to move and the distance the needle is to move from the last cleaning point need to be entered.

For example, the cleaning path for a standard grip-type needle cleaner typically starts with the needle positioned between the set of pneumatically operated grip jaws. After the jaws clamp on the needle simultaneously, the gantry typically raises the needle upward to the ending point, wiping the needle clean on the soft jaws in the process.

### Cleaner Setup Overview

Before needle cleaning operations can be used, some set up may be required. The set up required by the needle cleaner has probably already been done for you at the factory, however, most setup parameters may be modified, as needed, for process purposes. The system must be configured for the type of cleaner installed, various operational parameters must be established, and the coordinates for each point in the cleaning path must be taught.

The basic steps involved in setting up a needle cleaner are as follows:

1. **Establish Configuration & Operational Parameters.** Needle cleaner configuration is typically done at the factory - see the [Configuring Cleaner](#) (pg 3.144) discussion - however, you may modify various operational parameters, such as needle velocity during cleaning, the incremental distance moved between successive cleaning dispenses, and the number of increments made before operator intervention is required. To modify these configuration parameters, refer to the [Setting Cleaner Parameters](#) (pg 3.145) discussion.
2. **Teach Locations.** The cleaning path locations (coordinates) through which each head moves during the needle cleaning process are typically taught at the factory, however, you may re-teach these cleaning path locations if desired. To modify the locations at which needle cleaning operations begin and end, refer to [Teaching Cleaning Path](#) (pg 3.147).
3. For instructions on how to use the needle cleaner after set up is complete, refer to the following procedures in the *Dispenser Service Guide*:
  - *Needle Cleaner* in the *SETUP* section
  - *Needle Online with Needle Cleaner* in the *CLEAN* section

## Configuring Cleaner

Your system has already been configured for the type of automatic needle cleaner(s) installed, each cleaner has been assigned to a head, and unless it is replaced by a different type of hardware, this configuration information should not change. However, various other operational parameters within the configuration may be modified, such as needle velocity during cleaning, the incremental distance moved between successive cleaning dispenses, and the number of increments made before operator intervention is required.

The locations at which needle cleaner operations occur, i.e. the points in the cleaning path used during a program, may also be modified. The coordinates at which needle cleaning operations begin and end, the type of valve motion used, and the velocity at which it occurs are all variables you may change as needed.

### Other Configuration Choices

---

GPD Global offers different needle cleaner types and configurations to meet a variety of needs. A single needle cleaner can be scale-mounted or one or more needle cleaners can be table-mounted. Whenever needle cleaner hardware is installed or moved, the needle cleaner must be re-configured.

### Assigning Cleaner to a Head

---

As previously noted, the cleaner(s) on your system have probably already been assigned to a head. If circumstances dictate a change, then know that:

- A head must be assigned for each grip type needle cleaner.
- Head assignment is unnecessary for brush type needle cleaners.
- Multiple cleaners may be assigned to the same head.
- Typically, a maximum of three heads and three needle cleaners can be installed on a dispenser.

To assign a grip type needle cleaner to a head:

1. In the main menu bar of the Main Control Panel, click on Configuration > [Dispenser Configuration](#) (pg 3.136). The Edit Configuration and Configuration Definition windows display.
2. In Edit Configuration, set the Clean1X, Clean2X, and Clean3X fields to an appropriate value. The value you enter in each determines which head is assigned to that particular needle cleaner hardware. Needle Cleaner Field Needle cleaner hardware is identified by the field used in Edit Configuration:

<b>Needle Cleaner Field</b>	
Needle cleaner hardware is identified by the field used in Edit Configuration:	
<u>Needle Cleaner</u>	<u>Field</u>
first	Clean1X
second	Clean2X
third	Clean3X

<b>Head Value</b>	
Head hardware is identified by the value used in Edit Configuration:	
<u>Head</u>	<u>Value</u>
1	0
2	1
3	2

**EXAMPLE 1**

In the following example, the first cleaner has been assigned to Head 1, the second cleaner to Head 2, and the third cleaner to Head 3.

Field	Value
Clean1X	0
Clean2X	1
Clean3X	2

**EXAMPLE 2**

In the following example, both the first and second cleaners have been assigned to Head 1, and the third cleaner has been assigned to Head 2.

Field	Value
Clean1X	0
Clean2X	0
Clean3X	1

3. Close the Edit Configuration and Configuration Definition windows. You have completed assigning a head to the grip type needle cleaner.

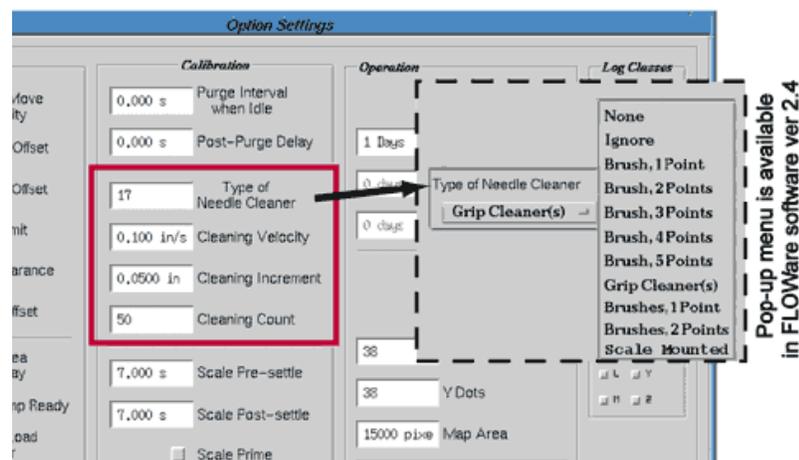
## Setting Cleaner Parameters

To establish or modify the needle cleaner configuration parameters:

1. In the main menu bar of the Main Control Panel, click on Configuration > Option Settings. Locate the needle cleaner parameter fields in the Option Setting window that displays.

### **IN EFFECT AS OF FLOWare software version 2.4**

A selection from the pop-up menu of needle cleaner types replaces the numerical entry previously required in the Type of Needle Cleaner field.



- If the type of needle cleaner hardware has been changed, set the Type of Needle Cleaner field to the new needle cleaner code appropriate for the type, quantity, and location of hardware, and the type of motion or number of moves to be used in the cleaning path.

**Table 26: Relating Needle Cleaner Codes and Characteristics**

Type of Cleaner	Number of Cleaners	Installed Location	Type of Motion or # of Moves in Cleaning Path	Notes	Code for Type of Cleaner
Grip	All	Table	Varies with the values input for Cleaning Velocity and Cleaning Increment.	The coordinates for each move are taught using Base Locations.	17
Brush	Single	Table	1	2 inch move in X direction from a point taught using Base Locations.	1
			2	The coordinates for each move are taught using Base Locations.	2
			3		3
			4		4
			5		5
	Scale	2	The coordinates for each move are taught using Base Locations.	11	
	Multiple	Table	1	2 inch move in X direction from a point taught using Base Locations.	21
2			The coordinates for each move are taught using Base Locations.	22	
Ignore	All	All	0	Cleaning is suppressed.	6
None	None	None	None	No needle cleaner is present. (Default)	0

- Cleaning Velocity.** To change the velocity at which the needle moves through the automatic needle cleaner, change the value in Cleaning Velocity. If no needle cleaner is present, the default is a 0.0 value.
- Cleaning Increment.** If the machine is equipped with either a scale-integrated needle cleaner or one to three grip-type needle cleaners, a value must be entered in Cleaning Increment for the incremental distance (mm) moved between successive cleaning dispenses.
- Cleaning Count.** If the machine is equipped with either a scale-integrated needle cleaner or one to three grip-type needle cleaners, a value must be entered in Cleaning Count to indicate the maximum number of increments the needle will move through a needle cleaner before the operator is notified for purposes of operator intervention.

**IN EFFECT AS OF FLOWare software version 2.3**

Cleaning Count is retained between programs, including offline operations; thus, the user cannot reset the count.

## Teaching Cleaning Path

The cleaning path locations through which a head moves during the needle cleaning process are typically taught at the factory, however, you may re-teach these locations as needed. You may modify the coordinates at which needle cleaning operations begin and end.

Teaching a location is a matter of selecting the name of the location you wish to teach, jogging the gantry to the coordinates you want to establish for the selected name, and then clicking several on-screen buttons.

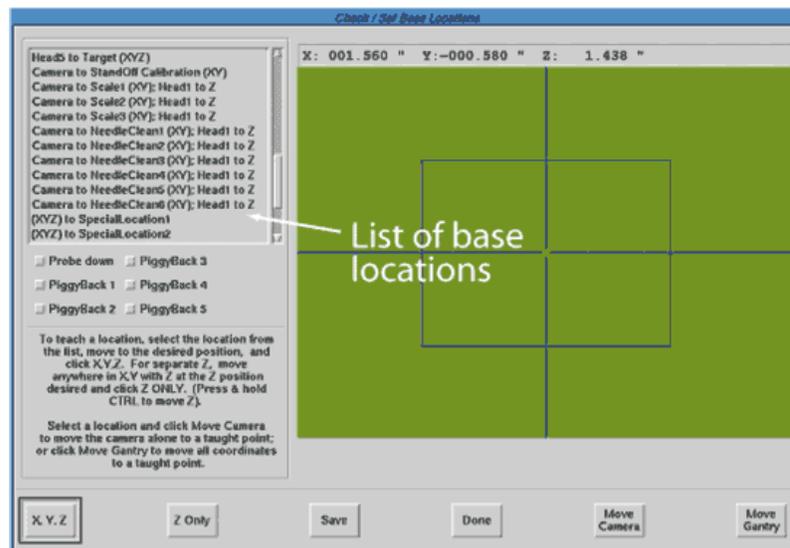
The XY and Z coordinates for each needle cleaning location are taught in a two step process. Be sure to first teach the XY coordinates using the camera over the desired location, and then teach the Z coordinate using the head mount position at the desired location.

To establish or modify needle cleaning coordinates:

1. Take the following steps to access the scrolling list from which you will choose base locations for the cleaning path:
  - a. Sign onto the system with a password with Configuration authority.
  - b. In the main menu bar of the main window, click on Configuration > Base Locations. The Check/Set Base Locations window displays.

**NOTE:** The normal multi-tasking capability of the system is unavailable while the Check/Set Base Locations window is open.

- c. Scroll down through the list of base locations until the series of locations labeled *Camera to NeedleCleanx (XY): Head1 to Z* displays.



2. To determine which base location(s) need to be taught in order to create the desired cleaning path, answer the following questions:
  - a. Which code is entered in the Type of Needle Cleaner field on the Option Settings window? (Refer to steps 1 and 2 of [Setting Cleaner Parameters](#) (pg 3.145). Find that same code, in the column marked *Code for Type of Needle Cleaner*, in [Base Locations Used by Needle Cleaner Codes 1-11](#) (pg 3.148) or [Base Locations Used by Needle Cleaner Codes 17-22](#) (pg 3.149).
  - b. To which head position (1, 2, or 3) is the needle cleaner assigned? Find that same head number in the column marked *Head Assignment*.

- c. If you answered question 2.a with:
- 1, 2, 3, 4, or 5, then answer the question *How many base location points are needed in the cleaning path?*
  - 11 or greater, then continue with the following step.
- d. The name of one or more base locations is listed in the column marked *Base Location(s) to be Taught*. When multiple base locations are to be taught, the initial location or starting point is typically positioned at one end or the other of the needle cleaner at the elevation at which the cleaning action will begin. The final location or ending point is typically positioned at the opposite end of the needle cleaner at an elevation clear of the needle cleaner.

**Table 27: Base Locations Used by Needle Cleaner Codes 1-11**  
**Codes 1-11**

Code for Type of Needle Cleaner	Head Assignment	Number of Moves in Cleaning Path	Base Location(s) to be Taught	Move that will Occur
1	1, 2, or 3	1	Camera to NeedleClean1 Camera to NeedleClean2 Camera to NeedleClean3 Camera to NeedleClean4 Camera to NeedleClean5 Camera to NeedleClean6	Starts at the location taught for Camera to NeedleClean1 and then moves 2 inch in the X direction. Refer to note below.†
2		2		Starts at the location taught for Camera to NeedleClean1 and then moves to the location taught for Camera to NeedleClean2. Refer to note below.†
3		3		Starts at the location taught for Camera to NeedleClean1 and then moves in sequence to the locations taught for Camera to NeedleClean2 and Camera to NeedleClean3. Refer to note below.†
4		4		Starts at the location taught for Camera to NeedleClean1 and then moves in sequence to the locations taught for Camera to NeedleClean2, Camera to NeedleClean3, and Camera to NeedleClean4. Refer to note below.†
5		5		Starts at the location taught for Camera to NeedleClean1 and then moves in sequence to the locations taught for Camera to NeedleClean2, Camera to NeedleClean3, Camera to NeedleClean4, and Camera to NeedleClean5. Refer to note below.†
11	1, 2, or 3	2	Camera to NeedleClean4	Start at the edge of the brushes with the corresponding Z coordinate at the dispense elevation.
			Camera to NeedleClean5	End at the opposite end of the brushes with the corresponding Z coordinate at an elevation above the brushes.

† To prevent inadvertent equipment damage, teach all six locations even though they may not all currently be used in the needle cleaning path. GPD Global suggests teaching any unused *Camera to NeedleClean n* base locates to the *(XYZ) to Refresh Location* coordinates. A full discussion of *Base Locations* is located in the appendices of the *Dispenser Service Guide*.

**Table 28: Base Locations Used by Needle Cleaner Codes 17-22**  
**Codes 17-22**

Code for Type of Needle Cleaner	Head Assignment	Base Location(s) to be Taught	Move that will Occur
17	1	Camera to NeedleClean1	† Start down between the jaws with the corresponding Z coordinate at an elevation where the needle wipe action is to occur.
		Camera to NeedleClean2	‡ End of cleaning path with the corresponding Z coordinate at an elevation above the grip jaw surface.
	2	Camera to NeedleClean3	† Start down between the jaws with the corresponding Z coordinate at an elevation where the needle wipe action is to occur.
		Camera to NeedleClean4	‡ End of cleaning path with the corresponding Z coordinate at an elevation above the grip jaw surface.
	3	Camera to NeedleClean5	† Start down between the jaws with the corresponding Z coordinate at an elevation where the needle wipe action is to occur.
		Camera to NeedleClean6	‡ End of cleaning path with the corresponding Z coordinate at an elevation above the grip jaw surface.
21	2	Camera to NeedleClean1 OR Camera to NeedleClean2	2 inch move in X direction starting at taught location.
		Camera to NeedleClean3 OR Camera to NeedleClean4	
		Camera to NeedleClean5 OR Camera to NeedleClean6	
22	1 or 2	Camera to NeedleClean1	Start at wipe elevation.
		Camera to NeedleClean2	End clear of jaw or brushes.

† Typically, the start location is taught at one end or the other of the needle cleaner.

‡ Typically, the end location is taught at the opposite end from the start location on the needle cleaner.

3. Now that you have identified which base location(s) to teach, make a selection from the scrolling list in the Check/Set Base Locations window.
4. Teach the X and Y coordinates by jogging the camera to the coordinates you want to teach for the selected base location and then click the XYZ button.
5. To teach the Z coordinate:
  - a. Mount the Head Calibration Tool in head 1 to emulate a valve.

**NOTE:** Always mount the Head Calibration Tool in the head 1 mount position regardless of the head assignment for the currently selected base location. For mounting details, refer to *Head Calibration Tool* procedure under *Tools & Equipment* in the *Routine Maintenance* section of the *Dispenser Service Guide*.
  - b. Jog head 1 to the desired elevation at the needle cleaner and then click the Z ONLY button.

**NOTE:** It is critical to teach a Z height that will not transfer material from the needle cleaner to the optional Rigid Needle StandOff if it is being used, nor damage the touch probe if a short needle is being cleaned.
6. To save the newly taught values, click SAVE. To cancel your input, exit the window without clicking SAVE.
7. Repeat steps 3 through 6 for any additional base locations to be used in the cleaning path.
8. Click DONE to close the Check/Set Base Locations window.
9. Boot the system so all changes take effect.

# 4 Tips & Tricks

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- [Program Creation](#) (pg 4.1)
- [Program Enhancement](#) (pg 4.52)
- [Procedures for Custom Hardware](#) (pg 4.76)

## Program Creation

- [Creating a Basic Program](#) (pg 4.1)
- [Tutorials - How to Program Basic Shapes](#) (pg 4.7)
- [Creating a SubBoard Program](#) (pg 4.37)
- [Creating a Pick & Place Program](#) (pg 4.44)

## Creating a Basic Program

Use the following guidelines when creating a program from the beginning (scratch) instead of importing or converting existing program data.

All of these basic steps are required to manually create a new program - perform all steps in the order listed:

- [1. Create Program Header](#) (pg 4.1)
- [2. Add Program Description](#) (pg 4.2)
- [3. Teach Program Parameters](#) (pg 4.2)
- [4. Select Material, Head, Needle](#) (pg 4.3)
- [5. Create Program Lines](#) (pg 4.4)
- [6. Define Subboards](#) (pg 4.5)
- [7. Add Options](#) (pg 4.6)
- [8. Verify Vision Calibration](#) (pg 4.6)

### 1. Create Program Header

To create a program header:

1. Open the Program Editor by double-clicking the Program Editor icon located on the main window. Verify that Edit Programs is selected.
2. **Program Name** - Create a name for the new program by clicking on ADD ITEM. Then in the prompt that displays, type a new program name and click OK. The new name will display alphabetically in the Available Items pane of the Program Editor. The new program name should remain selected (highlighted) so subsequent input is applied to it rather than some other program.
3. **Class** - Enter a name in [Class](#) (pg 3.35) if you want the ability to filter (include/exclude) the new program along with other programs with the same class name.
4. **Version** - Enter a prefix code in [Version](#) (pg 3.35) if you want the program to have the ability to use the shape name with a version prefix instead of using the shape name specified in the program.
5. **Board Dimensions** - If the dispenser is equipped with a conveyor, enter [Board Dimensions](#) (pg 3.36); otherwise, skip to the next step.

**NOTE:** Entry of the length dimension is critical for timing conveyor operations, especially if there are slots or holes in the board.

Conveyor timing is also dependent on the board transit speed entered in the Options window; this value is determined during conveyor calibration. If conveyor timing problems are encountered when you run your new program, perhaps the conveyor needs to be recalibrated per [Calibrate Conveyor Speed](#) (pg 3.125).

6. **Reference Point** - Establish the board origin point (upon which all other points in the program depend) by entering coordinates for [Reference Point](#) (pg 3.37). If the Reference Point X and Y fields are:
  - known values, enter them manually.
  - unknown, use the TEACH button and the resulting Jog window to teach the coordinates.

In either case, if the same location is to be used by both the Reference Point and the first fiducial point, first teach the reference point coordinates and then immediately enter zero in both coordinate fields for the first fiducial point.

7. Click APPLY EDITS to save your entries.

## 2. Add Program Description

Enter a program [Description](#) (pg 3.37) of descriptive text to record product and/or processing information about the new program:

1. If it is not still open, reopen the Program Editor and verify that Edit Programs is selected.
2. Also verify that the name for your new program is selected in the Available Items list.
3. Enter desired text in the Description pane.
4. Click APPLY EDITS to save your entry.

## 3. Teach Program Parameters

Teach program parameters:

1. If it is not still open, reopen the Program Editor and verify that Edit Programs and the name for your new program are selected.
2. **Patterns** - If you will be using existing patterns from the pattern library, skip to the next step; otherwise, create any new patterns you will need for defining fiducials and bad marks, especially if your dispenser is equipped with automatic vision. For details, refer to [Teaching a Pattern](#) (pg 3.62).
3. **Fiducial Points** - Teach as many fiducial points (from 0 to 3) as needed for product orientation. Teach these points as accurately as possible as they are used to align the board in x, y, and theta in relation to the Reference Point. The Reference Point should be taught prior to teaching [Fiducial Points](#) (pg 3.38).
  - a. In the Fiducials pane of the Program Editor, click on the button of the fiducial you want to teach (FIDUCIAL 1 X, FIDUCIAL 2 X, or FIDUCIAL 3 X). The Jog window displays.
  - b. Use Jog to move the camera to the desired fiducial coordinates and then click CLOSE. This action teaches the fiducial coordinates. Click MOVE TO only to visually verify the coordinates once they have been taught.
  - c. If the dispenser is equipped with an Automatic Vision System, assign a pattern to the fiducial point. The vision system will search for the pattern at the fiducial point coordinates during the program run. To assign a pattern from the [Patterns Library](#) (pg 5.16) to the fiducial point:
    - 1 - Click the PATTERN button associated with the selected fiducial point.
    - 2 - Select an existing pattern from the list that displays and click ACCEPT.

- d. Click APPLY EDITS to save your input.
  - e. Repeat the above steps to teach up to two additional fiducial points.
4. **Touch Span** - If the program will be performing high precision operations, use the touch span feature. The touch span coordinates represent the distance you want the dispenser to travel in each axis before it performs a board height sense. To teach the touch span parameters:
    - a. In the Fiducials pane of the Program Editor, manually enter the desired [Touch Span](#) (pg 3.41) coordinate values.
    - b. Click APPLY EDITS to save your input.
  5. **Bad Mark** - If the program is to trigger a particular action based on whether or not a [Bad Marks](#) (pg 3.39) pattern is detected, teach the appropriate coordinates, pattern, and flag value for a bad mark. Bad marks can be used for several different programming strategies.
    - a. In the Fiducials pane of the Program Editor, click on the BAD MARK X button. The Jog window displays.
    - b. Use Jog to move the camera to the desired coordinates and then click CLOSE.
    - c. If the dispenser is equipped with an Automatic Vision System, assign a pattern to the bad mark. The vision system will search for the pattern at the bad mark coordinates during the program run.
 

To assign a pattern to the bad mark, click the PATTERN button associated with Bad Mark. Then either select an existing pattern from the list that displays and click OK, or teach a new pattern.
  - d. Click APPLY EDITS to save your input.
  6. **Alignment Points** - If the program is going to use arrays:
    - a. Teach the alignment points as an aid for array-to-board edge alignment. For details, refer to [Arrays & Alignment Points](#) (pg 3.100).
    - b. Click APPLY EDITS to save your input.

#### 4. Select Material, Head, Needle

Select the type of head to be used, its mount position, and the material and gauge of needle to be used. You may also need to modify the material default parameters

1. If it is not still open, reopen the Program Editor and verify that Edit Programs and the name for your new program are selected.
2. **Head Position** - Define the station position for the valve or tool to be used in the program.
  - a. In the Program Editor, click the VALVE/TOOL MOUNTS button.
  - b. In the Mounts/Material Editor - [MOUNT](#) (pg 3.71) window that displays, select the appropriate head mount station position from the Mount Position drop-down menu.
  - c. Click APPLY to save your input.
3. **Material Type** - Define the type of material to be used by the head position selected in the prior step.
  - a. In the Mounts/Material Editor - [MOUNT](#) (pg 3.71) window, click the Material field button.
  - b. From the list of available materials that displays, select the name of the material to be used, and click ACCEPT. Typically, selection of a material will automatically enter a valve or tool name in the Valve/Tool field; a head type is usually assigned to a material when it is set up in the Material library.
  - c. Click APPLY to save your input.

4. **Head Type** - You may override the type of head automatically assigned during the prior step or assign one if none was automatically selected.
  - a. In the Mounts/Material Editor - [MOUNT](#) (pg 3.71) window, click the Valve/Tool field.
  - b. From the list of available heads that displays, select the name of the valve or tool to be used, and click ACCEPT.
  - c. Click APPLY to save your input.
5. **Material Parameters** - Any modifications you make to the material parameters here do not affect the material parameter values set up in the material library. If the material will be used repeatedly, it is more efficient to set up the material and make material parameter changes in the [Materials Library](#) (pg 5.7) rather than repeating the material setup steps every time you want to use the material in a program.

On the other hand, if you are only using the material or material parameters changes in this one program, define the material in this manner:

- a. Make any necessary changes to the default parameters for the selected material. In addition to all the parameter fields available via the Panel Selection drop-down menu, make any needed entries to the following fields and options: Group, Color, Description, Pattern Name, Auto Clean, Manual calibration, Skip Calibration, Feature ID, and Inspect Delay.
- b. Click APPLY to save your input.
6. **Needle Gauge** - Define the needle gauge, if any, to be used by the selected head.
  - a. In the Mounts/Material Editor - [MOUNT](#) (pg 3.71) window, click the Needle field button.
  - b. From the list of available needle gauge sizes that displays, select the gauge to be used, and click ACCEPT.
  - c. Click APPLY to save your input.
7. **Additional Heads** - repeat [Step 1](#) through [Step 6](#) for each additional head to be used by the current program.
8. Return to the Program Editor by clicking CLOSE in the Mounts/Material Editor MOUNT window.

## 5. Create Program Lines

A program usually consists of multiple program lines, each of which has a set of parameters associated with it. Program lines and parameters can be created or modified in any order. The Program Detail window is the source of all program line creation and modification.

1. If it is not already open, reopen the Program Editor and verify that Edit Programs and the name for your new program are selected.
2. **Add Program Line** - Define the position of the program line within the program.
  - a. Open [Program Detail](#) (pg 3.43) by clicking on EDIT DETAIL LINES in the Program Editor.
  - b. To establish the position of the new program line within the program, highlight the program line that will precede the new line. For example, if you highlight the second program line, the new program line will be added into the program as the third program line.
  - c. Click on either the LINE icon (located at the top of the window) or the ADD LINE button. A list of operations displays.
3. **Select Operation** - From the list of operations that you opened in the previous step, select an operation type to define the type of action or shape the new program line will define.

For a listing of operation types and their definitions, refer to [Summary of Operations \(Primitives\)](#) (pg 3.88).

- a. Highlight a selection in the operations list and click ACCEPT. If the operation you want to select is not listed, a class filter may have suppressed it.
  - b. Click APPLY to save your input.
4. **Define Program Line Parameters** - Consider the benefits of making the bulk of any common parameter modifications in a partition program line. Partition program lines use the default hierarchy inherent in the software for faster, more efficient programming.

For example, instead of repeatedly assigning parameter values in numerous program lines, define them once in a [Partition Line](#) (pg 3.91); the partition line defines the default values for all subsequent program lines.

5. **Additional Program Lines** - repeat [Step 2](#) through [Step 4](#) for each additional head to be used by the current program.
6. Click APPLY to save your input and then click DONE to return to the Program Editor.

## 6. Define Subboards

If your program will be using subboards, define them now; otherwise, skip to [7. Add Options](#) (pg 4.6).

Subboards must be defined for palletized (panelized) boards. By defining subboards, you will be converting an existing program for an individual board into a subboard program of multiple boards with different origins.

**NOTE:** A subboard cannot be defined until a program line is established. For further details, refer to [Creating a SubBoard Program](#) (pg 4.37).

1. Verify that Edit Programs and the name for your new program are selected in Program Editor.
2. Click on the MODIFY SUBBOARDS button to open SubBoard Editor.
3. **Subboard Name** - The subboard name is a reference used to identify an individual board within the pallet; the program name will not be affected. Sequence numbers (first, second, third) are typically used as subboard names.
  - a. As desired, type a name in the Name field.
  - b. Click APPLY to save your input.
4. **Subboard Parameters** - If you want subboard parameters to differ from those already defined for the pallet (refer to [3. Teach Program Parameters](#) (pg 4.2)), enter them now.
  - a. As needed, alter the subboard fiducial point coordinates. If you do not turn off the fiducials by clicking the fiducial Used buttons, the system will locate them twice on the first board – once as the pallet fiducial and again as the board fiducial.
  - b. **Bad Marks** - As desired, teach [Bad Marks](#) (pg 3.39) for subboards. To access the Bad Mark Location panel in the Sub Board Editor window, click MODIFY SUB BOARDS in the Program Editor window.
  - c. **Suppress Auto Height Probe** - Activate this setting if you want the touch probe to touch down on only the first subboard rather than on each subboard within a pallet prior to processing. For details, refer to [Subboard Touch Probe Frequency](#) (pg 4.40).
  - d. Click APPLY to save your input.
5. **Subboard Orientation** - Teach new coordinates for each subboard origin (reference point) that differs from the origin of the pallet. For details, refer to [Teach Origin for New Subboard](#) (pg 4.41).

- a. If the X and Y coordinates of a subboard reference point are known values, enter them manually. If the values are unknown, use the TEACH button and the resulting Jog window to teach the coordinates.
  - b. Click APPLY to save your input.
6. **Add the Subboard** - Assign the subboard information you've entered during the last several steps to a defined subboard:
    - a. Click the ADD button in the SubBoard Editor.
    - b. As desired, type the subboard name in the resulting query and click OK. Notice the entry that now appears in the Defined Boards pane.
    - c. Click APPLY to save your input.
  7. **Additional Subboards** - repeat [Step 3](#) through [Step 6](#) for each additional subboard to be defined.
  8. **Add Subboards to Program** - Save the subboard program:
    - a. Click APPLY to add the completed subboard subroutine to your program.
    - b. Click DONE to exit to the Program Editor.
    - c. Click APPLY EDITS to save the changes to the program.
  9. **Test Subboard Program** - After adding subboards to a program and prior to running the program live, first run the program in Inspect Mode to verify that all points are in their correct location.

## 7. Add Options

Add options as needed. Options include such choices as Skip if No Fiducial, Suppress Lifter, Pause on Bad Mark, Pre-scan Patterns, Pre-scan Probes, and Suppress Hold-Down.

To activate options for the currently selected program:

1. In the Program Editor, turn on any of the [Board Options](#) (pg 3.36) that apply to the new program.
2. Click APPLY EDITS to save your input.

## 8. Verify Vision Calibration

Verify that the vision system is properly calibrated:

1. In the Program Editor, click on the MISC PROGRAM SETTINGS button to open the Miscellaneous Program Settings window.
2. All default boxes in the Vision Calibration pane should be turned on (blue). This includes the default boxes for Gain, Offset, Tuning, Zoom, Focus, f-stop, Light Level, and Light on Dark. If any of the boxes appear gray, click on them now to turn them ON. (Your program will now use the default vision values established in the ..Default.. program).
3. Click on APPLY and then DONE.
4. Run your new program per [Testing & Inspecting](#) (pg 3.118) to verify that the vision system is calibrated correctly – it should be able to locate the calibration dot on the calibration station.

**NOTE:** If the camera cannot find the calibration dot, go to the [..Default.. Program](#) (pg 3.93) and examine the values in the vision calibration pane of the Miscellaneous Program Settings window.

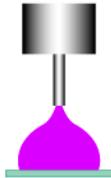
Your new program should now be ready to use in Run mode.

## Tutorials - How to Program Basic Shapes

Use the tutorials in this section as a guide to creating a basic shape and adding it to a program.

- [How to Program a Single Dot](#) (pg 4.7)
- [How to Program a Single Line Segment](#) (pg 4.12)
- [How to Program an Area Fill \(Rectangle\)](#) (pg 4.17)
- [How to Program a Circle](#) (pg 4.25)
- [How to Program an Arc](#) (pg 4.30)

### How to Program a Single Dot



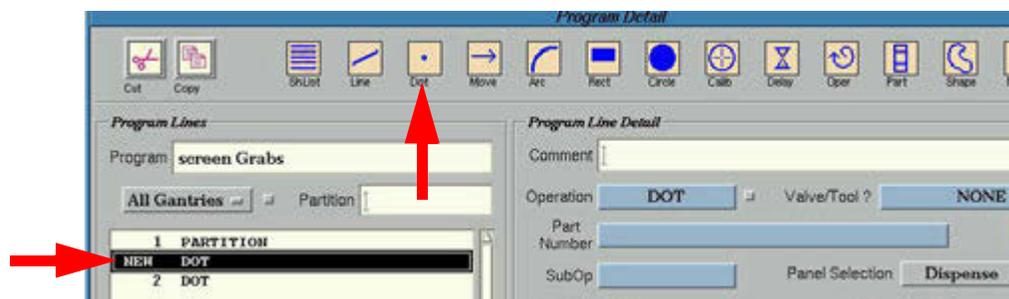
DOT is a primitive (preprogrammed routine) shape for which you may modify various parameters. DOT moves the valve to a height above the board and turns the valve on for a specified amount of time, then moves the valve to a safe height above the board before moving to the next operation point.

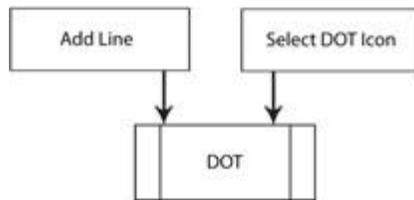
A DOT is the most basic type of dispense. A DOT program detail line can dispense a single dot or an array of dots.

To create a program detail line for a single dot in a program or shape:

1. Open a program:
  - a. From the Program Editor, select either an existing program (or shape) or create a new program (or shape).
  - b. Select the appropriate choice: Edit Programs or Edit Shapes.
  - c. Open Program Detail by clicking on EDIT DETAIL LINES.
2. Add a DOT program detail line:
  - a. Position the cursor so it highlights the program line that will precede your new DOT program line.
  - b. Click on either the DOT icon (located at the top of the window) or the ADD LINE button. If you choose to click ADD LINE, the Select List of operation choices displays; select DOT and then click ACCEPT.

In both cases, a new DOT program detail line displays in the Program Lines pane with a designation of NEW next to it.

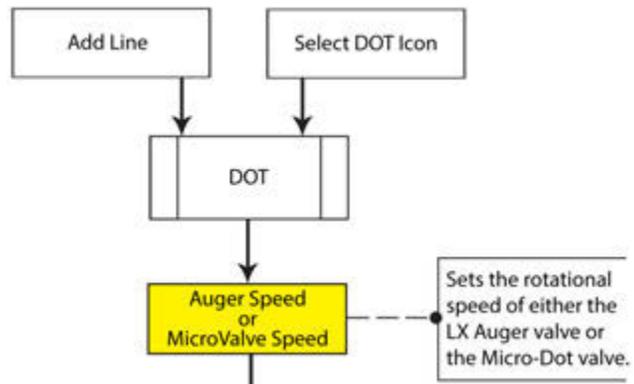




c. Click APPLY to save your input.

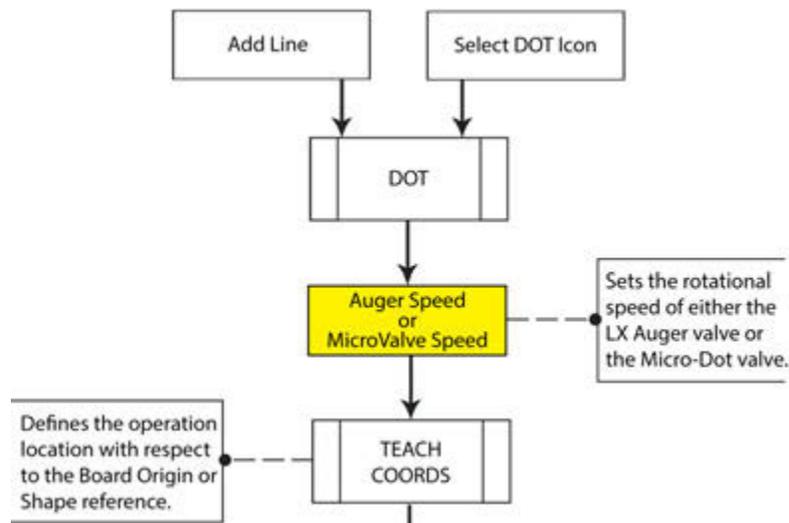
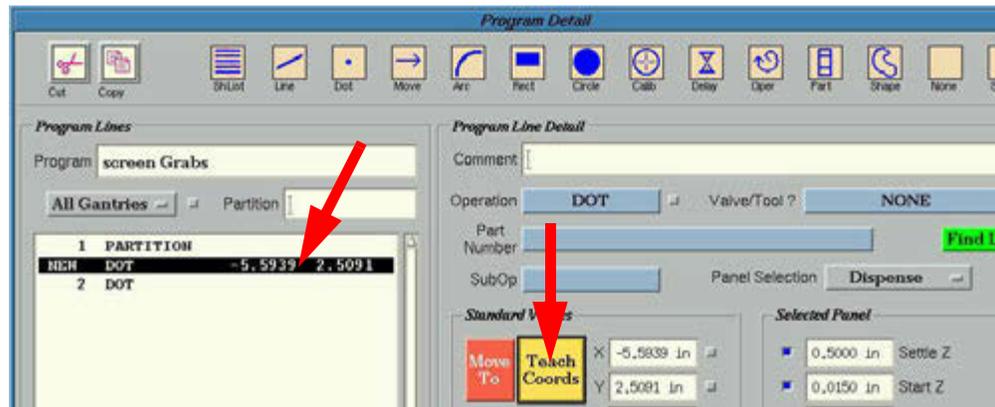
3. Enter a value in Auger Speed or Microvalve Speed, and then click APPLY to save your input.

**NOTE:** This procedure and the [Single Dot Guide](#) (pg 4.10) apply to all valve types, however, the guide focuses on building a dot using an auger type of valve. The parameters specific to a particular valve are Auger Speed for the LX Auger valve, and Micro-Valve Speed and Micro Valve Steps for the Micro-Dot valve.



4. Teach coordinates for the new dot:
  - a. Click TEACH COORDS. The Jog window displays.
  - b. Jog the camera to the point where the dot is to be dispensed.

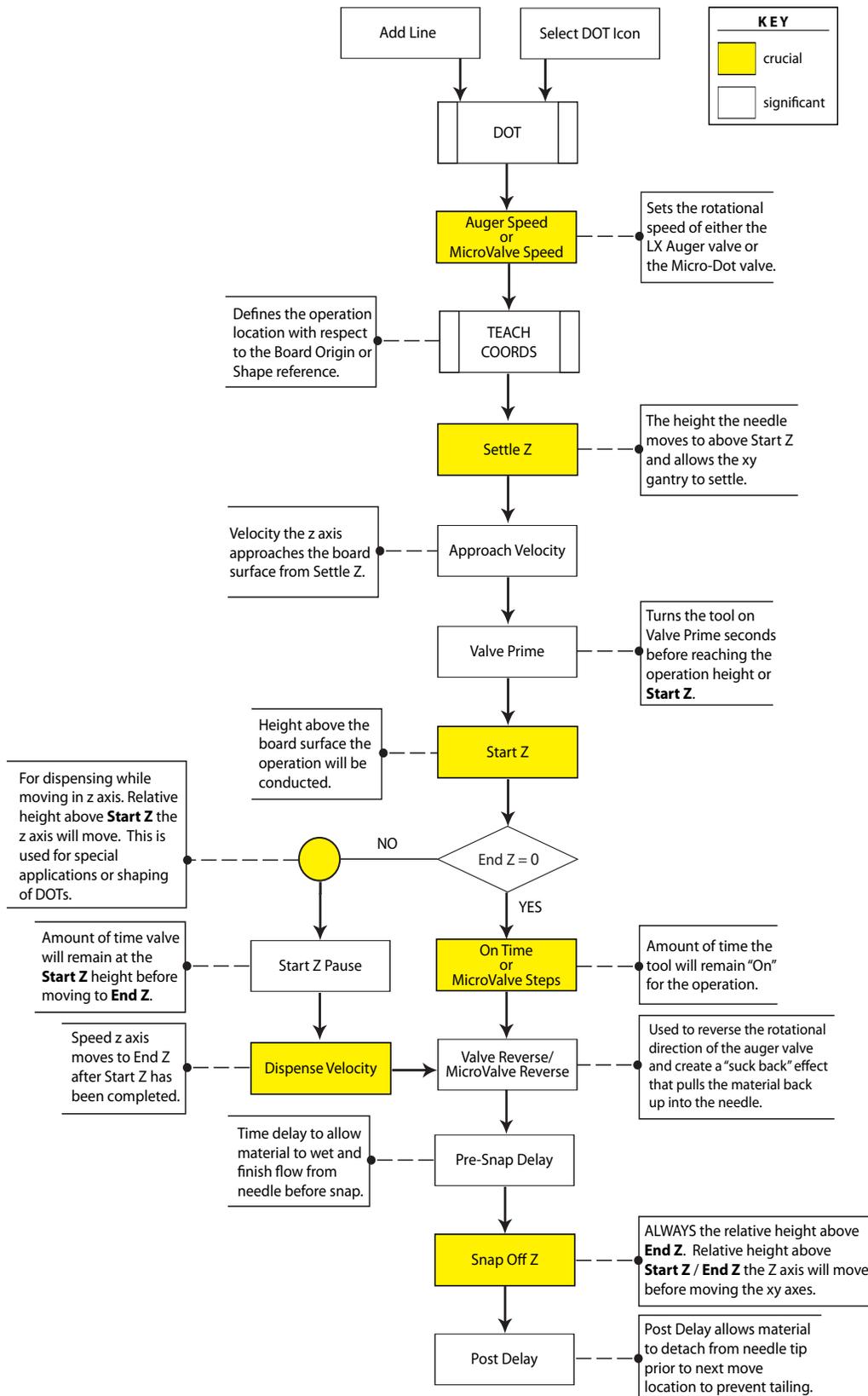
- c. Click OK in the Jog window. The resulting coordinates display in the new DOT program detail line.



5. Change any default parameter values not suitable for the new dot; parameters pertinent to a dot are located in the Dispense and Extra Controls [Selectable Panels](#) (pg 2.12). Use the [Single Dot Guide](#) (pg 4.10) to decide which parameter values to change for your new dot.

**NOTE:** For help deciding the value of **End Z**, refer to *End Z equals zero* and *End Z is not equal to zero* under [Dot](#) (pg 5.111).

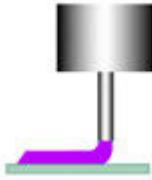
Figure 19: Single Dot Guide



6. Click APPLY to save your input, and then click DONE to return to the Program Editor.

This completes the creation of your new program detail line for a single dot.

## How to Program a Single Line Segment



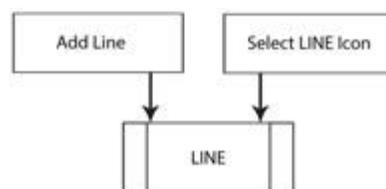
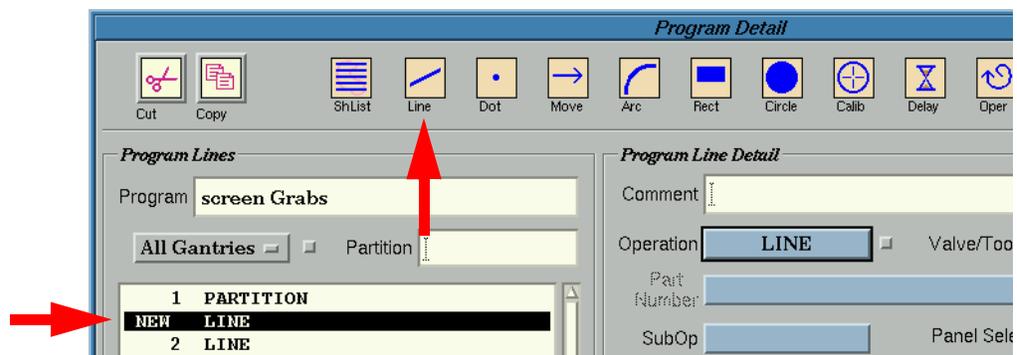
LINE is a primitive (preprogrammed routine) shape for which you may modify various parameters. LINE is used to move the valve to a specified height and keep the valve at that height for a specified x, y distance.

A LINE program detail line can dispense a single line or an array of lines.

To create a program detail line for a single line in a program or shape:

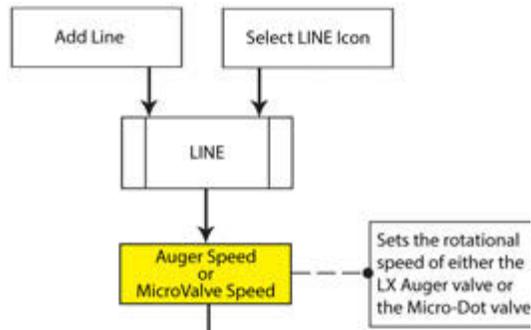
1. Open a program:
  - a. From the Program Editor, select either an existing program (or shape) or create a new program (or shape).
  - b. Select the appropriate choice: Edit Programs or Edit Shapes.
  - c. Open Program Detail by clicking on EDIT DETAIL LINES.
2. Add a LINE program detail line:
  - a. Position the cursor so it highlights the program line that will precede your new LINE program line.
  - b. Click on either the LINE icon (located at the top of the window) or the ADD LINE button. If you choose to click ADD LINE, the Select List of operation choices displays; select LINE and then click ACCEPT.

In both cases, a new LINE program detail line displays in the Program Lines pane with a designation of NEW next to it.



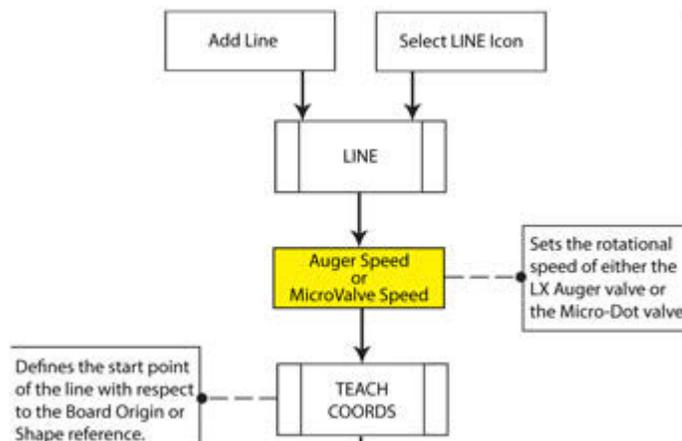
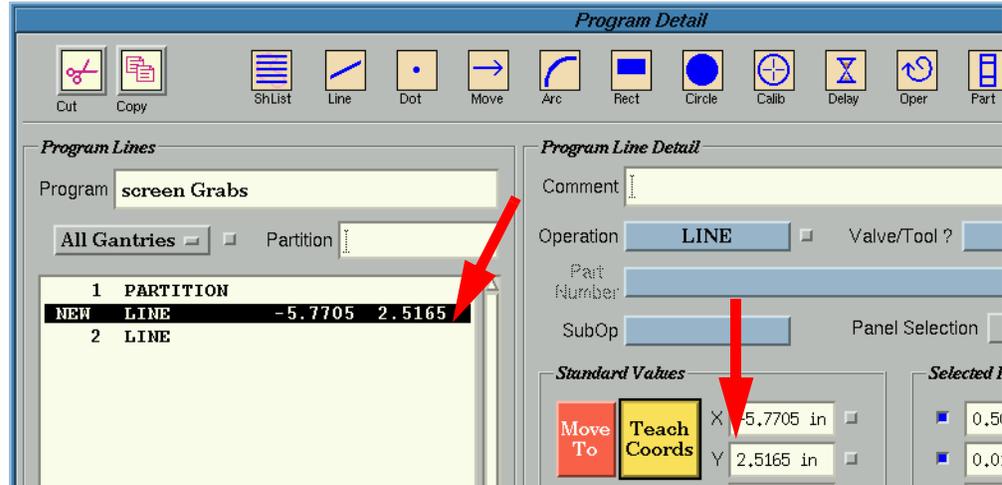
- c. Click APPLY to save your input.
3. Enter a value in Auger Speed or Microvalve Speed, and then click APPLY to save your input.

**NOTE:** This procedure and the [Single Line Segment Guide](#) (pg 4.15) apply to all valve types, however, the guide focuses on building a line using an auger type of valve. The parameters specific to a particular valve are Auger Speed for the LX Auger valve, and MicroValve Speed and Micro Valve Steps for the Micro-Dot valve.



4. Teach coordinates for the new line:
  - a. Click TEACH COORDS. The Jog window displays.
  - b. Jog the camera to the point where the start of the rectangle is to be dispensed.

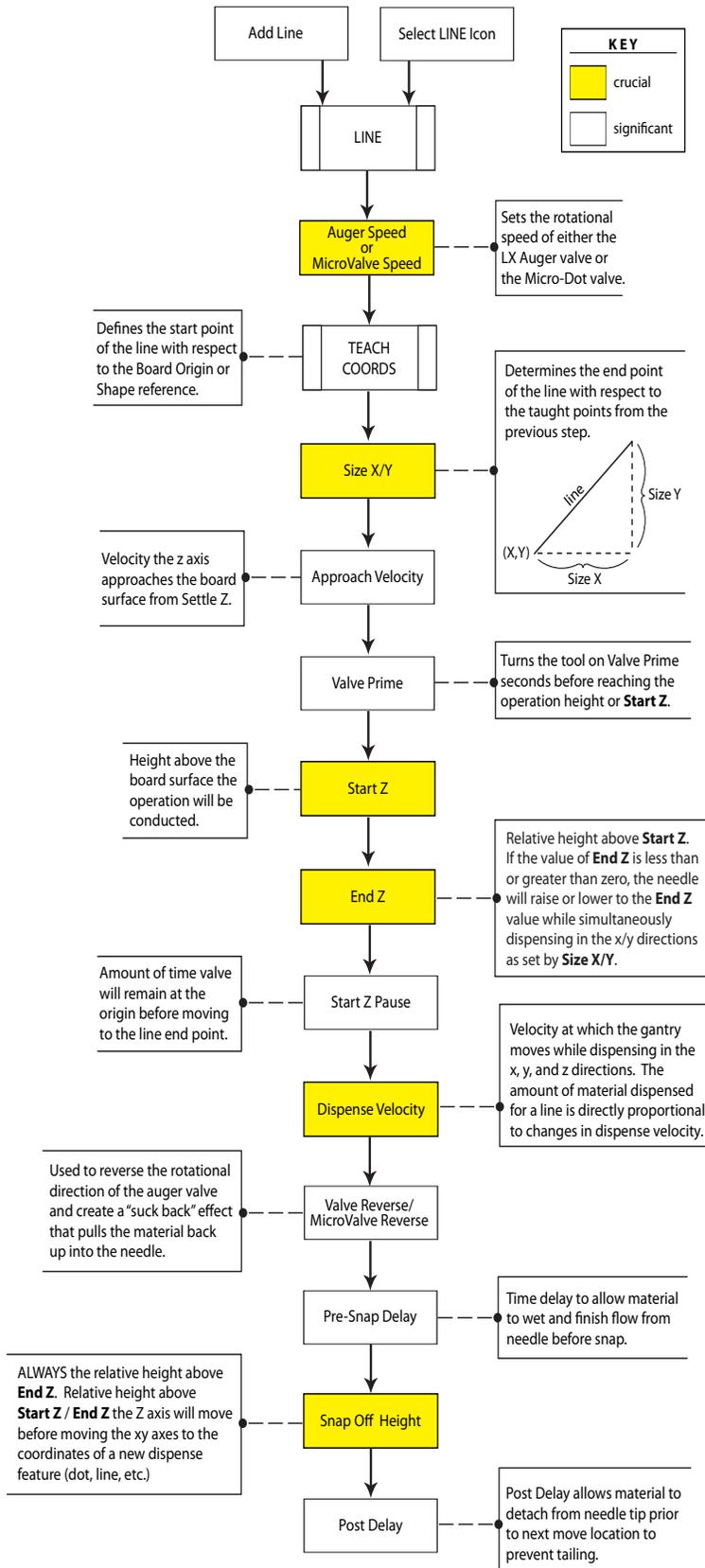
- c. Click OK in the Jog window. The resulting coordinates display in the new LINE program detail line.



5. Change any default parameter values not suitable for the new line; parameters pertinent to a line are located in the Dispense and Extra Controls [Selectable Panels](#) (pg 2.12). Use the [Single Line Segment Guide](#) (pg 4.15) to decide which parameter values to change for your new line.

**NOTE:** For an explanation of what happens during a single line dispense motion, refer to [Lines](#) (pg 3.22).

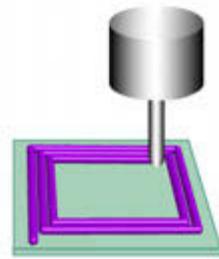
Figure 20: Single Line Segment Guide



6. Click APPLY to save your input, and then click DONE to return to the Program Editor.

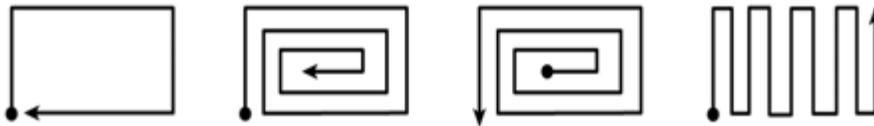
This completes the creation of your new program detail line for a single line.

## How to Program an Area Fill (Rectangle)



RECTANGLE is typically used as the area fill operation. RECTANGLE is a primitive (preprogrammed routine) shape for which you may modify various parameters. A RECTANGLE program detail line can dispense a single area fill or an array of area fills.

RECTANGLE is used to move the valve to a specified height and keep the valve at that height while conducting a fill over a specified x, y size. RECTANGLE may have a hollow, concentric, or zigzag fill.

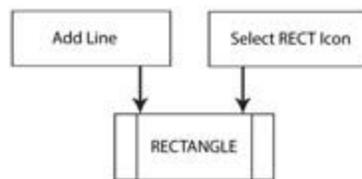
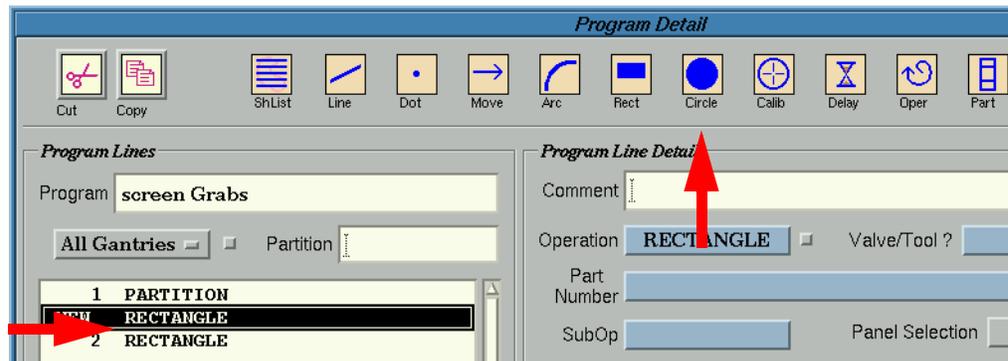


**NOTE:** For a detailed explanation of what happens during a RECTANGLE dispense motion, refer to [Rectangle](#) (pg 5.113).

To create a program detail line for an area fill:

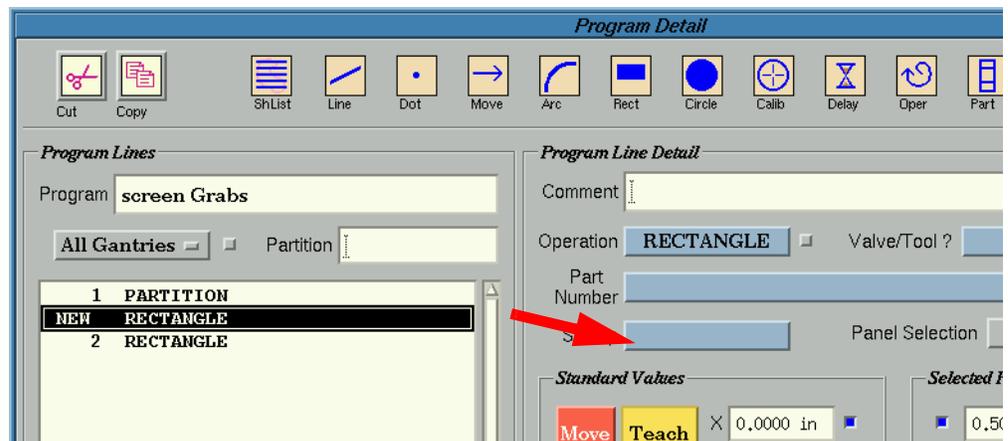
1. Open a program:
  - a. From the Program Editor, select either an existing program (or shape) or create a new program (or shape).
  - b. Select the appropriate choice: Edit Programs or Edit Shapes.
  - c. Open Program Detail by clicking on EDIT DETAIL LINES.
2. Add a RECTANGLE program detail line:
  - a. Position the cursor so it highlights the program line that will precede your new RECTANGLE program line.
  - b. Click on either the RECTANGLE icon (located at the top of the window) or the ADD LINE button. If you choose to click ADD LINE, the Select List of operation choices displays; select RECTANGLE and then click ACCEPT.

In both cases, a new RECTANGLE program detail line displays in the Program Lines pane with a designation of NEW next to it.

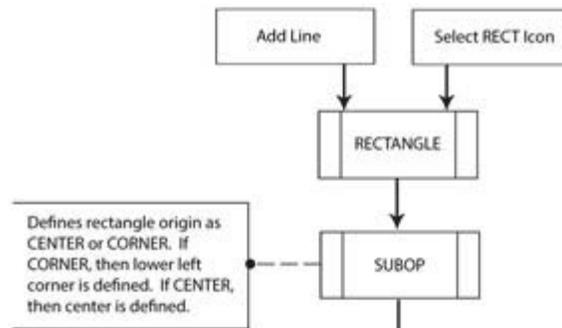
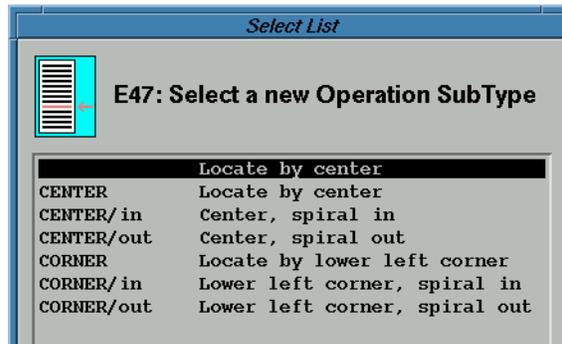


c. Click APPLY to save your input.

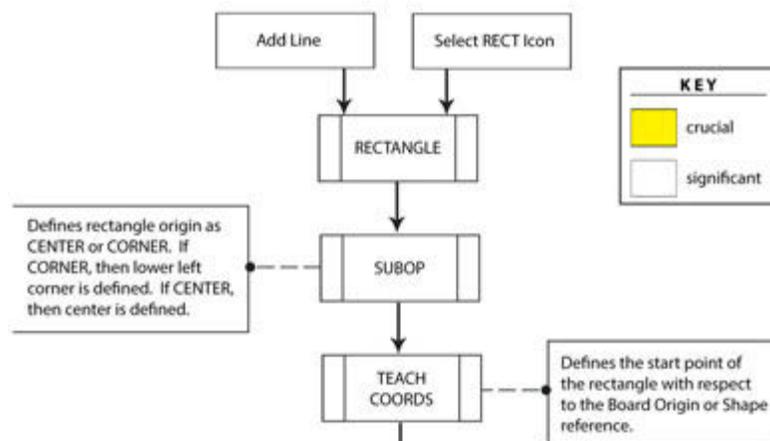
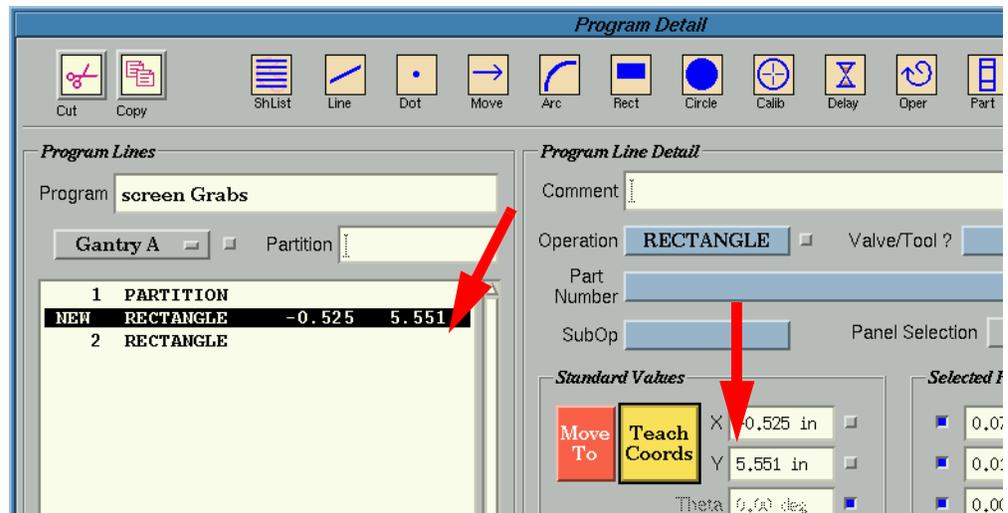
3. Choose an area fill sub-operation:
  - a. Click the SUBOP button.



- b. Select a subop from the list of RECTANGLE subops that displays and then click ACCEPT.

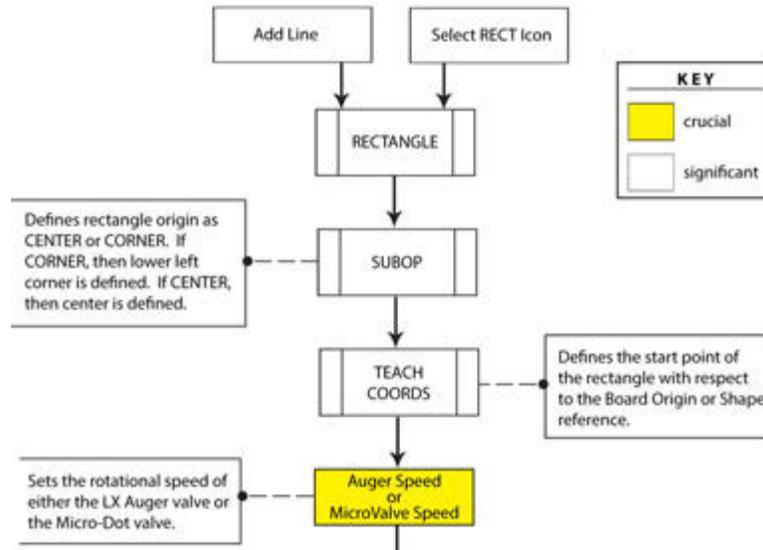


4. Teach coordinates for the new area fill:
  - a. Click TEACH COORDS. The Jog window displays.
  - b. Jog the camera to the point where the rectangle is to be dispensed.
  - c. Click OK in the Jog window. The resulting coordinates display in the new RECTANGLE program detail line.



- Enter a value in Auger Speed or Microvalve Speed and then click APPLY to save your input.

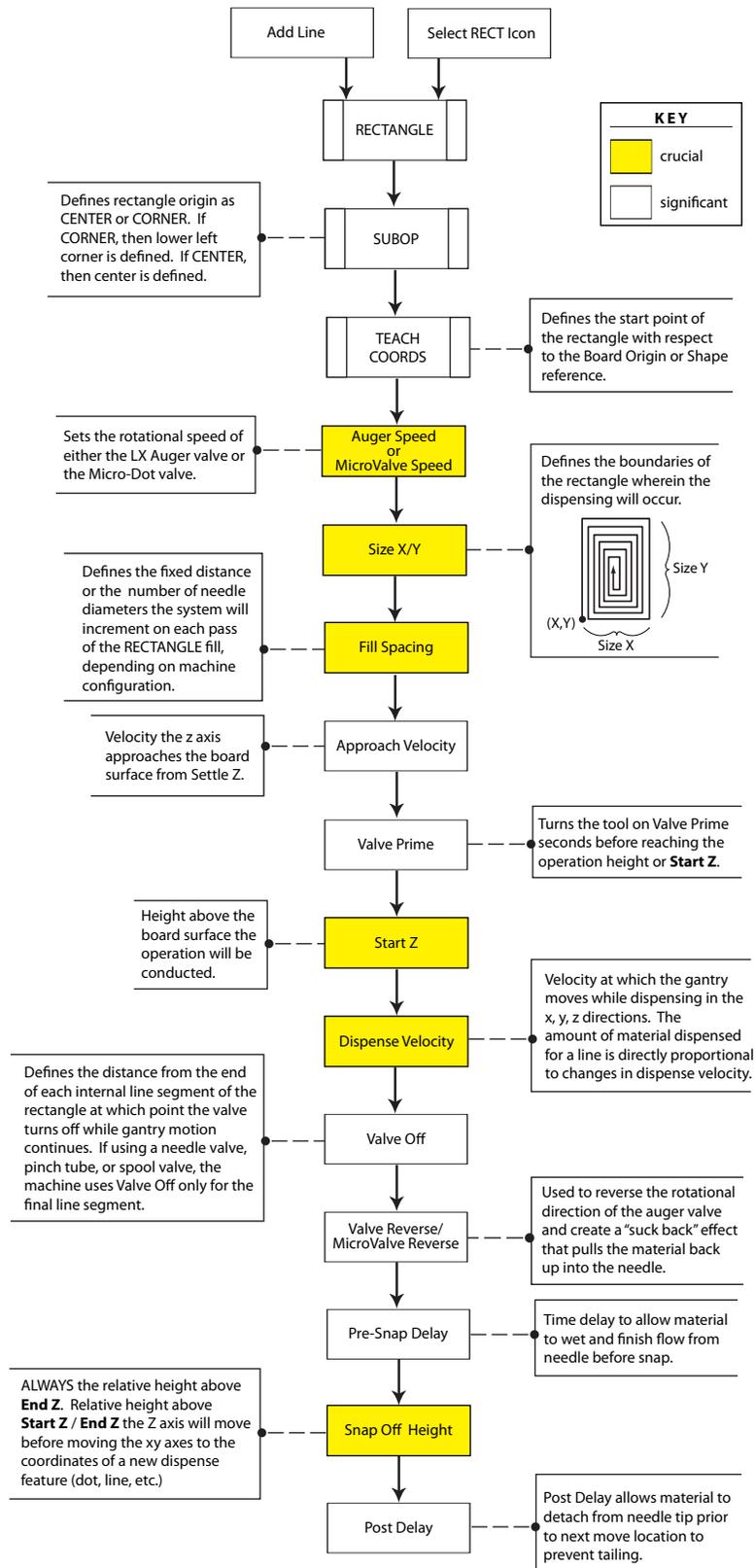
**NOTE:** This procedure and the [Area Fill Guide](#) (pg 4.22) apply to all valve types, however, the guide focuses on building an area fill using an auger type of valve. The parameters specific to a particular valve are Auger Speed for the LX Auger valve, and MicroValve Speed and Micro Valve Steps for the Micro-Dot valve.



- Change any default parameter values not suitable for the new area fill; parameters pertinent to an area fill are located in the Dispense and Extra Controls [Selectable Panels](#) (pg 2.12). Use the [Area Fill Guide](#) (pg 4.22) to decide which parameter values to change for your new area fill.

**NOTE:** Many variables affect the outcome of an area fill dispense. For additional insights, refer to [Helpful Hints for Area Fills](#) (pg 4.23).

Figure 21: Area Fill Guide



7. Click APPLY to save your input, and then click DONE to return to the Program Editor.

This completes the creation of your new program detail line for an area fill.

## Helpful Hints for Area Fills

### Continuous Moves

---

Rectangles, circles, and arcs can all be specified as Middle moves and can be used both in conjunction with each other and with other Moves for continuous dispensing.

### Rotation

---

**CENTER/in** and **CENTER/out** are the preferred RECTANGLE subops when rotation is to be used.

### Valve Off

---

When using a Needle valve to dispense an area fill, the Valve Off parameter shuts off the valve at the Valve Off distance prior to finishing the **final** line of the rectangle. Alternatively, when used with any other type of valve, Valve Off shuts off the valve at the Valve Off distance prior to finishing **every** line segment in the rectangle.

### Undersized or Shifting Area Fill

---

Using the **CENTER/out** RECTANGLE subop may generate a smaller than expected area fill or an area fill that appears to have shifted. Making adjustments to **Size X,Y** and **Fill Spacing** will remedy these problems.

If the final dispense pass would exceed the area fill boundaries then either the final pass is not dispensed, resulting in an undersized rectangle or only half of the final pass is dispensed, resulting in a rectangle that is both undersized and appears to have shifted as well.

### Avoid Voids

---

Using a **CORNER/in** or **CENTER/in** RECTANGLE subop may generate an area fill with a void in the center. Slight adjustments to either **Size X,Y** or **Fill Spacing** will remedy this problem in most cases.

### Gantry Motion

---

- *Dampen the intensity* of the gantry movement created during rectangle dispenses by using the **Standard Acceleration** parameter [located in the [Mounts/Material Editor](#) (pg 5.59) window under the Process selectable panel].
- *Erratic gantry motion* may occur if an End move control command is missing. An End command must be used after the use of a Middle move control command, especially with rectangles. Refer to [Move Controls](#) (pg 3.46).

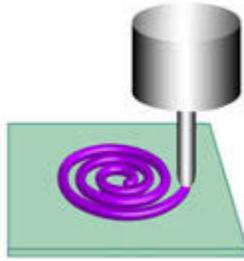
### **Seldom Used Parameters**

---

**End Z** is used only for the last line segment of an area fill. Alas, you cannot use this field to build pyramids.

**Start Z Pause** is not used with area fills since the pause would be applied to the start point of every line segment in the rectangle.

## How to Program a Circle



CIRCLE is a primitive (preprogrammed routine) shape for which you may modify various parameters. A CIRCLE program detail line can dispense a circle, ring, or an array of circles or rings.

CIRCLE is used to move the valve to a specified height and keep the valve at that height while dispensing a ring or filled circle over a specified x, y diameter.

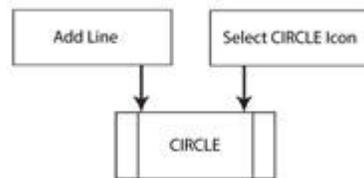
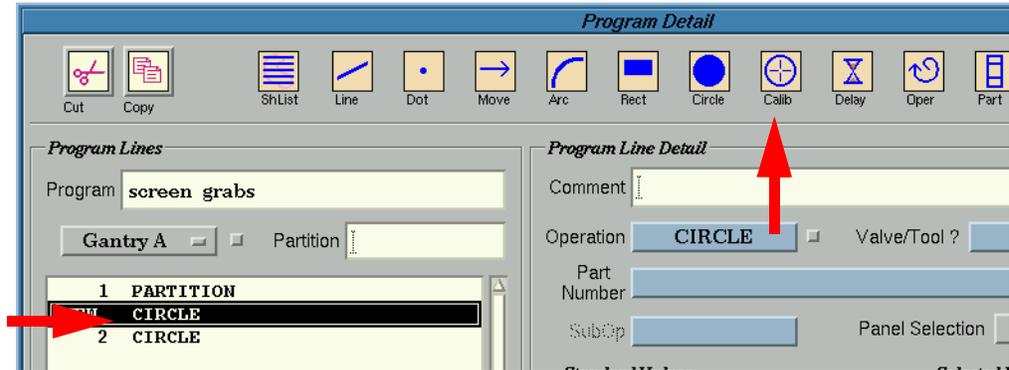
You have the choice of tracing a figure from either minor-to-major diameter (spiral outward) or from major-to-minor diameter (spiral inward). Spiral direction is based on the relationship of start and end diameter values entered in the Start Dia and End Dia fields.



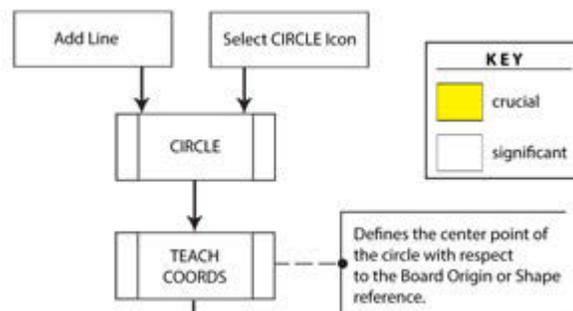
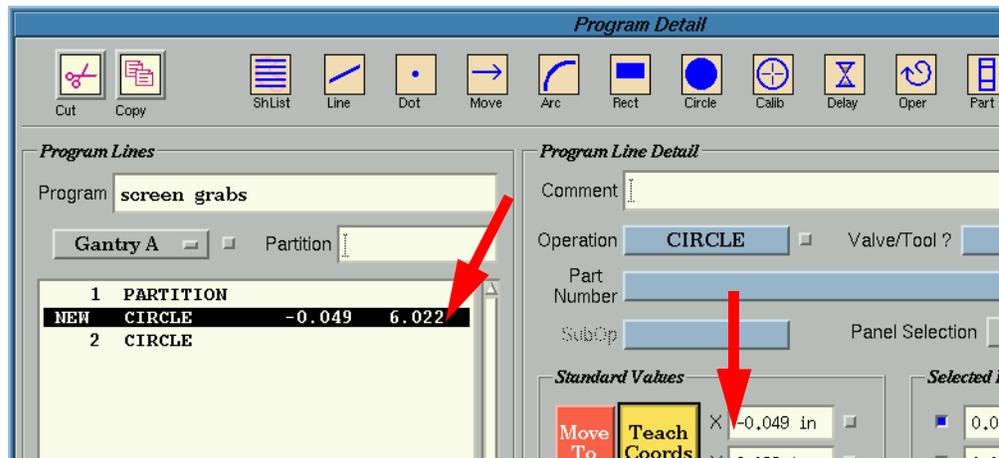
To create a program detail line for a circle:

1. Open a program:
  - a. From the Program Editor, select either an existing program (or shape) or create a new program (or shape).
  - b. Select the appropriate choice: Edit Programs or Edit Shapes.
  - c. Open Program Detail by clicking on EDIT DETAIL LINES.
2. Add a CIRCLE program detail line:
  - a. Position the cursor so it highlights the program line that will precede your new CIRCLE program line.
  - b. Click on either the CIRCLE icon (located at the top of the window) or the ADD LINE button. If you choose to click ADD LINE, the Select List of operation choices displays; select CIRCLE and then click ACCEPT.

In both cases, a new CIRCLE program detail line displays in the Program Lines pane with a designation of NEW next to it.

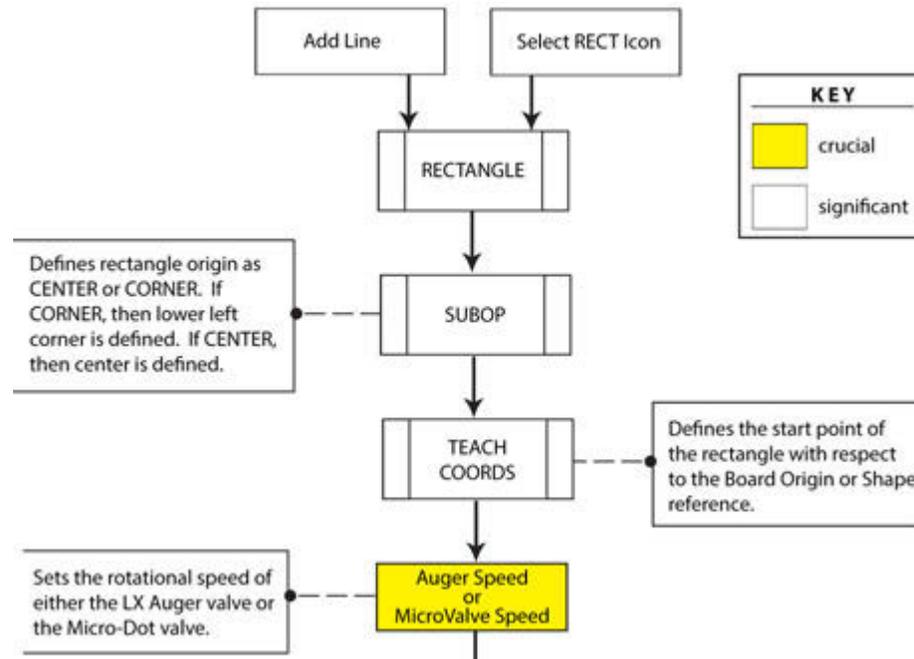


- c. Click APPLY to save your input.
- 3. Teach coordinates for the new circle:
  - a. Click TEACH COORDS. The Jog window displays.
  - b. Jog the camera to the point where the center of the circle is to be located.
  - c. Click OK in the Jog window. The resulting coordinates display in the new CIRCLE program detail line.



- Enter a value in Auger Speed or Microvalve Speed and then click APPLY to save your input.

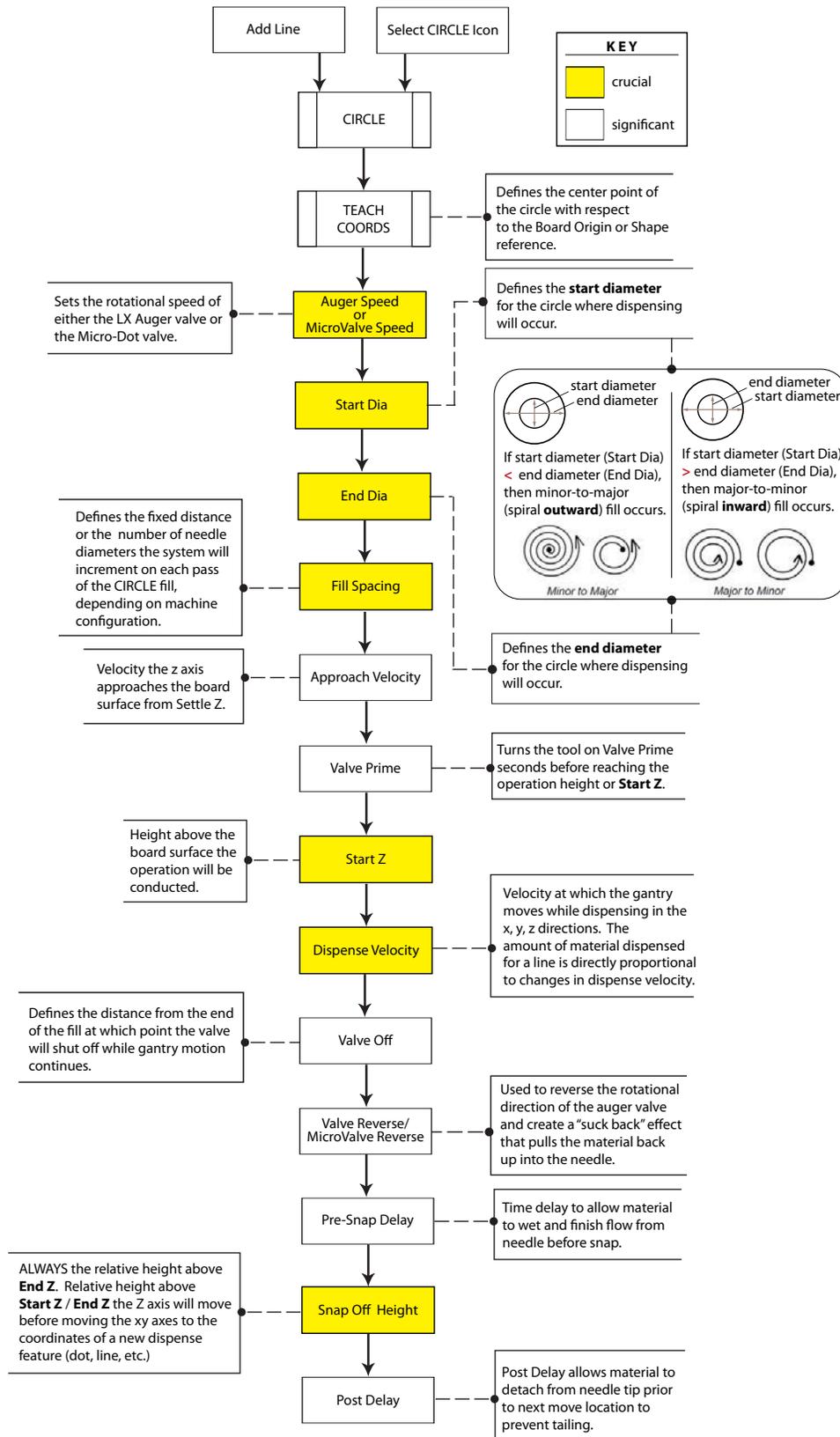
**NOTE:** This procedure and the [Circle Guide](#) (pg 4.28) apply to all valve types, however, the guide focuses on building a circle using an auger type of valve. The parameters specific to a particular valve are Auger Speed for the LX Auger valve, and MicroValve Speed and Micro Valve Steps for the Micro-Dot valve.



- Change any default parameter values not suitable for the new circle; parameters pertinent to a circle are located in the Dispense and Extra Controls [Selectable Panels](#) (pg 2.12). Use the [Circle Guide](#) (pg 4.28) to decide which parameter values to change for your new circle.

**NOTE:** Many variables affect the outcome of a circle dispense. For additional insights, refer to [Helpful Hints for Circles](#) (pg 4.29).

Figure 22: Circle Guide



6. Click APPLY to save your input, and then click DONE to return to the Program Editor.

This completes the creation of your new program detail line for a circle.

## Helpful Hints for Circles

### Continuous Moves

---

Circles, rectangles, and arcs can all be specified as Middle moves and can be used both in conjunction with each other and with other Moves for continuous dispensing.

### Rotation

---

The *start* point of an *inward* spiraling circle or the *end* point of an *outward* spiraling circle can be rotated using the Object Rotation parameter.

### Avoid Voids

---

Using minor-to-major circle fills with higher viscosity materials may help reduce voids.

### Avoid Excess Material

---

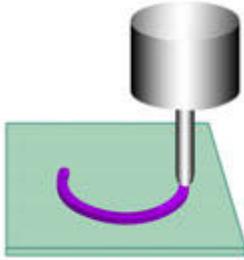
Using major-to-minor circle fills with lower viscosity materials will reduce the chance of material flowing over the top of the die during placement.

### Gantry Motion

---

*Dampen the intensity* of the gantry movement created while dispensing circles by using the **Standard Acceleration** parameter [located in the [Mounts/Material Editor](#) (pg 5.59) window under the Process selectable panel].

## How to Program an Arc



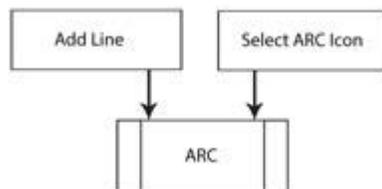
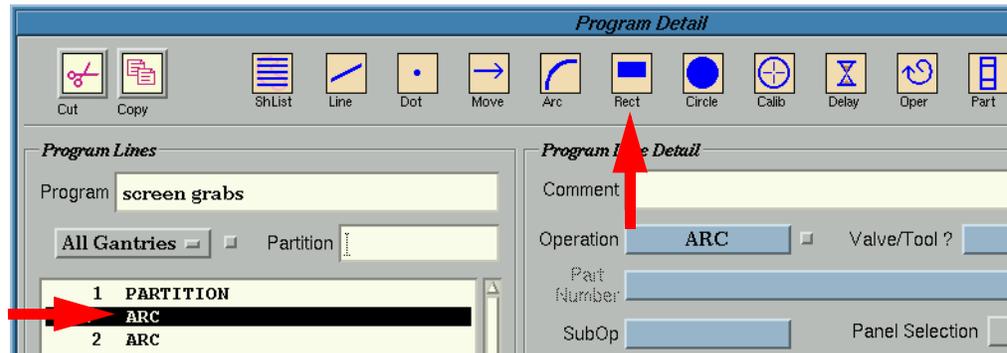
ARC is a primitive (preprogrammed routine) shape for which you may modify various parameters. An ARC program detail line can dispense a single circular arc or an array of arcs. ARC is used to move the valve to a specified height and keep the valve at that height while dispensing an arc over a specified x, y diameter.

There are two types of arcs from which to choose: a 3-point arc and a relative arc. The 3-point arc is the most commonly used type of arc and is created by defining start, middle, and end points. The relative type of arc is rarely used; it uses a center, angle, and start point.

To create a program detail line for a 3-point arc:

1. Open a program:
  - a. From the Program Editor, select either an existing program (or shape) or create a new program (or shape).
  - b. Select the appropriate choice: Edit Programs or Edit Shapes.
  - c. Open Program Detail by clicking on EDIT DETAIL LINES.
2. Add an ARC program detail line:
  - a. Position the cursor so it highlights the program line that will precede your new ARC program line.
  - b. Click on either the ARC icon (located at the top of the window) or the ADD LINE button. If you choose to click ADD LINE, the Select List of operation choices displays; select ARC and then click ACCEPT.

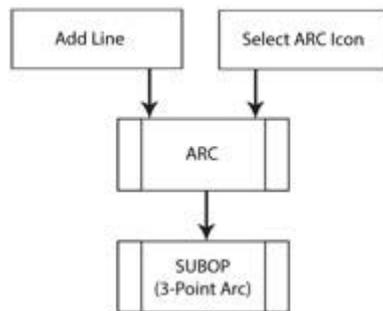
In both cases, a new ARC program detail line displays in the Program Lines pane with a designation of NEW next to it.



c. Click APPLY to save your input.

3. Click on the SubOp button and select 3-Point Arc.

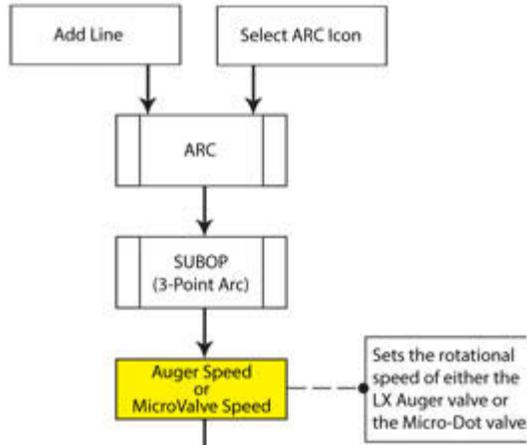
**NOTE:** This procedure focuses on the more commonly used 3-Point Arc. The rarely used Relative Arc is not addressed here.



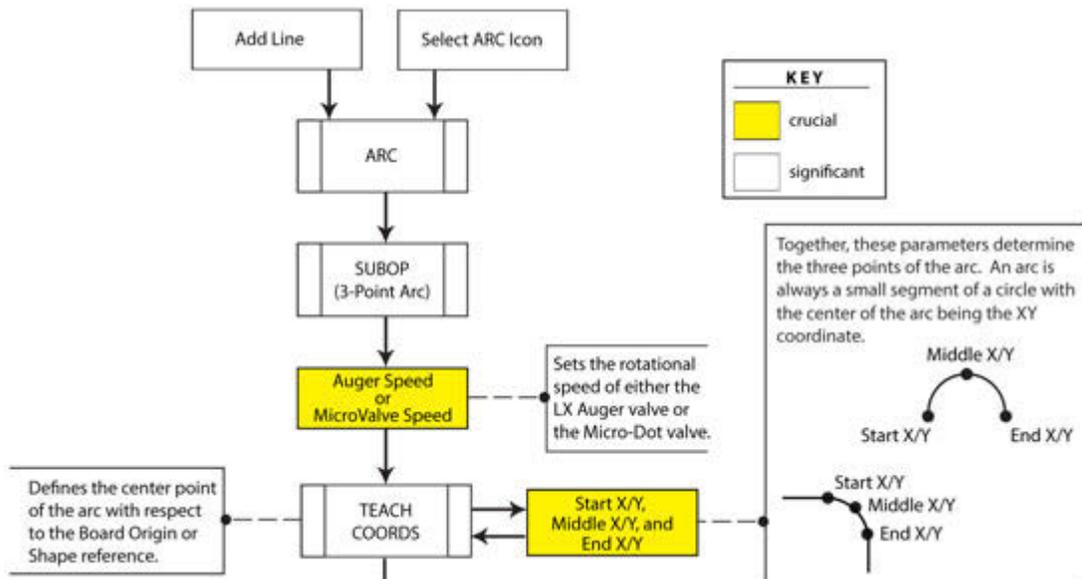
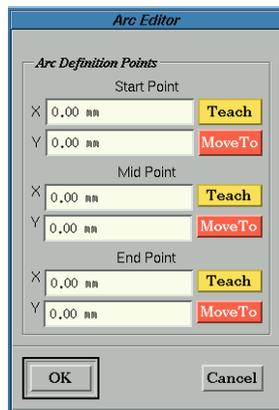
4. Enter a value in Auger Speed or Microvalve Speed and then click APPLY to save your input.

**NOTE:** This procedure and the [3-Point Arc Guide](#) (pg 4.35) apply to all valve types, however, the guide focuses on building an arc using an auger type of valve. The param-

eters specific to a particular valve are Auger Speed for the LX Auger valve, and Micro-Valve Speed and Micro Valve Steps for the Micro-Dot valve.



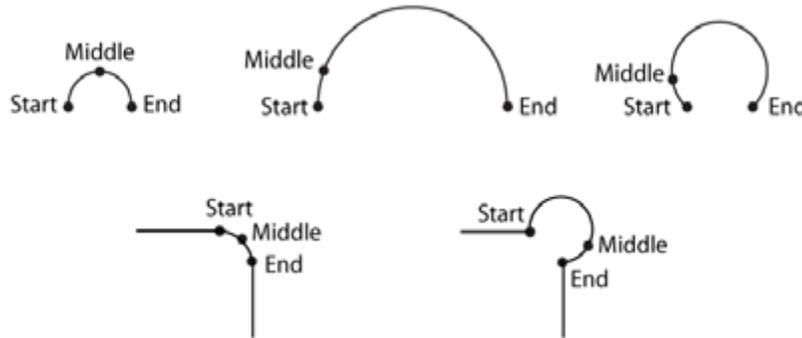
5. Teach coordinates for the new arc:
  - a. Click TEACH COORDS. The Arc Editor displays. You will use this window to teach the three points of the arc. Keep in mind that the arc must pass through each of the three points you will teach.



- b. Click the TEACH button next to **Start Point**, jog the camera to the coordinates where you want the beginning of the arc to be located, and then click OK.
- c. Repeat the same process for both **Mid Point** and **End Point**.

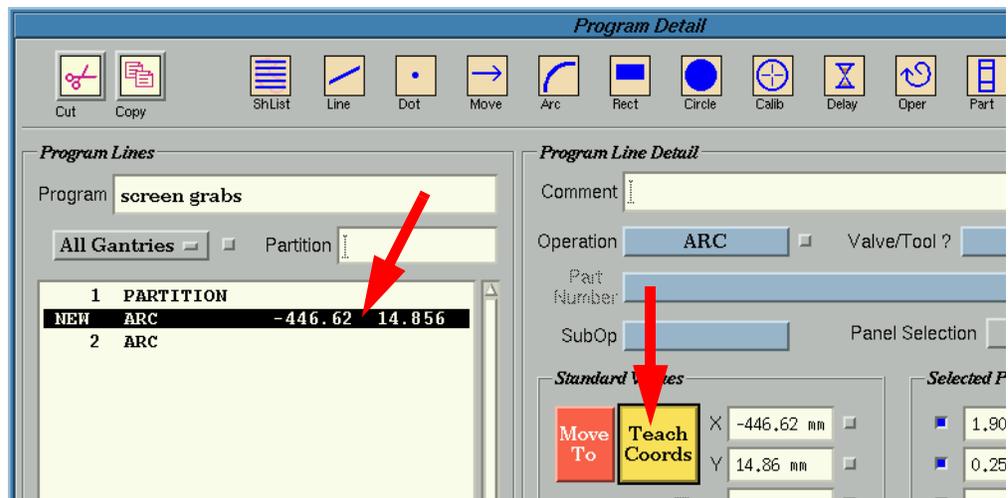


**IMPORTANT:** The location you choose for the Mid Point is key to obtaining expected results.

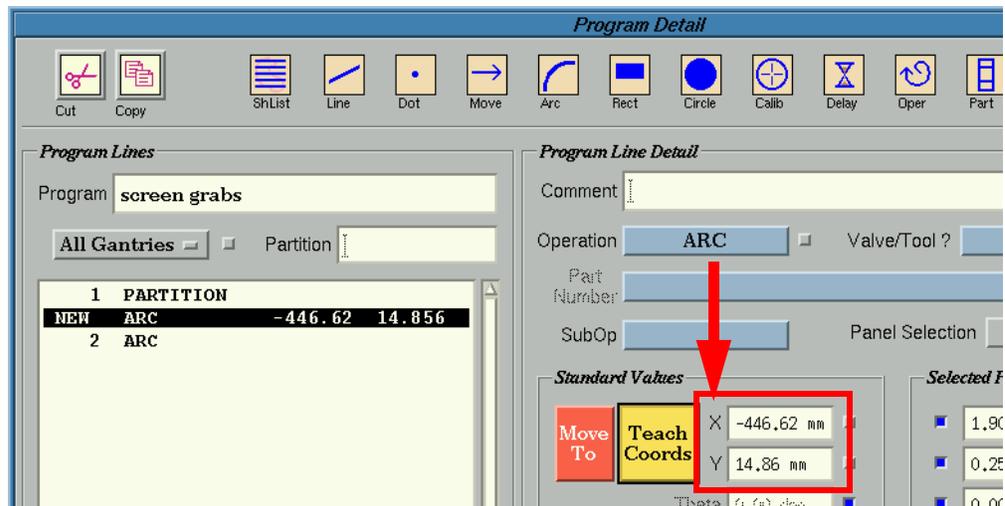
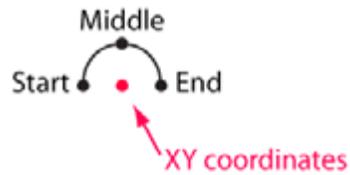


**NOTE:** Arc acceleration and deceleration will be affected slightly by the interpolation of the arc angle. Velocity is not constant throughout an arc dispense. Velocity will slow slightly at each end of the arc.

- d. After all three points have been taught, click OK in the Arc Editor window. Coordinates display in the new ARC program detail line.



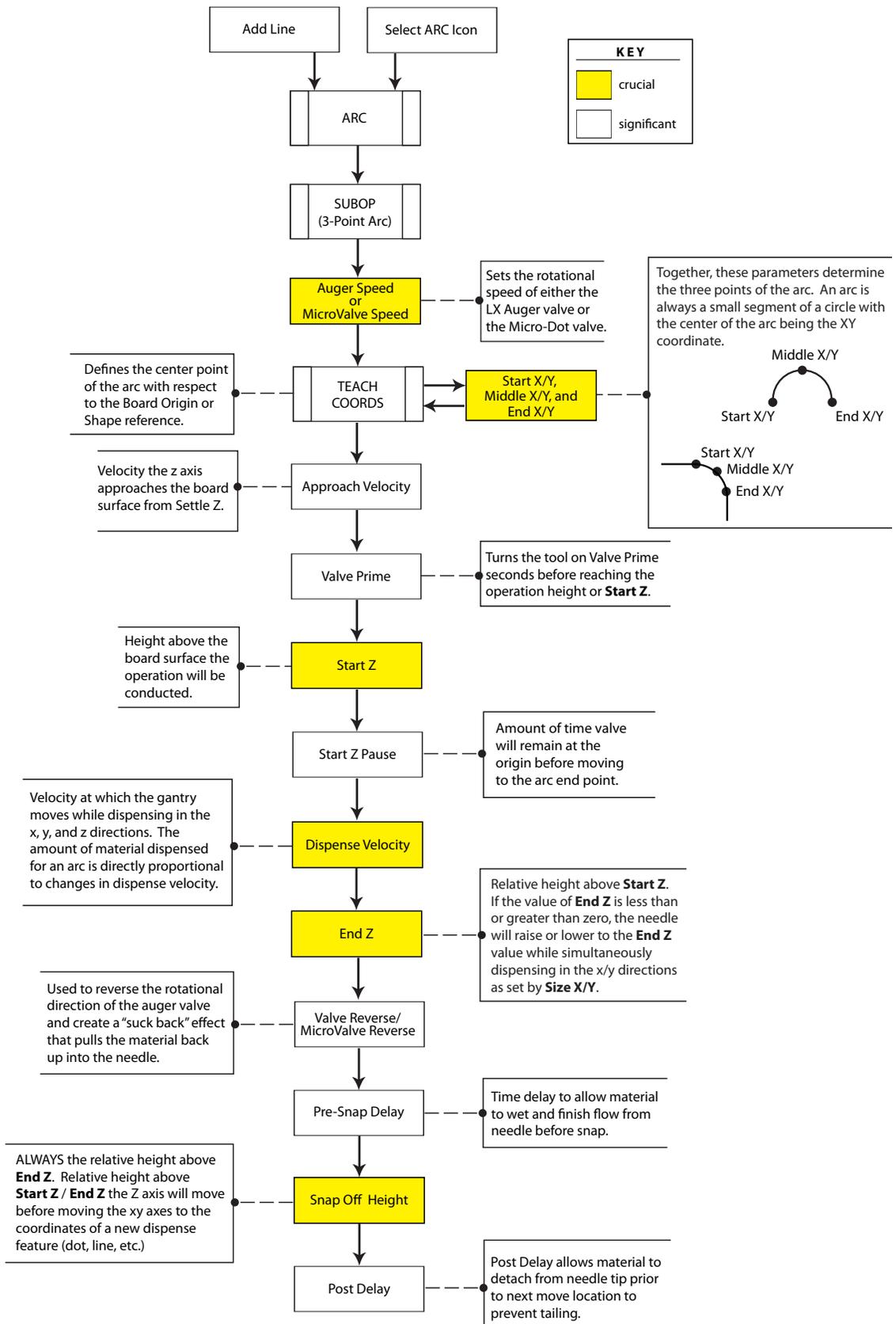
- e. Notice that the actual XY coordinates for the arc that display in the XY fields are located midway between the Start Point and the End Point, in what would be the center of the circle if you were to make the arc into a complete circle.



6. Change any default parameter values not suitable for the new arc; parameters pertinent to an arc are located in the Dispense and Extra Controls [Selectable Panels](#) (pg 2.12). Use the [3-Point Arc Guide](#) (pg 4.35) to decide which parameter values to change for your new arc.

**NOTE:** For tips about arc dispensing, refer to [Helpful Hints for Arcs](#) (pg 4.36).

Figure 23: 3-Point Arc Guide



7. Click APPLY to save your input, and then click DONE to return to the Program Editor.

This completes the creation of your new program detail line for an arc.

## Helpful Hints for Arcs

### Continuous Moves

---

Arcs, circles, and rectangles can all be specified as Middle moves and can be used both in conjunction with each other and with other Moves for continuous dispensing.

### Rotation

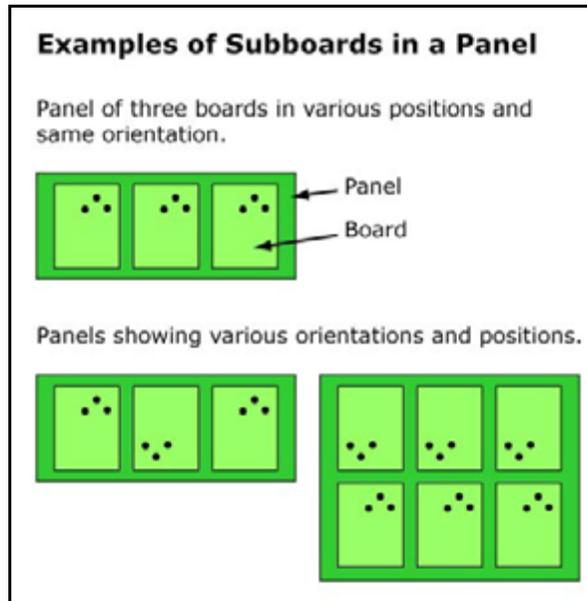
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The Start or End point positions of an arc can be rotated around its center point using the Object Rotation parameter.

## Creating a SubBoard Program

A subboard is one of a set of identical boards arranged into a single panel. All subboards within the set are identical except for position and possibly orientation.

A program describing a **single board**, with its own defined values for fiducial and origin location is converted into a program describing a **set of subboards in a panel**.



- [Why Subboards?](#) (pg 4.37)
- [Creating Subboards](#) (pg 4.38)
- [Teach Origin for New Subboard](#) (pg 4.41)

### Why Subboards?

Why use subboards when the same end result can be accomplished using shapes?

Subboards are more descriptive of a panel of multiple boards and can be generated more efficiently in a single pass. Also, a touch probe action occurs automatically for each subboard (unless suppressed); if using shapes, touch probe action does not occur unless programmed to do so.

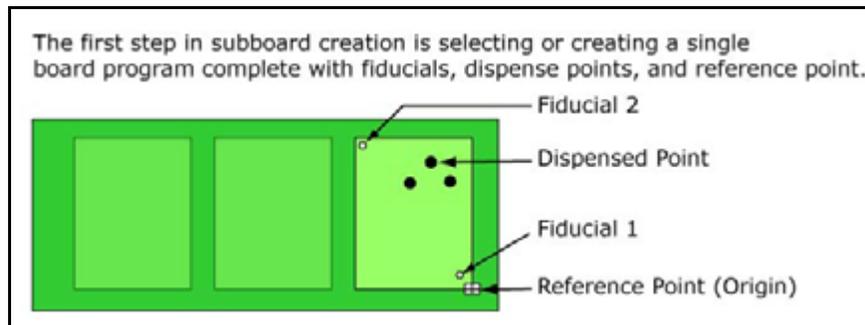
Refer also to [Shapes versus Subboards](#) (pg 3.50).

## Creating Subboards

By defining subboards for palletized or panelized boards, you will be converting an existing program for an individual board into a program for multiple subboards, each with a different origin. Before a subboard can be defined, a program line must be established.

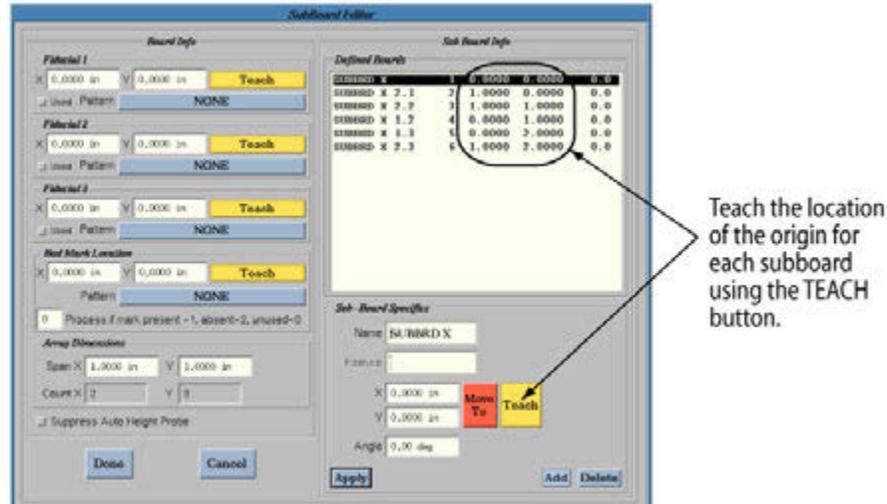
To create a subboard program:

1. In Program Editor, select or create a program for a **single board**. All aspects to be used to perform program operations should be defined because all program data defined now will be replicated later in each subboard program line during the conversion step.



2. Test the program to verify it produces expected results before using it as the basis for a subboards program.
3. Conversion transforms the original *single board* program into a *panel of subboards* program. To convert the program to subboards:
  - a. Verify the single board program is selected in Program Editor.
  - b. From the Program Editor menu bar, click Edit > Convert > Program-->Subboard.
  - c. Enter a name that will represent the new subboards. As you will see in the following step, a subboard program line with this new name is generated and displayed in Subboard Editor. (For example purposes, a name of SUBBRD X is used in the screen shot illustration.
4. Teach the origin of each new subboard. Details are listed here: [Teach Origin for New Subboard](#) (pg 4.41).

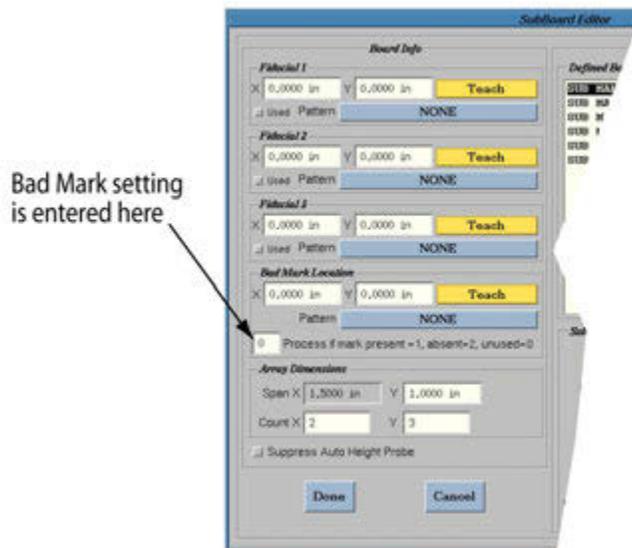
- The origin coordinates for each newly added line is (0,0). To teach the actual location coordinates, select a subboard line, click the TEACH button, and teach the location of the origin for that subboard. Repeat for each subboard.



- Optional: Set subboard bad marks.

### Subboard Bad Mark

The value you enter in the *bad mark process field* applies to all subboards, so it only needs to be entered once.



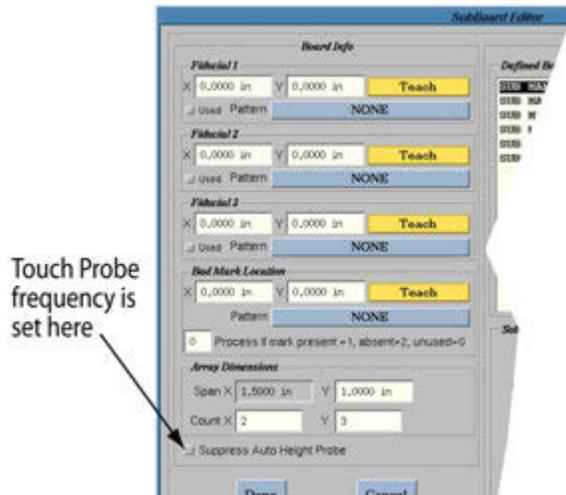
Choose and enter one of three values:

- To skip a board with a bad mark (process ignores bad mark), enter 0.
- To process board if a bad mark is present, enter 1.
- To process board if a bad mark is absent, enter 2.

- Optional: Change frequency of touch probe.

### Subboard Touch Probe Frequency

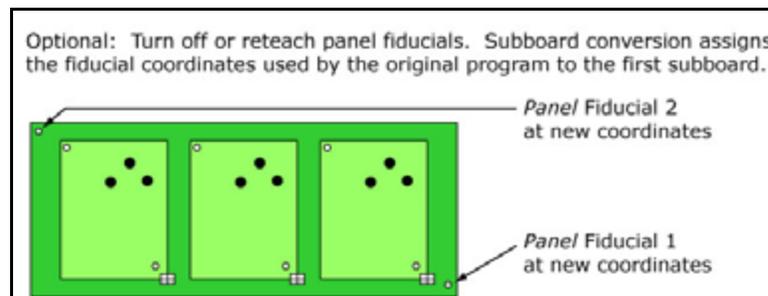
The choice you select for *Suppress Auto Height Probe* applies to all subboards, so it only needs to be entered once.



Choose whether the touch probe touches down on every subboard or just the first subboard.

- To activate the touch probe *on each subboard prior to processing*, turn OFF the Suppress Auto Height Probe box.
  - To activate the touch probe *only on the first subboard*, turn ON the Suppress Auto Height Probe box.
- Click APPLY to save the information and then click DONE to exit the SubBoard Editor.
  - OPTIONAL - Panel Origin: If the origin (reference point) coordinates of the actual panel differ from the (0,0) origin of the first subboard, go to the Program Editor and turn off or redefine the fiducials for the panel; **otherwise, the system will locate the fiducials twice in sequence on the first subboard** at the same coordinates - once as panel fiducials and again as subboard fiducials.

To avoid running the fiducials twice, either change the fiducials at the main level to true Panel fiducials or turn them off. When the program runs it will then only do the sub board fiducials.



- Click APPLY EDITS on Program Editor to save all changes made in Program Editor and any program line modifications made in Program Detail.
- Run the new subboard program to verify it operates as intended:

## Teach Origin for New Subboard

To teach the origin for a new subboard:

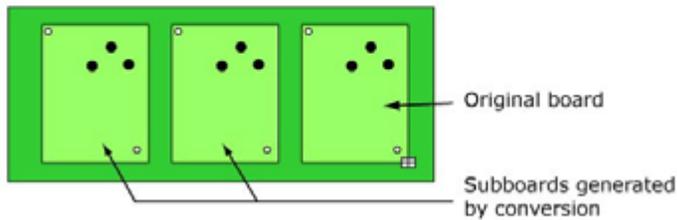
1. In the Program Editor, click the MODIFY SUB BOARDS button to open the SubBoard Editor.



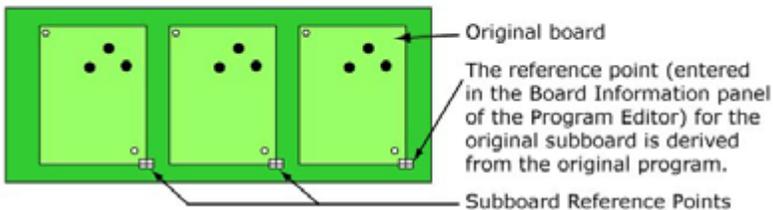
2. Choose one of the following alternatives for generating the origin coordinates of each subboard. Ultimately, orientation of each subboard will be defined in the subboard program line created for each subboard.

To Generate Subboard Lines:	Go to:
automatically using array dimensions	<a href="#">Generate Subboard Lines Automatically</a> (pg 4.42)
manually one at a time	<a href="#">Generate Subboard Lines Manually</a> (pg 4.43)
using a combination of the above methods	Perform <a href="#">Generate Subboard Lines Automatically</a> (pg 4.42) before proceeding to <a href="#">Generate Subboard Lines Manually</a> (pg 4.43).

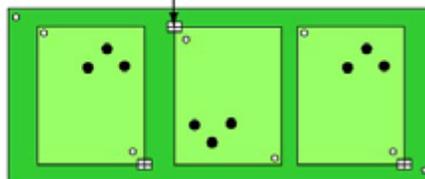
When a program is converted to subboards, fiducials are automatically generated with the subboards.



Teach the reference point (origin) for all but the original subboard.



**WHEN ROTATED:** If a board is presented in a rotated orientation (like the middle board shown at right), teach the rotated reference point in its rotated state.



## Generate Subboard Lines Automatically

Subboard lines can be generated automatically using Array Dimensions.

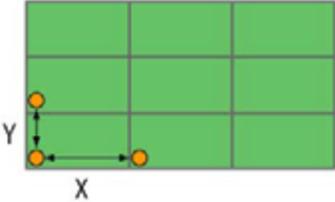
### Rules for Subboard Arrays

- Array creation erases and replaces all content within the Defined Boards panel of the Subboard Editor; therefore, only a single array can be generated at a time.
- After array creation, any single line can be modified, and single lines can be added one at a time at any point in the subboard program.

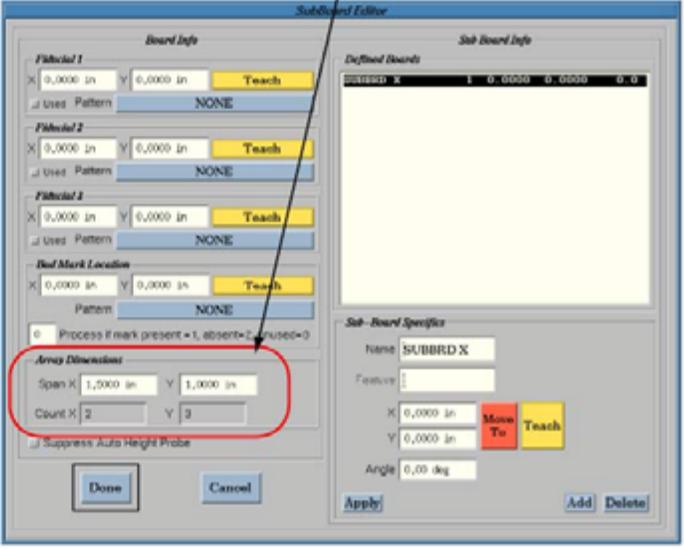
To generate subboard lines automatically using Array Dimensions:

1. Enter values in Span X and Y for the distance between a recognizable point on the board to another position; select positions that remain consistent from board to board. Then enter values in Count X and Y for the number of subboards in both directions.

First, measure actual distance from the same position in both X and Y directions from board-to-board. Negative values may be used.

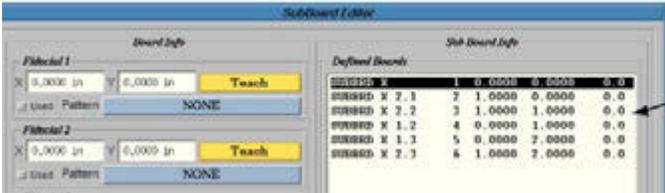


Then enter array data here



Distance X	Y	Distance Y	Angle
1	0.0000	0.0000	0.0

2. Click APPLY. Subboard line detail displays in the Defined Boards panel.



Subboard line detail generated by entry of array data.

Distance X	Y	Distance Y	Angle	
SUBBRD X 2.1	2	1.0000	0.0000	0.0
SUBBRD X 2.2	3	1.0000	1.0000	0.0
SUBBRD X 1.2	4	0.0000	1.0000	0.0
SUBBRD X 1.3	5	0.0000	2.0000	0.0
SUBBRD X 2.3	6	1.0000	2.0000	0.0

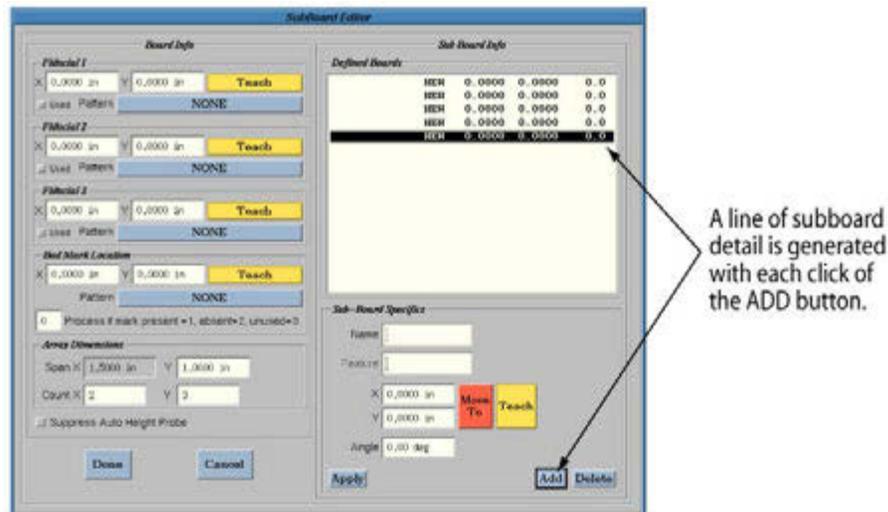
3. Choose one:
  - If no additional subboards need to be added, click DONE to exit SubBoard Editor and either resume with [Step 5 \(pg 4-39\)](#), or
  - If manually taught subboard lines are needed, continue with [Step \(pg 4-43\)](#).

## Generate Subboard Lines Manually

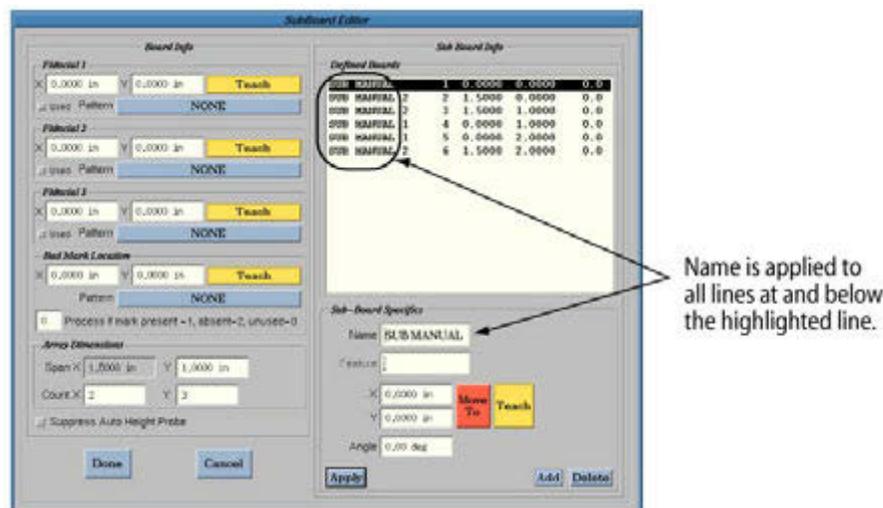
To manually teach the name, position, and angle of each subboard within the pallet:

1. In the Subboard Editor (opened by clicking MODIFY SUB BOARDS in Program Editor), click the ADD button once for each subboard in the pallet. This action creates a subboard program line for each subboard.

For example, if there are five subboards in the pallet, click ADD five times to create five new lines in the Defined Boards panel.



2. Select one of the subboard lines, enter a name for it, and click APPLY. The name will be applied to the highlighted line and all lines listed below it. The same name can be used for all the subboards. For example purposes, a name of SUB MANUAL is used in the screen shot.



## Creating a Pick & Place Program

### IN EFFECT AS OF FLOWare software version 2.8

To program for component pick and place applications, you will use two preprogrammed SubOps (PICK and PLACE) with either a vacuum tool or a pick tool with either vacuum or a gripper.

- [Requirements](#) (pg 4.44)
- [PICK & PLACE SubOps](#) (pg 4.45)
- [Programming Pick & Place](#) (pg 4.46)

## Requirements

The following tools and program elements are required when programming for pick and place applications:

### Physical Tools

- Pick Tool equipped with either a gripper and/or vacuum and release blow-off and/or eject
- (Optional) Force Feedback tool (with load cell) for component placement

### Program Elements

- Shapes
- Fixed Locations
- [PICK & PLACE SubOps](#)
- Vision Patterns

### Inputs & Outputs (I/O)

- IO/Head1/PickCtrl           Used for gripper and/or vacuum generator
- IO/Head1/PickSense       Senses vacuum when component is picked
- IO/Head1/ReleaseCtrl      Turns on component blow-off air solenoid and/or a component eject tool

GPD - Edit I/O Configuration						
F1=Help	#1	ds.io.cfg	LINE:	COL:	INS	
IO/Head2/AugerSloRev:	Output	343	Normal	False	PseudoIODriver	
IO/Head2/ShutOff:	Output	344	Normal	False	PseudoIODriver	
IO/Head2/AirTurbine:	Dynamic	345	Normal	False	PseudoIODriver	
IO/Head2/Air:	Dynamic	346	Normal	False	PseudoIODriver	
IO/Head2/Syringe:	Output	347	Normal	False	PseudoIODriver	
IO/Head2/Needle:	Output	10030	Normal	False	FieldBusDriver	
IO/Head2/PumpDetectCtl:	Dynamic	349	Normal	False	PseudoIODriver	
IO/Head2/PWMOnTime:	Dynamic	350	Normal	False	PseudoIODriver	
IO/Head2/PWMOffTime:	Dynamic	351	Normal	False	PseudoIODriver	
IO/Head2/PWMFirstDotTime:	Dynamic	352	Normal	False	PseudoIODriver	
IO/Head2/EtchMotor:	Output	353	Normal	False	PseudoIODriver	
IO/Head2/NeedleTemp:	Input	11016	Normal	False	FieldBusDriver	
IO/Head2/Mat1Temp:	Input	355	Normal	False	PseudoIODriver	
IO/Head2/NeedleTempCtl:	Output	10031	Normal	False	FieldBusDriver	
IO/Head2/Mat1TempCtl:	Output	357	Normal	False	PseudoIODriver	
IO/Head2/PiggyBack:	Output	10007	Normal	False	FieldBusDriver	
IO/Head2/DebrisVac:	Output	359	Normal	False	PseudoIODriver	
IO/Head2/PickupCtl:	Output	360	Normal	False	PseudoIODriver	
IO/Head2/PickupSense:	Input	361	Normal	False	PseudoIODriver	
IO/Head2/ReleaseCtl:	Output	362	Normal	False	PseudoIODriver	
IO/Head2/LevelDetect:	Input	363	Invert	False	PseudoIODriver	
IO/Head2/LowSense:	Input	364	Normal	False	PseudoIODriver	
IO/Head2/AltSense:	Input	365	Normal	False	PseudoIODriver	
IO/Head2/FlowCutOff:	Input	366	Normal	False	PseudoIODriver	



**CAUTION:** Only qualified service personnel or advanced programmers should access inputs and outputs. If inputs and outputs are set incorrectly, the dispenser will not function properly.

## PICK & PLACE SubOps

### PICK SubOp Routine

---

The PICK SubOp uses a fixed location that can be set up to pick components from either a single feed, pallet array, or array of pallet arrays. Fiducials for the fixed location can be defined using patterns trained to the component intended to be picked. Fixed locations are independent of the location information for the board reference point.

A typical PICK SubOp routine:

1. If set up to do so, the pick tool moves to the programmed fixed location (XYZ) using fiducials and patterns.
2. From this position, the pick tool piggyback extends and indexes downward in the Z axis at Approach Velocity (set in Dispense panel of Program Detail) to the actual component in increments based on the values in Maximum Z Value and Retries.
3. After each index, the gripper and/or vacuum is turned on.
4. The system waits for the amount of time set in Operation Time (set in the Operate panel of Program Detail).
5. The system tests for vacuum pressure. Sufficient vacuum indicates a component is present or picked.
6. The pick tool retracts to End Z position at Dispense Velocity (set in Dispense panel).
7. The pick tool piggyback retracts while leaving the vacuum on, thus completing the PICK SubOp.

### PLACE SubOp routine

---

The PLACE SubOp places a picked component at a user-defined location based on fiducials and patterns that can be set in a shape.

A typical PLACE SubOp routine:

1. The touch probe activates to probe the work surface and then the gantry moves the pick tool to Settle Z.
2. The Pick tool releases the component at Start Z using Approach Velocity (set in Dispense panel of Program Detail).
3. If a Force Feedback tool is present, the gantry continues moving downward until the Force Feedback tool reaches Pressure Value (set in Operate panel).
4. Before releasing the component, the system performs a vacuum test to verify the component is indeed still present.
5. If the component is present, the pick tool places the component and disengages the gripper/vacuum by activating a vacuum release/blow-off for the amount of time set in Blow-Off Time (set in Operate panel).
6. The pick tool retracts, thus completing the PLACE SubOp routine.

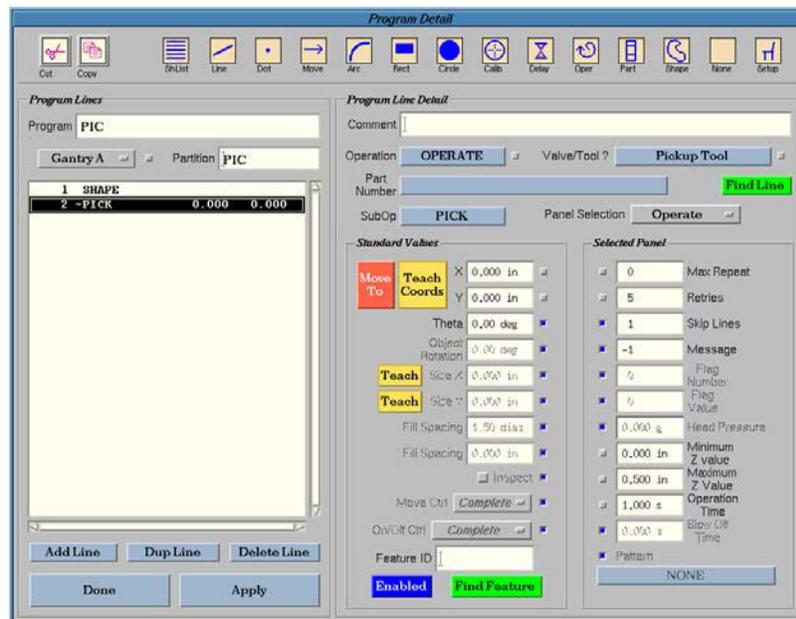
## Programming Pick & Place

Creating a component pick and place program involves all of the following steps.

### 1 - Create a Shape for Pick Operation

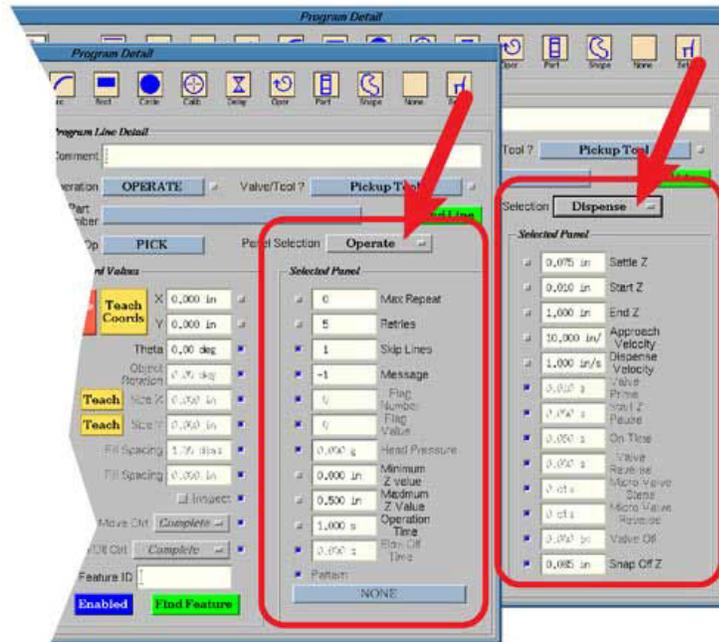
To create a shape for the pick operation:

1. Create a shape that will use the PICK SubOp:
  - a. In the Program Editor, select Edit Shapes.
  - b. Click the ADD ITEM button.
  - c. Enter a name of your choice. (For instructional purposes, we have used the name PIC.)
2. Create a valve/tool called Pickup:
  - a. In the Program Editor, select Libraries > Heads, and then select Pickup from the Type drop-down menu.
  - b. Open Program Detail by clicking the EDIT DETAIL LINES button, and then select Pickup Tool from the Valve/Tool drop-down menu.



3. Create an operate line with a PICK SubOp.
  - a. Choose one:
    - with the Shape partition selected, click the OPER icon, or
    - with the newly created line selected, click the OPERATION button and select OPERATE.
  - b. From the SUBOP button, select PICK, and then click APPLY.

- Enter desired values in the Operate and Dispense panel fields (see fields listed in chart below):



**Table 29: Operate & Dispense panel fields pertinent to Pick Operation**

Panel Location of Fields	Fields	Field Description
Dispense panel	End Z	distance above StartZ were pick ends.
	Approach Velocity	velocity at which tool approaches component (velocity from SettleZ to StartZ).
	Dispense Velocity	velocity at which tool moves to End Z.
Operate panel	Max Repeat	number of times the system attempts to pick up the component at the current Z location.
	Retries	number of Z axis increments used to move the tool downward, testing for component presence after each index. (If no component is detected, an error message will display.  Divide Maximum Z Value by Retries (total distance divided by number of increments) to figure out the distance per increment. For example, to make the Z axis index downward a total of 0.500 inches in five 0.100 inch increments: <ul style="list-style-type: none"> <li>• set Minimum Z Value to 0.0 inches</li> <li>• set Maximum Z Value to 0.500 inches</li> <li>• set Retries to 5</li> </ul>
	Maximum Z Value	maximum Z coordinate value allowed; the total distance Z axis will travel downward.
	Minimum Z Value	minimum Z coordinate values allowed.
	Operation Time	amount of delay after turning on vacuum/gripper and before testing vacuum/proximity sensor.

5. Create a new fixed location:
  - a. From the Program Editor, select Libraries > Fixed Locations.
  - b. Create a fixed location with desired name. (For instructional purposes, we have used the name PickLoc). For further detail about fixed location creation, refer to [Fixed Locations Library](#) (pg 5.3).

6. Teach the actual fixed location (typically, the center of a component):
  - a. Click the TEACH button.
  - b. Teach X/Y with the camera.
  - c. Teach Z with the pick up head touching the component surface.

**NOTE:** The PICK routine has the ability to compensate for variations in component height by using an indexing approach as described in [PICK SubOp Routine](#) (pg 4.45). The PICK routine will adjust to XY location using the fiducials and patterns set in the [Fixed Location Editor](#) (pg 5.35).

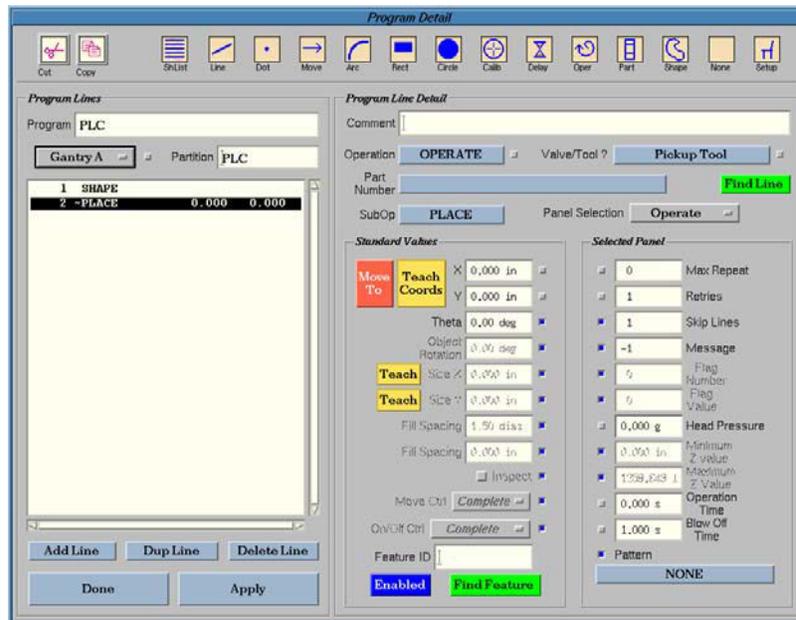
7. Teach the fiducials for the fixed location:
  - a. Click the FIDUCIALS button to open the [Fiducials & Bad Marks](#) (pg 5.33) window. The current coordinates at which the gantry is positioned should be displayed.

- b. Click APPLY.

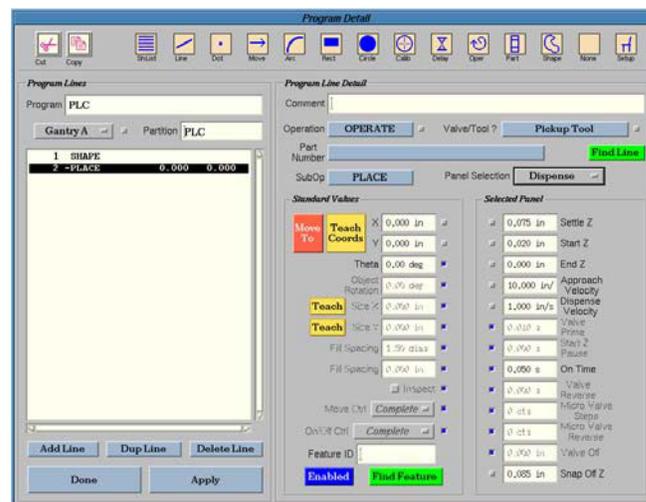
## 2 - Create a Shape for Place Operation

To create a shape for the place operation:

1. Create a second shape, this time using the PLACE SubOp:
  - a. In the Program Editor, verify Edit Shapes is still selected.
  - b. Click the ADD ITEM button.
  - c. Enter a name of your choice. (For instructional purposes, we have used the name PLC.)



2. Create an operate line with a PLACE SubOp:
  - a. Click the EDIT DETAIL LINES button to open Program Detail.
  - b. With the Shape partition selected, click the OPER icon.
  - c. With the newly created line selected, click the SUBOP button and select PLACE. The program will use the fiducials and patterns for the shape to establish the desired PLACE location.



3. Enter desired values in the following Operate and Dispense panel fields of Program Detail:

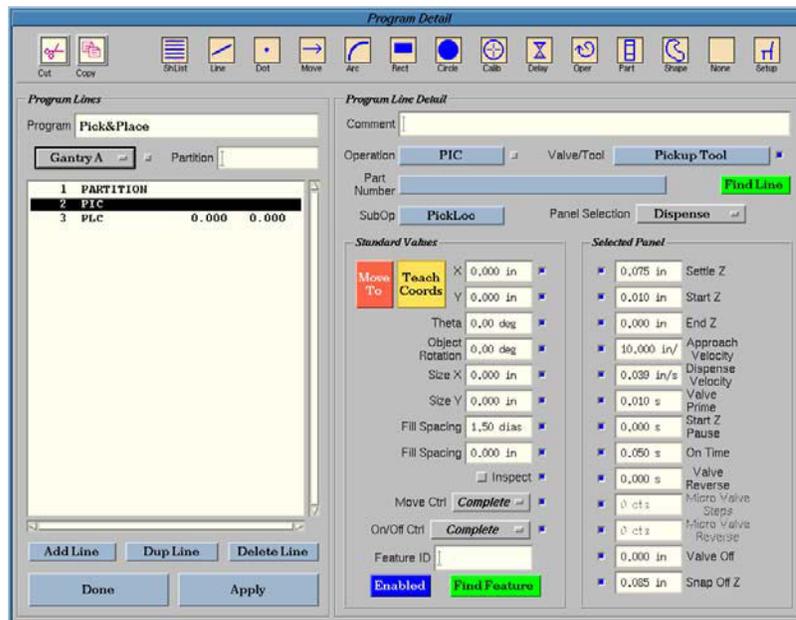
**Table 30: Operate & Dispense panel fields pertinent to Place Operation**

Panel Location of Fields	Fields	Field Description
Dispense panel	Start Z	height of Z axis for placement.
	End Z	location of Z axis after place operation.
	Approach Velocity	velocity at which tool approaches component (velocity from SettleZ to StartZ).
	Dispense Velocity	velocity at which tool moves to End Z.
Operate panel	Max Repeat	number of times the system attempts to pick up the component at the current Z location.
	Retries	<p>number of Z axis increments used to move the tool downward, testing for component presence after each index. (If no component is detected, an error message will display.</p> <p>Divide Maximum Z Value by Retries (total distance divided by number of increments) to figure out the distance per increment. For example, to make the Z axis index downward a total of 0.500 inches in five 0.100 inch increments:</p> <ul style="list-style-type: none"> <li>• set Minimum Z Value to 0.0 inches</li> <li>• set Maximum Z Value to 0.500 inches</li> <li>• set Retries to 5</li> </ul>
	Head Pressure	target operating pressure for the Force Feedback tool.
	Operation Time	amount of delay before turning off vacuum/gripper.
	Blow Off Time	amount of time for blow off/eject operation.

### 3 - Create a Program for Pick & Place Shapes

To create a program that incorporates the pick and place shapes generated from [1 - Create a Shape for Pick Operation](#) (pg 4.46) and [2 - Create a Shape for Place Operation](#) (pg 4.49):

1. Incorporate both the new pick shape and place shape into a new program:
  - a. Create a new program and name it as desired (Pick&Place, for example).
  - b. With the new program selected, click EDIT DETAIL LINES to open Program Detail.
  - c. Below the first partition line of the program, add the two shapes you created earlier in this procedure (PIC and PLC in the examples).
2. Assign a fixed location to the pick shape:
  - a. Highlight the pick shape line (shown in the screen illustration as the PIC line).
  - b. Click the SUBOP button to open a list of fixed locations.
  - c. Select the fixed location set up in [Step 4 of 1 - Create a Shape for Pick Operation](#) (pg 4.46) to pick the component.



3. Assign a fixed location to the place shape:
  - a. Highlight the place shape line (shown here as the PLC line).
  - b. Click the TEACH COORDS button in Program Detail and teach the location where the part should be placed.
  - c. Click APPLY and DONE.
4. In the Program Editor, teach a reference point for the pick and place program.
5. From the Valve/Tool drop-down menu in Program Detail, select Pickup Tool.
6. Test your new pick and place program to verify results are as expected.

## Program Enhancement

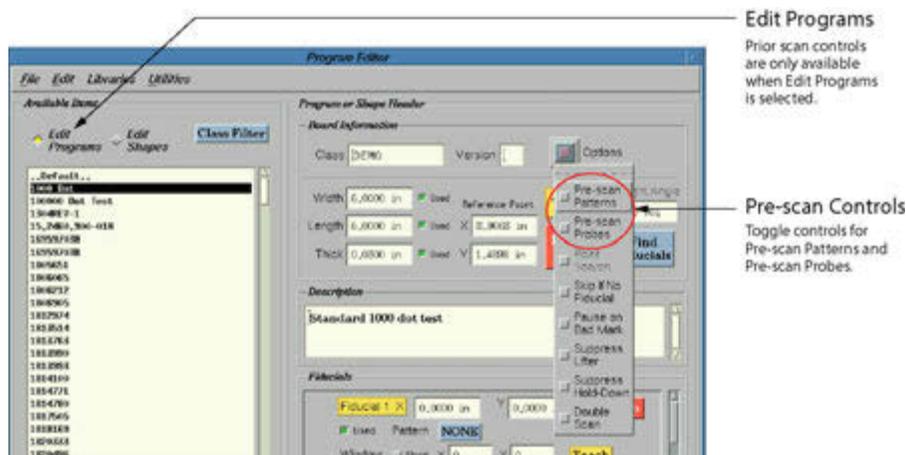
- [Pre-Scan](#) (pg 4.52)
- [Automatic Calibration Limits](#) (pg 4.53)
- [Counter Usage](#) (pg 4.55)
- [Material Expiration \(Pot Life\)](#) (pg 4.59)
- [Resumption Points for Underfill - UltiPath™](#) (pg 4.62)
- [Indexing Calibration Dots](#) (pg 4.70)
- [Material Purge Options](#) (pg 4.73)

## Pre-Scan

Activating the pre-scan options in a program can help reduce processing time by reducing gantry movement. When the pre-scan options are activated for a program, the gantry moves first to all camera-related (fiducial and bad mark) locations, and then to all programmed height sense (probe) locations before continuing with the regular program steps. In contrast, each visual verification and probe operation is performed in its programmed sequence when pre-scan options are not used.

One or the other or both of the Pre-Scan options can be used in a program. Both options, Pre-Scan Patterns and Pre-Scan Probes, can be activated from the Program Editor when Edit Programs is selected.

**SUGGESTION:** Use Pre-Scan Patterns with Pre-Scan Probes so visual verifications precede probe operations, thereby ensuring that height sense operations are performed at the proper coordinates and to verify the need for height sense.



### Pre-Scan Patterns

Pre-Scan Patterns will cause a program to find all fiducials and bad marks throughout the program before performing any other operation such as dispensing, probing, etc.

### Pre-Scan Probes

Activating Pre-Scan Probes will cause a program to perform all height sense-type operations before performing any other operation (such as dispensing) with one exception. Board orientation-type fiducials (global fiducials) and bad marks are always checked before Pre-Scan Probes height sensing occurs to ensure a board is present.

## Automatic Calibration Limits

Establish automatic program limits to prevent the Calibrate operation from executing every time it is encountered in a program. Program limits are examined by the Calibrate operation upon execution to determine:

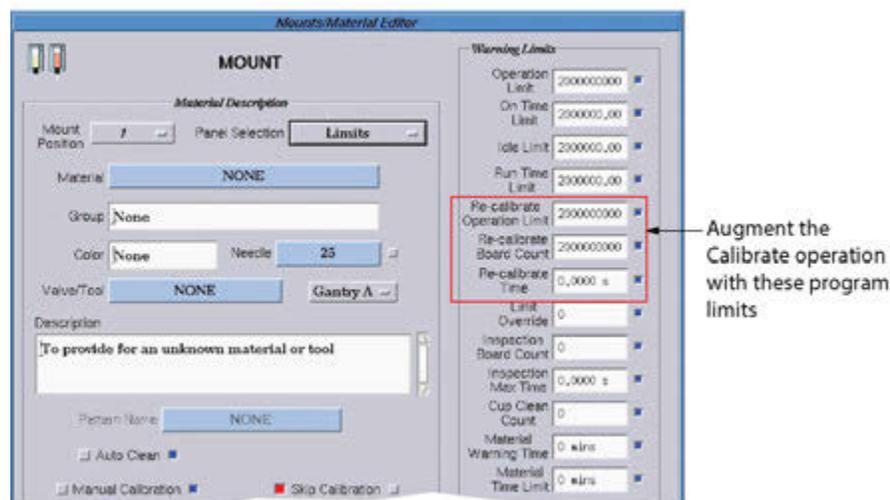
- if any limit is enabled and
- if the threshold for that limit has been exceeded.

If a limit is enabled and its threshold is exceeded, the Calibrate operation is performed. If a limit is enabled and its threshold is *not* exceeded, the Calibrate operation is *not* performed.

Any number of limits may be enabled simultaneously. If any of the enabled limits is exceeded, a single Calibrate is performed and thresholds for all enabled limits are reset [see [Preventing Over Calibration](#) (pg 4.54)].

## Program Limits

All program limits are located in the Limits panel of the program Mounts/Material Editor - MOUNT window:



To set limits for re-calibrating operation, board count, and/or time in the selected program, enter a value in any/all of these limit fields:

### Re-Calibrate Operation Limit

To enable this limit, set a value greater than 0.0 and less than 1000000 (1 million). When the number of operations (dots, lines, etc.) exceeds this value, the Calibrate operation is performed.

### Re-Calibrate Board Count Limit

To enable this limit, set a value greater than 0.0 and less than 1000000 (1 million). When the number of boards processed exceeds this value, the Calibrate operation is performed.

### Re-Calibrate Time Limit

To enable this limit, set a value greater than 0.0 and less than 1000000 (1 million). When the total amount of processing time exceeds this value, the Calibrate operation is performed.

## Preventing Over Calibration

All limit values are accumulated from the beginning of program execution. Times, board counts, operation counts, etc. do not span multiple program invocations.

The execution of a Calibrate operation resets *all* limit timers and counters to prevent calibration being performed too frequently.

### *Example*

Assume:

Time Limits = 100 seconds

Board Count Limit = 7 boards

If 7 boards process in 140 seconds (20 seconds per board), then we expect a calibration to be performed at 100 seconds AND 140 seconds (7 boards). This is 60 seconds before the Time Limit expires the second time.

To prevent this issue, the calibration performed at 100 seconds causes the board count threshold to reset so an additional 7 boards require processing before causing a calibration. Because the board threshold is greater than the time threshold, the board count threshold will never cause a calibration.

## No Program Limits

If no program limits are enabled (values are within valid ranges), the Calibrate operation is performed every time it is encountered.

## Counter Usage

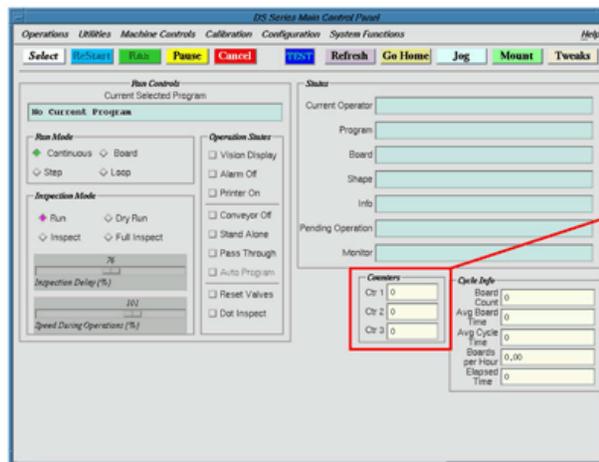
Various types of counters are available - those that increment or decrement, those that test one counter against another, and those that test a counter against a fixed value.

The values for selected [Counters](#) (pg 3.30) display on the main window only during a program run when counters are used in the active program. Counters are added to a program as an OPERATE line with a SubOp.

## Counter Rules

These rules apply to standard counters:

- Counters are numbered and can be assigned any number from 1 to 32,767.
- Any counter assigned a number less than 100 always starts at zero (0) with a program run and disappears when the program run ends.
- Any counter assigned a number of 100 or greater always starts with the value the last program left it at and keeps its value in the database.
- The panel of counter values displays on the main window only when a program asks for a display of one or more counters and only while the program is running.



Counter values display here during a program run when counters are used in the active program.

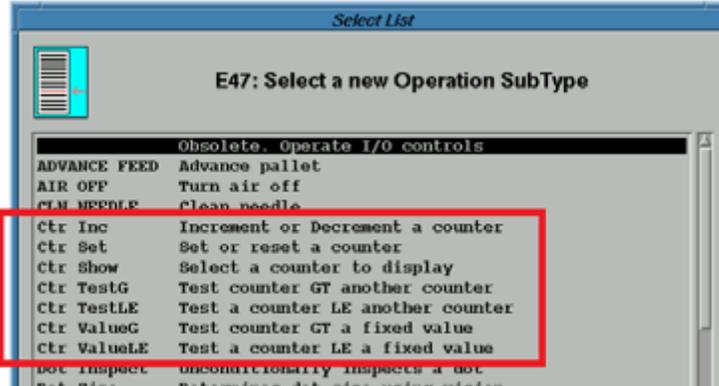
## Adding a Counter to a Program

All counter identities and values are established in the Operate selectable panel of Program Detail.

To assign a counter:

1. In Program Detail, add an OPERATE program line and then click SubOp.

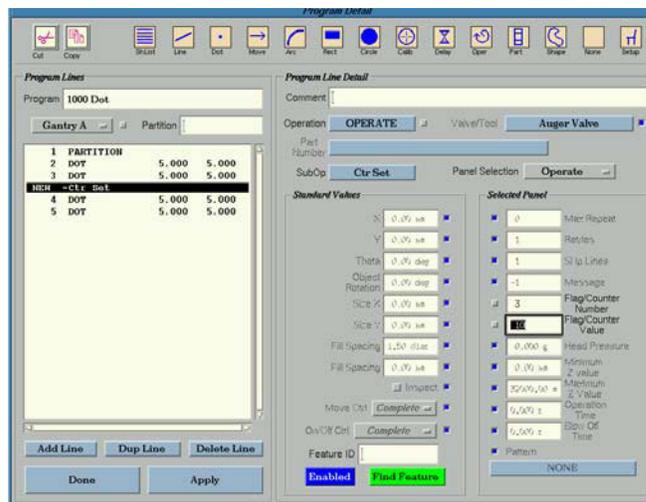
- From the list that displays, select a counter subop. For details about each counter subop, refer to [Counter Functions](#) (pg 4.56).



## Counter Functions

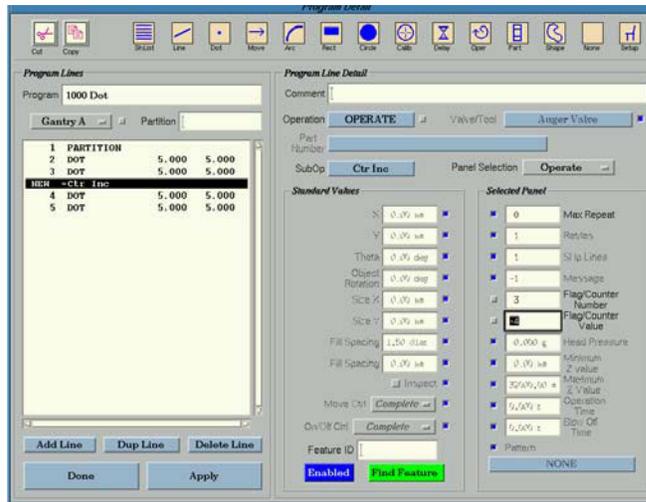
### Ctr Set

Ctr Set sets or resets a counter. Assigns a value to a specific counter. Negative values may be used. In the example shown here, counter 3 is assigned a value of 10.



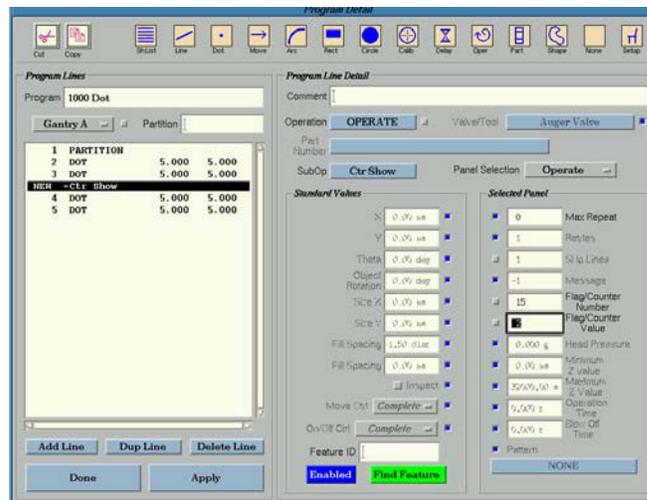
## Ctrl Inc

Ctrl Inc increments or decrements a counter. The designated counter will be increased/decreased by the amount specified. Negative values may be used. In the example shown here, counter 3 will be decreased by 4.



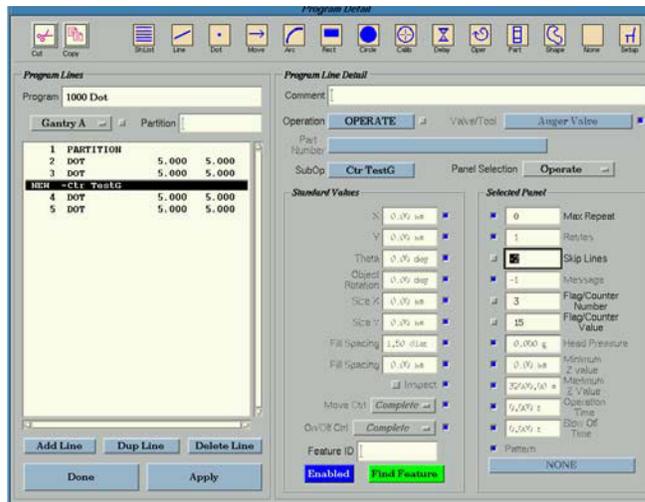
## Ctrl Show

Ctrl Show selects a counter to display. Designates which counter displays in the counter panel on the main window and in which of the three counter boxes in that panel it will display. In the example shown here, counter 15 will display in box Ctrl 2 on the main window.



### Ctr TestG

Ctr TestG tests a counter greater than another counter. In the example shown here, if counter 3 is greater than counter 15, the program will skip two program lines backward and resume with program line #3.

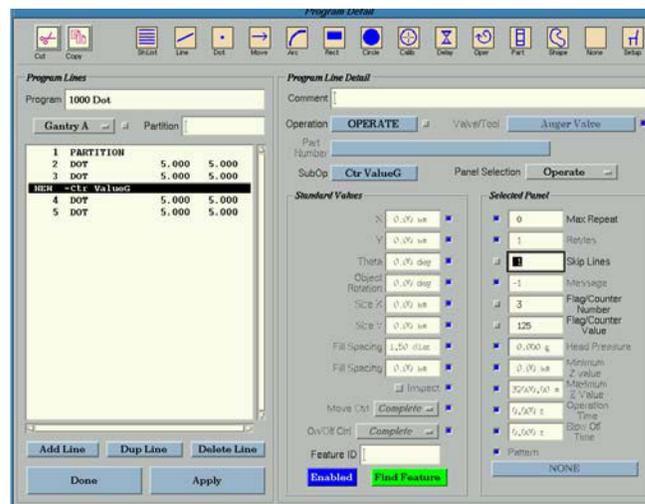


### Ctr TestLE

CtrTestLE test a counter less than or equal to another counter.

### CtrValueG

Ctr ValueG tests a counter greater than a fixed value. Negative values may be used. In the example shown here, if counter 3 is greater than 125, the program will skip a single program line and resume with program line #5.



### Ctr ValueLE

Ctr ValueLE tests a counter less than or equal to a fixed value. Negative values may be used

## Material Expiration (Pot Life)

### **IN EFFECT AS OF FLOWare software version 2.9.3**

The Material Expiration features allows setting a material *start date/time* and a *pot life*. When the combined start time and pot life has expired, messages are displayed indicating the material has expired.

When the material expires, the dispenser continues dispensing expired material normally but requires an operator to override the Material Expired condition.

### Using Material Expiration

To activate Material Expiration:

1. From the main menu bar, click on Operations > [Material Expiration](#) (pg 5.54). The Material Expiry dialog will display.

2. Enter an appropriate Start Date/Time and Pot Life.

If the entered values are valid, the actual expiration time/date is displayed and the OK button is enabled.

If the data is invalid (badly formed, in the past, etc.) the OK button is disabled.

3. Enter an appropriate Warn Time.
4. Set the Active/Inactive toggle.

**NOTE:** The Date/Time must be entered in this format: YYYY-MM-DD hh:mm

YYYY	A 4 digit year, example: 2018
MM	A 2 digit month (01-12), example: 04 is the month April
DD	A 2 digit day of month (01-31), example: 14 is the 14th day of the month
hh	A 2 digit hour in 24hr form (00-23), example: 13 is the 13th hour (1 o'clock PM)
mm	A 2 digit minute (00-59), example: 05

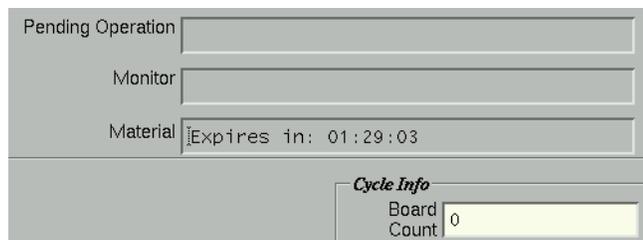
Examples:

2018-05-09 10:00	May 9, 2018 10AM
2019-11-29 16:30	November 29, 2019 4:30PM
2018/05/12 14:20	Bad Format - date elements must be separated by hyphens (-)
2018-10-14 8	Bad Format - no minutes specified
May 14, 2018 12:00	Bad Format

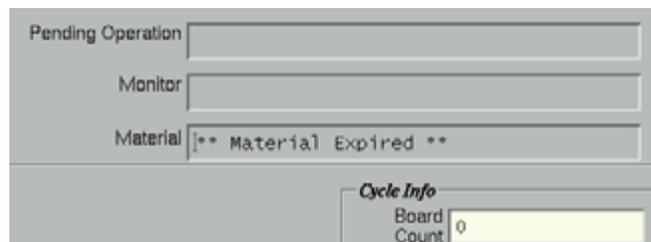
## Status Monitor

When the feature is enabled, an additional Monitor field displays on the main screen and is active at all times. This monitor field displays either the time remaining for the current material or an indication that the material is expired.

**Figure 24: Material Not Expired**



**Figure 25: Material Expired**



If the feature is disabled, this monitor field is removed from the screen entirely.

## Warning Dialogs

There are two cases in which a Material About To Expire warning dialog will display:

- When no process is running, a warning is displayed if the material expires within Warn Time minutes. This dialog is persistent; it displays until the material is updated or a process is executed (Run button).

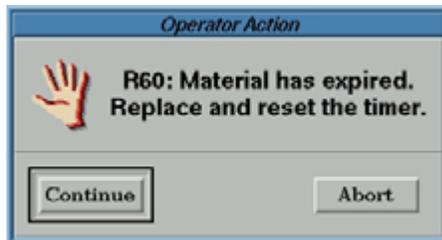


- When a process is running and the material expires within Warn Time minutes, a warning displays *before processing the next unit*.



## Expired Dialog

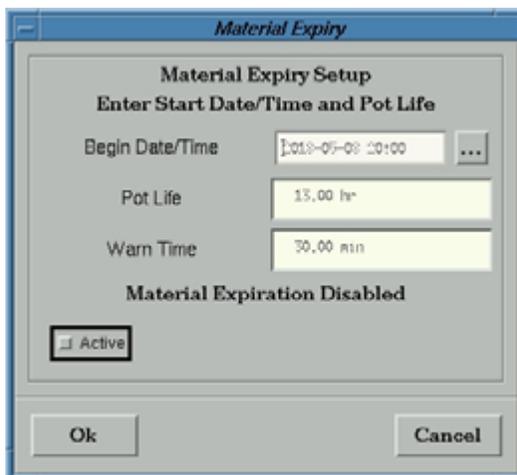
When a process is running and the material becomes expired, the following dialog is displayed *before processing the next unit*.



Continue	Dispenser will process the next unit; it will run one time.
Abort	Dispenser aborts the current process allowing the operator to change the material and update the expiration data.

## Disabling Material Expiration

If the Active toggle button is not enabled, the Date/Time, Pot Life, and Warn Time fields are disabled and the entire feature is deactivated. When deactivated, no warnings or messages display.



## Resumption Points for Underfill - UltiPath™

**IN EFFECT AS OF FLOWare software version 2.9.2**

### UltiPath™ Benefits Underfill

UltiPath™ underfill optimization increases throughput and reduces program setup time by automatically determining the fastest, optimized dispense path and eliminating the need for the operator to guess at the best route. This optimization is done on-the-fly so that changes to the program are automatically handled.

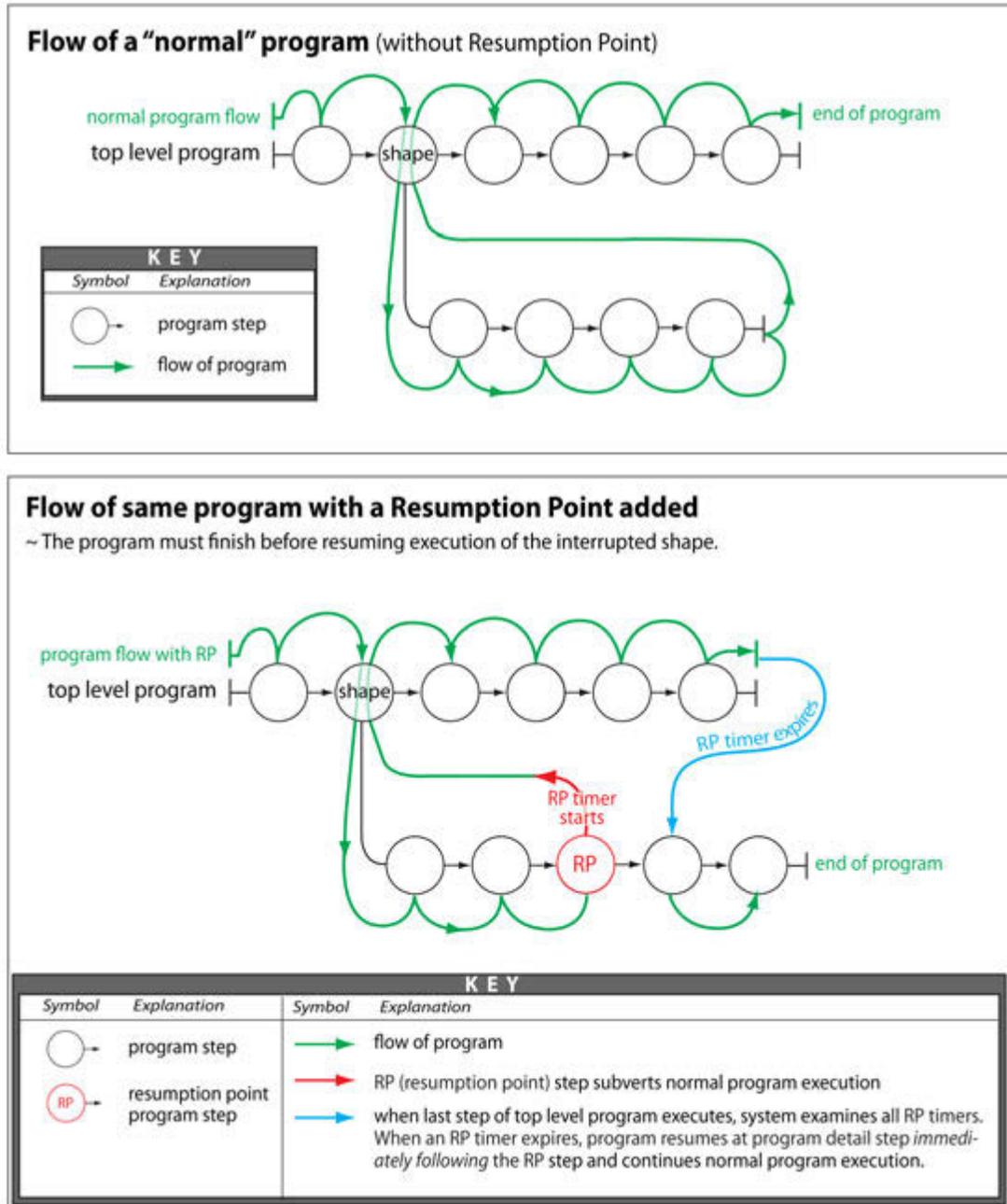
FLOWare software optimizes the best gantry path for the end-user by using resumption points. The optimization ensures the quickest cycle times for complex underfill processes. The result is reduced setup times, as well as quick updates for product changes and the addition or deletion of components.

- [UltiPath™ Uses Resumption Points](#) (pg 4.63)
- [Theory of Operation](#) (pg 4.65)
- [Resumption Point Rules](#) (pg 4.66)
- [Adding Resumption Points to a Shape](#) (pg 4.69)

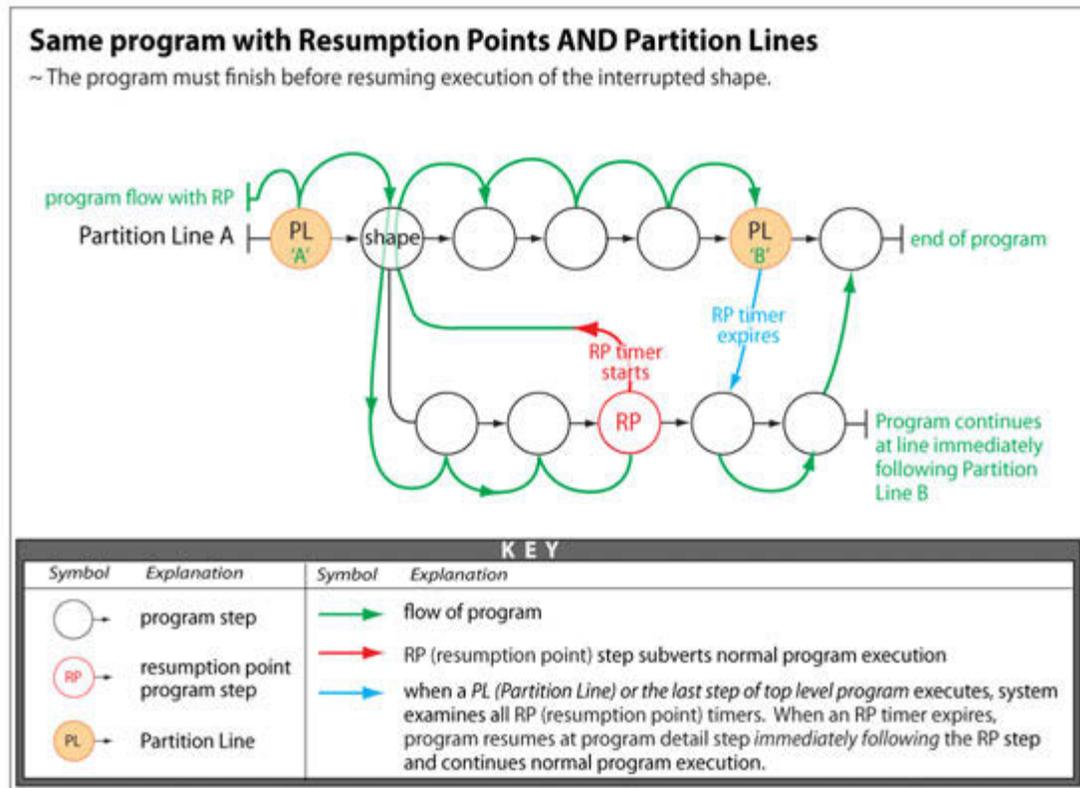
### UltiPath™ Uses Resumption Points

A resumption point is a standard call/return sequence with a closure, e.g., a point within a FLOWare software underfill program at which execution will be suspended and then resumed at a later point in time, i.e., a resumption point allows you to design a program in a manner that allows for the interweaving of operations with significant, inherent process delays.

Figure 26: How Program Flow changes when a Resumption Point is added into Program



**Figure 27: How Program Flow changes when Partition Lines are used with Resumption Points**



For example, assume several underfill operations are required on a board. Each operation is composed of a number of fill passes with a delay of several seconds required between each fill pass. One way to approach this scenario is to make your program execute the first fill pass, delay for some seconds, perform the second fill pass, delay for some seconds, and then repeat this sequence until the first component is completed and then move to the next component and repeat all these steps.

Resumption Points allow you to capitalize on the delay time between fill passes by performing (in this example) a fill pass on another component and returning to the original component to complete the next fill pass after some amount of time has expired. In other words:

1. A resumption point halts execution of a shape at the point at which the resumption point command is encountered.
2. Execution of the interrupted shape is resumed after and only after:
  - a. the program encounters either a Partition Line or the end of the program (see Figure 26 on page 4-63), and
  - b. the expiration time of the resumption point has expired (see Figure 28 on page 4-65).

3. When the resumption point is resumed, execution picks up at the line immediately following the resumption point command and continues until:
  - another resumption point command is encountered (see Figure 29 on page 4-67) or
  - the end of the shape is encountered.

**Figure 28:** Each Resumption Point can have a different Operation Time Value

The screenshot shows the 'Program Detail' window in FLOWare. On the left, the 'Program Lines' table is visible:

Line Number	Operation	Start Time	End Time
1	SHAPE		
2	FillPass	0.000	0.000
3	-Resume Pt		
4	FillPass	0.000	0.000
5	-Resume Pt		
6	FillPass	0.000	0.000

The 'Program Line Detail' window on the right shows the configuration for a selected line. The 'Operation Time' field is highlighted in red and set to 5.000 s. An arrow points from the text on the right to this field.

**Operation Time** is the minimum amount of time that must pass before the Resume Pt can be reactivated.

A different value can be assigned to Operation Time for each Resume Pt. For example, the first Resume Pt (see detail line 3) has been assigned a value of 5.000 seconds, but the second Resume Pt (see detail line 5) could be 7.750 seconds.

## Theory of Operation

When a resumption point is encountered in normal program execution flow, its location in the program is noted (saved) for later restoration and the time after which the resumption point may be restored is calculated. At that point, execution of the shape is aborted and program execution continues at the point at which the shape was invoked.

When the entire program has been executed, i.e. every line of the main program has been visited or a Partition line is encountered, then and only then is the collection of resumption points examined to determine which is to be resumed first. FLOWare will continually examine the collection of available resumption points until there are none left to perform. If a Partition line was encountered, program operation will continue after all resumption points have been executed. Refer to Figure 29.

A resumption point is performed when 1) its Operation Time number of seconds has passed since the resumption point was first encountered, and 2) the particular resumption point has been ready and waiting longer than any other resumption point. The resumption point which has been ready to execute longer than any other resumption point will be performed first.

## Resumption Point Rules

These rules apply to resumption points:

- Resumption points are designed for use in underfill processes. Forcing them to work in scenarios fundamentally different from underfill will probably result in failure.
- The program will continue either to the end of the program (and all that entails) or to a Partition line in the program. See Figure 29 on page 4-67.
- There is no **maximum** time within which a resumption point will be performed. If your process is waiting too long to return to a partially completed operation, then rearrange your process.
- **DO** place resumption points within shapes (see Figure 29 on page 4-67).
- **DO NOT** place resumption points:
  - in the top level of a program sequence; this will result in undefined behavior.
  - in the last step of a shape; this accomplishes nothing while slowing machine operations.
  - next to each other in a shape; this also accomplishes nothing.
- Resumption points can be used in up to 5 levels of nested shapes.
- A [Partition Line](#) (pg 3.91) can be used to separate a program into smaller segments (see following example). Partition lines should only be used in the program (not in a shape) and cannot be the *last* line of the program (or undesirable results will occur).

*Example of Partition Use:* In this scenario, a program that dispenses multiple materials is separated into subsections by using multiple partition lines: the first partition line begins the section of the program that masks off an area with a UV mask. A second partition line begins the section that cures the mask with a UV wand. A third partition line begins section that dispenses UV curable underfill material. A fourth partition line begins the section that cures UV underfill to prevent bleed-out. And a fifth partition line begins final program section that dispenses regular underfill material.

## Plays Well with Others

---

Resumption points work with these FLOWare software features:

- fiducials on shapes
- pre-scan controls
- array of shape
- nested shapes (to a depth level of 5)
- nested array of shape

Figure 29: How Program Flow changes with Multiple Resumption Points

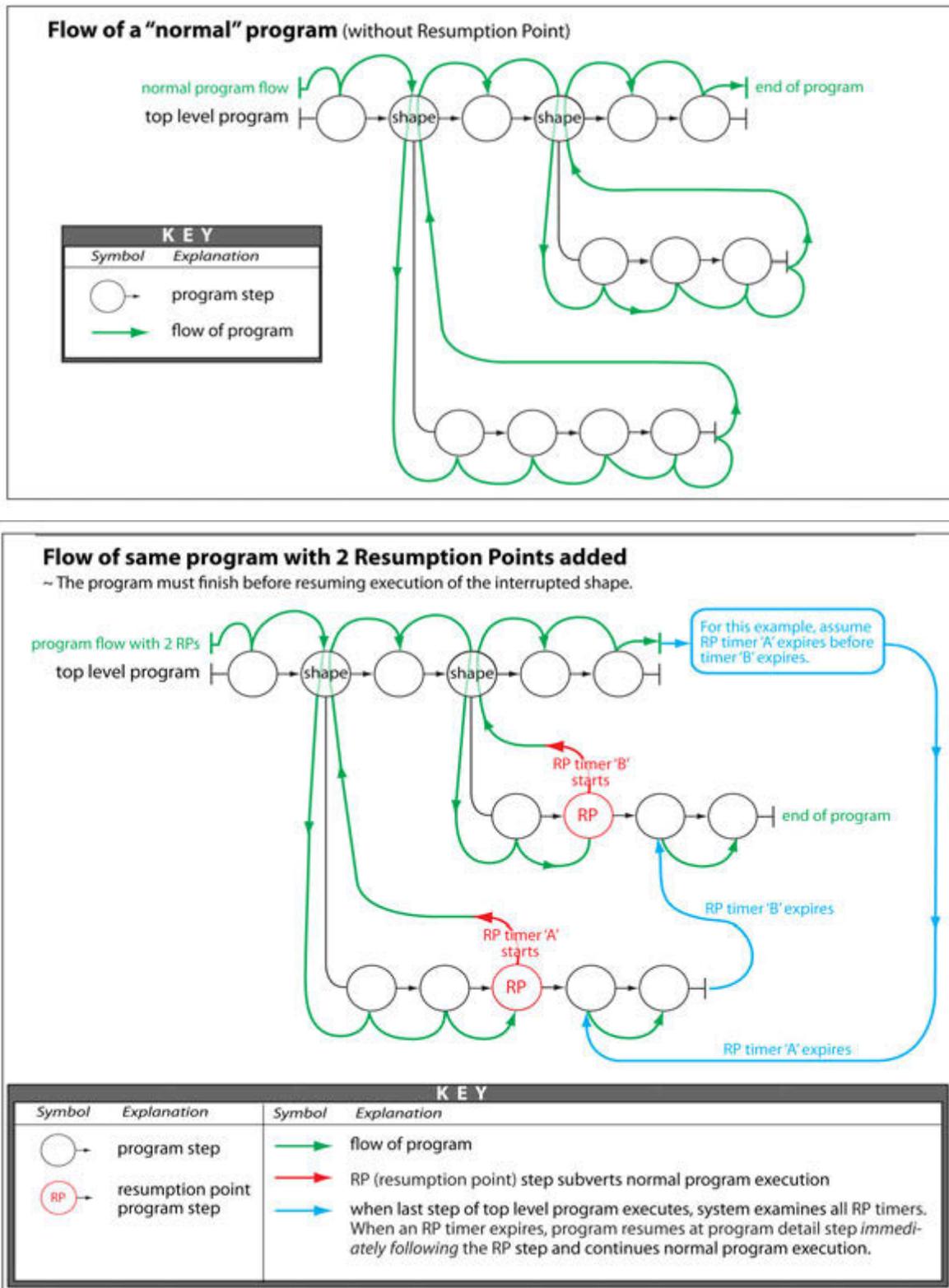
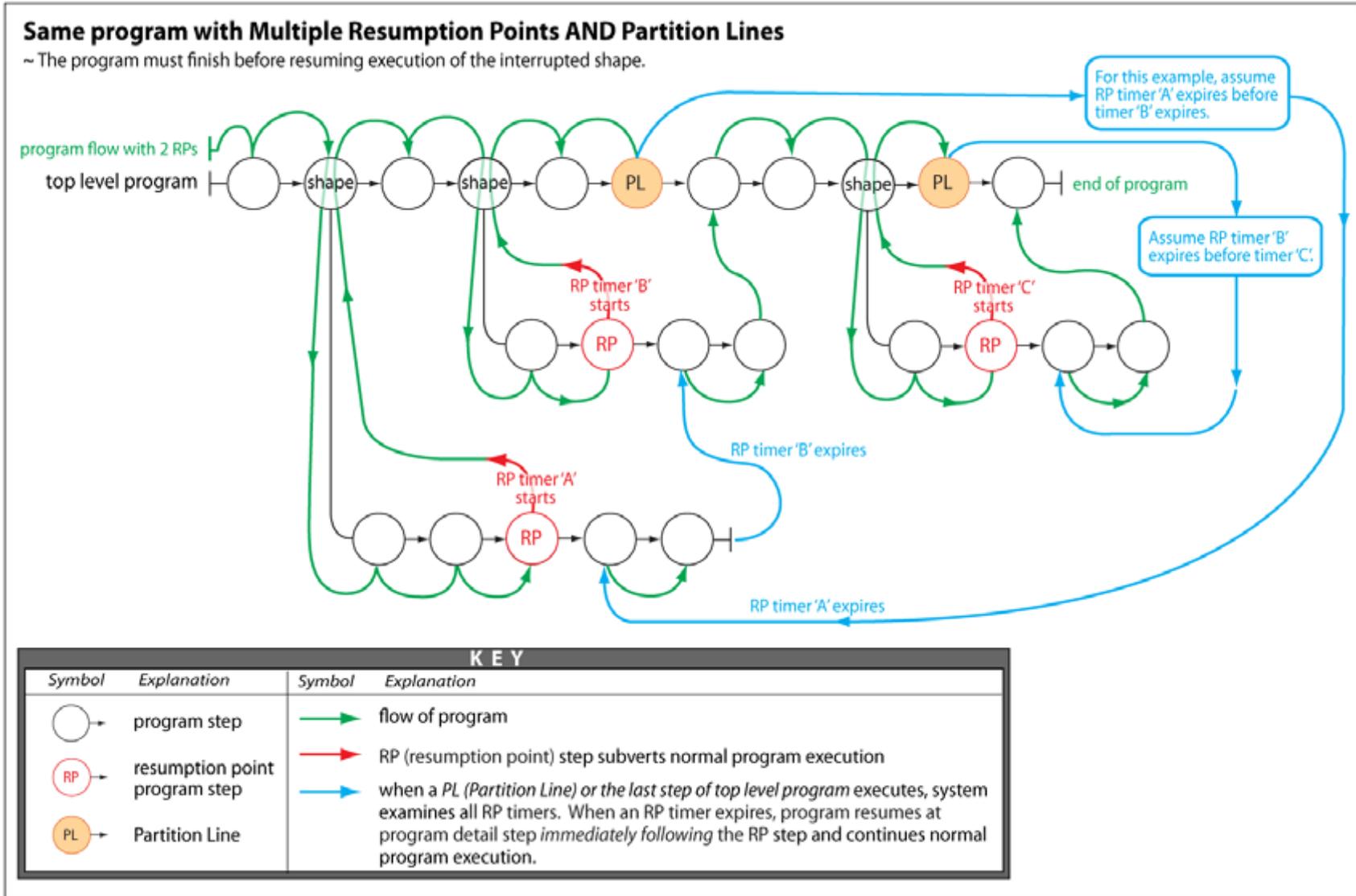


Figure 30: How Flow changes when Partition Lines are used with Multiple Resumption Points



## Adding Resumption Points to a Shape

To insert a resumption point in a shape:

1. In the Edit Shapes version of Program Detail, insert an Operation of OPERATE into a program at an appropriate position.

**NOTE:** Do not position a resumption point in the top level of a program sequence, in the last step of a shape, or next to another resumption point within a shape.

2. Select a SubOp of SetResumePt.
3. Enter a value in Operation Time (see Figure 28 on page 4-65) to represent the minimum number of seconds that must pass before the resumption point may be reactivated. This is the only parameter used by a resumption point.
4. Click APPLY.

## Indexing Calibration Dots

Use this procedure when setting up calibration dot indexing at the ceramic chip on a calibration station with chip backlighting (and no paper pad).

The changes described in the following procedure will cause the dispenser gantry to index to a new position at the calibration station chip each time a dot is dispensed in the calibration sequence.



**WARNING** The content of this section is NOT recommended for use by anyone besides GPD Global personnel or those working under the direct guidance of GPD Global personnel. Improper application of this information can lead to serious complications in FLOWare Software operations. Any non-GPD Global employee who uses this information beyond the stated application specified by GPD Global Service Department personnel is in danger of causing personal injury and invalidating their machine warranty.

<b>ATTENTION</b> <a href="#">Le contenu de cette</a>	<b>WARNUNG</b> <a href="#">Der Inhalt dieses</a>	<b>ATTENZIONE</b> <a href="#">Il contenuto</a>	<b>ADVERTENCIA</b> <a href="#">NO SE RECOMIENDA</a>
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## Set Up

To set up the dispenser so it dispenses indexing calibration dots on the ceramic chip at the calibration station, follow and complete all of the following steps in the order listed.

### 1 - Edit Configuration

---

To configure the basic calibration dot pattern at the calibration station:

1. From the main menu bar, click on Configuration > [Dispenser Configuration](#) (pg 3.136). The Edit Configuration and Configuration Definitions windows will display.
2. In the Edit Configuration window, scroll down until you locate lines of text similar to the following:

```
DrillPadType = n
DrillPadHeight = n
DrillPadWidth = n
```

3. Change the values to match the following:

```
DrillPadType = 1
DrillPadHeight = 20
DrillPadWidth = 20
```

**NOTE:** Height and width values are equal to half the physical length and width of the ceramic chip.

4. To save changes and exit the Edit Configuration window, press and hold down the ALT key and then type X and then S.
5. To exit the Configuration Definitions window, press and hold down the ALT key and then type X.

## 2 - Edit Option Settings

---

To define a single line, calibration dot pattern at the calibration station chip:

1. From the main menu bar, click on Configuration > Option Settings. The Option Settings window displays.
2. Enter a value of 30 in the Max Chip Index field. The number of times the dispenser indexes (Max Chip Index) is limited by chip width and the minimum Drill Spacing value.

EXAMPLE: The Max Chip Index value must be less than 40 for a 40 mm wide chip with a Drill Spacing of 1 mm. A value equal to or greater than the 40 mm chip width will cause dots to be dispensed beyond the chip surface.

3. Enter a value of 1 mm in the Drill Spacing field. It is important to set the distance between the calibration dots (Drill Spacing) at a value large enough to ensure that only a single dot at a time is visible in the camera field of view.
4. To save new settings and exit the window, click OK.

## 3 - Set Base Locations

---

To teach camera base locations pertinent to indexing dots at the calibration chip:

1. From the main menu bar, click on Configuration > Base Locations. The Check/Set Base Locations window displays.
2. Jog the camera so it is centered over the calibration station ceramic chip. It is important to center the Jog alignment cross hairs over the center of the ceramic chip because the chip center point is the origin point for the dot dispense pattern.
3. In the upper left-hand panel of the Check/Set Base Locations window, select *Camera to Paper Pad (XY)*.
4. Save new base location coordinates by clicking the XYZ button and then SAVE.
5. Without changing camera position, select *Camera to Drill Pad (XY)*.
6. Save new base location coordinates by clicking the XYZ button, and then SAVE.
7. Exit the window by clicking DONE.
8. Boot the system, using the standard Shutdown procedure, so the new base locations will take effect.

## 4 - Edit Material Library

---

To turn on the *Dot on Chip* function in the pertinent material record(s):

1. In the Program Editor menu bar, click on Libraries > Materials. The Mounts/Material Editor window displays.
2. Click on the Material button and select the material to be modified – select the material to be used when dispensing indexed calibration dots at the calibration station.
3. Click on the PANEL SELECTION button and select Calib Dot from the pop-up menu. Fields specific to Calibration Dot Parameters should display in the right-hand panel of the Mounts/Material Editor window.
4. Turn on the Dot on Chip default box.

5. To save the change, click on APPLY and then CLOSE.
6. Repeat steps 2 through 5 for any additional material(s) that should also generate indexed calibration dots.
7. To apply changes to the Program Editor, click on APPLY EDITS.

This completes the process of setting up for indexing calibration dots on the calibration station chip.

## Material Purge Options

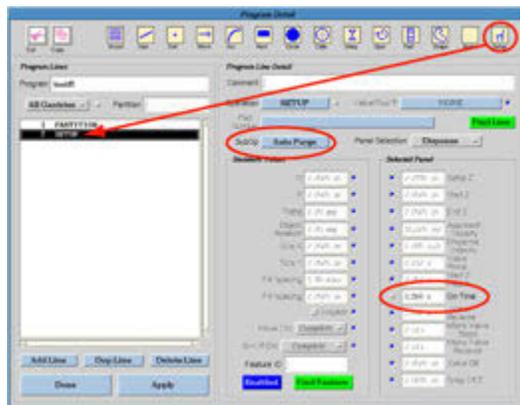
Material can be purged from a needle or nozzle while the system is idle or automatically as part of a program run. The location at which purging occurs can be varied automatically to prevent needle contamination.

### Needle Clean & Purge

A valve needle or nozzle can be cleaned and purged automatically as part of the program run. Using Auto Purge in a SETUP line enables the valve to purge while boards are moving on the conveyor.

To set up this scenario:

1. Create a SETUP program line in the Program Detail window by clicking the Setup icon in the upper right-hand corner.



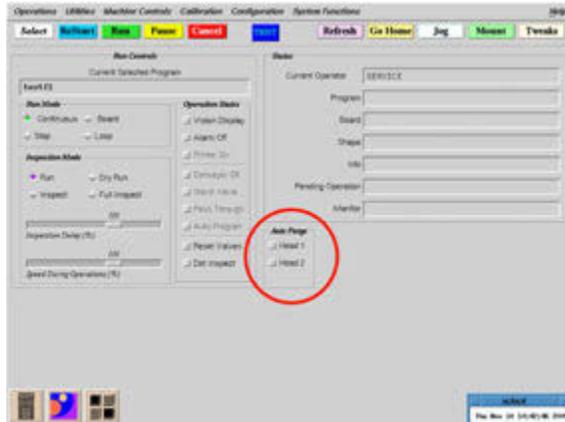
2. Select AutoPurge from the SubOp option menu.
3. Enter a purge time value in On Time.
4. Be sure to activate the Auto Clean function.

**IMPORTANT:** The Auto Clean box must be selected in the Mounts/Material Editor window in order for the needle to be cleaned online automatically as part of the program run; otherwise, the purge operation will consist of a purge only with a message to the operator to manually clean the needle.

## Auto Purge

When it is important to keep material flowing while the system is idle, as in the case of heated material or a material that sets up quickly, use the Auto Purge feature.

Auto Purge can be selected for Head 1, Head 2, or both head positions. When your system is configured for Auto Purge (DisplayAutoPurge must be set to True), these fields display on the main window.



To use Auto Purge:

1. Select one or both heads from the Auto Purge panel in the main window.

**IMPORTANT:** The Auto Purge head position you select must match the Mount Position and Head of the library record for the material you want to automatically purge.

2. Set the duration of the automatic purge by entering a value in the Purge On Time field in the Offline Operations window.
3. Set the duration of the automatic purge pause (the amount of time between automatic purges) by entering a value in Purge Interval When Idle in the Option Settings window.

## Shifting Purge Location

***IN EFFECT AS OF FLOWare software version 2.8V***

The location at which the valve needle automatically purges material into the purge cup (located on the calibration station) during a program run can be varied automatically. A shifting purge location prevents the needle from contacting previously purged material.

To set up an automatically shifting purge location:

1. Teach the following base locations at the center of the purge cup:
  - Camera to Purge Cup 1 (XY); Head1 to Z
  - Camera to Purge Cup 2 (XY); Head1 to Z
  - Camera to Purge Cup 2 (XY); Head1 to Z

Refer to *Appendix A - Base Locations* in the *Dispenser Service Guide* for further details.

2. Open [Option Settings](#) (pg 5.70) by clicking Configuration > Option Settings.
3. Locate the Cup Location Count and Cup Radius fields in the Calibration panel.
4. Enter a value in Cup Radius that is less than the actual radius of the purge cup. This defines the purge path (the circumference of the purge area within the purge cup).
5. Enter a value in Cup Location Count to represent the number of purge locations you want available for use around the circumference of the purge path.

## Procedures for Custom Hardware

- [Auto Mode](#) (pg 4.76)
- [Barcode Scan Program Select](#) (pg 4.81)
- [Board Flip Control](#) (pg 4.84)
- [Dynamic Load Program](#) (pg 4.85)
- [Material Weigh Module](#) (pg 4.86)
- [Weight Calibrated Shapes](#) (pg 4.92)
- [UV Wand Curing Light](#) (pg 4.98)

### Auto Mode

**IN EFFECT AS OF FLOWare software version 2.9.1** Previous title: *Barcode Program Selection.*

The Auto Mode feature is complex and not always suitable for simple conveyORIZED applications. Use Auto Mode for a conveyORIZED system with an upstream barcode reader and board flipper; otherwise, consider using this simpler option: [Dynamic Load Program](#) (pg 4.85).

### Overview

When the operator selects the barcode program selection mode, the dispenser automatically clears the nest, if a board is present, by moving the board downstream. A board is then requested from upstream.

When a board passes the system barcode reader, a file is generated to indicate the program to be used to process the board. When the board reaches the dispenser nest, the dispenser retrieves the file and executes the designated program.

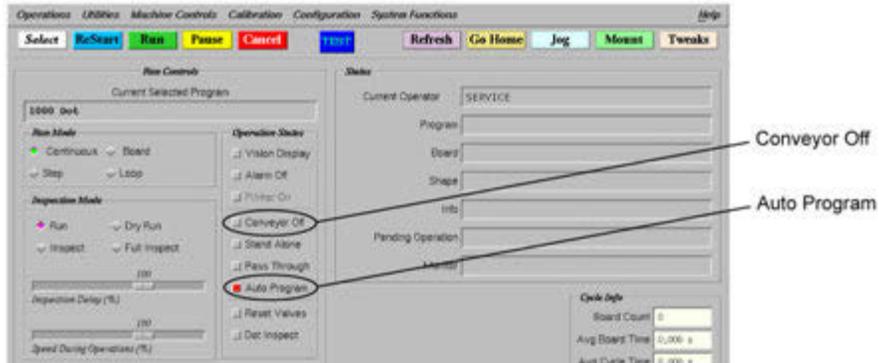
When the program is complete, the board is sent downstream and a new board is requested.

### Details

The barcode program selection feature puts the dispenser into an endless loop mode where, after emptying the dispenser nest to downstream if necessary, the dispenser waits for a board (or pallet) to travel down the conveyor and trigger a barcode reader mounted upstream from the dispenser. The dispenser loads and executes a program applicable to the current board based on information received from the barcode reader.

After the barcode reader is configured at the factory, it functions transparently and conforms with Auto Program, the FLOWare control software feature that enables barcode-driven program selection.

A board present sensor mounted at the barcode reader is triggered by the presence of a PCB on the conveyor when Auto Program is selected (turned on) and Conveyor Off is unselected (turned off).



The barcode reader scans the PCB barcode and runs the program associated with the data received from the barcode or, if the program specific to the scanned data is not available, the dispenser prompts the operator to make a selection:

- alter the ERROR-NO\_READ program to sound an alarm, display a message, etc., or
- react to a display when the condition occurs by choosing either (A) to click OPERATOR and then select a program to run, or (B) click RETRY.

The Auto Program mode and the RUN operation (triggered by the RUN button) are mutually exclusive operations. While Auto Program mode is selected, the RUN button becomes inoperable because board entry into the system and the reading of the barcode initiate a run.

## Best Practices

In order for Auto Program mode to operate properly, observe these requirements:

### Clear the System

Clear all boards from the system before selecting Auto Program. Any board arriving in the system while the system is powered off can cause an [Out-of-Sequence Condition](#) (pg 4.80).

**NOTE:** For the discussion of this barcode feature, the term “system” refers to the dispenser AND all devices including and between the device into which the barcode reader hardware is integrated. For example, if the barcode reader is mounted to a preheater upstream from the dispenser, the preheater and any other device inline between the preheater and the dispenser is considered part of the “system”.

### Auto Program

Turn on Auto Program mode BEFORE a board arrives at the barcode reader. See [Controlling Barcode Selection](#) (pg 4.78).

### Board Delay

Maintain a board feed delay that will allow the dispenser to begin processing the current board before the next board is allowed to trigger the barcode reader; otherwise, a [Lost Label](#) (pg 4.80) condition could result.

### Resumption Points

The [Resumption Points for Underfill - UltiPath™](#) (pg 4.62) feature can be used in a program that processes boards using a board flip device AND a barcode reader. If the barcode reader is not present, however, resumption points are incompatible with a board flip device.

## Controlling Barcode Selection

Turning the Auto Program mode on and off turns the barcode selection feature on and off.

### Turning On Auto Program

---

To turn on the Auto Program mode:

1. The dispenser uses its last known XYZ calibration during Auto Program mode, so before entering Auto Program mode, calibrate the valve:

**NOTE:** It is presumed that a "family" of boards is run with the barcode reader, i.e., all the boards in a run can be processed successfully using the same calibration template).

- a. Mount the valve that will be used during Auto Program mode.
  - b. Begin a calibrate program for the valve and then cancel the program after the calibration sequence part of the program is complete.
2. [Clear the System](#) (pg 4.78) of all boards.
  3. Select the Auto Program button. The button turns red when the option is turned on.



**DANGER:** The dispenser becomes active as soon as Auto Program is turned on. Automatic operations now control gantry movement.

4. Verify that both the Conveyor Off and Stand-Alone buttons are turned off.
5. Optional. To re-calibrate material dispense weight for each board as it enters the dispenser, add a Calibrate operation with a SubOp of Weight at the beginning of the program to be initiated by the barcode reader.

The barcode program begins its endless cycle until an error occurs or Auto Program is turned off.

### Turning Off Auto Program

---

To turn off the Auto Program mode, deselect the Auto Program used button located on the main window. The button turns gray when the option is turned off.

**NOTE:** If you turn off Auto Program while the dispenser is still in the process of running a program, the program will finish running and the system will return to the standard run mode.

## Stop Operations

### Emergency Stop

If either the Emergency Stop or Motion Stop buttons is pressed or a safety shield is opened while the dispenser is in Auto Program mode, Auto Program mode and the currently selected program are both canceled.

### Cancel

If the CANCEL button is pressed while the dispenser is in Auto Program mode, Auto Program mode and the currently selected program are both canceled. Occasionally a program will not abort immediately as the current operation has to execute fully.

### Pause

If the PAUSE button is pressed while the dispenser is in Auto Program mode, the current operation is stopped at a convenient place in the program and operations can be resumed by clicking the RUN button.

## Troubleshooting

### Waiting for Instructions

---

A Waiting for Instructions message can indicate the barcode reader failed to trigger. For example, if a board is already in the dispenser nest when Auto Program mode is turned on, the dispenser will wait for the operator to take action.

If the Waiting for Instructions message is allowed to time out, the operator is presented with a chance to select a program to run. Before running the newly selected program, Auto Program mode is automatically canceled and the current board is ejected from the dispenser nest.

## **ERROR\_NO\_READ**

---

The ERROR\_NO\_READ program name displays in the Currently Selected Program field on the main window when a barcode triggers the reader but the data is unsuccessfully read or decoded.

## **Fails to Find Fiducials**

---

If the dispenser cannot find the program fiducials, press ABORT in the Jog window to terminate the program and cancel Auto Program.

## **Lost Label**

---

A lost label condition could result if boards are fed into the system without a sufficient time delay between boards. A delay is needed between the time the dispenser begins processing the current board and the time the next board is allowed to trigger the barcode reader. A six (6) second delay is generally long enough to allow dispenser gantry motion to start.

For example, if board B arrives at the barcode reader before the dispenser has completely read the barcode file for board A, then the file for board A will be replaced with the file read for board B.

## **Out-of-Sequence Condition**

---

If the dispenser is powered off when a board arrives at the barcode reader, the dispenser will not receive barcode data from that board. The dispenser will display a *Waiting for Instructions* or *Waiting for Info* message and remain in a waiting status until the out-of-sequence condition can be cleared.

For example, if board A has already past the barcode reader and is waiting to enter the empty dispenser nest when you turn on the system and select Auto Program, then the barcode scan was not triggered. Board A will enter the nest, the next board in sequence (board B) will pass the barcode reader, and the dispenser will execute the program for board B on board A.

To clear an out-of-sequence condition:

1. Exit the Auto Program mode.
2. Remove all boards from the system.
3. You can now turn on Auto Program mode.

## **Calibration**

---

To recalibrate the dispense weight for each board that enters the dispenser, add a Calibrate Subop Weight at the beginning of the program.

## Barcode Scan Program Select

**IN EFFECT AS OF FLOWare software version 2.9.3P**

PN 2050-0094

This feature allows the operator to scan a barcode (*product code*) with a handheld scanner to configure which dispenser program will execute the next time a program is run by the dispenser.

A *product code to program id* mapping file is maintained on the dispenser. This file contains a list of *product codes* and their associated *dispenser program identifiers*. This mapping file allows multiple *product codes* to be mapped to dispenser programs. This reduces the number of required dispenser programs but requires maintenance of the *mappings file*.

There are two basic modes of operation:

- The dispenser executes the most recently selected program until that program is changed by scanning a different *product code*.
- The dispenser executes a program exactly once per scanned *product code*. This forces the operator to scan a product code prior to running *any* product.

### How to Use the Mappings File

To edit the mappings file:

1. Scan one of the [Command Codes](#) (pg 4.81).

Successful scan	The handheld scanner emits a single high pitched beep.
Unsuccessful scan	The handheld scanner emits a low pitched buzz.

When a scan is successful, the dispenser has recognized the scanned *product code* and opens a text editor on the FLOWare screen allowing you to edit the mappings file.

2. Review [Part Number Mappings File](#) (pg 4.82).
3. Edit the mappings file as necessary per [Editing the Mappings File](#) (pg 4.82).
4. Save the file and close the editor. The new mappings are in effect immediately.

### Command Codes

Choose either a graphical editor or a text editor to edit part number mappings. Scan the QR code that matches your choice.

---

#### Use Graphical Editor

to edit part number mappings.



#### Use Text Editor

to edit part number mappings.



## Part Number Mappings File

To configure a *product code* to program id mapping, the mappings file must be maintained.

The mappings file is a structured text file which contains program ids and their associated *product codes*.

The mappings file contains dispenser program ids followed by 1 or more *product codes* associated with that program id.

### Example 1 - single dispenser program with multiple *product codes*:

```
dispenseProgram1:
    SD-S14OB-022-V01
    SD-S18OB-009-V01
    SD-S19OB-001-20220-V01
```

These mappings designate that when any of the three product codes (SD-S14OB-022-V01,SD-S18OB-009-V01 and SD-S19OB-001-20220-V01) are scanned, the dispenser program `dispenseProgram1` will be loaded and executed.

### Example 2 - multiple dispenser programs each with multiple *product codes*:

```
productClass14:
    SD-S14OB-001-20220-V01
    SD-S14OB-002-20220-V11
    SD-S14OB-003-20220-V41
productClass18:
    SD-S18OB-009-V01
    SD-S18OB-001-20220-V01
productClass09:
    SD-S09OB-022-V01
    SD-S09OB-001-20220-V01
```

## Editing the Mappings File

There are two CQ [Command Codes](#) (pg 4.81). Each code starts a file editor on the proper mappings file, but each starts a different text editor:

- NEdit is a graphical editor which most users will find intuitive to use
- VEdit is a text based editor preferred by some

**SUGGESTION:** Print your preferred command code and store it near (or on) the dispenser for easy access.

## Rules

---

- Dispenser program ids must end with a colon (:)
- Dispenser program ids are any combination of letters, numbers, spaces, underscores, and hyphens.

- Dispenser program ids must match the expression designated by the `progid-patt` key in the configuration file. For details, refer to [Testing & Validating Mappings and Configuration](#) (pg 4.83).
- Product Codes are associated with the *immediately preceding program id*
- Product Codes must match one of the expressions designated by the `partno-patt` key in the configuration file. For details, refer to [Testing & Validating Mappings and Configuration](#) (pg 4.83).
- Comments and blank lines are allowed

#### Example - Mappings File:

Comments are prefixed with a hash (#).

```
## Product Code / Recipe ID Mappings
## Recipe Ids end with a colon
## Product codes are indented and associated with the preceding recipe id
##
## blank lines are allowed

# recipe id
recipe_001:
    # some product codes
    SD-S14OB-001-20220-V01 # uses recipe_001
    SD-S14OB-002-20220-V11 # uses recipe_001
    SD-S14OB-003-20220-V41 # uses recipe_001

# another recipe id
recipe_010:
    # some product codes
    SD-S18OB-001-20220-V01 # uses recipe_010
    SD-S17OB-002-20220-V11 # uses recipe_010
    SD-S11OB-003-20220-V41 # uses recipe_010
```

### Testing & Validating Mappings and Configuration

Refer to *Periodic Operations - TEST Barcode Scan Program* in the *Dispenser Service Guide* for details.

## Board Flip Control

### ***IN EFFECT AS OF FLOWare software version 2.8***

The board flip software control feature enables the following process:

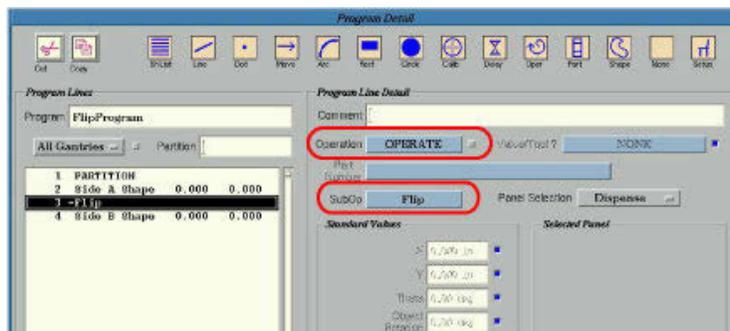
1. Equipment external to the dispenser presents a board to the dispenser conveyor.
2. The dispenser conveyor moves the board into the dispenser work area and begins program execution.
3. The dispenser program stops when it encounters a Flip program line.
4. The dispenser conveyor reverses direction and returns the board to the entrance end of the conveyor (or external equipment).
5. The external equipment flips the board and returns it to the dispenser.
6. The dispenser skips all programming up to and including the Flip program line, executes the remainder of the program, and then releases the board normally to the exit end of the conveyor.

### Requirements

Board flip software control requires an additional conveyor relay and two additional SMEMA lines. For further details about hardware and cabling, refer to the service document entitled *SMEMA Hardware & Cable*.

### Flip Program Line

To create a Flip program line, select an Operation of **OPERATE** and a SubOp of **Flip**.



### Flip Operations

If a program includes selections for pre-scan patterns and pre-scan probes, the dispenser will pre-scan everything on the initial board side prior to executing the Flip program line. After the board is flipped, the dispenser will again pre-scan everything on the new board side.

## Dynamic Load Program

### **IN EFFECT AS OF FLOWare software version 2.9.3K**

The Dynamic Load Program option allows a device instead of a user to select a program. It simplifies the loading of FLOWare software programs for most conveyORIZED scenarios by automatically loading a program selected by a device that generates a program ID.

#### **Examples:**

A barcode reader is a device that generates program IDs, as is a wafer handling unit.

[For a conveyORIZED system with an upstream barcode reader and board flipper, refer instead to [Auto Mode](#) (pg 4.76).]

#### **Assumptions:**

- FLOWare control software Version 2.9.3K or later is installed on the system.
- The system is configured with a conveyor and other relevant hardware.
- The system is configured for the Dynamic Load Program option (in a configuration file set up at the factory).
- The system is *not* placed in Auto Mode. Dynamic Load Program and Auto Mode are mutually exclusive - implementing one rules out use of the other.

## Process Flow

FLOWare control software tests for the existence of a Dynamic Load Program *file name* at various points in a run:

- immediately upon completion of a unit, or
- while waiting for unit delivery by the conveyor.

The current program remains selected from the time conveyor transport begins until the new unit is completely processed. A dynamically loaded program is treated exactly as if selected by a user except the user is not presented with the Mount dialog prior to calibration.

#### **File Name Found**

If the Dynamic Load Program *file name* is found and contains a valid *program name*, the designated program is loaded and processing continues as if the user had selected the new program and pressed the RUN button.

#### **File Name Not Found**

If the Dynamic Load Program *file name* is not found or does not contain a valid *program name*, processing continues normally using the current program.

## Material Weigh Module

### ***IN EFFECT AS OF FLOWare software version 2.9.30***

This software feature is intended for use with a precision weight scale.

Use the Material Weigh Module to monitor weights during a process by acquiring a weight measurement at any time during a process and comparing it against a reference weight to determine if quantities dispensed at the end of a process remain within tolerance.

This process monitoring tool is integral to a program and performs tests of process consistency by weight. This process tool allows you to (1) change how frequently weight sampling occurs and (2) edit the value of the tolerance range used when the module compares sample weight(s) to a reference weight.

A process program must be running because weigh operations are triggered during the process by the program.

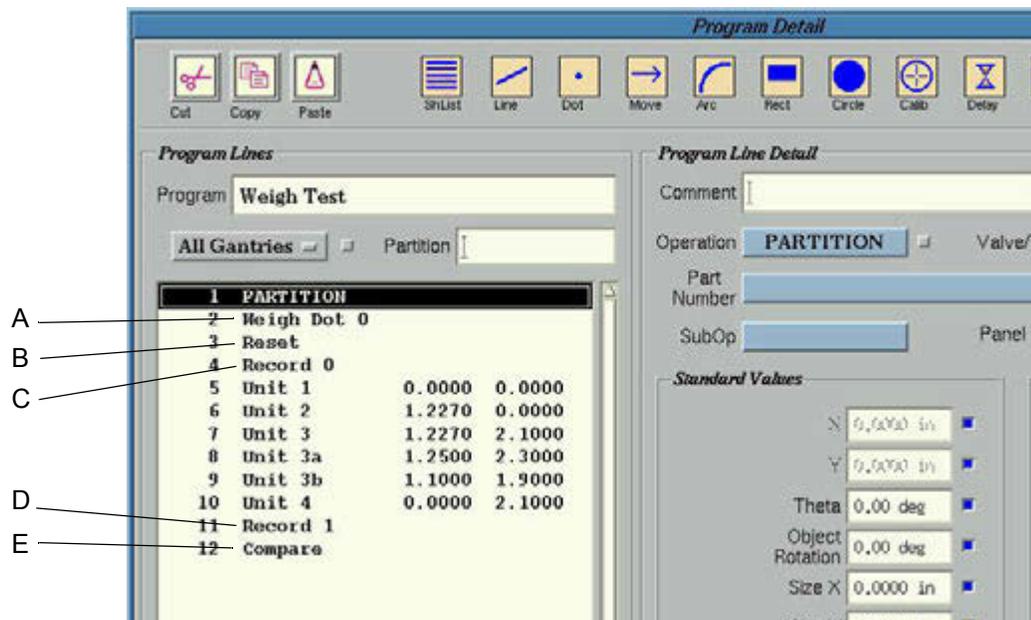
### Theory of Operation

Numerous sample weight operations can occur in a program but for purposes of this explanation, only two sample weights are used.

1. Start a program that includes the Material Weigh Module.
2. After the program dispenses material at the first component, a “monitoring” weight is dispensed and weighed at the scale. This weight is saved as the **reference weight** in **record location 0**.
3. After dispensing material at several more components, a “monitoring” weight is dispensed and weighed at the scale. This weight is saved as the **sample weight** for **record location 1**.
4. After dispensing material at the remaining components, another “monitoring” weight is dispensed and weighed at the scale. This weight is saved as the **sample weight** for **record location 2**.
5. All sample weights are compared against the reference weight. If sample weights are within tolerance, the program continues. If sample weights are outside tolerance, an error message displays and the program pauses for operator action.

## Sample Program using Material Weigh Module

The sample program shown here uses a single sample weigh operation. Values and frequency of the sample weigh operation will vary in your programs due to different processes, materials, and pumps.



- |   |                           |
|---|---------------------------|
| A | Priming shape             |
| B | Reset operation           |
| C | Reference weigh operation |
| D | Sample weigh operation    |
| E | Compare weights operation |

### Priming Shape

(optional) - Increases program efficiency. Performing priming prior to Reset decreases the weight difference between the reference weight and sample weight(s) using the fewest program lines.

### Reset

Clears weight values from all record locations.

### Reference Weigh

The reference weight is assumed to be the current value of a dispense. The value for the reference weight is always stored in record location 0.

### Sample Weigh

The weight value captured at any time during a process run between the Reference Weigh operation and Compare Weights operation. Each captured weight value is stored in a separate record location.

### Compare Weights Operation

Tests whether or not sample weights are within tolerance when compared to the reference weight. When a Compare operation is performed, all weights from Record 1 through Record  $n$  are compared against the reference weight. In the above sample program, Record 1 is compared to Record 0.

## Editing Material Weigh Module Program

You may change how frequently weight sampling occurs during a process run. You may also change the value of the tolerance used when the Material Weigh Module compares sample weight(s) to the reference weight.

### Frequency of Weight Sampling

To change how often the weigh operation occurs, edit the program. The number of sample weighs is controlled by the number of sample weigh operations in your program.

For example, the following is what the [Sample Program using Material Weigh Module](#) (pg 4.87) would look like if you increased weight sampling frequency to occur after every two dispense operations:

Line	Operation	Weight 1	Weight 2
1	PARTITION		
2	Weigh Dot 0		
3	Reset		
4	Record 0		
5	Unit 1	0.0000	0.0000
6	Unit 2	1.2270	0.0000
7	Record 1		
8	Unit 3	1.2270	2.1000
9	Unit 3a	1.2500	2.3000
10	Record 2		
11	Unit 3b	1.1000	1.9000
12	Unit 4	0.0000	2.1000
13	Record 3		
14	Compare		

A	Priming shape
B	Reset operation
C	Reference weigh operations
D, New	Sample weigh operation
E	Compare weights operation

### Rules for Sample Weigh Operations

RULE #1 - Use sample weigh operations anywhere in a program between the Reference Weigh and Compare operations.

Line	Operation	Weight 1	Weight 2
1	PARTITION		
2	Weigh Dot 0		
3	Reset		
4	Record 0		
5	Unit 1	0.0000	0.0000
6	Unit 2	1.2270	0.0000
7	Record 1		
8	Unit 3	1.2270	2.1000
9	Unit 3a	1.2500	2.3000
10	Record 2		
11	Unit 3b	1.1000	1.9000
12	Unit 4	0.0000	2.1000
13	Record 3		
14	Compare		

C	Reference weigh operations
E	Compare weights operation

RULE #2 - Each captured weight value is automatically stored in a separate record location.

*Captured Weight Values are Stored in Record Locations*

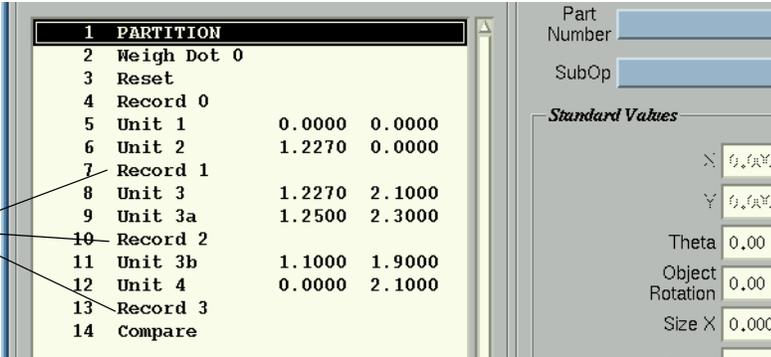
Record Location	Captured Weight Value
Record 0	<i>n</i>
Record 1	<i>n</i>
Record 2	<i>n</i>
Record 3	<i>n</i>
Record 4	<i>n</i>
Record 5	<i>n</i>
Record 6	<i>n</i>
Record 7	<i>n</i>

**NOTE:** If you require additional record locations, contact us.

## Recommendation for Sample Weigh Operations

### Maintain numeric sequence

Notice the numeric sequence of the sample weigh operations shown below. When using multiple sample weigh operations, we recommend maintaining numeric sequence as this lends clarity to future data analysis.



1	PARTITION		
2	Weigh Dot 0		
3	Reset		
4	Record 0		
5	Unit 1	0.0000	0.0000
6	Unit 2	1.2270	0.0000
7	Record 1		
8	Unit 3	1.2270	2.1000
9	Unit 3a	1.2500	2.3000
10	Record 2		
11	Unit 3b	1.1000	1.9000
12	Unit 4	0.0000	2.1000
13	Record 3		
14	Compare		

D Sample weigh operation

## Tolerance for Weigh Samples

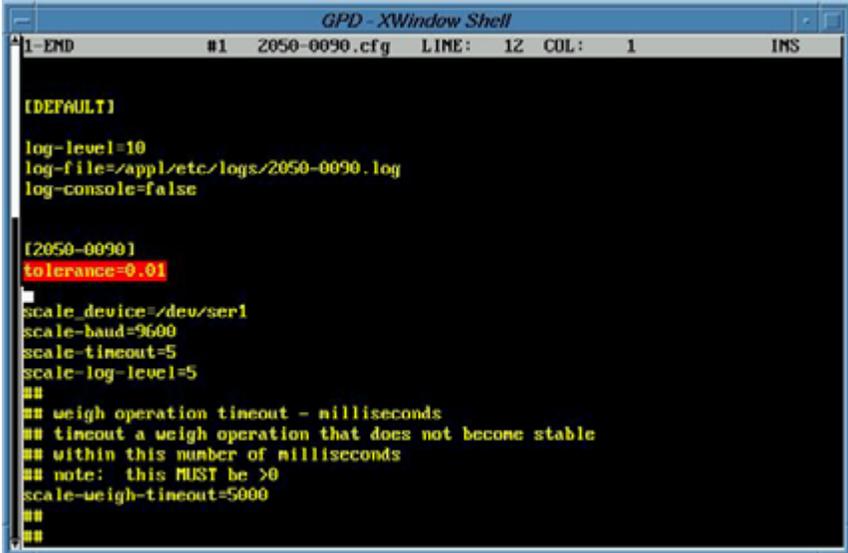
To change the allowable tolerance for the comparison function, open a shell and edit the tolerance value in the appropriate file.

**WARNING** The content of this section is NOT recommended for use by anyone besides GPD Global personnel or those working under the direct guidance of GPD Global personnel. Improper application of this information can lead to serious complications in FLOWare Software operations. Any non-GPD Global employee who uses this information beyond the stated application specified by GPD Global Service Department personnel is in danger of causing personal injury and invalidating their machine warranty.

<b>ATTENTION</b> <a href="#">Le contenu de cette</a>	<b>WARNUNG</b> <a href="#">Der Inhalt dieses</a>	<b>ATTENZIONE</b> <a href="#">Il contenuto</a>	<b>ADVERTENCIA</b> <a href="#">NO SE RECOMIENDA</a>
---	---	---	--

To edit the allowable tolerance value for the comparison function:

1. From the main menu bar, click on System Functions > Shell.
2. At the \$ prompt, type `cd /appl/etc/config/` and press Enter.
3. At the \$ prompt, type `2050-0090.cfg`
4. Edit the value for `tolerance`.



```

GPD - XWindow Shell
#1 2050-0090.cfg LINE: 12 COL: 1 IMS
[DEFAULT]
log-level=10
log-file=/appl/etc/logs/2050-0090.log
log-console=false

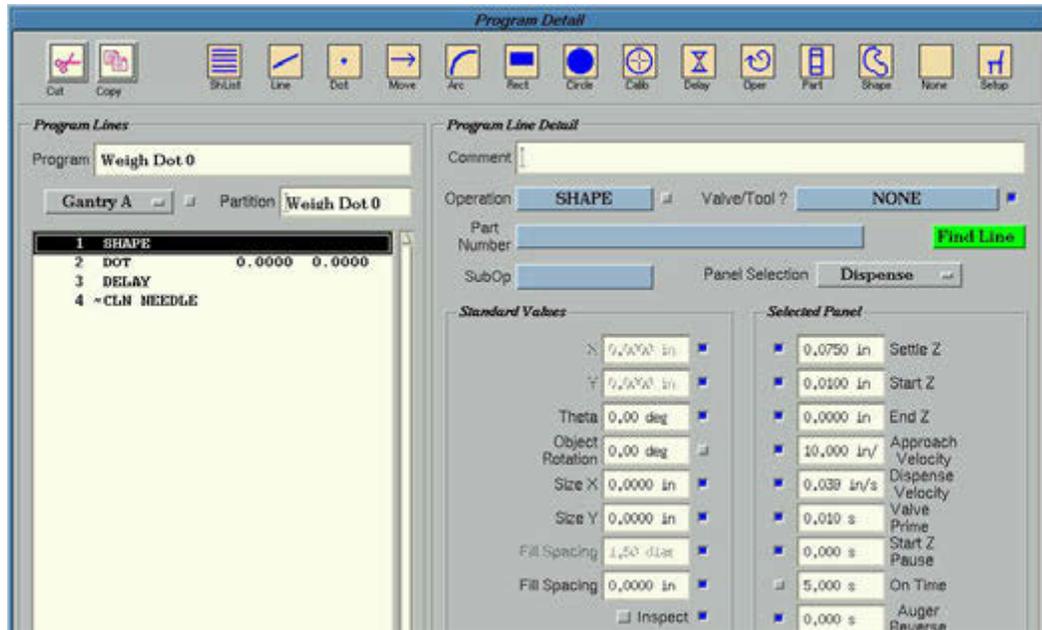
[2050-0090]
tolerance=0.01
scale_device=/dev/ser1
scale-baud=9600
scale-timeout=5
scale-log-level=5
###
## weigh operation timeout - milliseconds
## timeout a weigh operation that does not become stable
## within this number of milliseconds
## note: this MUST be >0
scale-weigh-timeout=5000
###

```

5. Save your change by pressing the ESC key, X for eXit, and Y to save all.
6. Reboot the system to implement the changed value.

## Editing Weigh Sample Parameters

To change the parameters for a weigh sample, edit the pertinent parameter(s) for the (standard) shape used in your program. For example, if your program uses the Dot shape, then for some pump types, you would change the OnTime value for the Dot shape.



## Weight Calibrated Shapes

**IN EFFECT AS OF FLOWare software version 2.9.1**

This software feature is intended for use with a precision weight scale.

### Why use Weight Calibrated Shapes?

Achieve the dispense pattern weight you want without performing trial-and-error program adjustments. Use the Contour Mapping software routine to:

- reduce setup time,
- program a complex dispense pattern consisting of lines, arcs, dots, etc., with as many features as required,
- make adjustments to a dispense pattern while maintaining a desired weight, or
- adjust the weight with the same pattern.

During pattern setup, a base pump speed is defined and the desired weight for the dispensed pattern is entered. The program is run and the system records pump starts, pump stops, and the movement time between segments. These starts, stops, and delays are then duplicated at the weight scale. The system adjusts pump speed to attain the desired weight.

Each dispense pattern used in a program can be calibrated to a specific weight or just to a specific pattern. This feature greatly reduces setup time and allows users to (1) make adjustments to the dispense pattern while maintaining the desired weight or (2) adjust the weight with the same pattern.

For other weight scale features and parameters, refer to [Scale Set Up within Software](#) (pg 3.130).

### Theory of Operation

The [Contour Mapping Editor](#) (pg 5.24) presents a list of shapes for the currently selected program. You need only enter weight calibration data on a shape-by-shape basis. At the next program run, the system attempts to dispense the desired amount of material (by weight) for the given shape(s):

1. When calibration is called for during the program run, the pump moves to the weight scale and dispenses at the program-specified speed for the amount of time previously measured for the shape being calibrated.
2. After the initial weight of the shape is determined, pump speed is adjusted and the pump once again dispenses material for the shape on the weight scale. If no suitable calibration data is located, the pump speed is used unchanged from the program.
3. If further adjustments are required to fine tune the actual weight being dispensed, then calibration is tried again. A total of three calibration attempts are made before operator intervention is required. If prompted, the operator is presented with these choices:
  - **Retry** - calibration is tried, at most, three more times.
  - **Ignore** - calibration is abandoned and the program continues using the previous calibration values (if any).
  - **Cancel** - the program is terminated.

## Guidelines for Shape Calibration

The Contour Mapping feature is only accessible when the dispenser is configured for the weight scale option (and the correct password has been entered).

**“Shape”.** The term “shape” refers to a shape programmed via the FLOWare software, NOT the shape of the material being dispensed.

**RULE:** A shape must be created as a shape, not by using a program.

**RULE:** A shape must be fully executed by a program at least once before the shape can be calibrated.

**Shape ID.** Because calibrated shapes are identified by both their *program AND shape*, calibrating a shape in one program does NOT calibrate the shape in another program.

**RULE:** A shape shared between programs has a separate and distinct calibration for each of the programs.

**Nested Shapes.** Do not calibrate both a nested shape and one of its sub-shapes.

**EXAMPLE:** If shape A contains shapes B and C, calibrate only shape A. Even though it is possible to do so, calibrating a nested shape and a sub-shape will generate undesirable results.

**RULE:** Calibrate only the nested shape, not the sub-shape.

**Weight Range.** To achieve good results, keep a shape's *programmed* weight reasonably close in value to the desired *calibrated* weight.

**EXAMPLE:** If a shape is programmed to dispense 500 mg of material and you try to calibrate it to dispense 5 mg of material through pump speed adjustment, the results will be disappointing.

**Weight Time.** Weight time cannot be set independently because weight calibration is specific to shape elements.

**RULE:** The value for Weighing On Time must be zero (0).

**Single Pump Speed.** If multiple pump speeds are used to dispense a shape, weight calibration will not work.

**RULE:** Only shapes using a single pump speed will calibrate properly.

**Pump.** The Contour Mapping feature functions for pumps with encoder count capability.

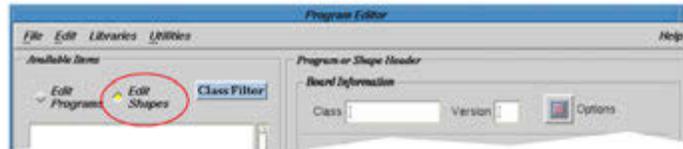
**EXAMPLE:** Micro-Dot, PCD3H, PCD4H, and LX Auger pumps.

## Calibrating Weight Data

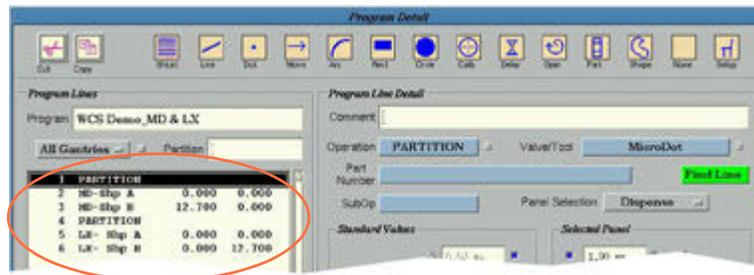
Once created and set up, a program can automatically calibrate one or more shapes during program execution.

### 1 - Create a Program with Custom Shapes

1. Create shapes to represent desired pattern. For details, refer to [Custom Shapes](#) (pg 3.56).



2. Create a program with all shapes that represent desired pattern.



3. For each pump used by the program, set the Weighing On Time to zero (0).



### 2 - Generate Timing Values

The first time the program runs, the system generates timing values for each shape, so follow these steps:

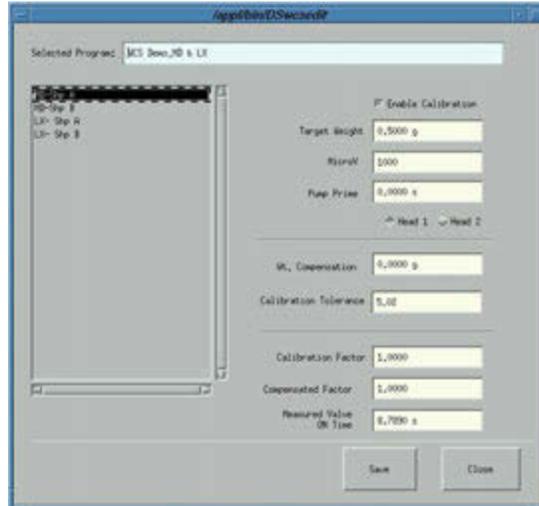
1. (Optional.) Use sample substrate for the first program run.
2. Select the program.
3. Run the program. Let the program and calibration sequence complete a full cycle.
4. Abort the program after it completes one full cycle.

### 3 - Enter Weight Calibration Data

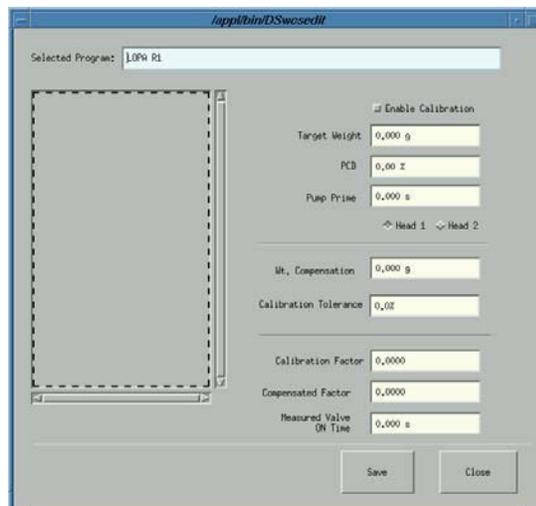
To enter weight calibration data for a shape:

1. Select SHPCAL in the main menu button bar to open the Contour Mapping Editor.

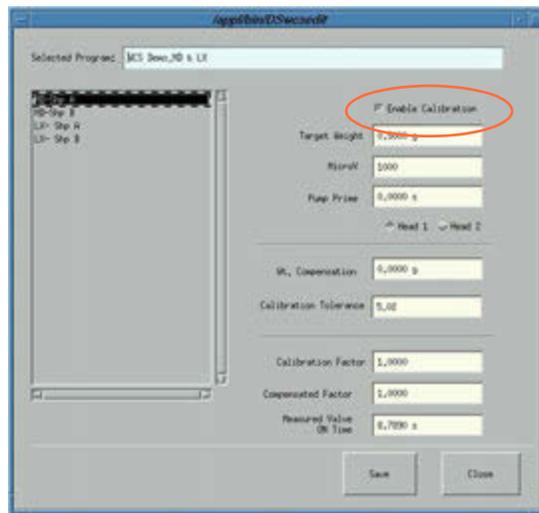
The name of the selected program displays in Selected Program. A list of all shapes in the currently selected program also displays.



An absence of a list of shapes suggests the program needs to be run. Perform [2 - Generate Timing Values](#) (pg 4.94).



2. Select (highlight) a shape in the list of shapes.
3. Check the Enable Calibration check box to activate weight calibration during program execution.



4. Enter desired material weight (in mg) of the shape in Target Weight.

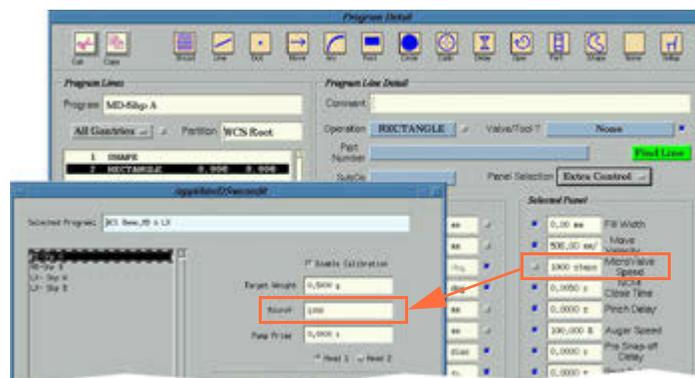
**NOTE:** The calibration routine can handle a minimum net weight of 0.001g. If the dispensed sample weighs less than this amount, the system interprets a net weight of 0.0g.

5. Enter correct value for pump speed.

**RULE:** The pump speed in Contour Mapping must equal the pump speed used in Program Detail or else incorrect data will result.

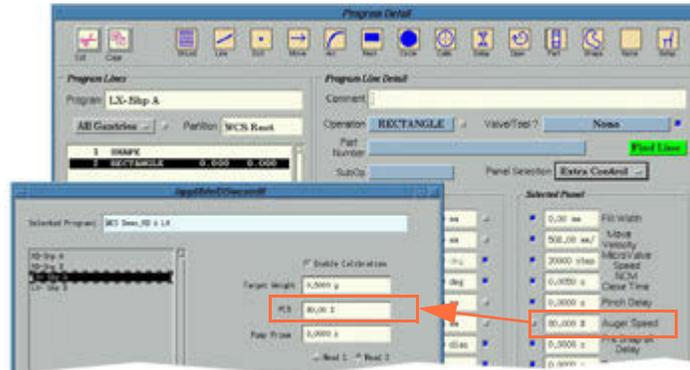
**EXAMPLE 1:** For Micro-Dot type pump, the value of *MicroV* must match *Micro Valve Speed*.

**Figure 31:** Match speed fields for Micro-Dot type pumps

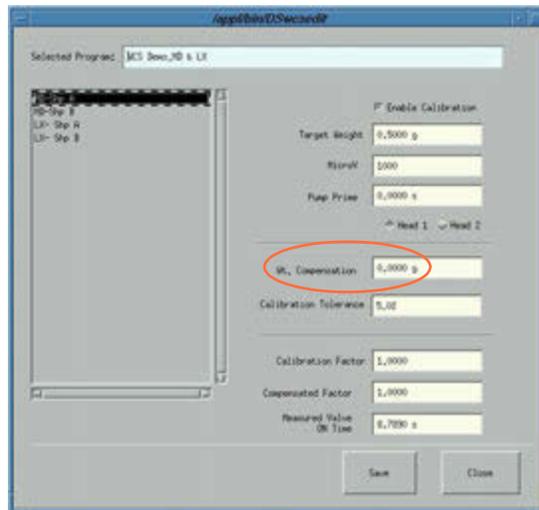


**EXAMPLE 2:** For PCD or LX Auger type pump, the value of *PCD* must match *Auger Speed*.

**Figure 32:** Match speed fields for PCD and LX type pumps



6. Click SAVE to save the data.
7. Click CLOSE to close the window.
8. Run the program. Calibration of each shape occurs prior to program execution.
  - If calibration results are within weight specification, your program is ready to for production.
  - If calibration results are not within weight specification, select the RETRY button, increase or decrease the Weight Compensation value, and run then the program again.



## UV Wand Curing Light

### ***IN EFFECT AS OF FLOWare software version 2.9.1***

When an optional UV curing light is integrated into the dispenser, UV wand control is managed by the FLOWare control software with the following customized SubOp controls created in the [SubType Editor](#) (pg 5.103) using SubType 0. (For additional details, refer to [SubOps & SubTypes](#) (pg 5.114).

#### **UV Bulb Functioning**

An input/output has been set up to detect the bulb ON state (i.e., not burned out). A program that calls for UV operations will operate only if the bulb is in the ON state and up to full light intensity. To check the UV bulb state before the lamp is to be used, use an Operate SubOp of **Lamp Lit**.

This function may not be available with all UV control boxes.

#### **UV Light ON/OFF (shutter open/closed)**

The UV bulb is always in the ON state due to the warm-up period required by the bulb to attain full light intensity. Light is emitted when the shutter is open. Control of the shutter is available by using the Operate SubOps of **UV ON** and **UV OFF**.

#### **UV Shutter Fault**

The UV shutter fault is checked to confirm that the shutter has opened when called for. This test should be run at the beginning of a program after UV ON has occurred. To verify that UV shutter fault is checked, add an Operate SubOp of **Shutter Open** after UV ON. A slight delay for checking can be added.

This function may not be available with all UV control boxes.

#### **Safety Package**

The UV bulb turns OFF when any dispenser window or shield is opened. Control of the UV bulb shutter is linked directly into the standard, interlocked, dispenser safety package.

To use the UV wand in a program:

1. Define the UV wand position using the **Head 4 to Target (XY)** base location.
2. To manage UV wand control in a program, add these program lines near the beginning of your program:
  - a. Optional. To verify the UV wand is ready, add an [Operate](#) (pg 5.112) program line with a SubOp of **Lamp Lit**.
  - b. To open the UV wand shutter, add another [Operate](#) (pg 5.112) program line, this time with a SubOp of **UV ON**.
  - c. Optional. To verify the UV light shutter has opened, add another program line with a SubOp of **Shutter Open**. A slight delay (between 0.5 second and 1 second) for checking can be added by entering a value in the Operation Time field.
3. To close the UV wand shutter after your program is done running, add an Operate program line with a SubOp of **UV OFF** near the end of your program.

# 5 References

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This chapter presents reference material from which you can obtain detailed information about the various libraries, window content, and preprogramming primitive operations used by the FLOWare software.

- [Libraries](#) (pg 5.1)
- [Windows & Fields](#) (pg 5.22)
- [Operations \(Primitives\)](#) (pg 5.108)
- [SubOps & SubTypes](#) (pg 5.114)
- [Legacy Controls & Operations](#) (pg 5.120)

## Libraries

Data is organized into a variety of libraries, each of which is discussed in this section. Each library is accessible with the proper access rights via the Program Editor.

- [Fixed Locations Library](#) (pg 5.3) - define and edit fixed locations.
- [Heads Library](#) (pg 5.5) - add, modify, or delete a mount position from the list of mount position types currently available.
- [Materials Library](#) (pg 5.7) - add, modify, or delete a material from the list of materials currently available.
- [Material Defaults Library](#) (pg 5.9) - define defaults for materials according to head mount position.
- [Needles Library](#) (pg 5.11) - define a needle or change the characteristics of an existing needle
- [Part Numbers Library](#) (pg 5.12) - define individual cross reference records or change the shape associated with an existing cross reference record.
- [Passwords & Access Rights Library](#) (pg 5.13) - add or delete a user name, change access rights for a user name, or change the password for a user name.
- [Patterns Library](#) (pg 5.16) to create or modify shapes to be used as patterns during fiducial or bad mark pattern recognition by the (optional) automatic vision system to locate a product and adjust for its orientation.
- [SubTypes Library](#) (pg 5.18) to define and edit subtypes.

## Changes and Deletions

The process by which library records can be changed or deleted is the same for many of the libraries; the required steps are listed below. When this is not the case, detailed instructions are provided in each library-specific section along with the instructions on how to add records to each library.

### Edit a Library Record

To change parameters in a library record:

1. Open the Program Editor, click on Libraries, and select a library from the pull-down menu. The editor window for the selected library will display.
2. Click the select button ▼ by the name field, select the record to be changed, and click ACCEPT.
3. Make desired changes. We strongly recommend you add text in the Description field to indicate why this record is significant to your site (what does this record do and/or what is its purpose).
4. Click APPLY to save the changes or click CLOSE to cancel.
5. Click CLOSE to exit the window.

### Delete a Library Record

To delete a record from a library:

1. Open the Program Editor, click on Libraries, and select a library from the pull-down menu. The editor window for the selected library will display.
2. Choose one of the following actions:
  - **Delete the Displayed Record**

To delete the record displayed in the name field, click the DELETE button. Click OK on the confirmation prompt that displays or click CANCEL to close the prompt without deleting.
  - **Select and Delete Record(s)**
    - Single records - to select and delete a single record, click the select button ▼ by the name field, select the record to be deleted, and click ACCEPT.
    - Multiple records - to select and delete multiple records, click the select button ▼ by the name field, use the <Ctrl> button to select as many records as you want to delete, then click ACCEPT.

## Fixed Locations Library

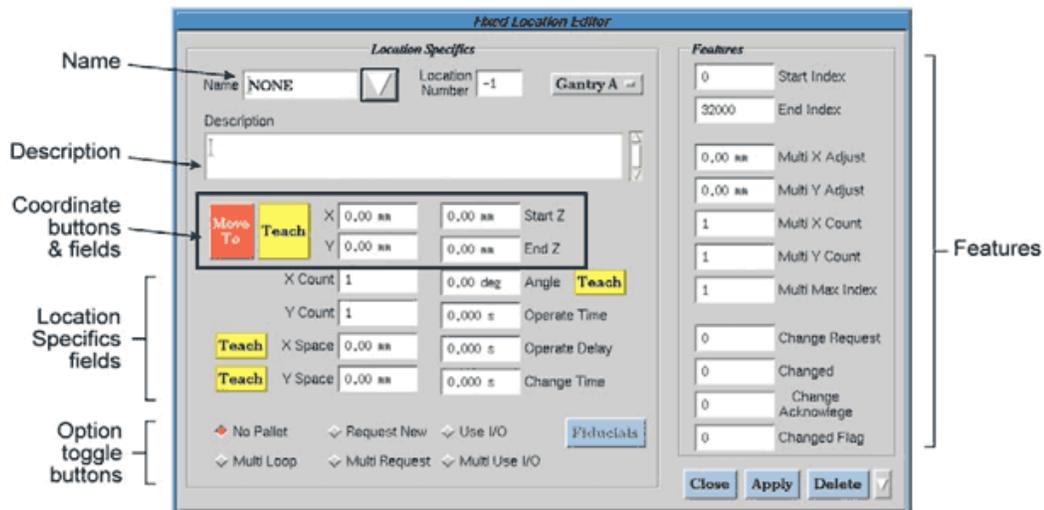
Fixed locations are normally used in pick-&-place programs and are typically taught at the part pick-up-point of a pallet or a feeder. Because they eliminate the need for height sensing at the pick-up-point, fixed locations can also reduce program execution time.

A fixed location defines a location fixed in accordance with the dispenser table – it is a point within the work area independent of board location, i.e., fixed locations remain unaffected by program compensation adjustments made for board orientation.

**The use of a fixed location enables pallets to be reset selectively.** A fixed location is the position of the first item on a pallet or a feeder and all device data points are measured from it. A fixed location will often be taught at the center or corner of a pallet pocket. A pallet is considered to be an array of pick up points; a multiple pallet is an array of pallets; and a feeder, also based on pallets, is considered to be a 1 row by 1 column pallet.

Pallet size, spacing, and other parameters are defined when the fixed location is defined. These types of parameters, along with the coordinates of the fixed location, can be changed within a program using the Fixed Location Editor. Fixed location coordinates should not be adjusted manually.

Fixed location values can and usually should be exported to permit reloading without the need to re-teach points. The import of fixed location values requires special system privilege.



## Add a Fixed Location

When creating a new fixed location, keep in mind that certain conditions that exist during execution of the program using this new fixed location need to be in place while you teach the fixed location coordinates. Also be aware that teaching accurate coordinates requires you to install the same head (valve or tool) that will be used during program execution. Be sure to install the head in the actual mount station position that will be used by the program.

To add a new fixed location:

1. Open the Program Editor and click on Libraries > Fixed Locations. [Fixed Location Editor](#) (pg 5.35) displays.
2. Create a fixed location record:
  - a. Enter a name in the Name field.
  - b. Type text in the Description box identifying the purpose for this fixed location.
  - c. **Click APPLY now** to save the new record name.
3. Teach the coordinates for the new fixed location record:
  - a. Install the valve or tool. To ensure accuracy and prevent equipment damage, use the actual head and mount station position designated for use with this fixed location.
  - b. Use the coordinate buttons and fields to teach X,Y and Z coordinates.
4. Add additional parameter detail as needed:
  - a. If a pallet or array rotation needs to be defined, teach the angle coordinate by using the Angle field TEACH button to teach the pallet pickup point farthest along the X axis from the point already taught for the XYZ coordinates.
  - b. As needed, enter or teach the remaining Location Specifics fields.
  - c. Verify that the option toggle button applicable to the new fixed location is activated.
  - d. Enter values, as needed, in the Features fields.
5. Click APPLY again to save your additional input or CLOSE to exit the window without saving the parameter detail.
6. Click CLOSE to exit the Fixed Location Editor.
7. Remove the teaching tool from the mount position station.

## Edit a Fixed Location

To change parameters for a fixed location, refer to [Edit a Library Record](#) (pg 5.2).

## Delete a Fixed Location

To delete one or more fixed locations from the fixed locations library, refer to [Delete a Library Record](#) (pg 5.2).

## Heads Library

The head library contains a set of predefined head records describing the properties and defaults for the various valves and tools that might be mounted on the machine. You may create and add new heads to the library or select an existing head and modify its characteristics.

The head library is useful for eliminating operator setup mistakes by:

- associating parameters with a particular valve type.
- associating valve parameters with a program.
- enabling you to add, modify, or delete a mount position from the list of available mount position types.

Head additions and modifications can be made at any time by accessing the Valve/Tool Editor either directly through the Program Editor or indirectly through the materials or material defaults libraries (the Mounts/Material Editor windows).

Clicking the selector button next to the Valve/Tool Name field opens the Select a Valve/Tool window displaying a list of existing heads from which you can choose. Alternately, if you define a new head name and click the APPLY button, the new name will be added to the heads list.

Only the operations and parameters that apply to the selected Type field will be active; those that are not applicable to the currently selected head will appear faded.

The image shows the 'Valve/Tool Editor' dialog box. It is divided into several sections:

- Valve/Tool Name:** A text field containing 'NONE' and a dropdown arrow.
- Type:** A text field containing 'Dummy'.
- Description:** A large text area for entering a description.
- Operations:** A group of checkboxes for various sensor and status options:
  - Low Material Sensor
  - Low Reservoir Sensor
  - Other Sensor
  - Retract Sensor
  - Extra Sensor
  - Jaw Sensor
  - Has Standoff
  - Has Shut Off
  - Has Jaws
  - Skip StandOff Calibration
  - Keep head status
  - Has Touch Probe
- Parameters:** A grid of input fields for various parameters:
  - X Offset: 0,000 in
  - Y Offset: 0,000 in
  - Z Offset: 0,000 in
  - Standoff X Offset: 0,000 in
  - Standoff Y Offset: 0,000 in
  - Stand Off Z: 0,000 in
  - Valve Speed: 0,000 %
  - Valve Ramp: 0,000 %/s
  - Stall Test: 0,000 %
  - Mixer Feed Rate: 0,000 in/s
  - Reload Mix Rate: 0,000 in/s
  - Micro Valve Velocity: 0 cts/s
  - Micro Valve Reverse: 0 cts
  - Micro Valve Acceleration: 1000000 ct
  - Hold Time: 0,000 s
  - Hold Center: 0,000 s
  - Air/Vacuum Pressure: 0,0 psi
  - Open Time: 0,000 s
  - Open Center: 0,000 s
  - Sealing Force: 0,000 g

At the bottom of the dialog are three buttons: 'Close', 'Apply', and 'Delete'.

## Add a Head

To add a new head to the head library:

1. Open the Program Editor and click on Libraries > Head. The Valve/Tool Editor displays. (You may also access the Valve/Tool Editor from either the Materials or Material Defaults libraries.)
2. Enter a name in Valve/Tool Name.
3. Click on the Type button and make a selection from the drop down menu that appears.
4. If desired, type text in the Description box.
5. Activate each operation box applicable to the new head.
6. Enter values in the parameter fields applicable to the new head.
7. Click APPLY to save your input or CLOSE to exit the window without saving.

## Edit a Head

To change any of the characteristics for a head, refer to [Edit a Library Record](#) (pg 5.2).

## Delete a Head

To delete one or more heads from the head library, refer to [Delete a Library Record](#) (pg 5.2).

## Materials Library

Use the materials library to make material parameter changes to a particular material record. This single change will affect all programs using that material — this is more efficient than making the same change repeatedly in every program that uses that material. If, however, the change is applicable to all materials, we recommend making the change in the material defaults library rather than repeating the step for every material record in the materials library. Refer to [Material Defaults Library](#) (pg 5.9).

New materials can be added to the materials library by selecting an existing material and modifying its characteristics. The materials library is represented by the Mounts/Material Editor - MATERIAL window. (See [Mounts/Material Editor](#) (pg 5.59).) Clicking the selector button next to the Material field opens a list of existing materials from which you can make a selection.

Only the operations and parameters that apply to the selected material will be active; those that are not applicable to the currently selected material will appear faded. If you enter a new name and click the APPLY button, the newly created material will be added to the materials list.

The screenshot shows the 'Mounts/Material Editor' window. The 'MATERIAL' section includes fields for 'Mount Position' (7), 'Panel Selection' (Valves), 'Material' (NONE), 'Group' (None), 'Color' (None), 'Needle' (25), and 'Valve/Tool' (NONE). There is a 'Description' field with the text 'To provide for an unknown material or tool'. Below this are checkboxes for 'Auto Clean', 'Manual Calibration', and 'Skip Calibration', along with a 'Feature ID' field and an 'Inspect Delay' field set to 2,000 s. The 'Valve Settings' section on the right lists various parameters such as Auger Speed, Auger Idle, Auger Reverse, Micro Valve Reverse, Minimum Shut-off, Snap Off Z, Pinch Delay, Micro Valve Speed, Micro Valve Acceleration, Pre Snap Off Delay, Post Delay, Snap Off Velocity, and Snap Off Acceleration, each with a numerical value and a unit.

### Add a Material

To add a new material to the material library:

1. Open the Program Editor and click on Libraries > Material. The Mounts/Material Editor - MATERIAL window displays.
2. If a material similar to the one you want to create already exists, click the select button ▼ by the Material field, select the existing material, and click ACCEPT.

If you are creating a completely new material, we recommend selecting the NONE material name to use as a base.

3. Enter values in the parameter fields applicable to the new material and activate each applicable operation box.

We strongly recommend adding text in the Description field to indicate why this record is significant to your site. The text should indicate what the record does and/or its purpose.

4. Click APPLY to save your input or CLOSE to exit the window without saving.

### **Edit a Material**

To change any of the characteristics for a material, refer to [Edit a Library Record](#) (pg 5.2).

### **Delete a Material**

To delete one or more materials from the material library, refer to [Delete a Library Record](#) (pg 5.2).

## Material Defaults Library

The material defaults library is the repository for the most commonly used material parameter values. The default value for basically everything — needle size, valve speed, head type, etc. — can be set here for each head position. The predefined values provided for you can be changed to meet your needs.

**NOTE:** New records cannot be added to the material defaults library, nor can any of its existing records be deleted. New material records must be added in the materials library.

When a particular value affects most of your materials, enter it in the materials default library. For example, if your programs use primarily solder paste and adhesive materials and almost always use the solder paste in head mount position 1 and the adhesive in head mount position 2, we recommend setting up these defaults in the material defaults library.

The values in the material defaults library are the default values for the materials library which, in turn, contains the defaults for the Mounts window. This default hierarchy lends itself to an efficient programming strategy:

- Enter **the most commonly used material parameter values** in the material defaults library,
- Enter values **affecting only a particular material** in the [Materials Library](#) (pg 5.7), and
- Enter values that affect only a **specific program** in the [MOUNT](#) (pg 3.71) window.

The material defaults library is represented by the Mounts/Material Editor - DEFAULTS window.

Clicking the Material button in this window opens a list of existing materials from which you can make a selection. Only the operations and parameters that apply to the selected record will be active and available for modification; those that are not applicable to the currently selected record will appear faded.

## Edit a Material Parameter Default

To change any of the characteristics for a material default record, refer to [Edit a Library Record](#) (pg 5.2) or refer to the following example.



**IMPORTANT:** The default value for basically everything — needle size, valve speed, head type, etc. — can be set in the Material Defaults library for each head position with Mount Position 6 acting as a default master for the material library, **HOWEVER**, the default values are only used if the values in [Valve/Tool Editor](#) (pg 5.105) **AND** the [Materials Library](#) (pg 5.7) are set to default (the default buttons are blue).

### For Example - Changing Needle Size Default

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The default size for valve needles can be changed to the most commonly used size. Potentially, this saves the user from having to change the needle size every time a material is selected.

To change the default needle size for a material:

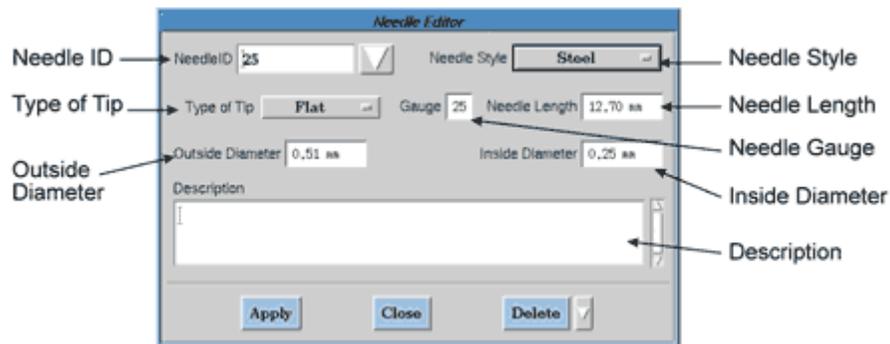
1. From the Program Editor menu bar, click Libraries > Material Defaults. This action opens the window for the [Material Defaults Library](#) (pg 5.9).
  2. Select desired material by clicking MATERIAL, selecting a material from the list that displays, and then clicking ACCEPT.
  3. Define the desired default needle size for each mount position:
    - a. Define the new needle size by clicking NEEDLE, selecting a size from the list that displays, and then clicking ACCEPT.
    - b. Click APPLY to save the change.
    - c. Select the next available MOUNT POSITION.
    - d. Repeat the steps above to update each available mount position with the new needle size.
- SUGGESTION:** Change the default for each available mount positions (1 through 6) to avoid future confusion.

4. Click CLOSE to exit the window.

## Needles Library

The needle library contains a set of predefined needle records. You may select existing needle records or create and add new needle records to the needle library.

Any needle characteristic can be modified. Needle record additions and modifications can be made at any time by accessing the Needle Editor either directly through the Program Editor or indirectly through the materials or material defaults libraries (Mounts/Material Editor windows).



### Add a Needle

To add a new needle record to the needle library:

1. Open the Program Editor and click on Libraries > Needle. The Needle Editor displays. (You may also access the Needle Editor from either the Materials or Material Defaults libraries.)
2. Enter a name or number for Needle ID.
3. Make a selection from the drop down menus that appear when you click on the Needle Style and Type of Tip buttons.
4. Enter values in the Gauge, Outside Diameter, and Inside Diameter fields.
5. If desired, type text in the Description box.
6. Click APPLY to save your input or CLOSE to exit the window without saving.

### Edit a Needle

To change needle characteristics in a needle record, refer to [Edit a Library Record](#) (pg 5.2).

### Delete a Needle

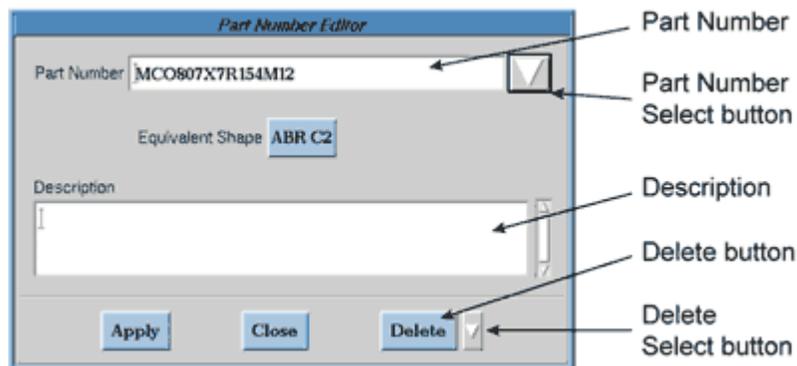
To delete one or more needle records, refer to [Delete a Library Record](#) (pg 5.2).

## Part Numbers Library

FLOware software part numbers are cross references that correlate a user's pick-and-place part numbers with dispenser operation types. These cross reference records are generally created in bulk when converting pick-and-place data into dispenser import format by means of a conversion program or by importing a cross reference table from a spreadsheet platform. On the other hand, to create, edit, or delete an individual cross reference, use the Part Number Editor.

If *part number-to-operation type* equivalence is needed, use the Part Number Editor to define cross reference records or change the shape associated with an existing cross reference record. From the Part Number Editor you can select an existing part number from a list and change or delete it. You may also define a new part number, automatically adding the new number to the list of part numbers.

For detailed descriptions of the elements used in the Part Number Editor window, refer to [Part Number Editor](#) (pg 5.77).



### Add a Part Number

To create a new cross reference between a part number and a shape:

1. Open the Program Editor.
2. Click on Libraries > Part Numbers. The Part Number Editor displays.
3. Type a part number in the Part Number field.
4. Click on the Equivalent Shape button.
5. Select a shape from the Select a Shape window that displays and then click ACCEPT.
6. If desired, type text in the description field.
7. Click APPLY to save the entry and then click CLOSE to exit the window.

### Change a Part Number

To edit an existing part number, refer to [Edit a Library Record](#) (pg 5.2).

### Delete a Part Number

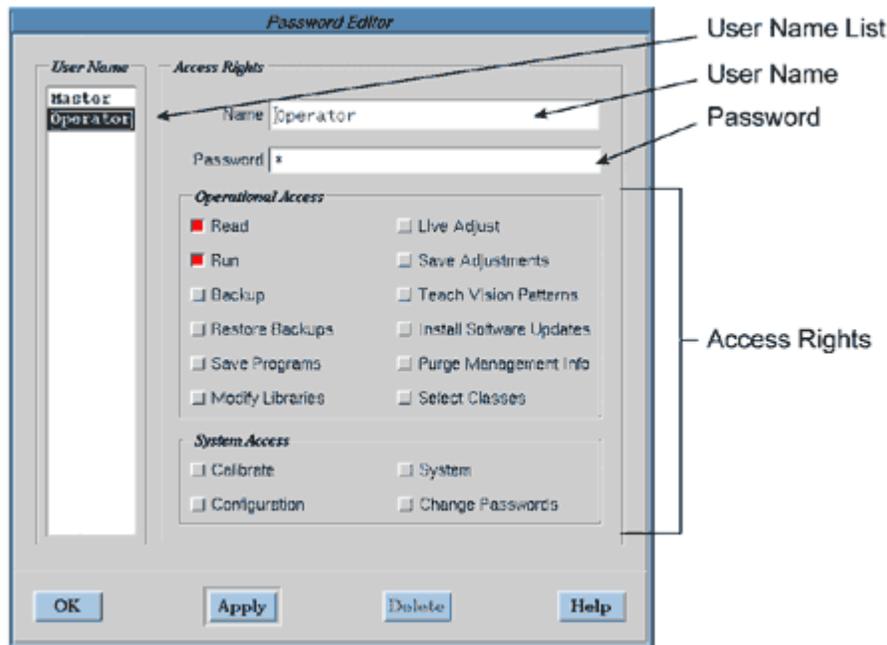
To delete one or more part numbers, refer to [Delete a Library Record](#) (pg 5.2).

## Passwords & Access Rights Library

Access to various system features is controlled by unique, user-defined passwords that protect unauthorized use of the access rights assigned to a user name. Use the Password Editor to add or delete a user name, change the password for a user name, or change the access rights assigned to a user name.

All available access rights are displayed on the Password Editor window. Any combination of access rights can be assigned to any user name.

Whenever the dispenser is powered on, the default password in effect allows minimal access (at the Operator level) to the system.



### Enter a Password

To enter a password:

1. From the main menu bar, click on Operations > Enter Password.
2. Enter a password and click OK.

### Clear a Password

To cancel the current password and return the system to the operator access level, go to the main menu bar and click on Operations > Clear Password.

## Change a Password

To change the password for a user name:

1. From the main menu bar, click Operations > Enter Password.
2. Change to a user name with access to the Change Passwords access right.
3. Open the Program Editor.
4. Click Libraries > Password. The Password Editor displays.
5. Select the desired User Name from the User Name list.
6. Click on the Password field.
7. Type a new password over the existing entry.
8. Click APPLY.
9. Click OK.

## Add a User Name

To add a user name:

1. From the main menu bar, click Operations > Enter Password.
2. Change to a user name with access to the Change Passwords access right.
3. Open the Program Editor.
4. Click Libraries > Password. The Password Editor displays.
5. Type a new user name over the existing entry in the Name field.
6. Type a password over the existing entry in the Password field.
7. Click on each access right in the Access Rights panel pertinent to the new user name.
8. Click APPLY. The new user name will display in the User Name list.
9. Click OK.

## Delete a User Name

To delete a user name:

1. From the main menu bar, click Operations > Enter Password.
2. Change to a user name with access to the Change Passwords access right.
3. Open the Program Editor.
4. Click on Libraries > Password. The Password Editor displays.
5. Select the desired User Name from the User Name list.
6. Click DELETE. The selected user name disappears from the User Name list.
7. Click OK.

## Change an Access Right

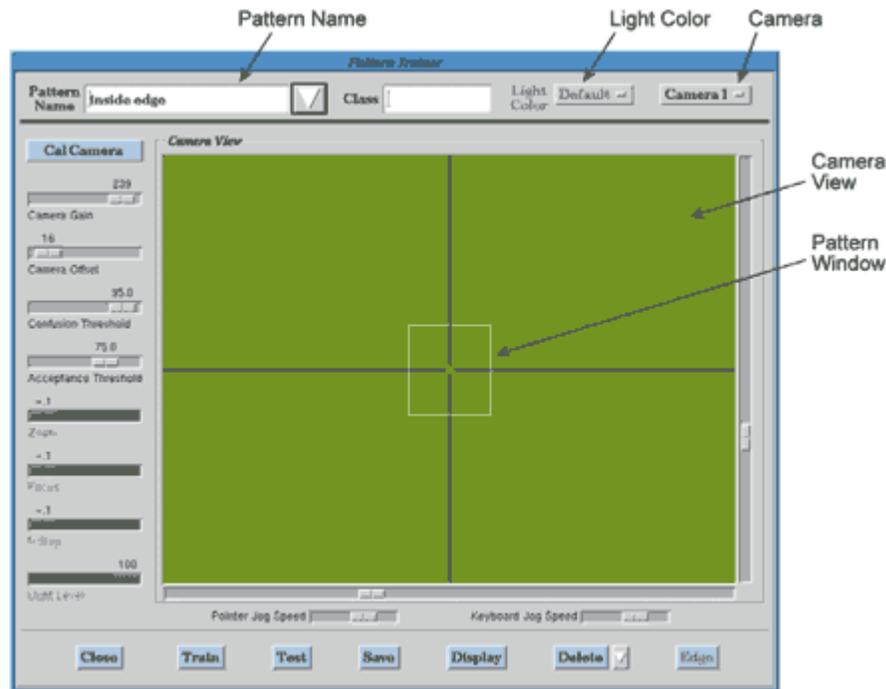
To change the access rights for a user name:

1. From the main menu bar, click Operations > Enter Password.
2. Change to a user name with access to the Change Passwords access right.
3. Open the Program Editor.
4. Click on Libraries > Password. The Password Editor displays.
5. Select the desired User Name from the User Name list.
6. Click each access right in the Access Rights panel pertinent to the selected user name.
7. Click APPLY.
8. Click OK.

## Patterns Library

Patterns are used to define fiducials and bad marks on dispensers equipped with automatic vision. The pattern provides the automatic vision system with the parameters necessary to locate a product-related image during pattern recognition and adjust for product orientation. When a program run encounters pattern recognition requirements, the system software searches for the pattern you select.

The user can teach, delete, or select and modify a pattern and store the results in the patterns library for later use. Open teaching, along with unlimited image storage, allows the user to customize any image for use as a pattern. The patterns library also contains a set of predefined pattern records and associated information from the vision system.



## Restrictions

The following restrictions apply to the patterns library and Pattern Trainer window.

- The patterns library is only accessible via the Pattern Trainer window when the dispenser is configured for the Automatic Vision Alignment System option and the correct password has been entered.
- Pattern parameters are dependent on current conditions, search results, and desired search speed. Therefore, adjusting camera alignment or lighting can affect existing program patterns and may require changes be made to the patterns to accommodate the hardware or condition changes.
- When a manual camera (Optem Lens) is present, changing the zoom value can adversely affect program results. Changing the zoom setting changes camera position in the Z axis. It is suggested that you either use the same zoom setting throughout a program or delays will result from the additional camera calibration operations.
- The NONE pattern is protected and cannot be modified.

- SAVE vs. TRAINER buttons: The SAVE button may be used if the only changes made are to the position of the Confusion Threshold and Acceptance Threshold sliders. If any additional pattern parameters are modified, you must click the TRAIN button instead.
- Only the sliders and buttons applicable to the selected Pattern will be active; those that do not apply to the currently selected pattern will appear faded.

## Select a Pattern

To select a pattern:

1. From the Program Editor menu bar, click on Libraries > Patterns. Pattern Trainer displays.
2. Either type a name in the Pattern Name field or select an existing pattern similar to the one you want to create by clicking the button ▼ next to the Pattern Name field and typing the new name in the Pattern Name field.

**NOTE:** When teaching a new pattern, you must enter an original name.

## Edit a Pattern

To change parameters for a pattern, refer to [Edit a Library Record](#) (pg 5.2).

## Delete a Pattern

A pattern cannot be deleted if it is used anywhere in the control software.

To delete a pattern from the pattern library, refer to [Delete a Library Record](#) (pg 5.2).

## Teach a Pattern

For details on how to teach a pattern, refer to [Teaching a Pattern](#) (pg 3.62).

## SubTypes Library

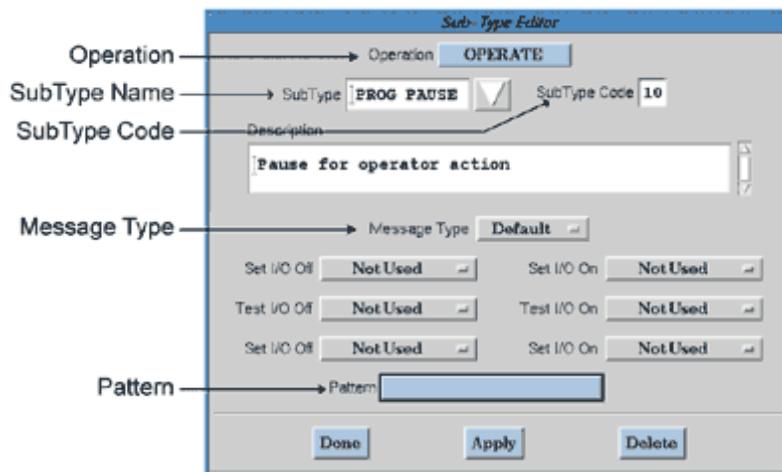
Subtypes define extensions of operations (shape primitives); that is, a subtype alters the meaning of an operation. Subtypes are most commonly used to operate and test a specific I/O (input/output) or to modify an operation.

**CAUTION** Care must be taken if subtypes are moved from one machine to another since subtypes relate to both the hardware and software.

<b>ATTENTION</b> <a href="#">Faire attention si les</a>	<b>VORSICHT!</b> <a href="#">Vorsicht beim</a>	<b>ATTENZIONE</b> <a href="#">Prestare attenzione</a>	<b>PRECAUCIÓN</b> <a href="#">Precaución al mover</a>
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A unique set of subtypes is associated with each operation type. For example, the subtypes Fixed and Optimize relate to the Partition operation; subtypes Circular, XMajor, XStagger, YMajor, and YStagger relate to the Dot operation.

A subtype code is the key to each subtype. Subtypes without a valid subtype code are ignored by the system. You may add and modify subtypes but not subtype codes. Some subtypes are available for all machines and some apply only to unique features on a specific machine.



The following references are available for further information about subtype codes and operation types:

- Subtype codes are defined and correlated with operation types in the *Subtype* section of the *Import/Export Data Reference Guide*.
- Operation types are explained in [Operations](#) (pg 3.86).
- Additional detail about each operation type is available from [Operations \(Primitives\)](#) (pg 5.108).

### Modify an Operation with a SubType

A subtype can be used to modify an operation. For example, rather than define a rectangle operation by a corner, a subtype can be used to define a rectangle operation by its center.

Another application for subtypes is to create multiple subtypes that function the same but are performed at different points in a program. Synonyms of a subtype can be created by using the same subtype code and changing one or more of the variables associated with it: the SubType name, Message, and/or Pattern.

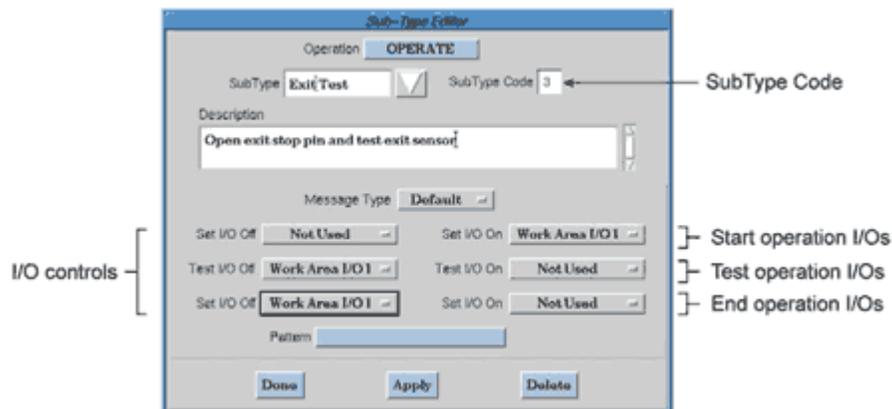
For instance, an existing subtype that pauses an operation to wait for an operator action and displays a message can be used to create numerous other subtypes that also pause and wait but display a different message. You need only modify the SubType name and Message Type.

In order to work properly, some subtypes may need specific detail parameters entered in the program detail. For example, all blob conditions should be entered when a blob test subtype is to be used. Examine the non-faded fields displayed in the Operate panel of the Program Detail window and determine which fields require a value to be entered.

### Operate or Test an I/O with a SubType

Operating or testing a specific I/O (input/output) most commonly requires the use of a 3 in the Subtype Code field. Using 3 allows you to change the state of an I/O, test the condition of a different I/O, and then return the original I/O to its original state.

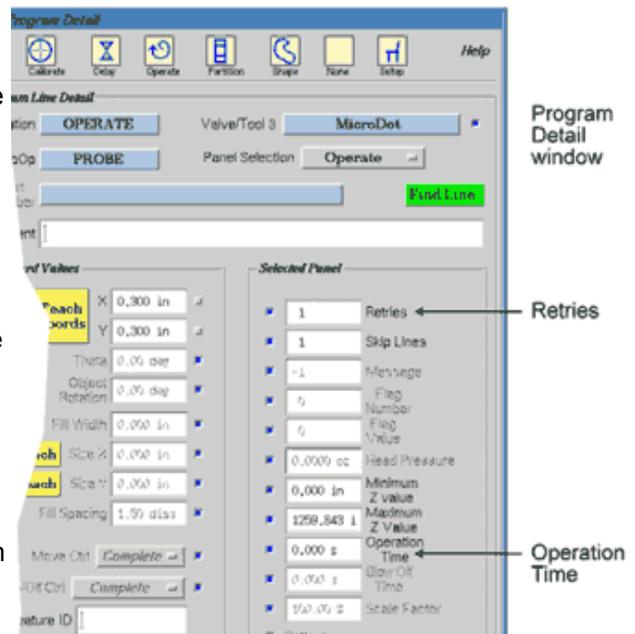
A pair of I/O control buttons, each with a drop down menu, is available for each stage of I/O operation testing: start, test, and end.



When testing an I/O, you may also use the Program Detail window fields of Retries and Operation Time in conjunction with each other to maximize the number of retries and minimize the amount of time that passes before the operation continues after either passing or failing the test.

For a focus on function, enter the number of retries you want in Retries and then enter an Operation Time value that accommodates that number of retries.

When focusing on optimization, set the Operate Time to a small value and then enter a number of retries in Retries that minimizes the amount of time the system will have to wait for test failure to occur.

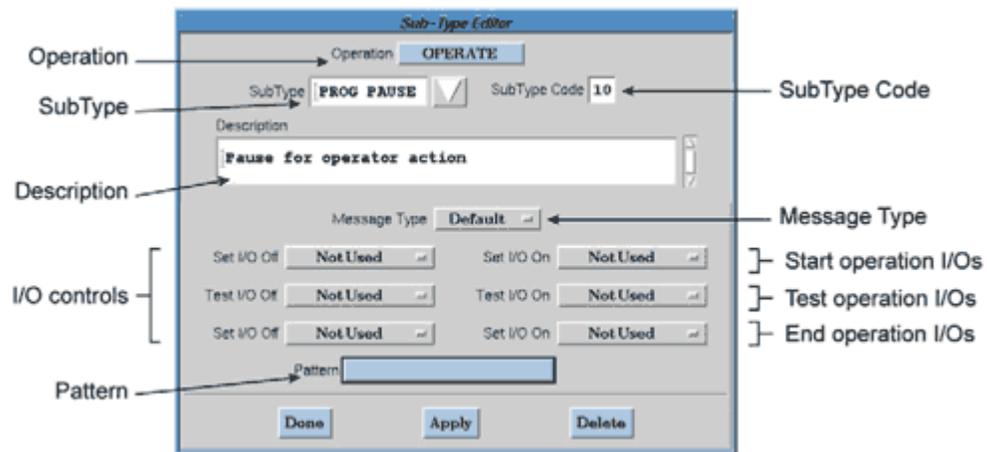


## Add a SubType

You may either create a new subtype from the starting point or by editing a similar, existing subtype.

To add a new subtype:

1. Open the Program Editor and click on Libraries > SubTypes. SubType Editor displays.



2. Create a subtype record:
  - a. Click the Operation button, select an applicable operation from the drop down menu, and click ACCEPT.
  - b. Type a label in the SubType field.
  - c. Enter a value in SubType Code. Only valid entries allow a subtype to be saved. For a listing of Operate subtype codes and their definitions, refer to [SubType Editor](#) (pg 5.103).
  - d. Type text in the Description box identifying the purpose for this subtype.
3. If applicable, make a selection from the Message Type button drop down menu.
4. If applicable, make a selection from the drop down menu for each I/O control button.
5. If applicable, click the Pattern button, select a pattern, and click ACCEPT.
6. Click APPLY to save your input or DONE to exit the window without saving.
7. Click DONE to exit the SubType Editor.

## Edit a SubType

To change parameters for a subtype:

1. Open the Program Editor and click on Libraries > SubTypes. SubType Editor displays.
2. Click the Operation button, select the operation associated with the subtype to be modified, and click ACCEPT.
3. Click the select button ▼ by the SubType field, select the subtype you want to change, and then click ACCEPT.
4. Make desired changes.
5. Click APPLY to save the changes or DONE to cancel.
6. Click DONE to exit the SubType Editor.

## Delete a SubType

To delete a subtype from the subtype library:

1. Open the Program Editor and click on Libraries > SubTypes. SubTypes Editor displays.
2. From the Operation drop down menu, select the operation associated with the subtype to be deleted.
3. Click the select button ▼ by the SubType field, select the subtype to be deleted, and then click ACCEPT.
4. Click the DELETE button. To delete the subtype, click OK on the confirmation prompt that displays, or click CANCEL to close the prompt without deleting.
5. Click DONE to exit the SubType Editor.

## Windows & Fields

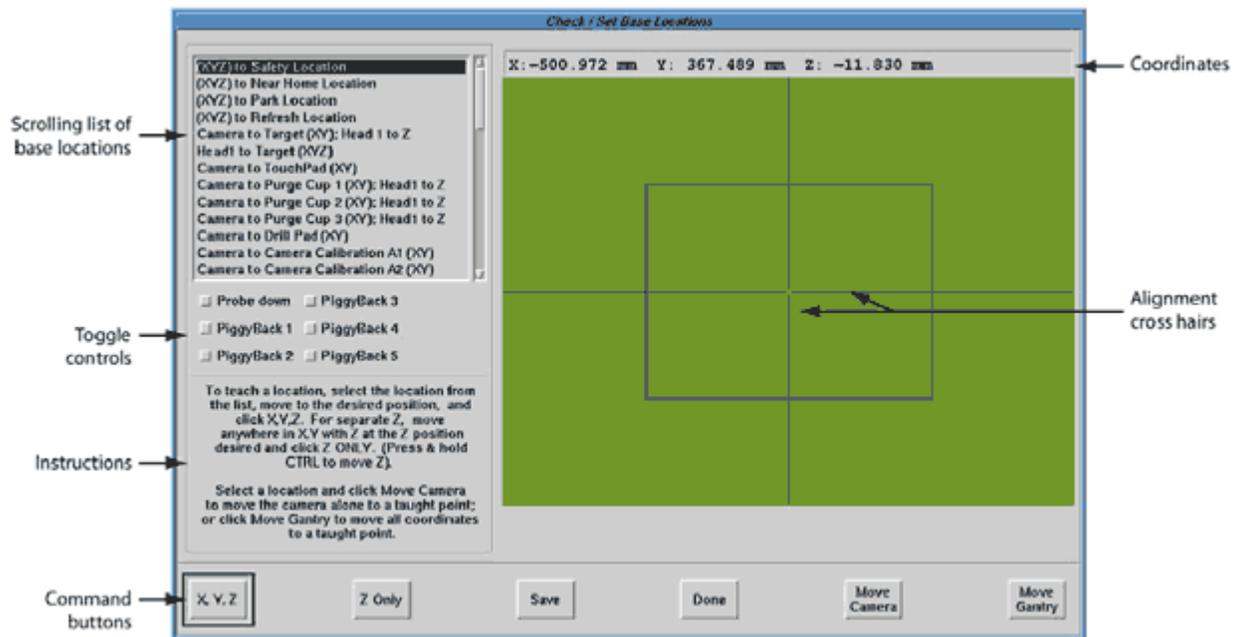
The FLOWare software windows are each dedicated to displaying specific types of information. The purpose for each window is described in this section along with definitions for all fields and controls contained within the window. Instructions on how to access each window are also included.

- [Check/Set Base Locations](#) (pg 5.23)
- [Contour Mapping Editor](#) (pg 5.24)
- [Data Converter](#) (pg 5.25)
- [Data Export](#) (pg 5.26)
- [Data Import](#) (pg 5.28)
- [Enter Operator Instructions](#) (pg 5.29)
- [Export](#) (pg 5.30)
- [Fiducials & Bad Marks](#) (pg 5.33)
- [File Selection](#) (pg 5.34)
- [Fixed Location Editor](#) (pg 5.35)
- [Import](#) (pg 5.37)
- [Interim Report Generation](#) (pg 5.40)
- [IoView](#) (pg 5.42)
- [Jog](#) (pg 5.44)
- [Live Program Adjustment](#) (pg 5.46)
- [Live Video Parameters](#) (pg 5.48)
- [Main Control](#) (pg 5.49)
- [Material Expiration](#) (pg 5.54)
- [Miscellaneous Program Settings](#) (pg 5.55)
- [Mounts Table](#) (pg 5.57)
- [Mounts/Material Editor](#) (pg 5.59)
- [Needle Editor](#) (pg 5.66)
- [Offline Operations](#) (pg 5.67)
- [Optimize Current Program](#) (pg 5.69)
- [Option Settings](#) (pg 5.70)
- [Part Number Editor](#) (pg 5.77)
- [Password Editor](#) (pg 5.78)
- [Pattern Trainer](#) (pg 5.81)
- [Print Selected Program](#) (pg 5.85)
- [Program Detail](#) (pg 5.86)
- [Program Editor](#) (pg 5.94)
- [Select List](#) (pg 5.98)
- [Set Pressure/Temperature](#) (pg 5.99)
- [Set Shape Reference Point](#) (pg 5.100)
- [SubBoard Editor](#) (pg 5.101)
- [SubType Editor](#) (pg 5.103)
- [Valve/Tool Editor](#) (pg 5.105)
- [View Notes](#) (pg 5.107)

## Check/Set Base Locations

Check/Set Base Locations enables you to teach, verify, and modify base locations. It is used to establish ALL base locations and positions around the work area used for automatic adjustments, e.g., the purge and refresh operations.

**TIP:** To access Check/Set Base Locations, go to the main menu bar and click on Configuration > Base Locations.

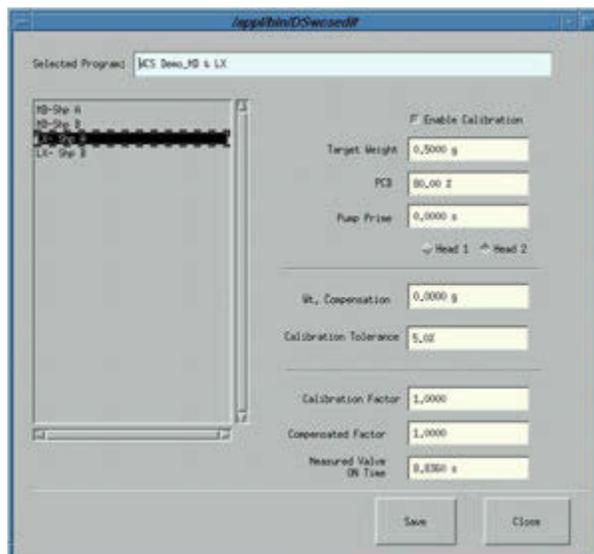


**Table 31:** Check/Set Base Locations window

Element	Description
scrolling list	Alphabetic listing of all available base locations.
toggle controls	Down/Up toggle controls for the Touch Probe and Valve/Tool mount positions 1 through 5.
instructions	Basic instructions for teaching a base location.
coordinates	A display of current camera coordinates. These coordinates are relative to the active reference point.
alignment cross hairs	Guides for precise alignment.
X, Y, Z	Teaches the XYZ coordinates.
Z ONLY	Teaches the Z coordinate.
SAVE	Saves changes made to this window.
DONE	Exits this window.
MOVE CAMERA	Moves the camera to the XY and Z location for the SafetyZ base location.
MOVE GANTRY	Moves the gantry to the XY and Z location for the selected base location.

## Contour Mapping Editor

**TIP:** To access Contour Mapping Editor, go to the main menu bar and click on SHPCAL.



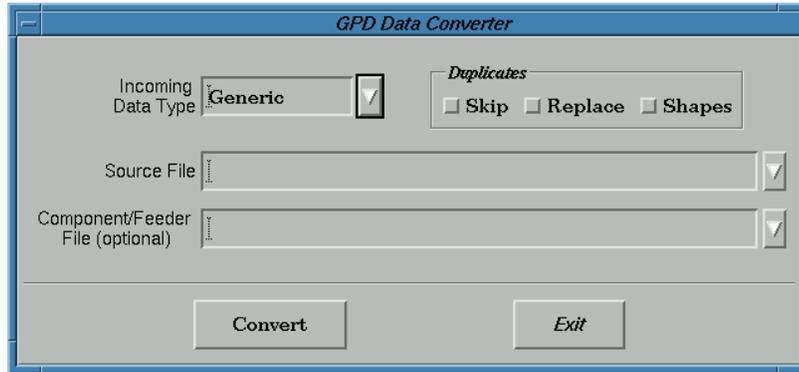
**Table 32:** Contour Mapping Editor window

Element	Description
Selected Program	Displays name of currently selected program.
list of shapes	List of all available shapes for currently selected program. Any values saved in the Contour Mapping Editor window are applied to the highlighted shape.
Enable Calibration	default = not enabled  <b>Enabled</b> - If check box is enabled, the highlighted shape in the selected program becomes a candidate for calibration. Calibration is performed and pump speed is adjusted during execution of the shape.  <b>Not enabled</b> - If check box is not enabled, no calibration is performed and no adjustment is made to pump speed.
Target Weight	Value (mg) entered by user as the desired weight of the selected shape.
PCD MicroV	The label and units for this field change depending on pump type.  Pump base speed used in shape. This value must match the Weight Time value entered during material setup.  [Pump adjustment factor by which the calculated calibration factor may be adjusted.]
Pump Prime	Amount of time the pump is primed prior to calibration.
Wt. Compensation	An independent adjustment factor by which the calculated calibration factor may be adjusted. This is implemented as an offset to Target Weight.
Calibration Tolerance	Percentage of Target Weight by which the calibration may be imprecise and still considered allowable.  Example: An entry of 50% is stored as 50, not 0.5.
Calibration Factor	Scaling factor applied to pump speed at run time.
Compensated Factor	Amount of adjustment.
Measured Valve On Time	Total pump on time (s) for this shape. Total pump times are collected every time the program runs, whether pump speeds are adjusted or not.
SAVE	Saves calibration factors to the currently displayed shapes.
CLOSE	Closes the window. Any changes not saved with the SAVE button will be lost.

## Data Converter

The data converter is used to import data from various external sources after converting it to a specific format that meets dispenser requirements.

**TIP:** To access Data Converter, go to the main menu bar and click on Utilities > Import/Export > Convert.



**Table 33:** Data Converter window

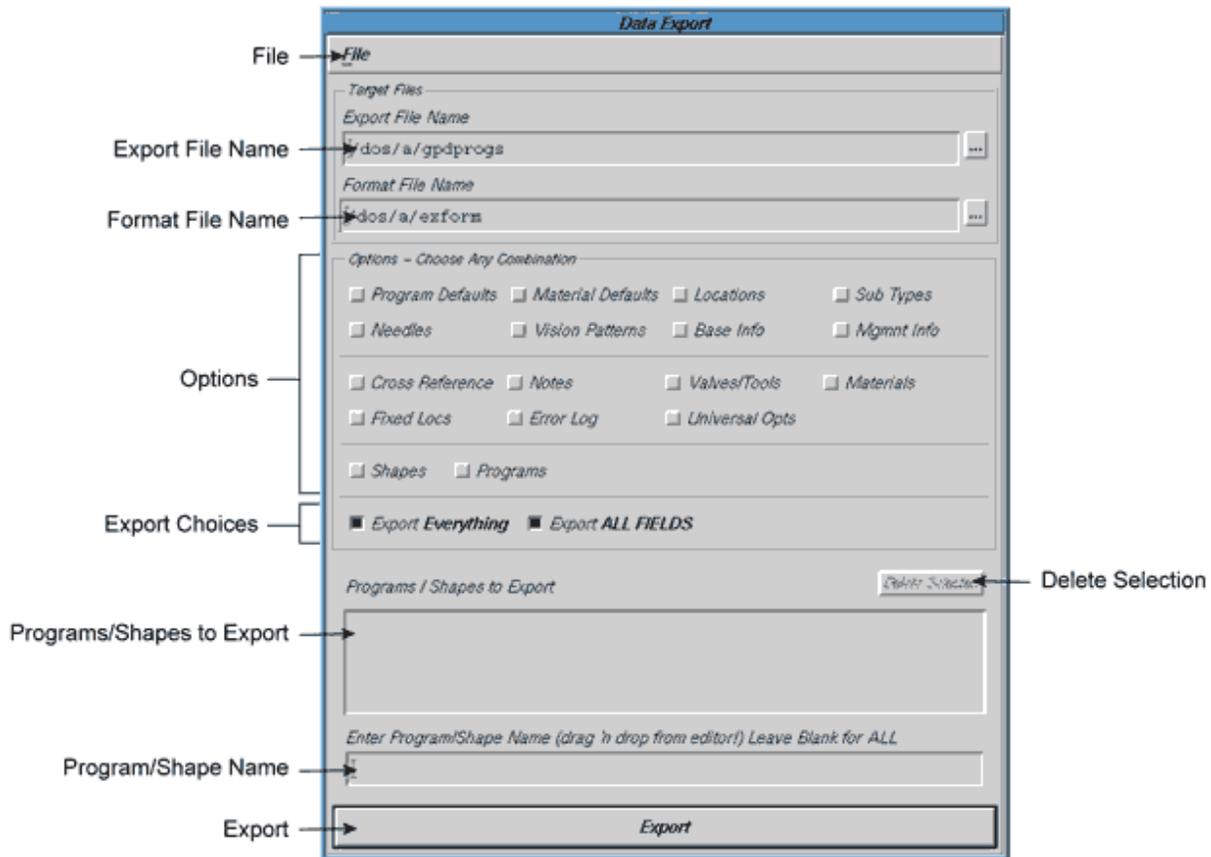
Element	Description
Incoming Data Type	The type of machine (typically a pick-and-place unit) that produced the data.
Source File	Location of the main data.
Component/Feeder File	Defines the feeder location and the type of component that each feeder processes; used only for some incoming data types.
Skip	Ignores any duplicate programs/shapes.
Replace	Replaces any old program/shape with the new duplicate.
Shapes	Includes or excludes shapes from the conversion.

## Data Export

**SUGGESTION:** Use the newer [Export](#) (pg 5.30) window rather than the Data Export window.

Use the Data Export window to export data to a new dispenser file, a network, or a floppy disk.

**TIP:** To open Data Export, go to the main menu bar and click on Utilities > Import/Export > Export.



**Table 34: Data Export window**

Element	Description
File	Allows exit from export; provides an alternate button to start the export.
Export File Name	The name and path of the export data file.
Format File Name	The name and path of the file that defines the format parameters under which the export file will be exported.
Options	Any combination of options may be selected. To quickly select all options, click on Export Everything. To export all fields, click on Export ALL FIELDS.
Program Defaults	<b>OBSOLETE AS OF FLOWare software version 2.4</b> Provides the ultimate parameter values for Program Detail lines when there is no other way to determine the values.
Needles	Inside and outside diameters, and other parameters for standard needle gauges.

**Table 34: Data Export window (Continued)**

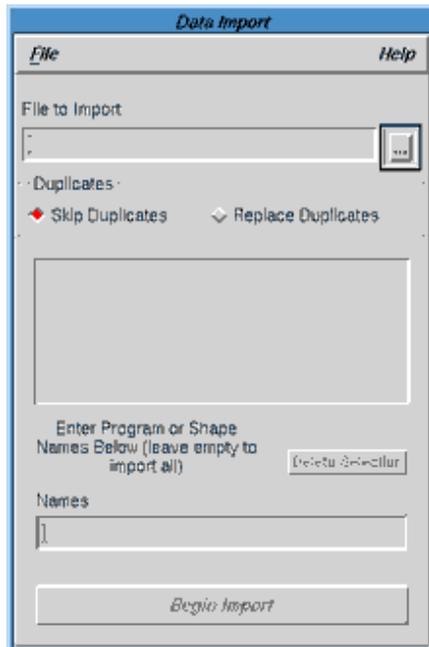
<b>Element</b>	<b>Description</b>
Material Defaults	Provides the ultimate parameter values for mounted values/tools when there is no other way to determine the values.
Vision Patterns	Patterns from the vision system and associated information.
Locations	Basic positions for each gantry.
Base Info	Machine definition and summary information by gantry about the machine.
Sub Types	Defines extension to shape primitives.
Mgmt Info	Detailed information by gantry about each machine run.
Cross Reference	Connects a shape with a part number by providing an OpType for known part numbers.
Fixed Locs	Locations of pallets or other points around the work area but outside of the nest.
Notes	A table of operator notes.
Error Log	List of messages selected by message class.
Dot Sizes	Not currently used. Diameter (mm) of desired dots.
Valves/Tools	Properties and defaults for various heads that may be mounted on the machine.
Universal Opts	General options independent of installed hardware.
Shapes	Shape name.
Programs	Dispenser program names.
Export Everything	Equivalent to clicking all of the above Options.
Export ALL FIELDS	Generates a new Format File (exform file) containing all fields for all options. A format file exporting all fields will be created.
Programs/Shapes to Export	A list of program/shape names to export if any of the following options are selected: Shapes, Programs, Export Everything. Use <b>Enter Program/Shape Name</b> to enter program/shape names here.
Delete Selection	Clears items from the <b>Program/Shapes to Export</b> panel.
Enter Program/Shape Name	Enter the name of a program/shape to be selected either with the keyboard or by dragging the name from some other list. Press ENTER to move the selection to the <b>Program/Shapes to Export</b> panel. This process can be repeated for multiple program/shape names.
EXPORT	Executes the export of selected file(s).

## Data Import

**SUGGESTION:** Use the newer [Import](#) (pg 5.37) window rather than the Data Import window.

Data Import provides the means for importing dispenser programs and operating information from various external sources.

**TIP:** To access Data Import, go to the main menu bar and click on Utilities > Import/Export > Import.



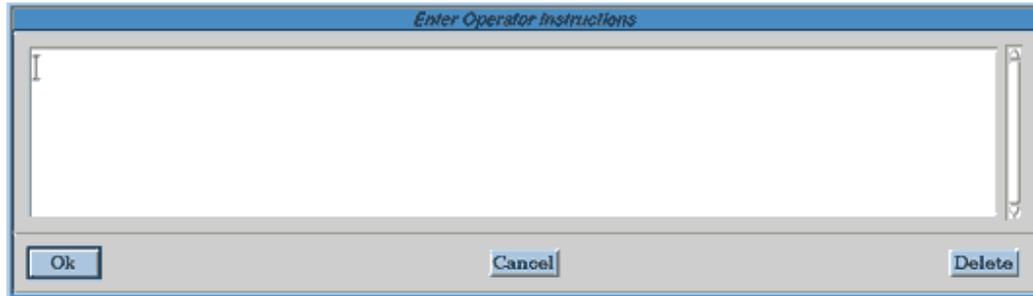
**Table 35: Data Import window**

Element	Description
File	Opens drop-down menu with the choices of Do Import and Exit. Do Import imports the selected data the same as the BEGIN IMPORT button does. Exit closes the Data Import window.
File to Import	The file (in dispenser format) to be imported.
... button	Opens a file selection window for use in selecting the file to be imported.
Skip Duplicates	Replaces any old program/shape with the new updates.
DELETE SELECTION	Use to delete selected programs/shapes from the list panel.
Names	Limits the import to the programs/shapes shown in the list panel.
BEGIN IMPORT	Imports the selected data.

## Enter Operator Instructions

Text intended for display in the Operator Instructions panel of the Mounts Table for the currently selected program can be entered, modified, and deleted using Enter Operator Instructions.

**TIP:** To access Enter Operator Instructions, open Program Editor and click on OPERATOR INSTRUCTIONS.



**Table 36:** Enter Operator Instructions window

Element	Description
text panel	Text entered here displays in the Operator Instructions panel of the Mounts Table for the currently selected program.
OK	Saves changes and exits this window.
CANCEL	Exits this window without saving changes.
DELETE	Deletes all displayed text.

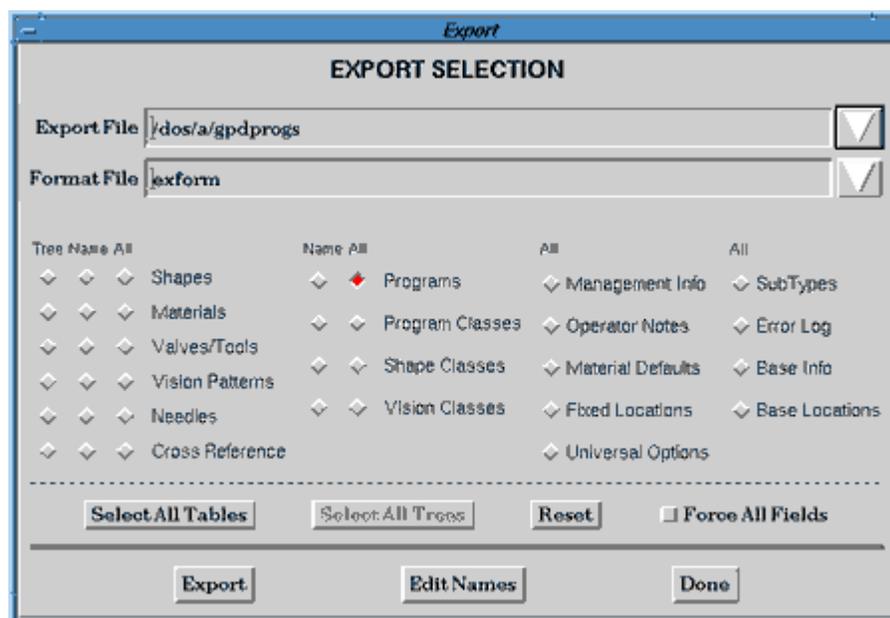
## Export

Use the Export window to export data to a new dispenser file, a network, or a floppy disk.

**IN EFFECT AS OF FLOWare software version 2.6**

**SUGGESTION:** Use the Export window instead of the [Data Export](#) (pg 5.26) window. Export is faster, more flexible, and has more selection options for expanded data export results.

**TIP:** To access Export, click on Utilities > New Export from the menu bar in the main window.



**Table 37: Export window**

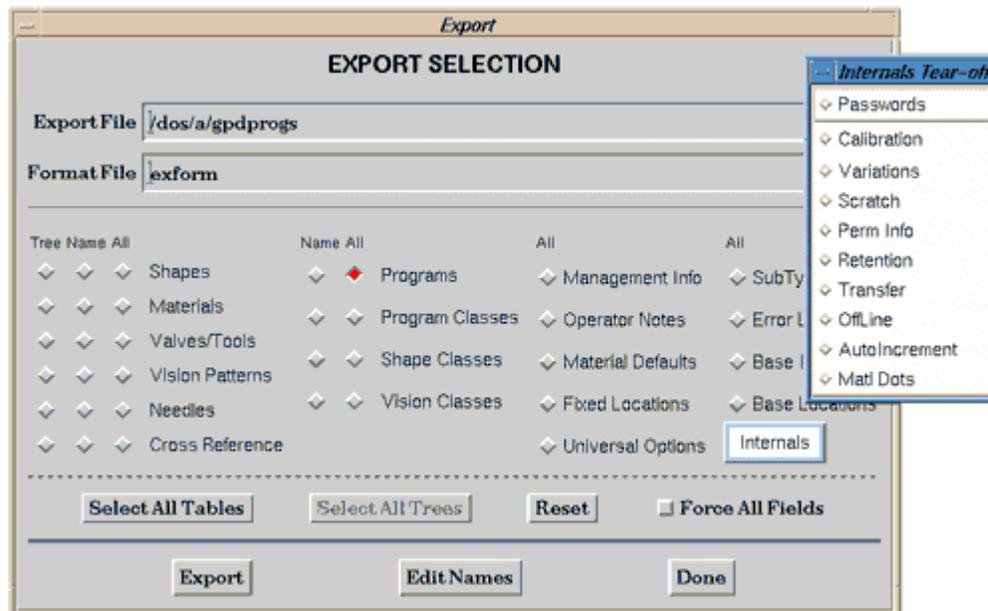
Element	Description
Export File	The name and path of the export data file.
Format File	The name and path of the file that defines the format parameters under which the export file will be exported.
Tree	Not currently available.
Name	Activates a list of names from which to choose.
All	Exports everything in the file corresponding to the ALL button. For example, when the ALL button (next to Programs) is activated, as shown above, all records in the programs file are exported.
Shapes	Properties for shapes located in the shapes library.
Materials	Properties and defaults for materials located in the materials library.
Valves/Tools	Properties for various heads that may be mounted on the machine.
Vision Patterns	Patterns from the vision system and associated information.
Needles	Inside and outside diameters, and other parameters for standard needle gauges.
Cross Reference	Connects a shape with a part number by providing an OpType for known part numbers.
Programs	Dispenser program names.

**Table 37: Export window (Continued)**

Element	Description
Program Classes	Activating the <b>NAME</b> button for Program Classes, Shape Classes, and Vision Classes will export the <i>programs, shapes, and vision patterns</i> for the class names selected in the Class Filter window; i.e., the objects of the selected class names are exported.
Shape Classes	
Vision Classes	
	Activating the <b>ALL</b> button for Program Classes, Shape Classes, and Vision Classes will export the <i>names of the classes</i> selected in Class Filter.
Management Info	Detailed information by gantry about each machine run.
Operator Notes	A table of operator notes.
Material Defaults	Provides the ultimate parameter values for mounted valves/tools when there is no other way to determine the values.
Fixed Locations	Locations of pallets or other points around the work area but outside of the nest.
Universal Options	General options independent of installed hardware.
Sub Types	Defines extensions to shape primitives.
Error Log	List of messages selected by message class.
Base Info	Machine definition and summary information by gantry about the machine.
Base Locations	Basic positions for each gantry.
SELECT ALL TABLES	Any combination of options may be selected. To quickly select all options, click on SELECT ALL TABLES.
SELECT ALL TREES	Not currently active.
RESET	Resets the Export window to its default display of a single selection: ALL programs.
FORCE ALL FIELDS	Generates a new format file containing all fields for all options.
EXPORT	Executes the export of selected file(s).
EDIT NAMES	Invokes a window listing the names of all currently selected files for export.
DONE	Exits the window.

## Internal Tables

An additional button, INTERNALS, is **available only at the super user access level**. The Internals tear-off menu that displays when the INTERNALS button is clicked lets you make multiple selections from other tables.



These additional tables fall into the following basic categories:

**Table 38: Export window - Internal Tables**

Table	Category
Passwords	Provides the user with access to the export of <b>all passwords</b> .
Permanent Info	Cannot be changed. Can be exported but not imported.
Auto increment	
Calibration	
Scratch	Semi-temporary data related to current process/setup.
Retention	
Transfer	
Offline	
Material Dots	
Variations	Not yet implemented.

## Fiducials & Bad Marks

Used to teach the fiducials for a fixed location. Displays the current coordinates at which the gantry is positioned.

**TIP:** To access Fiducials & Bad Marks, open Program Editor and click on Fixed Locations, and then from the resulting Fixed Location Editor click the FIDUCIALS button.

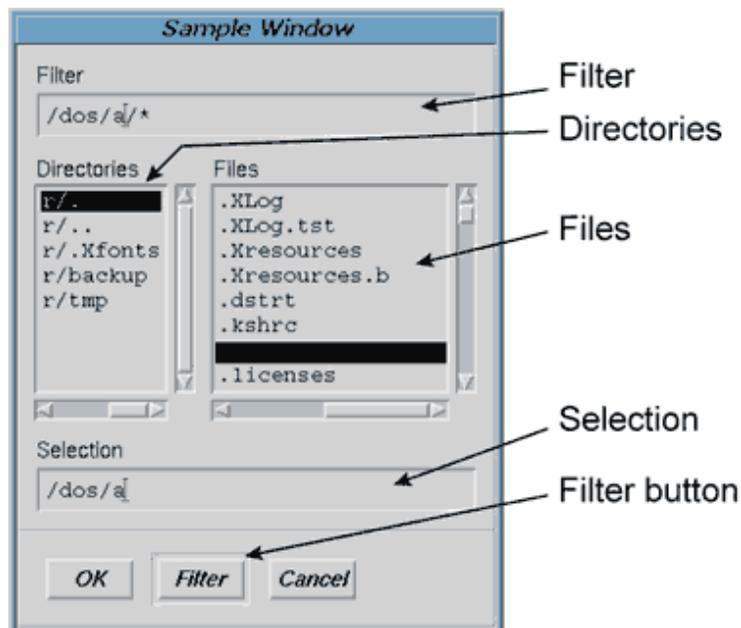
**Table 39:** Fiducials & Bad Marks window

Element	Description
Fiducial n X, Y	Current coordinates for designated fiducial.
Bad Mark X, Y	Current coordinates for designated bad mark.
TEACH	Teaches the X and Y coordinates for the fiducial or bad mark.
MOVE TO	Moves the gantry IMMEDIATELY to the coordinates designated in the X and Y fields.
Pattern	Name of a pattern, up to 24 characters long.
Used	Indicates whether or not the associated pattern is used.
Window	Not currently functional. Primarily used to prevent false positives by masking objects similar to the pattern for which you are searching.
Used	Not currently functional. Indicates whether or not the associated window is used.
X, Y	Not currently functional. X, Y size of the search window.
TEACH	Not currently functional. Teaches the window area (X, Y).

## File Selection

A file selection window serves to retrieve or send file data by providing a means to find a particular file and its path.

**TIP:** There are numerous file selection windows; the window titles may vary.



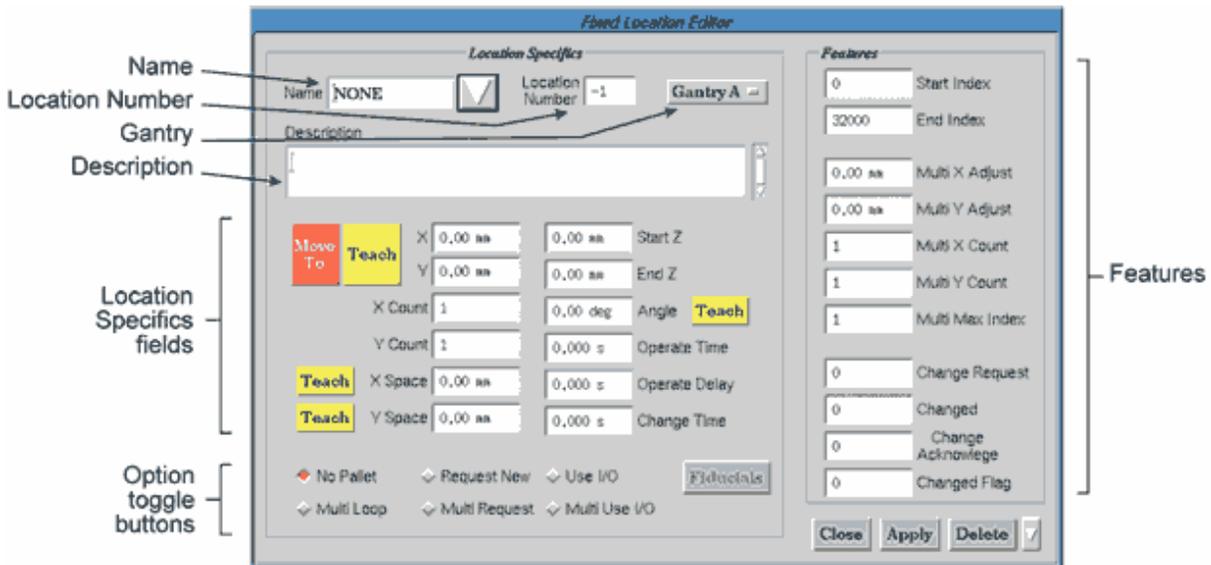
**Table 40:** File Selection window

Element	Description
Filter	Enter a partial path in this field to limit the directories (folders) and files displayed. Wild cards may be used.
Directories	Directory results of a filtered search are displayed here for selection.
Files	File results of a filtered search are displayed here for selection.
Selection	Upon clicking the OK button, the file and path displayed in the Selection field will be entered in the file definition field of the window from whence you just came.
FILTER	Refreshes the Directories panel to display only those directories included within the scope of the path you typed in the Filter field.

## Fixed Location Editor

Use the Fixed Location Editor to define and edit fixed locations (locations fixed in accordance with the work table like pallets and feeders).

**TIP:** To access Fixed Location Editor, open the Program Editor and click on Libraries > Fixed Locations.



**Table 41:** Fixed Location Editor window

Element	Description
Name	Name of the fixed location. may be up to 12 alphanumeric characters long.
Location Number	Type code. The system automatically generates this code; it cannot be altered.
Gantry	Indicates the gantry used. Choices are gantry A, B, or C only or any gantry.
Description	Comment and description field of up to 250 characters. Text will print fully on printouts. The 40 characters entered up to the first hard return entered will display on some window lists.

### LOCATION SPECIFIC FIELDS

X Y	The absolute coordinates (mm) for this location; the distance from work area origin.
Start Z End Z	Start and end absolute Z coordinate for this location.
X Count Y Count	Whole number of pallet elements in the X and Y directions.
Angle	Pallet (array) rotation for this location. When teaching with the Angle TEACH button, jog to the pallet pickup point farthest along the X axis from the point already taught for the X,Y coordinates.
Operate Time	Operate time (ms).

**Table 41: Fixed Location Editor window (Continued)**

Element	Description
X Space Y Space	Distance (mm) between pallet entries in the X and Y directions.
Operate Delay	Delay (ms).
Change Time	Time (ms) to wait for a new pallet before asking operator.

**OPTION TOGGLE BUTTONS**

Only a single option toggle button can be active at any one time.

No pallet	Recycle without stopping when pallet run is done.
Request New	Ask operator for a new pallet when pallet run is done.
Use I/O	Use CHANGE I/Os when pallet run is done.
Multi Loop	Recycle across multi-pallets.
Multi Request	Ask operator for a new multi-pallet when all pallet runs are done.
Multi Use I/O	Use CHANGE I/Os for a new multi-pallet when all pallets are done.

**FEATURE FIELDS**

Start Index End Index	Start and end pallet indices. Pallet starts at Start Index and ends when End Index is exceeded, regardless of X Count and Y Count.
Multi X Adjust Multi Y Adjust	Adjustment distances to move from one multi-pallet to the next.
Multi X Count Multi Y Count	The number of multi-pallets in the X and Y direction.
Multi Max Index	Total number of multi-pallets for this pallet. This value is set internally.
Change Request	Work area output number requesting a pallet change.
Changed	Work area output acknowledging change of a pallet.
Change Acknowledge	Work area input acknowledging pallet change request.
Changed Flag	Work area input indicating a pallet was changed.

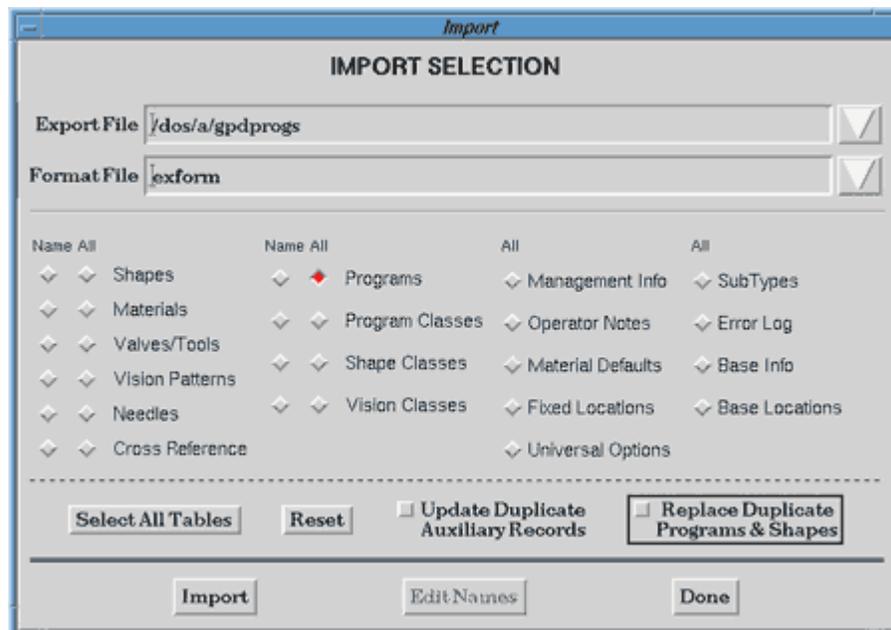
## Import

Data Import provides the means for importing dispenser programs and operating information from various external sources.

### **IN EFFECT AS OF FLOWare software version 2.6**

**SUGGESTION:** Use the Import window instead of the [Data Import](#) (pg 5.28) window. Import is faster, more flexible, and has more selection options for expanded data import results.

**TIP:** To access Import, click on Utilities > New Import from the menu bar in the main window.



**Table 42: Import window**

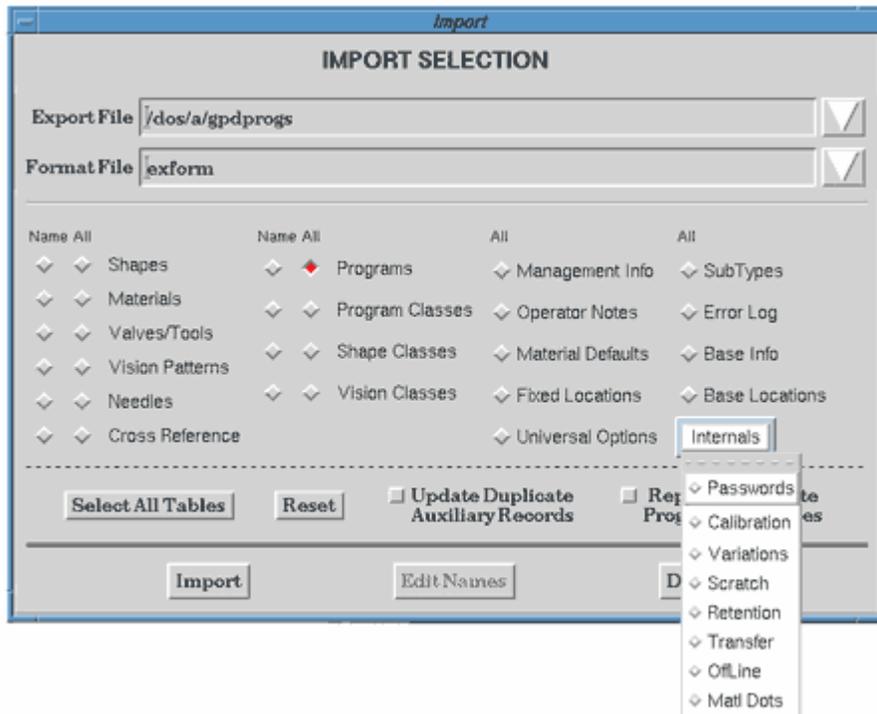
Element	Description
Export File	The name and path of the file created by the export program.
Format File	The name and path of the file that defines the format parameters under which the exported file will be exported.
Name	Activates a list of names from which to choose.
All	Imports everything in the file corresponding to the ALL button. For example, when the ALL button (next to Programs) is activated, as shown above, all records in the programs file are imported.
Shapes	Properties for shapes located in the shapes library.
Materials	Properties and defaults for materials located in the materials library.
Valves/Tools	Properties for various heads that may be mounted on the machine.
Vision Patterns	Patterns from the vision system and associated information.
Needles	Inside and outside diameters, and other parameters for standard needle gauges.
Cross Reference	Connects a shape with a part number by providing an OpType for known part numbers.
Programs	Dispenser program names.

**Table 42: Import window (Continued)**

Element	Description
Program Classes	Activating the <b>NAME</b> button for Program Classes, Shape Classes, and Vision Classes will import the <i>programs, shapes, and vision patterns</i> for the class names selected in the Class Filter window; i.e., the objects of the selected class names are imported.
Shape Classes	
Vision Classes	
	Activating the <b>ALL</b> button for Program Classes, Shape Classes, and Vision Classes will import the <i>names of the classes</i> selected in Class Filter.
Management Info	Detailed information by gantry about each machine run.
Operator Notes	A table of operator notes.
Material Defaults	Provides the ultimate parameter values for mounted valves/tools when there is no other way to determine the values.
Fixed Locations	Locations of pallets or other points around the work area but outside of the nest.
Universal Options	General options independent of installed hardware.
Sub Types	Defines extensions to shape primitives.
Error Log	List of messages selected by message class.
Base Info	Machine definition and summary information by gantry about the machine.
Base Locations	Basic positions for each gantry.
SELECT ALL TABLES	Any combination of options may be selected. To quickly select all options, click on SELECT ALL TABLES.
RESET	Resets the Import window to its default display of a single selection: ALL programs.
Update Duplicate Auxiliary Records	Updates any existing records with new updated version. If this option is not selected, duplicates will be ignored.
Replace Duplicate Programs & Shapes	Deletes and replaces existing programs/shapes with new updated version. If this option is not selected, duplicates will be ignored.
IMPORT	Executes the import of selected file(s).
EDIT NAMES	Invokes a window listing the names of all currently selected files for import.
DONE	Exits the window.

## Internal Tables

An additional button, INTERNALS, is **available only at the super user access level**. The Internals tear-off menu that displays when the INTERNALS button is clicked lets you make multiple selections from other tables.



These additional tables fall into the following basic categories:

**Table 43: Import window - Internal Tables**

Table	Category
Passwords	Provides the user with access to the import of <b>all passwords</b> .
Calibration	Semi-temporary data related to current process/setup.
Scratch	
Retention	
Transfer	
Offline	
Material Dots	Not yet implemented.
Variations	

## Interim Report Generation

Reports can be generated for each run of a process (when the job accounting feature is set to collect the data) using the Interim Report Generation window.

This window is also used to purge the same information.

**TIP:** To access Interim Report Generation, go to the main menu bar and click on Utilities > Management Info > Show Job Info.

**Table 44:** Interim Report Generation window

Element		Description
Program Name	reporting	Enter the name of a single program for which a report is to be generated or leave blank if the report is to include all programs as selected by other conditions.
	purging	Enter the name of a single program for which a data is to be deleted, or leave blank if all programs selected by other conditions are to be deleted.
Operator Name	reporting	Enter the name of a single operator for which a report is to be generated or leave blank if the report is to include all operators as selected by other conditions.
	purging	Enter the name of a single operator for which data is to be deleted, or leave blank if data for all operators selected by other conditions are to be deleted.
Report this many days back	reporting	Limits report to a particular time frame. For example, to include only operations that occurred during the last ten days, enter <b>10</b> in this field. The other alternative is to enter a zero in this field and include a date in the <b>Earliest date on report</b> field.
	purging	To delete data more than 10 days old, enter <b>10</b> in this field. Alternatively, enter a zero in this field and include a date in the <b>Earliest date on report</b> field.

**Table 44: Interim Report Generation window (Continued)**

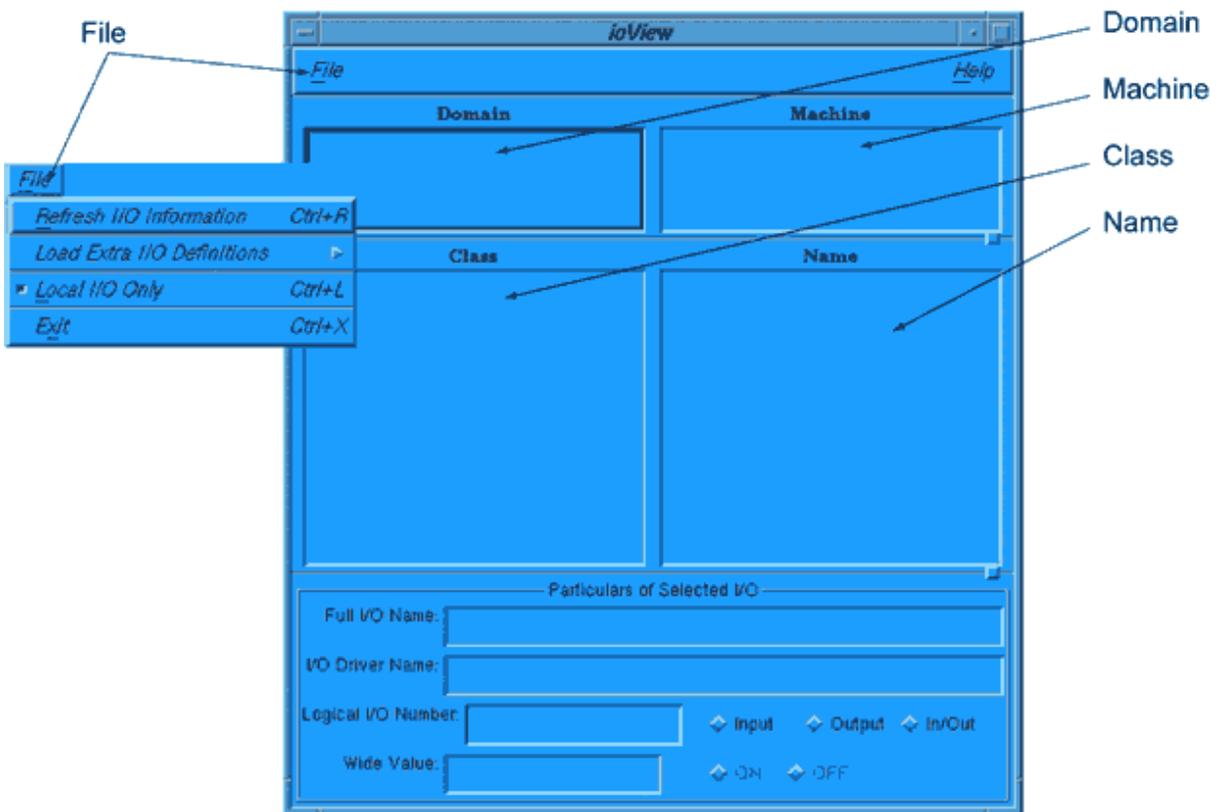
Element		Description
Earliest date on report	reporting	Enter the earliest date for which data is to be reported; this option requires a zero be entered in the <b>Report this many days back</b> field. If the <b>Report this many days back</b> field is not zero, the <b>Year</b> , <b>Month</b> , and <b>Day</b> fields are ignored.
	purging	Enter the earliest date for which data is NOT to be deleted. If <b>Year</b> , <b>Month</b> , and <b>Day</b> are all blank, all available data will be deleted. If these fields are not blank, these fields are ignored.
Print to Disk		The report is placed on a floppy disk in printer format. The floppy disk must contain a newly formatted disk before you click OK on the Interim Report Generation window. The name <b>acctpmt</b> is assigned to the disk file.
Data to Disk		The report is placed on a floppy disk in a format suitable for use with a spreadsheet. The floppy disk drive must contain a newly formatted disk before you click OK on the Interim Report Generation window. The name <b>acctdata</b> is assigned to the disk file.
Print to Printer		The report is sent directly to an attached printer. A printer must be connected to the dispenser; otherwise, do not use this option.

## IoView

The IO Viewer is a tool to help determine if a device I/O (input or output) is wired properly and receiving the correct voltage.

**⚠ WARNING** The content of this section is NOT recommended for use by anyone besides GPD Global personnel or those working under the direct guidance of GPD Global personnel. Improper application of this information can lead to serious complications in FLOWare Software operations. Any non-GPD Global employee who uses this information beyond the stated application specified by GPD Global Service Department personnel is in danger of causing personal injury and invalidating their machine warranty.

<b>ATTENTION</b> <a href="#">Le contenu de cette</a>	<b>WARNUNG</b> <a href="#">Der Inhalt dieses</a>	<b>ATTENZIONE</b> <a href="#">Il contenuto</a>	<b>ADVERTENCIA</b> <a href="#">NO SE RECOMIENDA</a>
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**Table 45: ioView window**

Element	Description
Domain	Used to operate the I/O system on a different, networked machine.
Machine	
Class	A term to define a type of data defining a collection of programs, shapes, or vision patterns that share the same characteristics. A class of programs, shapes, or vision patterns is typically selected for display.
Name	The label assigned to each I/O number.
Refresh I/O Information	Loads I/Os for viewing in the IoView window.

**Table 45: IoView window (Continued)**

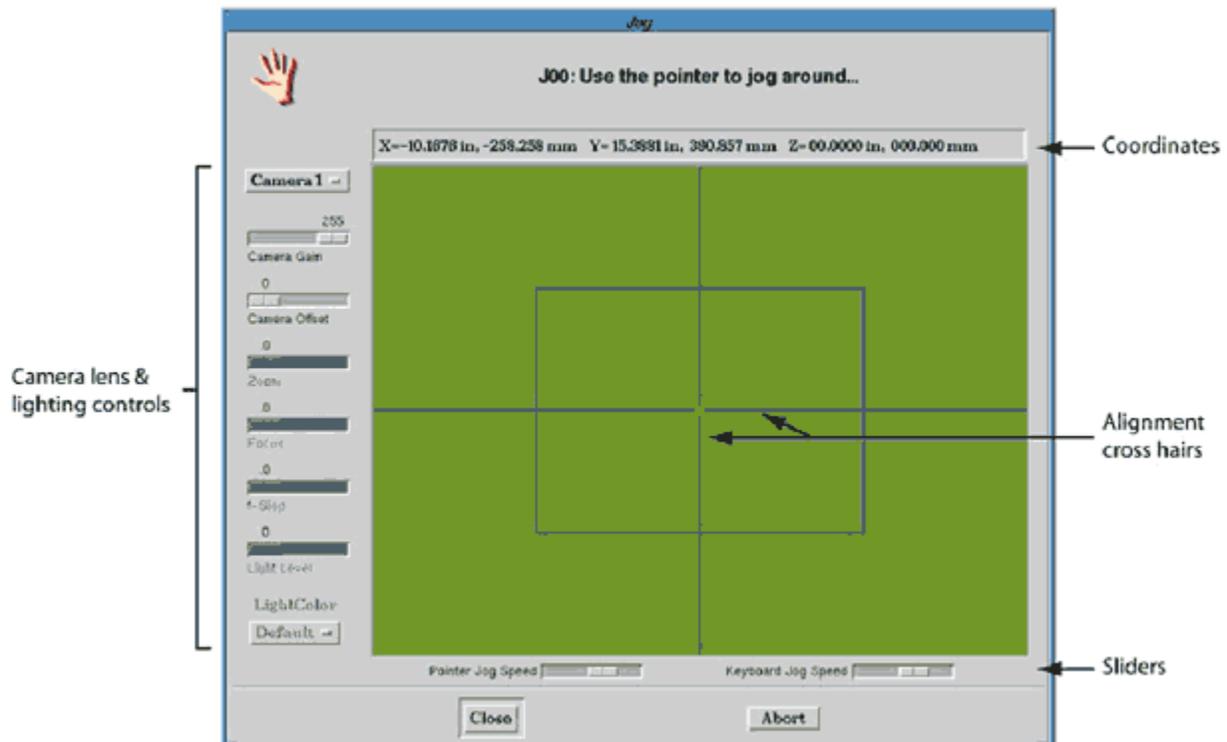
<b>Element</b>	<b>Description</b>
Load Extra I/O Definitions	Not currently used.
Local I/O Only	Not currently used.
Exit	Closes the IoView window.
Input Output	How the selected I/O is configured.
In/Out	Denoted as a dynamic I/O in configuration files.
On Off	The current state of the selected I/O.
Wide Value	Displays the value of a pseudo I/O.
<i>speed sliders</i>	(located on IO by Class window) change the rate of refresh display and the reaction time between command and I/O response.

## Jog

Jog provides the means to manually move the X, Y, and Z axes of the gantry using the trackball and keyboard in order to position the camera, teach program coordinates, align offset points, and reposition the gantry when necessary.

Jog will automatically display during various procedures.

**TIP:** To manually open a Jog window, go to the main button bar and click JOG. The JOG button is also available on other various windows.



**Table 46: Jog window**

Element	Description
coordinates	A display of the current coordinates for the camera. These coordinates are relative to the active reference point.
alignment cross hairs	Guides for precise alignment.

### **CAMERA LENS & LIGHTING CONTROLS**

Camera x	Camera location for this camera.
Camera Gain	Vision system gain; gain to how the vision system sees the camera image.
Camera Offset	Vision system offset; offset to how the vision system sees the camera image.
Zoom	Focal length for programmable focus lens camera.
Focus	Focus for programmable focus lens camera.
f-stop	f-stop for programmable focus lens camera.

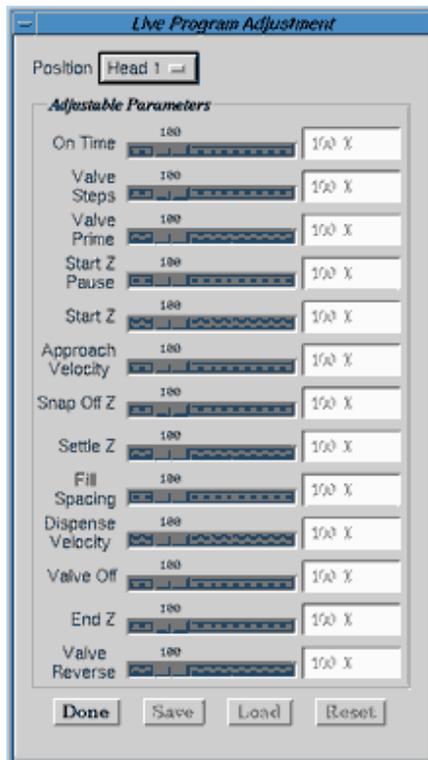
**Table 46: Jog window (Continued)**

Element	Description
Light Level	Level of camera light intensity. Only functional when the dispenser is configured with a programmable focus lens camera.
Light Color	<p>Controls the light color. Used to enhance the field of view when vision is affected by surface colors or textures. Only functional when the dispenser is configured with a programmable focus lens camera.</p> <p>Choices available are typically Red or Blue for a dispenser configured with the Intensity Control option, or between Ring Light Diffuser and Diffuse On Axis Light for a dispenser configured with the Multi-Axis Illumination option.</p>
<b>SLIDERS</b>	
Pointer Jog Speed	Changes the overall operating speed of the cursor.
Keyboard Jog Speed	Changes the overall operating speed of keyboard controls.

## Live Program Adjustment

Live Program Adjustment is a program development tool used during a program run to temporarily adjust machine parameters for a designated valve mount station. For details, refer to [Tweaks for Valves/Tools](#) (pg 3.120).

**TIP:** To access Live Program Adjustment, go to the main button bar and click TWEAKS.



**Table 47:** Live Program Adjustment window

Element	Description
Position	Mount station location of the valve/tool for which parameters are to be adjusted.
On Time	The total amount of time a valve is on to dispense, delay time, or any other time value required to perform an operation.
Valve Steps	Number of steps (encoder counts) for a Micro-Dot valve to dispense a dot.
Valve Prime	The time it takes to start valve operation before reaching Start Z (the Z location where dispensing or other operation takes place); this is used to prime a valve.
Start Z Pause	In-position delay between attaining Start Z position (the Z location where dispensing or other operation takes place) and the start of any motion associated with the operation.
Start Z	Distance above the board where dispensing or other operation is to take place for this feature; negative to drill into a drill pad.
Approach Velocity	Speed of the motion from Settle Z (where the gantry settles before the operation) to Start Z (the Z location where dispensing or other operation takes place).
Snap Off Z	Distance to move the valve/tool up during the snap-off action to prevent tailing.
Settle Z	Distance above Start Z (the Z location where dispensing or other operation takes place) where the gantry settles before the move to Start Z.

**Table 47: Live Program Adjustment window (Continued)**

<b>Element</b>	<b>Description</b>
Fill Spacing	Defines the spacing between successive lines of fill for filled features such as circles and rectangles.
Dispense Velocity	Speed of any motion required during an operation. For example, Z velocity while building a pillar, or coordinated motion velocity while drawing a line.
Valve Off	The distance prior to the end of a fill at which the valve is turned off to prevent possible material dribble at the end of the operation. When applying this only to the last line or circle of a fill, make sure the length of the last line/circle allows this.
End Z	Distance above Start Z (the Z location where dispensing or other operation takes place) for the operation to end. This value is non-zero to create pillars or to dispense along an angle to the plane of the board.
Valve Reverse	The amount of time the valve motor is on in the reverse direction to perform suck-back action for an LX Auger Valve.
DONE	Exits this window.
SAVE	Save changes made to this window.
LOAD	Loads the tweak settings (the Adjustable Parameters in the Live Program Adjustments window) that were previously saved.
RESET	Sets all tweaks (the Adjustable Parameters in the Live Program Adjustments window) to 100%.

## Live Video Parameters

Used to align Cognex cross-hair generator with video capture.



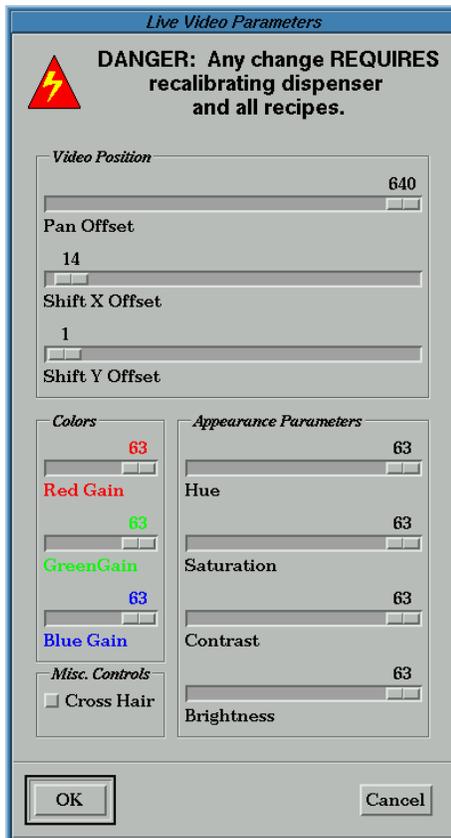
**WARNING** The content of this section is NOT recommended for use by anyone besides GPD Global personnel or those working under the direct guidance of GPD Global personnel. Improper application of this information can lead to serious complications in FLOWare Software operations. Any non-GPD Global employee who uses this information beyond the stated application specified by GPD Global Service Department personnel is in danger of causing personal injury and invalidating their machine warranty.

<b>ATTENTION</b> <a href="#">Le contenu de cette</a>	<b>WARNUNG</b> <a href="#">Der Inhalt dieses</a>	<b>ATTENZIONE</b> <a href="#">Il contenuto</a>	<b>ADVERTENCIA</b> <a href="#">NO SE RECOMIENDA</a>
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The standard settings for systems using a WinTV video capture card or an NVideo VGA card are a Shift X Offset of 14 and a Shift Y Offset of 2. Settings differ for systems with the older VideoMail VGA cards.

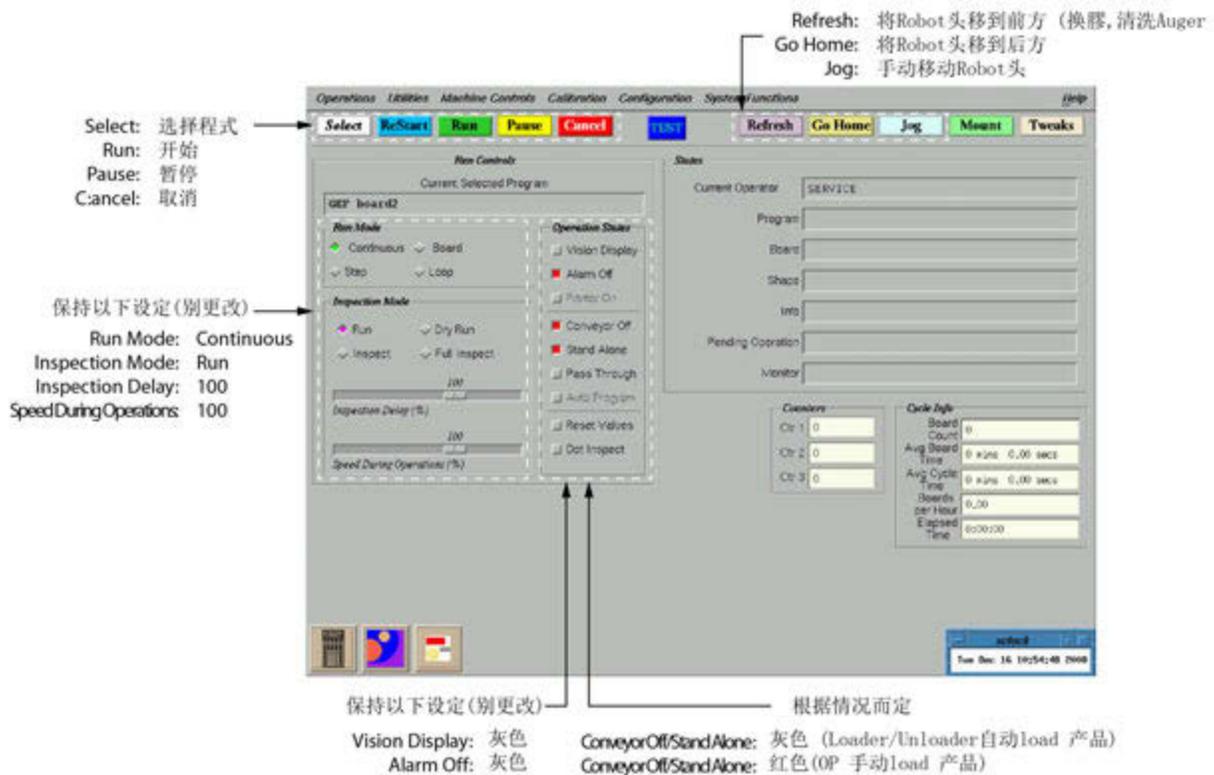
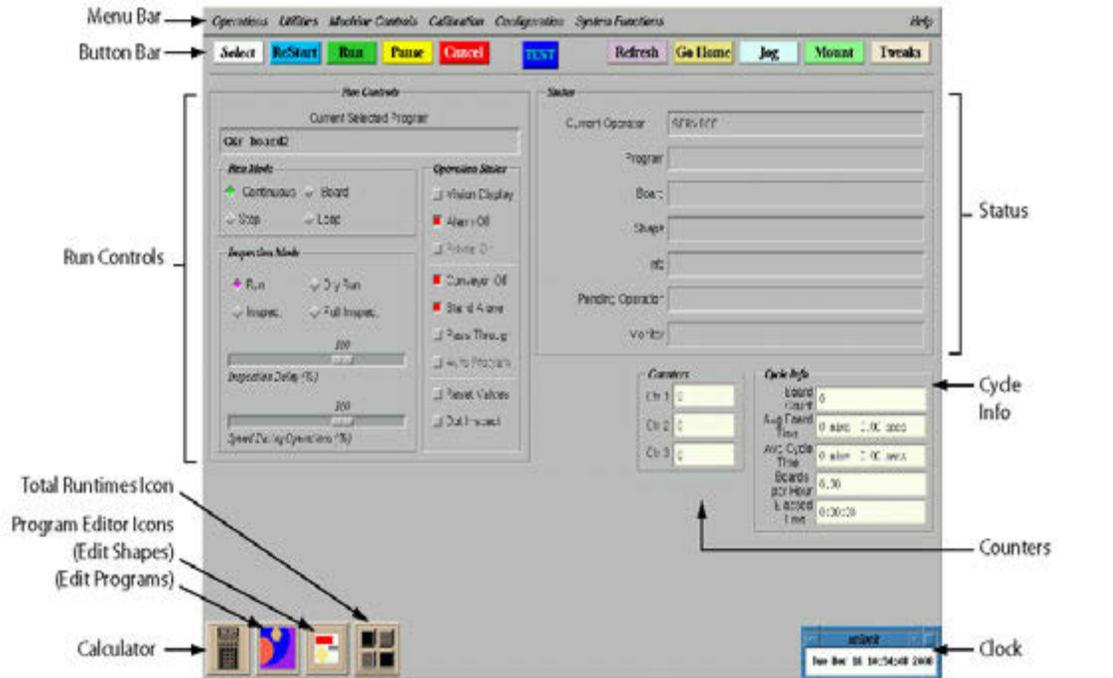
The system must be rebooted before changes take effect.

**TIP:** To access Live Video Parameters, go to the main button bar, click Calibration > Live Video Parameters.



## Main Control

The main control window displays when the system is ready to run and is the site where all user interaction with FLOWare control software begins. Whether or not all menu bar and button bar choices are displayed depends upon the current access rights. All choices are displayed here.



**Table 48: Main Control window**

Element	Description
<b>MENU BAR</b>	
Operations	Displays a drop-down menu of basic operations such as entering/clearing the password, shutting down the system, rebooting, exiting the main control window, and displaying the icons that appear along the bottom edge of the main control window.
Utilities	Displays a drop-down menu of utility functions such as backups, imports/exports, installation of software updates, data management, and add/view notes.
Machine Controls	Displays a drop-down menu of manual machine controls.
Calibration	Displays a drop-down menu of calibration choices including conveyor speed, conveyor width, work area surface mapping, and D2A/A2D boards.
Configuration	Displays a drop-down menu of configuration choices. Of particular interest is the option settings choice; the other choices are not intended for typical customer use.
System Function	Displays a drop-down menu of various system functions which are not intended for typical customer use.
Help	The About choice displays the title and version number of the resident control software.
<b>BUTTON BAR</b>	
SELECT	Enables you to choose a program to run. The dispenser will always run the currently selected program.
RESTART	Functions the same as RUN except none of the setup parameters are changed. RESTART will not prompt for the lifter pins to be repositioned, and, if pallets or feeders are being used, the program will continue where it left off without resetting the pallets or feeders (whereas RUN will start the program at the beginning of the pallet or feeder).
RUN	Starts the currently selected program in the current program mode after prompting you to calibrate the valves/tools and load the product. If pallets and feeders are used by the program, they are reset.
PAUSE	Stops the current operation at a convenient place in the program; e.g., gantry motion may not stop immediately after you click on PAUSE. This is a non-destructive command; the system will not stop in the middle of a dispense of any kind. Operations may be resumed when convenient with the RUN button.
CANCEL	Ends program execution. Once a program is canceled, it can only be restarted from the beginning with the normal RUN procedure. Occasionally, a program will not abort immediately as the current operation has to execute fully.
REFRESH	Moves the gantry to the front of the machine where valves/tools can be refreshed conveniently.
GO HOME	Moves the gantry out of the way, usually to the left rear corner of the machine.
JOG	Enables manual control of the camera/gantry position.
MOUNT	Executes a substrate fixturing routine. MOUNT applies to both stand-alone and conveyor systems.

**Table 48: Main Control window (Continued)**

<b>Element</b>	<b>Description</b>
TWEAKS	Can be used during a run to adjust machine parameters per valve mount station. All listed parameters can be changed by a percentage based on the original program.
<b>RUN CONTROLS</b>	
Current Selected Program	Name of the program currently selected.
Run Mode	Determines how the currently selected program will execute.
Continuous	Program execution continues without pause except for required operator intervention. This is typically the normal production pattern.
Board	Processes a subboard on a panel without pause, except for required operator intervention, and then prompts the operator before the next panel. The operator can either continue with the next subboard or skip it.
Step	Processes a single program step and then prompts the operator to continue.
Loop	Processes the same board repeatedly without pause except for required operation intervention. This is typically used as a demonstration or test mode.
Inspection Mode	Determines how the currently selected program will be processed, either full or in one of various inspections modes.
Run	Program will execute as designed.
Dry Run	Same as Run except no valve/tool operation or material dispensing occurs and no movement below the board surface (trace cutting) is made.
Inspect	The camera, not the valves/tools, moves to the coordinates of each program line, providing a visual inspection of the program. The gantry pauses for a specified time at each location to allow inspection. To adjust pause duration, use the Inspection Delay slider.
Full Inspect	Same as Inspect except the camera fully traces all moves, lines, arcs, fills, and dot arrays. To adjust the speed, use the Speed During Operations sliders.
Inspection Delay	The length of time the camera will wait over a coordinate.
Speed During Operations	The speed at which the camera moves over fills, lines, arcs, and moves during a Full Inspect. This is a relative speed, either slower or faster than the current setting.
Operation States	Operation State toggle boxes enable/disable the stated control over the camera, alarm, conveyor, printer, etc.
Vision Display	Displays the camera image whenever the camera is located over a significant feature.
Alarm Off	Prevents the audible alarm from operating.
Printer On	Activate to use a printer attached to dispenser parallel port. Various other print controls throughout the system (such as Print Scale Values) can be set to print and then globally controlled here with Printer On.
Conveyor Off	Turns on the conveyor belt briefly in order to seat a board against the nest stop pin.
Stand Alone	Prevents SMEMA communication (the conveyor ignores upstream and downstream signals) and requires manual product placement and removal.
Pass Through	Causes the conveyor to pass all product through the dispenser without processing.
Auto Program	Enables a device outside the dispenser (such as a matrix reader) to scan information (such as barcode) from incoming product and dictate various instructions to the dispenser (such as which program to run, the number of boards to run before the next program, etc.).

**Table 48: Main Control window (Continued)**

Element	Description
Reset Valves	Provides a quick reset of the servo-drive model of Micro-Dot valve as required after a valve change and if the valve was not connected prior to power up. (More recent stepper drive models do not require a reset.)
Dot Inspect	Not currently functional; it has no effect on anything in either the On or Off state.

**STATUS**

Current Operator	Displays the name of the current user.
Program	Displays the name of the program currently processing.
Board	When in Inspect Mode, the name of the board the program is currently processing displays here.
Shape	When in Inspect Mode, the name of the shape the program is currently processing displays here.
Info	Displays information when a process is waiting, such as <b>loading a program, operating in pass-through mode, or waiting to release the exit board</b> . When in Inspect Mode, the operation being executed displays.
Pending Operation	Displays the pending operation when a pallet is at a fixed location and the pallet needs changing.
Monitor	Displays the number of boards the program has completed processing along with the grams of pressure exerted by the pressure pick-up tool, if that tool is installed.
Material	When the Material Expiration feature is enabled, the Monitor field is present and displays either the time remaining for the current material or an indication that the material is expired. If the feature is disabled, the Monitor field is not present.

**CYCLE INFO**

Tracks cyclic aspects of a program run. All fields reset to zero when a program run is initiated.

Board Count	Number of boards processed through the dispenser during the current program run. When pallets are present, the complete board is counted, not individual pallets.
Avg Board Time	The average time per board spent executing program commands. The initial board typically takes longer to run due to the calibration process that occurs at the beginning of a program run.
Avg Cycle Time	The average time per board to complete a cycle includes Avg Board Time plus all other events that occur within the cycle such as pausing for operator intervention, waiting for upstream/downstream equipment, etc.
Boards per Hour	Number of boards processed during an hour based on the value of Avg Board Time.
Elapsed Time	Time elapsed since the current program run began.

**COUNTERS**

Ctr 1 Ctr 2 Ctr 3	<p>Counter values display only during a program run when counters are used in the active program.</p> <p>Various types of counters are available for adding to a program as an OPERATE line with a SubOp. Counters can increment or decrement, test one counter against another, or test a counter against a fixed value.</p> <p>Counters are numbered and can be assigned any number from 1 to 32,767. Any counter assigned a number less than 100 always starts at zero (0) with a program run and disappears when the program run ends. Any counter assigned a number of 100 or greater always starts with the value the last program left it with and keeps its value in the database.</p>
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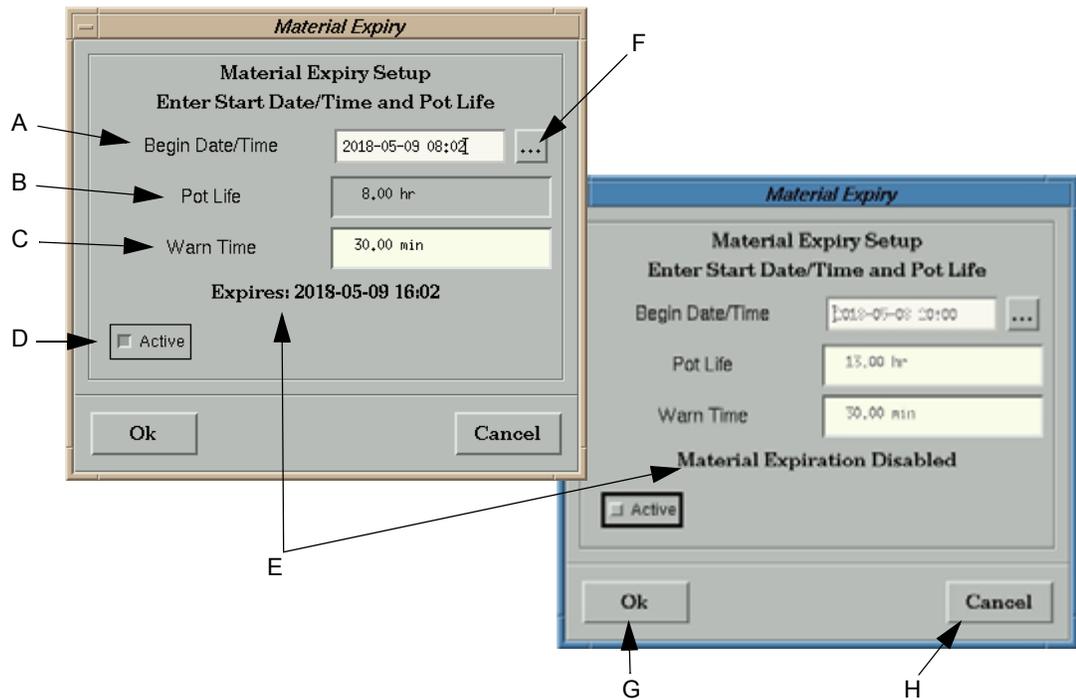
**Table 48: Main Control window (Continued)**

Element	Description
<b>ICONS</b>	
Calculator	Display a fully operational calculator. This is a standard X-Windows feature.
Program Editor: Edit Shapes Edit Programs	One of two variation of the Program Editor icon can display on the main control window. Icon appearance is related to which selection tool is active in the Program Detail window. Typically, only a single Program Editor icon is displayed at a time.
Clock	Displays the system date and time.

## Material Expiration

The Material Expiration features allows setting a material *start date/time* and a *pot life*. When the combined start time and pot life has expired, messages are displayed indicating the material has expired.

**TIP:** To access Material Expiration, go to the main menu bar and click Operations > Material Expiration.



**Table 49: Material Expiration window**

A	Expiration Period Starting Date and Time	Must be in this form: YYYY-MM-DD HH:MM If the date/time is entered incorrectly, the dialog will display 'Malformed Date/Time' in area E.
B	Pot Life	Pot Life is entered in hours; this may include fractional hours, e.g. 4.25 Examples: 1.5 is 1½ hours
C	Warn Time	Warning Time is entered in minutes; this may include fractional minutes. The number of minutes before expiration when the system begins persistent notification about material expiring.
D	Active/Inactive	Enables/Disables the entire material expiration feature. If disabled, no messages are displayed.
E	Message Area	Displays expiration date/time or 'Invalid Data' messages.
F	Set NOW	Sets the Starting Date/Time to 'Now'.
G	Accepts current data	Current data becomes immediately active.
H	Cancels data entry	Discards all changes.

## Miscellaneous Program Settings

When building a program, use the Miscellaneous Program Settings for various purposes: to refine the translation between vision system pixels and XY gantry motion (millimeters/inches); to control device temperature; to control board rotation relative to bad mark count; and to set device pressure values.

**TIP:** To access Miscellaneous Program Settings, open the Program Editor, select the name of the program you wish to modify, and then click on the MISC PROGRAM SETTINGS button.

**Table 50: Miscellaneous Program Settings window**

Element	Description
<b>VISION CALIBRATION</b>	
Gain	Camera gain (0-255) for dispensed or drilled dot calibration. A value of -1 disables change.
Offset	Camera offset (0-255) for dispensed or drilled dot calibration. A value of -1 disables change.
Tuning	Camera tuning (1-1000) for dispensed or drilled dot calibration.
Zoom	Focal length (0.0 to 1.0) for an auto focus camera for dispensed or drilled dot calibration.
Focus	Focus (0.0 to 1.0) for an auto focus camera for dispensed or drilled dot calibration.
f-stop	f-stop (0.0 to 1.0) for an auto focus camera for dispensed or drilled dot calibration.
Light Level	Level of camera light intensity for dot calibration. Only functional when machine is configured for the Multi-Axis Illumination option.

**Table 50: Miscellaneous Program Settings window (Continued)**

Element	Description
Light on Dark	ON = enables camera to see <i>light</i> dot on <i>dark</i> background for dot calibration. OFF = enables camera to see <i>dark</i> dot on <i>light</i> background for dot calibration.
Light Color	Controls the light color for dot calibration. used to enhance fiducial or pattern identification when vision is affected by surface colors or textures.  Choose a color (typically Red or Blue) when the system is configured with the Intensity Control option, OR  Choose a lighting configuration (typically Ring Light or Diffuse On Axis Light) when the system is configured with the Multi-Axis Illumination option.
TEACH VISION	Changes the settings on this screen to match the settings to which the camera is set.
ADJUST VISION	Adjusts the camera to the settings defined on this screen.
JOG	Opens a Jog screen.
Max Pixel Count	Maximum pixel count for calibration dot.
Min Pixel Count	Minimum pixel count for calibration dot.
Dot Volume	Volume of dot for calibration dot.

**TEMPERATURES**

Not yet functional. Temperature control is currently handled with CAL 9900 hardware.

Pre-Heat Heater On	Activates or deactivates temperature control for the pre-heat station.
Pre-Heat Temperature	Temperatures (degrees C) at which the pre-heat station is to be maintained.
Pre-Heat Range	Temperature range (degrees C) plus or minus adjacent to the specified pre-heat temperature.
Pre-Heat PID	Activates or deactivates PID control at the pre-heat station.
blank button	Select a PID name.
Post-Heat Heater On	Activates or deactivates temperature control for the post-heat station.
Post-Heat Temperature	Temperatures (degrees C) at which the post-heat station is to be maintained.
Post-Heat Range	Temperatures range (degrees C) plus or minus adjacent to the specified post-heat temperature.
Post-Heat PID	Activates or deactivates PID control at the post-heat station.
blank button	Select a PID name.
Work Area Heater On	Activates or deactivates temperature control for the work area.
Work Area Temperature	Temperatures (degrees C) at which the work area is to be maintained.
Work Area Range	Temperatures range (degrees C) plus or minus adjacent to the specified work area temperature.
Work Area PID	Activates or deactivates PID control at the work area.
blank button	Select a PID name.

**OTHER**

Bad Mark Count	If the bad mark count is exceeded, a request to rotate the board is issued.
Post Press	Pressure (grams) for post-press pressure.
Post Press Range	Range (grams) for post-press pressure.
Post Press Time	Time (sec) for post-press pressure.

## Mounts Table

Early in a program run, the Mounts Table displays to indicate to the operator which valves/tools, materials, and needles to install for the program being run.

**TIP:** Mounts Table displays when either the RUN or MOUNT buttons are activated from the main button bar.

**R35: Prepare and Mount Items Specified.**

Mount Position	Tool/Valve	Material	Needle	Air Pressure	Skip Calibration		
					All	StandOff	Scale
1	Auger w/standoff	Amicon D125F	25	69 kPa	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>
2	NONE	NONE	25	69 kPa	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>
3	NONE	NONE	25	0 kPa	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>

Lot #  Type  Category

Select Feature ID Variation  Select Feature IDs  Use Tweaks

**OPERATOR INSTRUCTIONS**

**Table 51: Mounts Table window**

Element	Description
Tool/Valve	Displays the name of the valve/tool to be mounted in the designated Mount Position.
Material	Displays the name of the material to be dispensed. Up to 32 characters long.
Needle	Displays the name of the needle to be used.
Air Pressure	The value for the valve syringe air pressure may be entered here. Pressure is automatically regulated via the system for the MicroMax models, however, the DS Series models require manual adjustment.
Skip Calibration	Determines omission of all calibration for this valve/tool (All), omits calibration only for the rigid needle standoff (StandOff), or omits calibration only at the scale (Scale). When the stale calibration time value expires, calibration will be forced.
Lot #	Enter up to 18 characters for Lot # if your work site uses job accounting; otherwise, this field defaults to a blank. To collect this entry, the Job Accounting function must be turned on; otherwise, it is only retained in this window display.
Type	Enter up to 18 characters for Type # and/or Category if your work site uses job accounting; otherwise, these fields default to the last values used for this program. To collect these entries, the Job Accounting function must be turned on; otherwise, entries are only retained in this window display.
Category	

**Table 51: Mounts Table window (Continued)**

<b>Element</b>	<b>Description</b>
Select Feature ID Variation	Not currently function. Indicates whether to use a particular collection of feature IDs.
Select Feature IDs	Indicates whether to use feature IDs.
Use Tweaks	Indicates whether to use tweak values (set in the Live Program Adjust window) in place of the program values.
Operator Instructions	The optional text entered in Program Editor displays here. Displays instructions for the operator to see during the initial step of a program run.
CONTINUE	Saves changes and continues the program run.
ABORT	Closes this window without saving changes and terminates the program run.

## Mounts/Material Editor

There are three different versions of the Mounts/Material Editor window, each with a different purpose and a unique access path. Parameter definitions remain the same across all three versions of the editor, although not all fields are active in all three windows.

- Mounts/Material Editor - MOUNT is used to define head location and the type of material at the program level. For details, refer to [MOUNT](#) (pg 3.71).
- Mounts/Material Editor - MATERIAL is the [Materials Library](#) (pg 5.7).
- Mounts/Material Editor - DEFAULTS is the [Material Defaults Library](#) (pg 5.9).

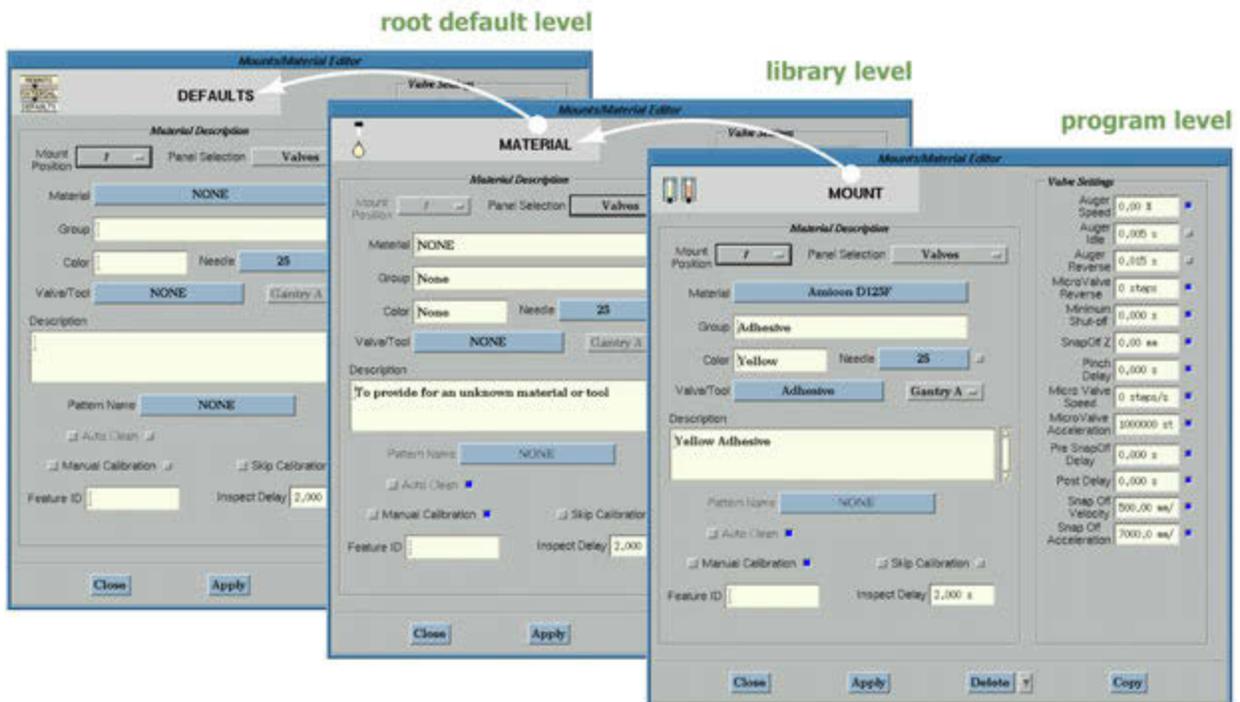
Details about the default hierarchy beyond the general concept shown in Figure 33 are discussed in [Mounts & Material Defaults](#) (pg 3.94).

**TIP:** To open these windows, use the following guide:

**Table 52: Guide to Opening the Mounts/Material Editor Windows**

Version of Editor	To Open the Window
MOUNT	From Program Editor, select program, then click VALVE/TOOL MOUNTS button.
MATERIAL	From Program Editor, click Libraries > Material.
DEFAULTS	From Program Editor, click Libraries > Material Defaults.

**Figure 33: General concept of default hierarchy for Mounts/Material Editors**



**Table 53: Mounts/Material Editor windows**

Element	Description
<b>MATERIAL DESCRIPTION</b>	
Mount Position	Mount location for this valve/tool. If this information is omitted, the first mount location is automatically assigned.
Panel Selection	A pull down menu of choices, each of which will display a different set of fields in the right-hand side of the window: Valves, Process Defaults, Warning Limits, Scale Parameters, Temperatures, Calibration Dot, X-Y Calibration, and Observation. For details, refer to the subsequent Panel Selection subsections in this table.
Material	Name of the material to be dispensed. May be up to 32 characters long. If present, this name must match the name of the material in the Materials library; if it does not match, the program will be rejected.
Group	Group of the material; copied from the Materials library. May be up to 32 characters long.
Color	Color of the material; copied from the Materials library. May be up to 32 characters long.
Needle	Gauge of the needle used with this valve.
Valve/Tool	Name of the valve/tool to mount. May be up to 18 characters long. This name must match the tool/valve name in the Heads library; if it does not match, the program will be rejected.
Gantry	Gantry identification code for use with multi-gantry systems.
Description	Optional comment field of up to 250 characters.
Pattern Name	Name of the pattern used with this valve/tool. This name can be up to 24 characters long.
Auto Clean	Activates or deactivates automatic needle cleaning at the material level, making the Auto Clean setting the default in every program using the current material. When Auto Clean is activated and the system is configured with a needle cleaner device, a needle can be cleaned online automatically as part of a program run. When Auto Clean is deactivated, the system will stop when appropriate and wait for the operator to clean the needle before continuing with normal operations.
Manual Calibration	Activates or deactivates a forced manual calibration. When this field is deactivated, the camera is not used to find the calibration dot; this is particularly useful for use with clear materials.
Skip Calibration	Controls omission of all calibration for this valve/tool; enables/disables the ability to choose calibration at the start of a program.
Feature ID	Not yet functional. Name of a feature, up to 12 characters long. This field is used to describe the record as part of a discernible feature on the board.
Inspect Delay	Minimum time (ms) for operation during inspection.
COPY	The Copy button is only active for certain selectable panels and allows, for example, copying data from the XY Calibration selectable panel to the Observation selectable panel. For the Mounts/Material Editor - MOUNT window, the Copy button allows copying the entire controls panel from one mount location to another.
<b>SELECTABLE PANEL - VALVE SETTINGS</b>	
Auger Speed	Percent of velocity for variable speed auger valve.
Auger Idle	Total time delay; the time between turning off an auger valve and starting the reverse suck-back action. This field will not display if the system is configured for a non-contact jetting pump rather than an auger valve.

**Table 53: Mounts/Material Editor windows (Continued)**

Element	Description
Auger Reverse	Total time the auger valve will run in reverse to suckback material. This only applies to the LX Auger Valve and other valves with similar control. This field will not display if the system is configured for a non-contact jetting pump.
NCM Close Time	Close time range is 1 ms to 100 ms (10*0.0001 to 1000*0.0001). Total time delay; the time between closing and opening a non-contact jetting pump. All fields using the <i>seconds</i> measurement unit change to 4 place values (0.0000 rather than 0.000).
NCM Open Time	Close time range is 1 ms to 100 ms (10*0.0001 to 1000*0.0001). Total time the non-contact jetting pump will remain open. This only applies to the NCM5000 pump and other pumps with similar control. All fields using the <i>seconds</i> measurement unit change to 4 places values (0.0000 rather than 0.000).
Micro Valve Reverse	Number of Micro-Dot valve suckback steps.
Minimum Shut-off	Minimum time (ms) after dispenser stops and before valve shut off is activated.NCM
Snap Off Z	Distance (mm) to move the valve/tool up during snap off action to prevent tailing.
Pinch Delay	Delay (ms) before operating a pinch tube.
Micro Valve Speed	Micro-Dot valve speed (encoder uses steps per second).
Micro Valve Acceleration	Micro-Dot valve acceleration/change of velocity.
Pre SnapOff Delay	Time (ms) to delay after dispense but before beginning snap off.
Post Delay	Post operation delay (ms).
Snap Off Velocity	Snap off velocity (mm/sec).
Snap Off Acceleration	Snap off acceleration/change of velocity.

**SELECTABLE PANEL - PROCESS DEFAULTS**

Air Pressure	Value in kPa for syringe air pressure. Pressure is automatically regulated via the system for MicroMax dispenser, but requires manual adjustment for DS Series dispensers.
Air Control	Determines the way air pressure is handled. <b>Auto</b> - Air pressure turns on/off as operations dictate. <b>On</b> - If the machine is equipped with automatic air pressure control, the valve air pressure is set to the value of Air Pressure at the start of a program. <b>Off</b> - If the machine is equipped with manual air controls, the value in Air Pressure is informational only - it is displayed for the operator who must make a manual adjustment to set the air pressure.
Minimum Air Time	Minimum time (ms) to apply air pressure to the valve. This suppresses the constant on/off pressure to the valve.
Purge Time	Time (ms) to operate the valve for automatic purge.
Standard Acceleration	Speed (mm/sec/sec) at which the gantry moves for any operation with an acceleration value not otherwise specified.
Dispense Pressure	Force (gm) applied to MV valve during dispense.
Idle Pressure	Force (gm) applied to MV valve when idle.

**SELECTABLE PANEL - WARNING LIMITS**

Operation Limit	Counts dots; limit for the number of operations (dots to dispense) before the operator is warned (at product change) to refresh the material or replace the drill bit. Implies that material is low or drill has become dull.
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**Table 53: Mounts/Material Editor windows (Continued)**

Element	Description
On Time Limit	Limit (ms) of total valve on time before operator is warned (at product change) to refresh the material.
Idle Limit	Limit (ms) of valve/tool idle time before operator is warned of needed material purge.
Run Time Limit	Limit (ms) of elapsed run time before operator is warned to refresh the material.
Re-calibrate Operation Limit	Number of (program) operations after which a valve is recalibrated with the scale. Weight calibration is repeated after this number of operations have run.
Re-calibrate Board Count	Limit for number of boards to process before repeating weight calibration.
Re-calibrate Time	Elapsed time (ms) after which a valve is recalibrated with the scale. Weight calibration is repeated after this time has elapsed.
Limit Override	Number of boards allowed after low material has been sensed.

**SELECTABLE PANEL - SCALE PARAMETERS**

Weighing On Time	Time (ms) for valve operation to perform a weight calibration.
Target Weight for On Time	Amount (grams) of material expected from Weighing On Time.
Tolerance for Weight	Tolerance (grams) within which Target Weight for On Time will not change Weighing On Time and Dispense Velocity (for 1 or 2 part valves) values.
Scale Settle Time	Time (ms) allowed for the scale to settle after dispensing.
Maximum Scale Adjust	Maximum percent of weight variation allowed before operator is notified.
Maximum Scale Retry	Maximum number of consecutive re-weighing (weight calibration retries) before operation notification.
Multiple Dot Count	Not currently functional. Maximum number of dots to dispense before repeating weight calibration.
On Times from Program	Time (ms) obtained from the [uniquely defined] program. On = obtains the On times from the first six active program lines. Off = the On times will be used as they are entered.
Skip Weighing	Activates (Y) or deactivates (N) precision weighing for this valve/tool.
Scale Jog Z	Distance (mm) to jog above scale after dispensing.

**SELECTABLE PANEL - TEMPERATURES**

Material Temperature	Temperature (degrees C) at which the material (tube or reservoir) is to be maintained.
Material Temp Range	Temperature (degrees C) range plus or minus adjacent to the specified material temperature.
Material Heater On	Determines whether or not the temperature control is used.
Material PID Name	PID name for material temperature control.
Needle Temperature	Temperature (degrees C) at which the needle is to be maintained.
Needle Temp Range	Temperature (degrees C) range plus or minus adjacent to the specified needle temperature.
Needle Heater On	Determines whether or not the needle temperature control is used.
Needle PID Name	PID name for needle temperature control.

**SELECTABLE PANEL - CALIBRATION DOT PARAMETERS**

On Time	Main control of dispensed volume; value of the total time (ms) a valve is on to dispense a dot during calibration.
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**Table 53: Mounts/Material Editor windows (Continued)**

Element	Description
Approach Velocity	The speed (mm/sec) at which the Z axis moves from Settle Z (where the gantry settles before calibration) to Start Z (the Z location where dispensing or other operation takes place) during the calibration.
Valve Prime	Time (ms) to start valve operation before reaching Start Z (the Z location where dispensing or another operation takes place) during calibration; this is used to prime a valve prior to reaching target.
Start Z	Distance (mm) above the board where dispensing or other operation is to take place during calibration; a negative value will drill into a drill pad.
SnapOff Z	Height above Start Z to move the valve after a dispense is complete and during snap-off action to prevent tailing.
Move Velocity	Speed (mm/sec) at which the system moves the gantry during calibration operations.
Dot on Chip	Indicates whether a material dot is to be placed on a chip rather than on paper.
Settle Z	Distance (mm) above Start Z (the Z location where dispensing or other operation takes place) where the gantry settles before the move to Start Z.
Snap Off Velocity	Speed (mm/sec) at which snap off action occurs to prevent tailing.
Snap Off Acceleration	Acceleration (mm/sec/sec) of motion during snap off action to prevent tailing. Typically faster than standard acceleration to emphasize snapping motion.
Post Delay	Delay time (ms) after the valve/tool has turned off and reach Snap Off Z (snap off height). Used to assist in material-to-needle separation for stringy materials.
Micro Valve Steps	Number of encoder steps for a Micro-Dot valve to dispense a calibration dot.
Micro Valve Speed	The speed at which the Micro-Dot valve turns to dispense the calibration dot in cts/s.
Micro Valve Reverse	Number of reverse steps for a Micro-Dot valve to perform suckback action.
End Z	End Z distance for calibration dot.
Pre Snap Delay	Time (ms) to delay after dispense and before beginning snap off of calibration dot.

**SELECTABLE PANEL - X-Y CALIBRATION**

Gain	Camera gain (0-255) for dispensed or drilled dot calibration. A value of -1 disables change.
Offset	Camera offset (0-255) for dispensed or drilled dot calibration. A value of -1 disables change.
Tuning	Camera tuning (1-1000) for dispensed or drilled dot calibration.
Zoom	Focal length (0.0 to 1.0) for a programmable focus lens camera for dispensed or drilled dot calibration.
Focus	Focus (0.0 to 1.0) for a programmable focus lens camera for dispensed or drilled dot calibration.
f-stop	f-stop (0.0 to 1.0) for a programmable focus lens camera for dispensed or drilled dot calibration.
Light Level	Level of camera light intensity for dot calibration. Only functional when machine is configured for the Multi-Axis Illumination option.
Light on Dark	<b>On</b> - Enables camera to see <i>light</i> dot on <i>dark</i> background for dot calibration. <b>Off</b> - Enables camera to see <i>dark</i> dot on <i>light</i> background for dot calibration.

**Table 53: Mounts/Material Editor windows (Continued)**

Element	Description
Light Color	Controls the light color for dot calibration. Used to enhance fiducial or pattern identification when vision is affected by surface colors or textures. Choose a color (typically Red or Blue) when the system is configured with the Intensity Control option. OR Choose a lighting configuration (typically Ring Light or Diffuse On Axis Light) when the system is configured with the Multi-Axis Illumination option.
JOG	Opens a Jog window.
TEACH VISION	Adjusts the camera to the settings defined on this screen.
ADJUST VISION	Changes the settings on this screen to match the settings to which the camera is set.
Max Pixel Count	Maximum pixel count for dot calibration.
Min Pixel Count	Minimum pixel count for dot calibration.
Dot Volume	Volume of dot for dispensed dot calibration.
Backlight	<b>On</b> - Visually enhances the calibration dot for the camera. Turns off the camera light and turns on the calibration station backlight while the camera is looking at the calibration dot. <b>Off</b> - Not used.

**SELECTABLE PANEL - OBSERVATION**

Gain	Camera gain (0-255) for fiducial and dot inspection on the board. A value of -1 disables change.
Offset	Camera offset (0-255) for dot inspection on the board. A value of -1 disables change.
Tuning	Camera tuning (1-1000) for dot inspection on the board.
Zoom	Focal length (0.0 to 1.0) for a programmable focus camera for dot/fiducial inspection.
Focus	Focus (0.0 to 1.0) for a programmable focus camera for dot inspection on the board.
f-stop	f-stop (0.0 to 1.0) for a programmable focus camera for dot inspection on the board.
Light Level	Level of camera light intensity for dot inspection. Only functional when machine is configured for the Multi-Axis Illumination option.
Light on Dark	<b>On</b> - Enables camera to see <i>light</i> dot on <i>dark</i> background for dot inspection on the board. <b>Off</b> - Enables camera to see <i>dark</i> dot on <i>light</i> background for dot inspection on the board.
Light Color	Controls the light color for dot inspection. Used to enhance fiducial or pattern identification when vision is affected by surface colors or textures. Choose a color (typically Red or Blue) when the system is configured with the Intensity Control option. OR Choose a lighting configuration (typically Ring Light or Diffuse On Axis Light) when the system is configured with the Multi-Axis Illumination option.
JOG	Opens a Jog window.
TEACH VISION	Adjusts the camera to the settings defined on this screen.
ADJUST VISION	Changes the settings on this screen to match the settings to which the camera is set.
Max Pixel Count	Maximum pixel count for dot inspection.

**Table 53: Mounts/Material Editor windows (Continued)**

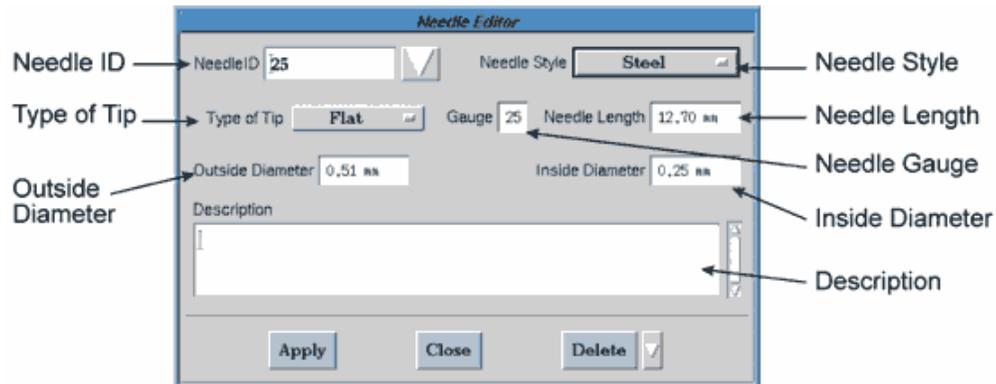
<b>Element</b>	<b>Description</b>
Min Pixel Count	Minimum pixel count for dot inspection.
Dot Volume	Volume of dot for dispensed dot inspection.

## Needle Editor

Use the Needle Editor to define a needle or change the characteristics of an existing needle.

Clicking the button next to the Needle ID field opens the Select a Needle window from which you can choose an existing needle. Alternately, if you define a new needle ID and click the APPLY button, the new ID will be added to the list of needles.

**TIP:** To access Needle Editor, open the Program Editor and click on Libraries > Needle.



**Table 54:** Needle Editor window

Element	Description
Needle ID	Name of the needle. May be up to 12 characters long.
Needle Style	Drop down menu of needle styles (Steel, Plastic, One Piece, Tapered Plastic, Teflon Lined, Vacuum Cup, and Flat Surface).
Type of Tip	Drop down menu of needle tip styles (Flat, Conical, Round Tool, and Square Tool).
Gauge	Gauge of the needle.
Needle Length	Length (mm) of the needle.
Outside Diameter	Outside diameter (mm) of the needle.
Inside Diameter	Inside diameter (mm) of the needle.
Description	Optional comment field of up to 250 characters. Text displays only in the Needle Editor window but prints in full for printouts.
APPLY	Applies and saves entries to the currently displayed needle ID.
CLOSE	Closes the window. Any changes not saved with the APPLY button will be lost.
DELETE	Deletes the currently displayed needle ID and removes it from the needle ID list.

## Offline Operations

When the dispenser is offline (not running a process), various operations may be performed independently from the program using the Offline Operations window:

- purging a valve
- cleaning a needle
- filling a syringe
- weighing dispensed material

**TIP:** To access Offline Operations, go to the main menu bar and click Machine Controls > Offline Operations.

**Table 55:** Offline Operations window

Element	Description
Mount Position	Mount location for this valve/tool.
Suppress Calibration	Indicates whether calibration operations are to be suppressed.
Valve	Dictates which valve will be used during the offline operation. May be up to 18 characters long.
Material	Name of the material dispensed during the offline operation. May be up to 32 characters long.
Program	Not currently functional. Program from which to obtain scale on-times for automatic entry in the Weight On Time(s) fields.
Expected Weight	The weight expected from the given On Times.
Purge On Time	On Time for offline purging. If value is 0, purging is under operator control.
Syringe On Time	On Time for offline syringe filling. If value is 0, filling is under operator control. (The SyringeFill value must be set to true in the configuration options file for this field to be functional.)
Weight On Time(s)	On Time(s) to weigh a dispensed shot offline.

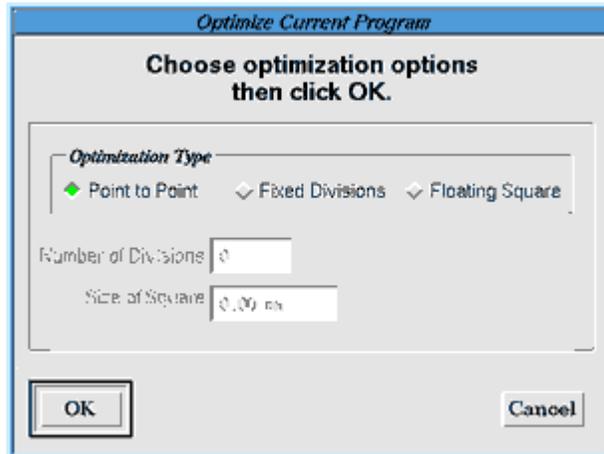
**Table 55: Offline Operations window (Continued)**

Element	Description
Weight On Times from Program	Not currently functional. Indicates whether On Time(s) are obtained from the program selected by the Program field.
WEIGH	Weighs Dispensed Material for a Specific On-Time Value - the scale is zeroed, the gantry moves forward, the specified amount of material is dispensed and weighed, the needle is cleaned, and the weighing results are displayed in a window.
PURGE	Purges the Needle - the gantry moves forward to the purge cup, the needle is purged, and the needle is cleaned. Purging ends when the specified purge time has elapsed or when, provided Purge On Time equals zero, the operator manually stops it by clicking DONE on the Information prompt.
SYRINGE	Fills the Syringe - the gantry moves forward, the operator is prompted to mount a syringe, the gantry moves to the syringe fill station and fills the syringe, and then the needle is cleaned. Syringe filling ends when the specified fill time has elapsed or when, provided Syringe On Time equals zero, the operator manually stops it.
CLEAN	Cleans the Needle - the gantry moves forward, the specified needle is cleaned at the needle cleaner or prompts the operator to clean the needle, and then the gantry moves to the safety location. This button is only functional if the dispenser is configured for needle cleaner hardware.

## Optimize Current Program

The Optimize feature reorganizes the current program to minimize execution time. Typically, Optimize is used on programs originally optimized for pick-and-place machines. Optimize is not intended for use on programs containing drawing-type operations such as move and arc.

**TIP:** To access Optimize Current Program, open the Program Editor and click on Utilities > Optimize.



**Table 56:** Optimize Current Program window

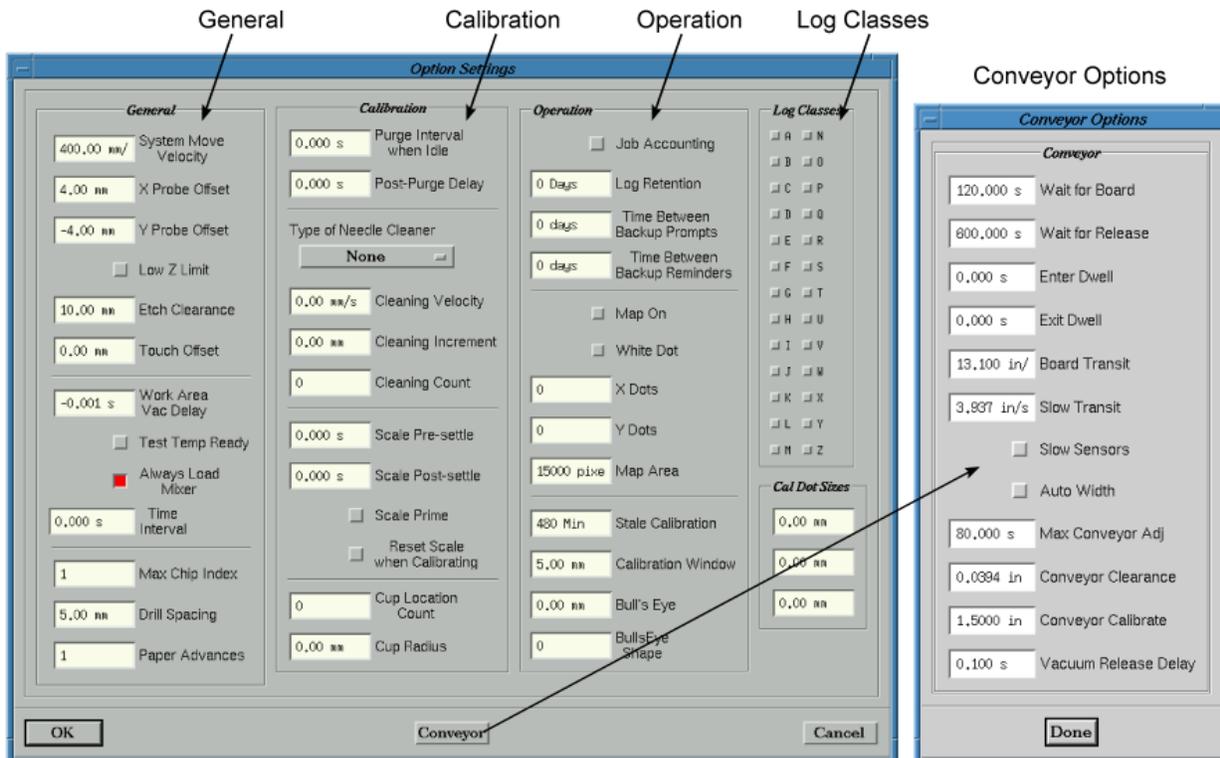
Element	Description
Point to Point	Optimizes the program to go from one location to the next closest point.
Fixed Divisions	Optimizes the program by dividing the board into sections. The user enters the desired number of sections per board in the Number of Divisions field.
Floating Square	<p>Optimizes the program by performing all program functions within a defined square area before moving to a new square area to perform the functions required in it.</p> <p>The order in which square areas are processed is determined by which new area is closest to the ending point of the just completed area. In other words, after completing the first square, the square closest to the last point of the first square is the one that is processed next. This pattern continues until all squares are processed.</p> <p>The user defines the size of the floating area in the Size of Square field.</p>

## Option Settings

Use the Editor to define and edit fixed locations (locations fixed in accordance with the work table like pallets and feeders).

Upon closing the Option Settings window by clicking OK, you will be prompted to reboot the machine in order for changes to become effective. Clicking CANCEL will erase any changes made making rebooting the machine unnecessary; the Reboot message will not display

**TIP:** To access Option Settings window, go to the main menu bar and click Configuration > Option Settings.



**Table 57: Option Settings window**

Element	Description
<b>GENERAL</b>	
System Move Velocity	Velocity default = 400.0 mm/sec Provides a default velocity for any dispenser gantry move (X,Y, and Z) not otherwise defined. This does not normally need changing; slow moves can cause time-outs and fast moves can cause gantry movement to be unpredictable.
X Probe Offset Y Probe Offset	X Probe Offset default = 4 mm Y Probe Offset default = -4 mm The X and Y distances to offset an etch head from the center of the touch pad to calibrate the drill position. These values should be chosen so the probe touches the calibration station itself, entirely missing the touch pad. The default values are normally sufficient; they seldom, if ever, need changing.
Low Z Limit	default = Off If a board is missing, a surface sense may move the gantry Z axis low enough to damage fixtures. If an appropriate Z coordinate is taught when teaching the Base Location for the probe, this coordinate can be used as a lower limit for Z axis movement. Set this parameter as On only after teaching such a coordinate.
Etch Clearance	default = 10.0 mm Specifies the distance to lift the etch head above the board to prevent dragging. Smaller values speed the use of the etch head but may cause unwanted contact with the board.
Touch Offset	default = 0.0 mm If TouchOffset has a positive value, motion of the Z axis during touch-off is fast until the probe is this distance above touch-pad elevation. If it is 0.0, motion during touch-off is slow starting at the safety location.
Work Area Vac Delay	default = -1 ms The work area vacuum delay determines how hold-down vacuum is handled on a machine with no conveyor. It has a value of -1 to suppress use of work area vacuum; otherwise, it is a delay introduced between operating the crowders and turning the vacuum on.
Test Temp Ready	default = Off If this parameter is On, temperature ready signals are tested before every board and the process is suspended until all temperatures are within range.
Always Load Mixer	default = On If Always Load Mixer is On, the mixer valve is always reloaded whenever it is turned Off. If it is Off, the valve is reloaded only when purging/filling and at the end of a board.
Time Interval	Time interval to repeat dot size inspection (sec).
Max Chip Index Drill Spacing	Max Chip Index default = 1 Drill Spacing default = 5 mm Applies to dispensing on a chip or drilling holes in a chip on the calibration station. Max Chip Index is the number of dots to dispense or holes to drill. Drill Spacing is the distance between dots or holes.

**Table 57: Option Settings window (Continued)**

Element	Description
Paper Advances	default = 1 Paper Advances is the number of steps the calibration station test paper is advanced each time an advance is made. The value is normally 1, but if the dispensed material spreads on the paper, several advances may be required to clear the paper area for the next dispense.
<b>CALIBRATION</b>	
Purge Interval when Idle	default = 0 ms Limit of tool/valve idle time before the operator is warned of needed material purge. If this parameter is non-zero, the value is the time between purges when the dispenser is idle.
Post-Purge Delay	default = 0 ms This parameter allows a delay after every purge to prevent dripping. (It is temporarily in Options; it will be moved later to the Materials file.)
Type of Needle Cleaner Cleaning Velocity Cleaning Increment Cleaning Count	Type of Needle Cleaner default = 0 Cleaning Velocity default = 0.0 mm/sec Cleaning Increment default = 0.0 mm Cleaning Count default = 0  <i>Cleaning Velocity</i> provides the velocity for movement through any automatic needle cleaner. This value is set to 0.0 if the machine has no automatic cleaner.  <i>Type of Needle Cleaner</i> is set to one of the following: * 0 if there is no needle cleaner present, or * 1-5 equal to the number of points needed if the machine has a needle cleaner requiring no operator intervention. * 6 to suppress cleaning altogether.  <b>Standard Needle Cleaner</b> Needle clean points 1-5 are usable for an automatic needle cleaner if the machine is so equipped. If Type of Needle Cleaner equals 1, the first needle clean point alone is used with a 2 inch move in the X direction; if 2 or greater, the required number of needle clean points are used to define a path through the needle cleaner.  ~ continued ~

**Table 57: Option Settings window (Continued)**

Element	Description
Type of Needle Cleaner Cleaning Velocity Cleaning Increment Cleaning Count	<p>~ continued ~</p> <p><b>Multiple Standard Needle Cleaners</b> If the machine is equipped with multiple standard needle cleaners, the value of Type of Needle Cleaner is set to 21 or 22 where the value 21 indicates a single point used with a 2 inch move in the X direction and a value of 22 indicates the use of two points. In these configurations, special location points 1 and 2 define the needle cleaner used for Head 1, points 3 and 4 the cleaner used for Head 2, and points 5 and 6 the cleaner used for Head 3. Setting Type of Needle Cleaner to 6 will suppress cleaning.</p> <p><b>Scale- Integrated or Clamp Cleaner</b> If the machine is equipped with a scale-integrated or clamp cleaner, values of Cleaning Increment must be set to the increment between successive dispenses and Cleaning Count to the maximum increments before operator intervention. In this case, needle clean special location point 4 is the first dispense point of the integrated cleaner and needle clean point 5 is the withdrawal point above the last dispense point of the integrated cleaner. Type of Needle Cleaner is set to one of the following:</p> <ul style="list-style-type: none"> <li>* 6 to suppress cleaning altogether.</li> <li>* 11 if a scale-mounted type of cleaner is present. Cleaning Increment and Cleaning Count must be set.</li> <li>* 17 if a clamp type of cleaner is present. Cleaning Increment and Cleaning Count must be set.</li> <li>* 21-22 if multiple cleaners are present.</li> </ul>
Scale Pre-Settle Scale Post-Settle Scale Prime Reset Scale when Calibrating	<p>Scale Pre-Settle default = 0 sec Scale Post-Settle default = 0 sec Scale Prime default = Off Reset Scale when Calibrating default = Off</p> <p>Scale Pre-Settle is the amount of time to allow after moving to the scale before dispensing.</p> <p>Scale Post-Settle is the amount of time to allow after dispensing on the scale before attempting to read the scale.</p> <p>Scale Prime is On to dispense material to prime the valve before weighing.</p> <p>Reset Scale when Calibrating is On to use no adjustments when weighing; if Off, each weighing starts with the defined values rather than the adjusted values from prior weighings.</p>
Cup Location Count	Number of divisions around the circumference of the purge cup.
Cup Radius	Radius of the purge cup.
<b>OPERATION</b>	
Job Accounting	<p>default = Off</p> <p>Jog Accounting is set to On to record details about each job run. Information includes start/end times, operator, valve/tools, materials, program name, etc. If this is set to Off, no information is recorded.</p> <p>Note that this data must eventually be purged to prevent too much accumulation or filling the computer hard drive.</p>
Log Retention	<p>default = 0</p> <p>Number of days logging information is to be retained. The default value is 0, for which logging data is retained indefinitely.</p>

**Table 57: Option Settings window (Continued)**

Element	Description
Time Between Backup Prompts	Time Between Backup Prompts default = 0 Time Between Backup Reminders default = 0
Time Between Backup Reminder	Time Between Backup Prompts is the number of days between scheduled backups. The default value of 0 equates to a setting of Off. Time Between Backup Reminders is the number of days between the display of reminder windows when a backup is overdue. The default value of 0 equates to a setting of Off.
Mapping On	default = Off Mapping On is Off to boot the system in normal operating mode. Set Mapping On to On and reboot to use DScal to map a glass plate (the system must be shutdown and restarted for Mapping On to take effect). A message at startup will state <i>Modified Servo call for Mapping</i> . After mapping is complete, set Mapping On back to Off and reboot the system for normal operation.
White Dot	default = Off This applies only to mapping with DScal, not to normal operations. Set White Dot to Off to map with DScal if the dot on the glass plate is black on a white background; set White Dot to On if the dot is white on a black background.
X Dots Y Dots	X Dots default = 35 Y Dots default = 35 There are several sizes of glass plates used for mapping with DScal. On each plate, the physical size of the glass is 1 inch larger in length and height than the area of dots since the dots start 1/2 inch in from the edge on all sides. The software needs to know the number of dots to be scanned, not where the edge of the glass is located. Therefore, count the number of dots: * For an 18" x 18" glass plate, X Dots=35, Y Dots=35 * For an 21" x 21" glass plate, X Dots=41, Y Dots=41 * For an 27" x 27" glass plate, X Dots=53, Y Dots=53
Map Area	default = 15000 Number of pixels in the area of the dot on the glass plate. 15000 is the default value for a standard lens. If a 2x or greater programmable lens is used, this value must be increased.
Stale Calibration	default = 480 minutes Provides an expiration time for head calibration. Even if calibration is suppressed, it will be performed if the last calibration is not within this time limit. The default (480 minutes = 8 hours) forces recalibration for a new shift.
Calibration Window	default = 5 mm Provides the size of a window of acceptance (mm) when calibrating a dispense or etch valve/tool. If the valve/tool must be moved outside this window to find the dot or hole, the operator is prompted to confirm the extent of movement. Other than causing an extra operator prompt, this has no effect on operation.
Bull's Eye	default = 0 mm Determines the size of the flashing Bull's Eye figure that displays in the center of the Jog and Pattern Trainer windows. A zero value in this field turns off the Bull's Eye function. A non-zero value in this field defines the diameter of the flashing figure. After the first calibration at the dot on the calibration station, the flashing figure will display in the specified size in either the Jog window or the Pattern Trainer window.

**Table 57: Option Settings window (Continued)**

Element	Description
Bull's Eye Shape	default = 1, 2, or 3 Determines which figure (a circle, cross, or rectangle) will represent the Bull's Eye. A zero value in this field turns off the Bull's Eye display. The following values determine which figure will display: 1 = circle 2 = cross 3 = rectangle

**LOG CLASSES**

Log Classes A-Z	default = 0 Log Classes is a set of selections for logging messages. Every message has a class (A-Z) associated with it. A message is logged and saved only if its class is selected in Log Classes. Note that a blank class is never logged.
A	Air or safety problem.
C	Calibration errors (e.g., cannot find pattern).
D	Debug messages (should never appear).
E	Operator errors (e.g., bad password).
H	Hardware failure (e.g., no serial communication).
I	Information to operator (e.g., homing).
M	Maintenance (e.g., refresh material).
N	New names.
O	Operator instructions (e.g., clean a needle).
P	Program errors (e.g., missing shape definition).
R	Results (e.g., material weight).
S	System errors (e.g., missing files).
U	User messages (user defined).
X	Where multiple selects or multiple deletes are allowed.
Z	Post-press device.
B, F, G, J-L, Q, T, V, W, Y	Unassigned. These log classes can be used to flag messages for which the user has manually changed the class in the resource file.

**CAL DOT SIZES**

Cal Dot Sizes	These fields contain the true (mm) sizes of the three calibration dots: A, B, and C used during <a href="#">Dot Inspection</a> (pg 3.106).
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**CONVEYOR OPTIONS**

Wait for Board Wait for Release	Wait for Board default = 10 seconds Wait for Release default = 10 seconds  These may be set to very high values on a continuous line to wait indefinitely for a board transfer without an operator present.  Wait for Board is the time the machine will wait for a board from upstream before requesting operator intervention.  Wait for Release is the time the machine will wait to release a board to downstream before requesting operator intervention.
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**Table 57: Option Settings window (Continued)**

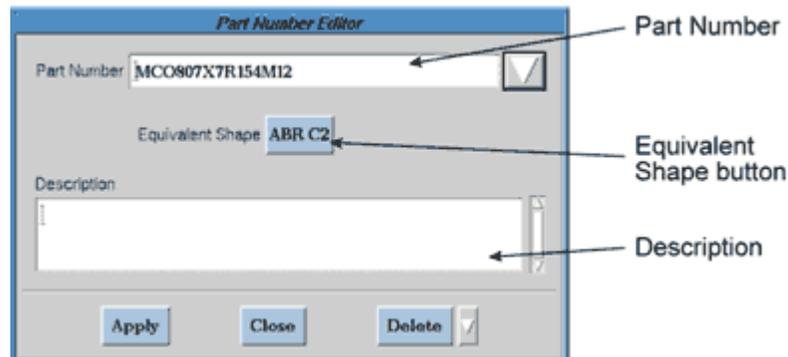
Element	Description
Enter Dwell Exit Dwell	<p>Enter Dwell default = 0 ms Exit Dwell default = 0 ms</p> <p>Some machines have heaters at the entry and exit stations. To heat the product properly, a dwell is required at these stations. Set Enter Dwell and Exit Dwell to a default time needed on such a machine. Note: These parameters are available to the program.</p>
Board Transit Slow Transit	<p>Board Transit default = 100.0 ms/in Slow Transit default = 100.0 ms/in</p> <p>If these values are too low, the boards may not move to the stop pins before the conveyor stops. If these values are too high, premature time outs may occur, in some cases trapping a board in transit with a stop pin. To calculate these values, refer to the <i>Calibration Conveyor Speeds</i> portion of the <i>Periodic Operations - CALIBRATION</i> section in the <i>Dispenser Service Guide</i>.</p> <p>Board Transit is the time for a board to move one inch when the conveyor is running at high speed; i.e., it is the transit timing for a board.</p> <p>Slow Transit is the equivalent when a two-speed conveyor is running at low speed.</p>
Slow Sensors	<p>default = Off</p> <p>Slow Sensors is normally set to Off unless the conveyor has adjustable intermediate-position sensors used to slow the conveyor to prevent movement of mounted parts when the board is stopped at a stop pin. The value of this parameter is ignored if a conveyor and/or sensors are not configured.</p>
Auto Width	<p>default = On</p> <p>Auto Width determines whether to use the automatic width adjust feature on a conveyORIZED machine. It is normally On, but may be set to Off if there is no automatic width adjust on the machine or if the width adjust is not operational.</p>
Max Conveyor Adj	<p>default = 30000 ms</p> <p>The maximum time required to adjust the conveyor width from minimum to maximum size. Used to computer time-out and hang-ups when adjusting the conveyor width automatically.</p>
Conveyor Clearance	<p>default = 1.0 mm</p> <p>The clearance allowed for the board motion when adjusting conveyor width. For example, if this value is 1 mm and the board is 150 mm wide, the conveyor is adjusted to 151 mm.</p>
Conveyor Calibrate	<p>default = 38.1 mm</p> <p>The conveyor width at calibration, hence the minimum width allowed for conveyor width adjustment. If board width is less than this value (normally 0 when board width is not specified), manual adjustment is required. The default value is 1.5 inches, the width of the standard gauge block.</p>
Vacuum Release Delay	<p>default = 50 ms</p> <p>The time delay between turning lifter vacuum off and dropping the lifter. Increase this delay if the board is pulled down when the lifter drops.</p>

## Part Number Editor

Use the Part Number Editor to define individual cross reference records or change the shape associated with an existing cross reference record. The part number is a cross reference connecting a shape with a known part number.

Clicking the button next to the Part Number field opens the Select a Part Number window from which you can choose an existing part number. Alternately, if you define a new part number and click the APPLY button, the new part number will be added to the list of part numbers.

**TIP:** To access Part Number Editor, open the Program Editor and click on Libraries > Part Numbers.



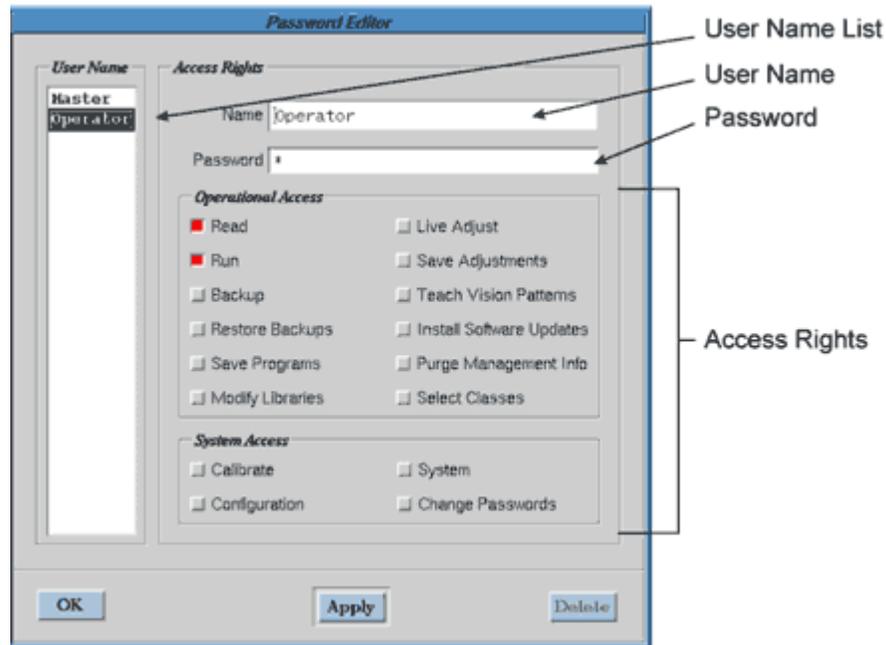
**Table 58:** Part Number Editor window

Element	Description
Part Number	A part number may be up to 36 characters long.
Equivalent Shapes	Opens the Select a Shape window from which you can choose an existing shape.
Description	Optional comment field of up to 250 characters. Content in this field usually comes from pick-and-place data. Comments are only viewable in the Part Number Editor window but print in full for printouts.

## Password Editor

Use the Password Editor to add or delete a user name, change the password for a user name, or change the access rights assigned to a user name.

**TIP:** To access Password Editor, open the Program Editor and click on Libraries > Passwords.



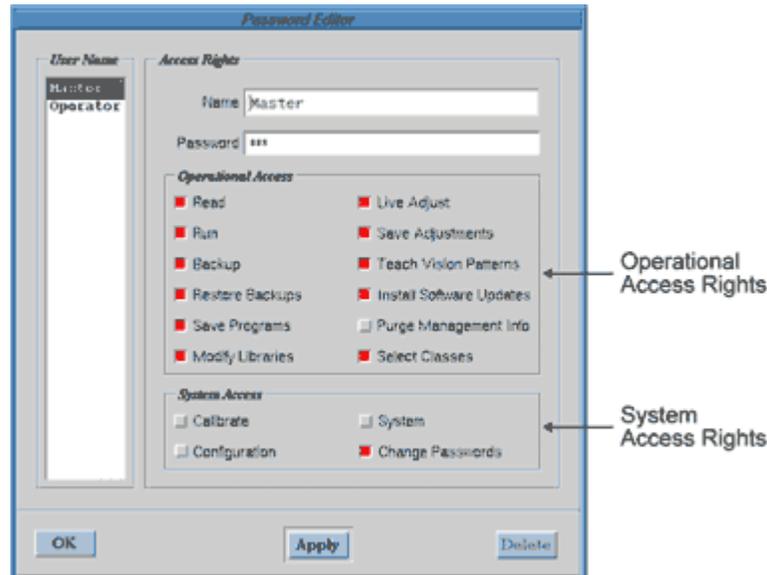
**Table 59:** Password Editor window

Element	Description
User Name List	All user names currently set up on the system are listed here. Highlighting a user name in the list displays the access rights currently assigned to that user name.
User Name	A user name may consist of 24 alphanumeric characters and spaces are allowed. Any user name can have any combination of access rights assigned to it. The user names of Master and Operator cannot be deleted or renamed.
Password	<p>Passwords are case sensitive and may consist of up to 12 alphanumeric characters. Spaces are allowed.</p> <p>A password is not revealed when typed; each character/space is displayed as a *. The number of passwords you create is limited only by the capabilities of the hardware. No entry in this field makes it equivalent to Operator, allowing anyone to log in.</p>
Access Rights	<p>Any combination of access rights can be assigned to any user name.</p> <p>Changing access rights requires you to enter the appropriate password with the following exceptions: when the machine defaults to Operator upon start up and when the current access rights are cleared.</p> <p>Refer to the following section, <i>Access Right Descriptions</i>, for further details.</p>

## Access Right Descriptions

All available access rights are displayed on the Password Editor window. Any combination of access rights can be assigned to any user name.

Access rights are grouped into two categories: operation and system. Operational access rights are typically assigned to users who perform normal machine operations. Conversely, it is suggested that system access rights be reserved for use by technical or engineering staff on an as needed basis only.



**Table 60: Password Editor window - Access Rights**

Access Right	Allows Access to:
<b>OPERATIONAL ACCESS RIGHTS</b>	
Read	Basic login access and use of Program Editor to examine programs/shapes and perhaps other tables, but does not allow table modification without additional access.
Run	Homing the machine and running (executing) any program.
Backup	Backup and Export execution without special access passwords.
Restore Backups	Restoring backups, import execution without special access passwords.
Save Programs	Editing and saving programs and shapes; optimizing programs.
Modify Libraries	Editing and saving Heads, Materials, and other libraries.
Live Adjust	Program modification/tweaking for the current run only.
Save Adjustments	Savings programs modified by tweaking during the current run.
Teach Vision Patterns	Teaching or changing vision patterns for fiducials or other purposes.
Install Software Updates	Installing software updates.
Purge Management Info	Purging current job accounting data.
Select Classes	Class filter thereby allowing expansion and restriction of the program or shape names that display during program selection and in the Program Editor.

**Table 60: Password Editor window - Access Rights (Continued)**

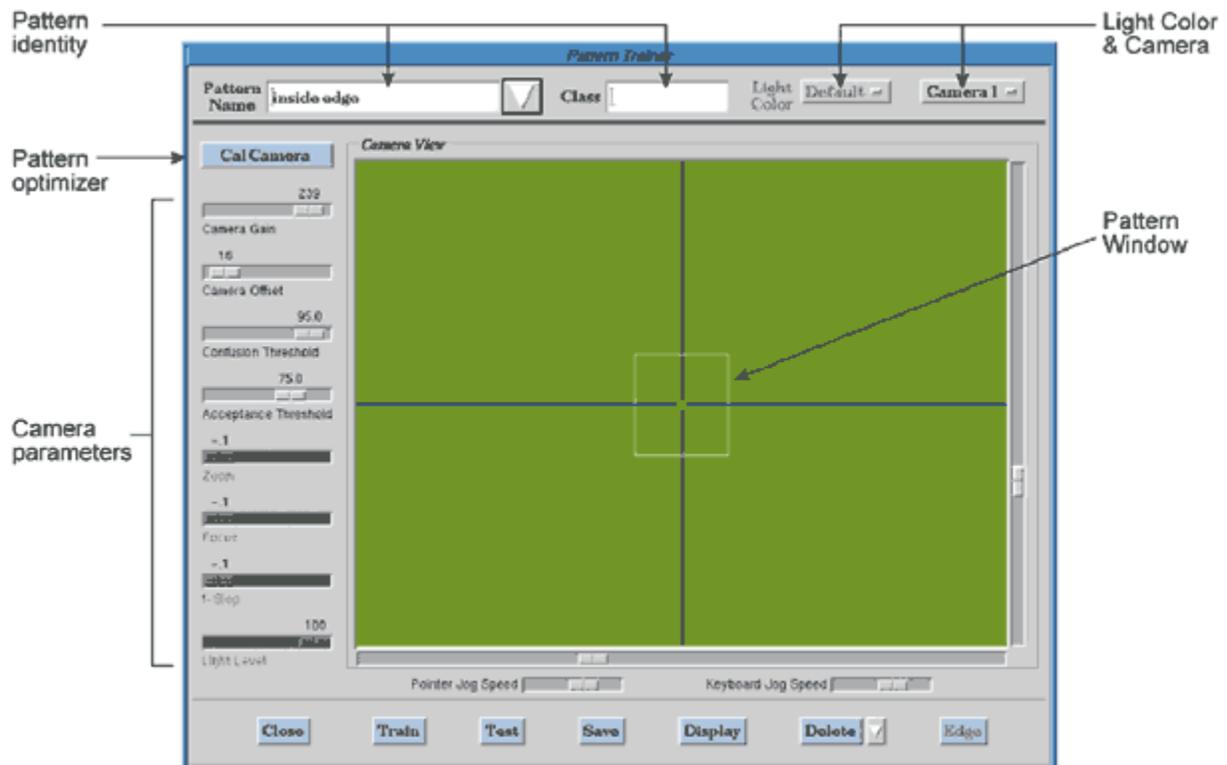
Access Right	Allows Access to:
<b>SYSTEM ACCESS RIGHTS</b>	
Calibrate	Calibration of various hardware features.
Configuration	Changing configuration tables, such as the IO and Options tables. Custom Controls modification, and other optimal configuration.
System	Access to system features from the system pull-down menu.
Change Passwords	Altering any and all passwords for anyone. This access right allows full access to the system.

## Pattern Trainer

Patterns are used to define fiducial shapes for use by the Automatic Vision Alignment System during pattern recognition. Use the Pattern Trainer to create a pattern or change the characteristics of an existing pattern.

**NOTE:** The patterns library is only accessible when the dispenser is configured for the Automatic Vision Alignment System option (and the correct password has been entered).

**TIP:** To access Pattern Trainer, open the Program Editor and click on Libraries > Patterns.



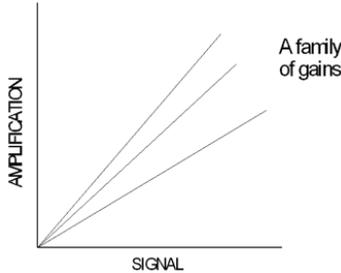
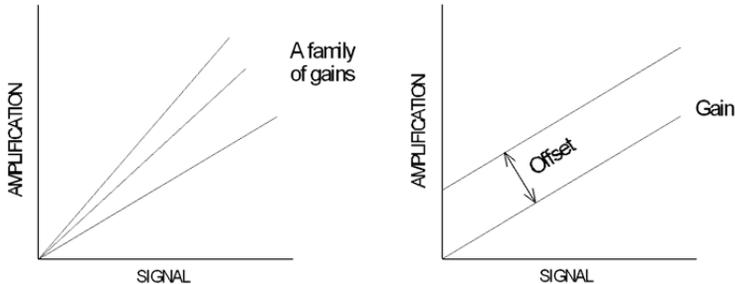
**Table 61:** Pattern Trainer window

Element	Description
Pattern Name	A pattern name may consist of up to 24 alphanumeric characters. A list of patterns automatically displays in alphabetic order.  Clicking the selector button next to the Pattern Name field opens the Select a Pattern window which displays a list of existing patterns from which you can choose. Alternatively, if you define a new pattern name and click the SAVE button, the new name will be added to the pattern list.
Class	Not yet functional. Use to select a class of vision patterns for display. Text field of up to 12 alphanumeric characters containing any text.
Light Color	Use to select a color and type of illumination to enhance pattern identification when vision is affected by surface colors or textures. The choices available from the pull down menu are dependant upon whether or not the applicable illumination hardware is installed on your machine.
Camera #	Number of the camera to be selected.

**Table 61: Pattern Trainer window (Continued)**

Element	Description
<p>Pattern Window</p>	<p>The Camera View panel contains a Pattern Window within which the pattern is defined. Everything displayed inside the Pattern Window is considered to be the pattern being taught.</p> <p>The size and shape of the view encompassed by the Pattern Window can be enlarged or reduced by using the horizontal and vertical sliders. When the Pattern Trainer first opens, both of these threshold sliders will be set to values for the previously loaded pattern.</p> <div data-bbox="565 520 1351 892" data-label="Image"> </div> <p>Note the suggested MAXIMUM sliders positions shown in the following illustration.</p> <p><b>NOTE:</b> DO NOT exceed the maximum limit for pixel size by tweaking the sliders beyond their maximum positions; doing so will cause the vision system to abort. Tweaking can occur indirectly as the sliders work together - moving one also repositions the other one.</p> <div data-bbox="769 1129 1156 1465" data-label="Image"> </div>
<p>Bull's Eye</p>	<p>The diameter of the Bull's Eye that flashes in the center of the Pattern Trainer window can be resized by changing the value of the Bull's Eye field in the Option Settings window.</p>
<p>CAL CAMERA</p>	<p>Optimizes camera display parameters for current conditions.</p>

**Table 61: Pattern Trainer window (Continued)**

Element	Description
<p>Camera Gain</p>	<p>Value by which the video signal is amplified. Camera gain and camera offset work together to condition the video signal.</p>  <p>If, for images with low contrast, you choose to set values manually with the sliders instead of automatically with the CAL CAMERA slider, note that inappropriate values could cause amplification of signal noise and obliterate detail in the image.</p>
<p>Camera Offset</p>	<p>Value added to the video signal before amplification. Camera gain and camera offset work together to condition the video signal.</p> <p>If, for images with low contrast, you choose to set values manually with the sliders instead of automatically with the CAL CAMERA slider, note that inappropriate values could cause amplification of signal noise and obliterate detail in the image.</p> 
<p>Confusion Threshold</p>	<p>Value is dependent upon the video scene being used during pattern training. Affects search speed.</p> <p><b>REQUIREMENT:</b> This value must always be greater than or equal to Acceptance Threshold.</p> <p><b>High range</b> - tends to decrease search speed, but a high value may be necessary to ensure the correct feature is found. Use a higher value if the trained pattern will appear in multiple locations within the video scene.</p> <p><b>Low range</b> - tends to increase search speed under certain conditions. Use a lower value if the trained pattern is unique within the video scene.</p>
<p>Acceptance Threshold</p>	<p>The acceptance threshold is the shape score that a feature must equal or exceed to be considered found by the pattern window. Affects search speed.</p> <p><b>High range</b> - tends to decrease search speed at the risk of not finding the pattern being searched for because it is different than the trained pattern (due to image degradation).</p> <p><b>Low range</b> - tends to decrease search speed and you risk finding a similar scene rather than the one you really wanted.</p>
<p>Zoom</p>	<p>Camera zoom value for the automatic camera.</p>
<p>Focus</p>	<p>Camera focus value for the automatic camera.</p>

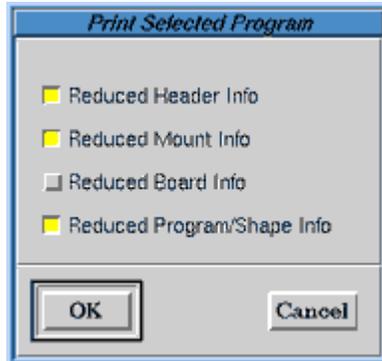
**Table 61: Pattern Trainer window (Continued)**

Element	Description
f-Stop	Not yet functional. Camera f-stop value for automatic camera.
Light Level	Controls the intensity of the light illuminating the camera field. A specific light level can be defined here to enhance pattern identification. This function is only available for machines equipped with the Illuminator Intensity Control option.
CLOSE	Closes the Pattern Trainer window without saving any changes.
TRAIN	Teaches pattern using the camera's current view and criteria.
TEST	Initiates a search for the pattern currently selected in the Pattern Name field.
SAVE	Saves the currently selected pattern and all other search criteria.
DISPLAY/LIVE	DISPLAY - displays the currently defined pattern in the video area. LIVE - switches the video area from the generated <i>displayed view</i> back to the live camera view.
DELETE	Deletes the currently selected pattern and removes it from the patterns list.
EDGE	Not yet functional. Cognex codes.

## Print Selected Program

The print options in Print Selected Program allow you to print the currently selected program, optionally reducing detail with the use of one or more filters.

**TIP:** To access Print Selected Program, open the Program Editor and click on File > Print.



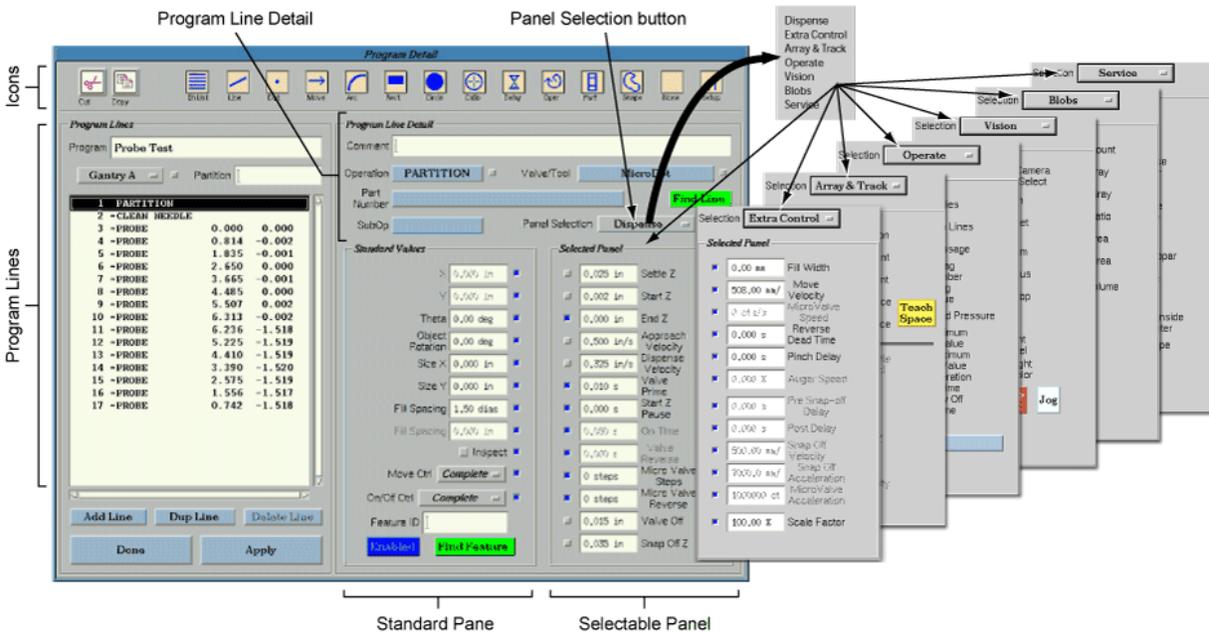
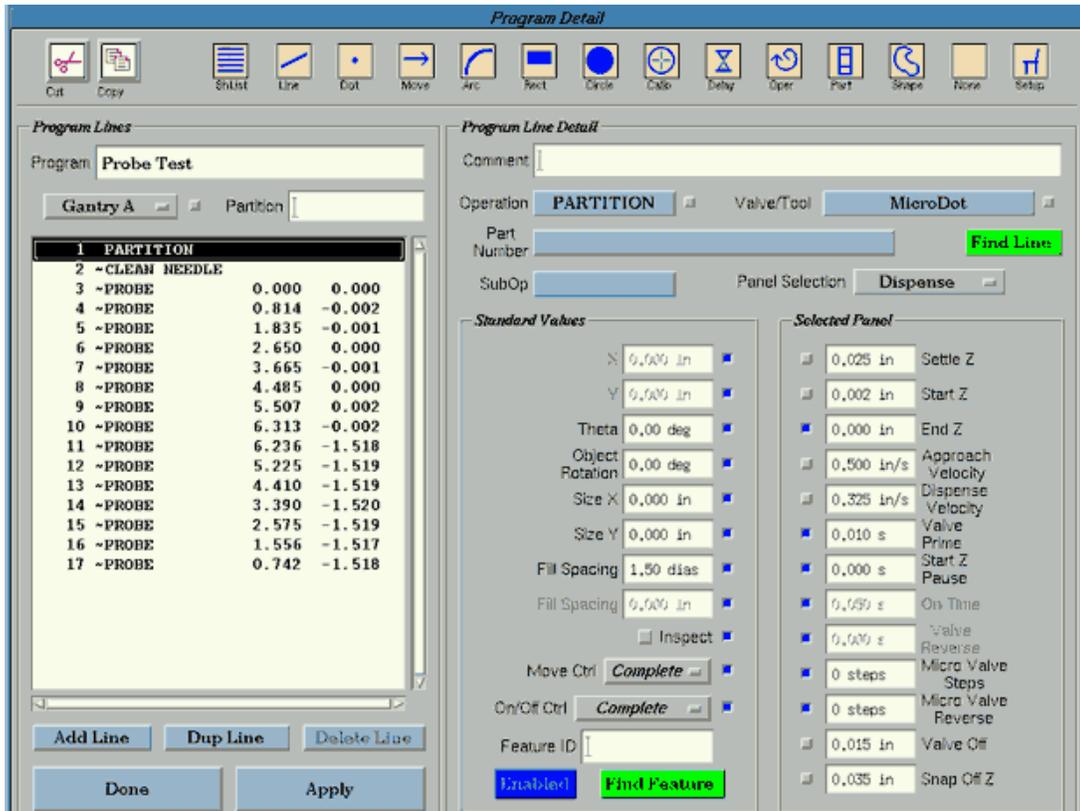
**Table 62:** Print Selected Program window

Element	Description
Reduced Header Info	Prints program with minimally identifiable header detail.
Reduced Mount Info	Prints program with minimally identifiable mount detail.
Reduced Board Info	Prints program with minimally identifiable subboard detail.
Reduced Program/Shape Info	Prints program with minimally identifiable program/shape detail.

## Program Detail

Program Detail enables the user to establish or modify operation parameters of any line for the currently selected program.

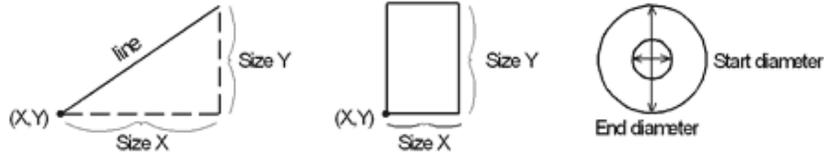
**TIP:** To access Program Detail, open the Program Editor and click on EDIT DETAIL LINES.



**Table 63: Program Detail window**

Element	Description
<b>ICONS</b>	
Cut	Cut one program line.
Copy	Copy one program line.
Icons	Use these icons to insert a primitive operation below the currently highlighted program line. The set of icons represent primitive operations: Line, Dot, Move, Arc, Rectangle, Circle, Calibrate, Delay, Operate, Partition, Shape, None, and Setup. Click an icon to insert that primitive operation below the currently highlighted program line. The ShList icon brings up a list of all currently available (non-class filtered) shapes.
<b>PROGRAM LINE</b>	
Program	Name of the currently selected program.
Gantry	Gantry identification code.
Partition	Partition/Shape name, up to 12 characters long. This usually appears only on a Partition or Shape record and is allowed to default on subsequent records. Embedded shapes use this field to define the shape name.
program lines	The partition lines and shape lines that make up the program.
<b>PROGRAM LINE DETAIL</b>	
Comment	Any text, up to 72 characters long, describing this line for documentation purposes. Typically used when converting pick-and-place data to dispenser input format.
Operation	Name of the operation to perform for the current program line. May be up to 12 characters long, and may be the name of one of the primitive operations (DOT, LINE, RECTANGLE, etc.) or it may be the name of a shape. (The shape must exist before running a program using the shape.)
Valve/Tool n	Dictates which head will be used during the operation for the current program line. May be up to 18 characters long. This usually appears only for a Partition record. A head must be selected for each program line or else it will default to NONE. (This name should match the name of the valve/tool in the Mounts library; if it does not, the program will not run.)
Part Number	Optional part number up to 36 characters long. This field is usually filled in when converting pick-&-place data to dispenser input format. Import uses this field to determine the operation type from the cross reference library.
FIND LINE	Allows a specific program line to be found within the current program by jogging to the physical location associated with the program line.
Sub Op	List of sub operations from which to select. The choices displayed are dependent upon the operation used in the Operation field.
Panel Selection	A pull down menu of choices, each of which will display a different set of fields in the right-hand side of the window. Refer to the following definition tables for details about the choices: Dispense, Extra Control, Array & Track, Operate, Vision, Blobs, and Service.
<b>STANDARD VALUES</b>	
X Y	Location where this operation is to occur relative to the board reference point.
Theta	Rotation (radians) of the fourth axis for this head.

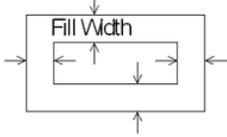
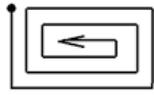
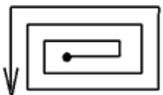
**Table 63: Program Detail window (Continued)**

Element	Description
Object Rotation	<p>Rotation of a feature about (X, Y). Rotation is counterclockwise for a positive value. This angle applies to the shape, line, rectangle, etc. defined by the Operation field.</p> <p><b>NOTE:</b> Rotation, rather than Object Rotation, should be used to rotate an array because Rotation rotates the array, not the individual items within the array.</p>
Size X Size Y	<p>X-size of a line/rectangle or the start diameter of a circle. Y-size of a line/rectangle or the start diameter of a circle.</p>  <p>The diagrams show three cases: 1. A line starting at point (X,Y) with a horizontal dimension labeled 'Size X' and a vertical dimension labeled 'Size Y'. 2. A rectangle starting at point (X,Y) with a horizontal dimension labeled 'Size X' and a vertical dimension labeled 'Size Y'. 3. A circle with a horizontal diameter labeled 'Start diameter' and a vertical diameter labeled 'End diameter'.</p>
Fill Spacing	For filled features such as circles and rectangles, this field defines spacing between successive lines of the fill in units of needle diameters. A typical value is 1.5 needle diameters.
Fill Spacing	Alternate value of Fill Spacing in millimeters rather than needle diameters.
Move Ctrl On/Off Ctrl	<p>Most operations are performed in 3 stages:</p> <p>FIRST stage - the gantry moves to the point (X, Y, Start Z + Settle Z) where the Z coordinate is the distance to the board. It then moves vertically to a Z coordinate Start Z, turning the valve on and performing additional operations while moving.</p> <p>SECOND stage - the gantry performs the function at the target point, such as filling a rectangle or dispensing a dot.</p> <p>THIRD stage - the gantry moves to a Z coordinate of Start Z + End Z + Snap Off Z at high speed and acceleration, turning the valve off and performing additional operations while moving.</p> <p>To function continuously across several operations (e.g., when drawing a pattern), these stages must be performed independently. Move Ctrl and On/Off Ctrl are integer controls allowing the moves and on/off operations to be performed separately:</p> <p>0 = Complete - perform all three stages. (this is the default).  1 = Start - perform first and second stages only.  2 = Middle - perform second and third stages only.  3 = End - perform second stage only.  4 = No Operation - for On/Off control, perform none of the stages.</p>
Feature ID	Any name up to 12 characters long associated with this program line. Typically, this is a board location (C10, U15, R25, etc.). Describes a discernible feature on the board to allow selection or rejection of program lines by Feature ID. A feature ID can be assigned to any program line. Any program line without a feature ID (blank) will always run.
ENABLED/DISABLED	Toggle button indicates whether this detail line is to be used. Any program line can be easily enabled and disabled.
FIND FEATURE	Allows a specific program line to be found within the current program by typing the name of the Feature ID associated with the program line.
<b>SELECTABLE PANEL - DISPENSE</b>	
Settle Z	Distance above Start Z (the Z location where dispensing or other operation takes place) where the gantry settles before the move to Start Z.

**Table 63: Program Detail window (Continued)**

Element	Description
Start Z	Distance above the board where initial dispensing or other operation is to take place for this feature; a negative value will drill into a drill pad.
End Z	Final dispense height distance above/below Start Z (the Z location where dispensing or other operation takes place) for a dot (pillar) or three dimensional coordinated motion. This value is non-zero to create pillars or to dispense along an angle to the plane of the board. Use a zero value if no motion is desired.
Approach Velocity	Speed at which the Z-axis moves from Settle Z (where the gantry settles before the operation) to Start Z (the Z location where dispensing or other operation takes place).
Dispense Velocity	Speed at which the gantry moves during any motion required during a constant dispense operation (e.g., Z velocity while building a pillar, or coordinated motion velocity while drawing a line).
Valve Prime	Used to start valve material flow prior to reaching the target. The time between turning the valve on and reaching Start Z (target).
Start Z Pause	This allows for the creation of a puddle; it is a position pause/delay after reaching Start Z. After this delay, the head moves at Dispense Velocity until the specified On Time has elapsed. To be effective, Start Z Pause must be less than On Time.
On Time	The main control of dispensed volume. The total time a head remains on during dispense, delay time, or any other time value required to perform an operation.
Valve Reverse	Number of encoder counts to dispense desired dot size with a Micro-Dot valve. If dispensing any shape other than dots, enter a value based on the length of time required by the program to dispense the shape. This value is ignored if the valve used is not a Micro-Dot valve.
NCM Open Time	Total time the non-contact jetting pump will remain open. This field does not display if the system is not configured for a non-contact jetting pump.
Micro Valve Steps	Number of encoder counts to dispense a dot with a Micro-Dot valve. If dispensing any shape other than dots, enter a value based on the length of time required by the program to dispense the shape.
Micro Valve Reverse	Reverses auger direction for the specified number of encoder counts. Used primarily to relieve pressure built up inside the needle and hub and can also be used to pull material back up into the needle.  This technique, commonly known as <i>suck-back</i> , is used to help prevent drip when using low viscosity materials, help control dot repeatability by controlling the amount of residual material on the tip, and it improves snap-off for some materials.
Valve Off	Distance before the end of a constant fill (line, circle, rectangle) where the dispenser turns off. Used mainly with fluid materials to control drooling. When performing a fill, a needle may dribble unwanted material at the end of the operation. To prevent this, the valve is turned off Valve Off mm before the fill ends. When this applies only to the last line or circle of the fill, make sure the length of the last line/circle allows this.
Snap Off Z	Helps avoid material tailing. Distance to move the valve/tool up during the snap-off action to prevent tailing. Height above End Z (after Start Z) to which the dispenser moves after a dispense is complete.

Table 63: Program Detail window (Continued)

Element	Description
<b>SELECTABLE PANEL - EXTRA CONTROL</b>	
Fill Width	<p>The wall dimension (the width of each side) of a hollow rectangle. The pattern is covered in increments of Fill Spacing needle diameters and motion is at vector speed Dispense Velocity, and turning the valve off Valve Off needle diameters before completion of movement for each line.</p> <p>Fill Width applies only to spiral rectangle fill. It is ignored for serpentine rectangular fills.</p> <div style="text-align: center;">  </div> <div style="display: flex; justify-content: space-around; margin-top: 20px;"> <div style="text-align: center;">  <p>Corner/In Spiral</p> </div> <div style="text-align: center;">  <p>Center/Out Spiral</p> </div> <div style="text-align: center;">  <p>Serpentine</p> </div> </div> <p>If Fill Width is 0, the entire rectangle is filled. Conversely, a hollow rectangle can be created by specifying a non-zero Fill Width; spiral lines are drawn toward the center or away from the center of the defined rectangle until pattern width reaches Fill Width.</p>
Move Velocity	Speed at which the gantry moves between two consecutive points.
Micro Valve Speed	Micro-Dot valve velocity.
Reverse Dead Time	Allows a specified delay between stopping the auger and reversing its direction. Use this action to wet to a surface with material prior to material suck-back.
NCM Close Time	Allows a specified delay between closing and opening a non-contact jetting pump. This field does not display if the system is not configured for a non-contact jetting pump.
Pinch Delay	Delay before operating a pinch tube; for additional process control. Used only when a Pinch Tube style of dispense valve is mounted on the machine. Pinch Tube valves use a rod that squeezes the body of the material feed tube shut to stop the flow of material.
Auger Speed	Speed at which to operate a variable speed auger.
Pre Snap-off Delay	Time to delay after dispense but before beginning snap-off.
Post Delay	Post operation delay.
Snap Off Velocity	Snap-off velocity.
Snap Off Acceleration	Snap-off acceleration.
Micro Valve Acceleration	Micro-Dot valve acceleration.
Mixer Velocity	Speed at which to operate the mixer valve.
Scale Factor	Scales a feature up or down by a particular percent. Applies especially to shapes; a shape can be executed as a different size than it is defined.

**Table 63: Program Detail window (Continued)**

Element	Description
<b>SELECTABLE PANEL - ARRAY &amp; TRACK</b>	
Rotation	Angle through which the array is to be rotated, independent of Object Rotation. The entire array is rotated as a unit about the point (X, Y).  <b>NOTE:</b> Object Rotation, rather than Rotation, should be used to rotate a single item because Object Rotation rotates individual elements of the array, not the array itself.
X Count Y Count	default = 1 for a non-array Number of array elements in the X and Y directions before rotation of the array.
X Space Y Space	default = 0 Specifies the spacing between array elements in the X and Y directions before rotation of the array. To jog to desired space in the XY direction, you can click TEACH SPACE.
TEACH SPACE	Calculates offsets for X Space and Y Space. Appears only when valid coordinates are used in the X and Y fields of the Standard Values panel.
Needle Track	default = N Indicates whether to backtrack over last fill line.
Mixer Valve	Velocity of mixer valve.
X Y	Location where backtracking is to occur relative to the board reference point.
Start Z	Distance above the board where backtracking is to take place; a negative value indicates drilling into a drill pad.
End Z	Distance above Start Z (the Z location where backtracking takes place) for the operation to end. This value is non-zero to create pillars or to dispense along an angle to the plane of the board.
Velocity	Speed at which the gantry moves from Start Z to End Z.
<b>SELECTABLE PANEL - OPERATE</b>	
Max Repeat	Number of times the system attempts to pick up the component at the current Z location.
Retries	Number of times to retry a failed operation.
Skip Lines	Number of program lines to skip forward (+) or backward (-).
Message	Message number (-1 and greater) associated with this operation.
Flag Counter Number Flag/Counter Value	Bit number (0-31) and value (0-1) to change or test bit flags. Used to test the status of various conditions within a program/shape and, based on the test results, direct the control software to either continue or skip program detail lines.
Head Pressure	Operating pressure for this head.
Minimum Z Value Maximum Z Value	Minimum and maximum Z coordinate values allowed (mm).
Operation Time	Operating time for this operation.
Blow Off Time	Blow-off time to release a part.
Pattern	Name of a pattern, up to 24 characters long. This field is used when an OPERATE line requires a vision pattern.

**Table 63: Program Detail window (Continued)**

Element	Description
<b>SELECTABLE PANEL - VISION</b>	
Camera Select	Camera number to be used in this operation.
Gain	Camera gain (0-255). Use -1 to disable.
Offset	Camera offset (0-255). Use -1 to disable.
Zoom	Value (0.0 to 1.0) of focal length for an automatic focus camera for changes within the program.
Focus	Value (0.0 to 1.0) for focusing an automatic focus camera for changes within the program.
f-stop	Value (0.0 to 1.0) for f-stop on an automatic focus camera for changes within the program.
Light on Dark	A <b>Y</b> indicates use of a light dot on a dark background for dot inspection on the board. An <b>N</b> indicates use of a dark dot on a light background.
Light Level	Level of lighting for changes within the program.
Light Color	Light color for changes within the program.
<b>SELECTABLE PANEL - BLOBS</b>	
Blob Count	Number of blobs to be found by the vision system (0-50).
Low Gray	Gray level pixel values (0-255) for low limit.
High Gray	Gray level pixel values (0-255) for high limit.
Blob Ratio	Minimum to maximum length ratio for blobs.
Min Area	Minimum area (pixels) of blobs for blob search.
Max Area	Maximum area (pixels) of blobs for blob search.
Window Height Window Width	Used to determine the size of a search window for dot inspection. Establishing a narrow area only slightly larger than the dot to be found is suggested. Refer to <a href="#">Dot Inspection</a> (pg 3.106).
Dot Volume	Dispensed dot volume.
Target Size	Desired blob (dot) size. Refer to <a href="#">Dot Inspection</a> (pg 3.106).
Target Range	Desired tolerance value. Refer to <a href="#">Dot Inspection</a> (pg 3.106).
<b>SELECTABLE PANEL - SERVICE</b>	
Program Code	Internal use. Code to identify the program. The value is inherited from the @PRORAM or @SHAPE record.
Program Flag	Internal use. Indicator used internally to select items.
Sequence Number	Internal use. Code to sequence the detail records. Records are re-sequenced automatically as they are encountered.
PS Type	Internal use.
Alternate PS Type	Internal use.
MoPar Index	Internal use.
Snap Mopar	Internal use.
ST Code	Internal use.
Ident	Internal use.
Needle Inside Diameter	Internal use.

**Table 63: Program Detail window (Continued)**

Element	Description
Head Type	Internal use.

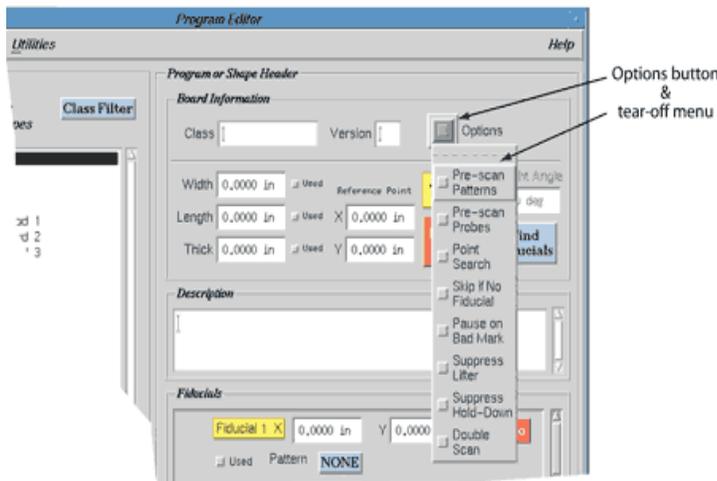
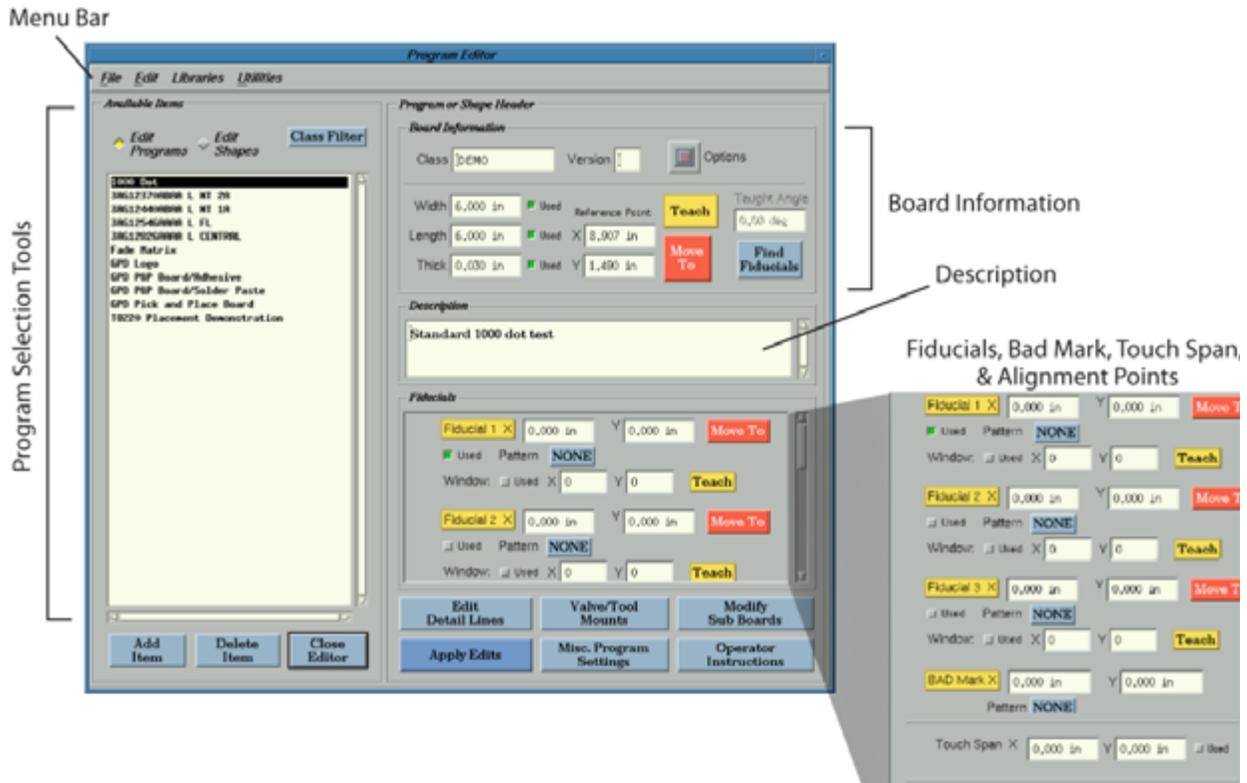
**SELECTABLE PANEL - FUNCTIONS**

Only functional when the dispenser is configured for Wedge configuration. Refer to custom Wedge project documentation.

## Program Editor

Program Editor provides access to the creation, modification, and selection of programs in addition to the libraries and tools that directly affect program characteristics.

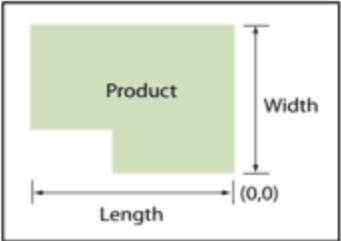
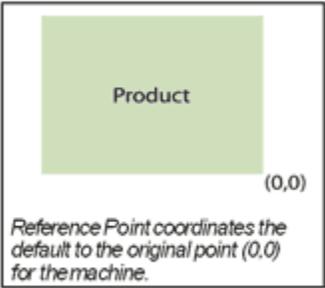
**TIP:** To access Program Editor, click on the Program Editor icon on the main control window.



**Table 64: Program Editor window**

Element	Description
<b>MENU BAR</b>	
File	Drop down menu of the following choices.
Print	Prints the currently selected program with the option of reducing details by category if a printer is attached.
Exit	Closes the Program Editor and deletes the icon from the Main Control Panel.
Edit	Drop down menu of the following choices.
Rename Program	Enables a new name to be assigned to the currently selected program or shape.
Cut	Not currently functional.
Copy	Copies the currently selected program or shape.
Paste	Not currently functional.
Convert	Allows you to convert a shape to a program, a program to a shape, or a program to a subboard.
Clear	Not currently functional.
Refresh Program List	Use when the displayed list may not be accurate.
Libraries	Drop down menu of the following choices that pertain to the machine configuration (only the choices applicable to your machine will display).
Patterns	Creates or modifies shapes to be used as patterns during fiducial or bad mark pattern recognition by the (optional) automatic vision system to locate a product and adjust for its orientation.
Materials	Add, modify, or delete a material from the list of materials currently available.
Needle	Define a needle or change the characteristics of an existing needle.
Part Numbers	Define individual cross reference records or change the shape associated with an existing cross reference record.
Head	Add, modify, or delete a mount position from the list of mount position types currently available; e.g., auger, liquid dispense, trace cut, etc.
Fixed Locations	Define and edit fixed locations.
Password	Add or delete a user name, change access rights for a user name, or change the password for a user name.
Material Defaults	Define defaults for materials according to value/tool mount position.
SubTypes	Define and edit subtypes.
Utilities	Drop down menu of the following choice:
Optimize	Reorganizes the current program to minimize execution time with either point-to-point, fixed divisions (number of divisions), or a floating square (size of square).
<b>PROGRAM SELECTION TOOLS</b>	
Edit Programs Edit Shapes	Toggle controls which determine the type of programs (programs or shapes) displayed in the Available Items panel.
Class Filter	Use to select a class of program or shape for display. Expands or restricts the combination of programs or shapes displayed in the Available Items panel.

**Table 64: Program Editor window (Continued)**

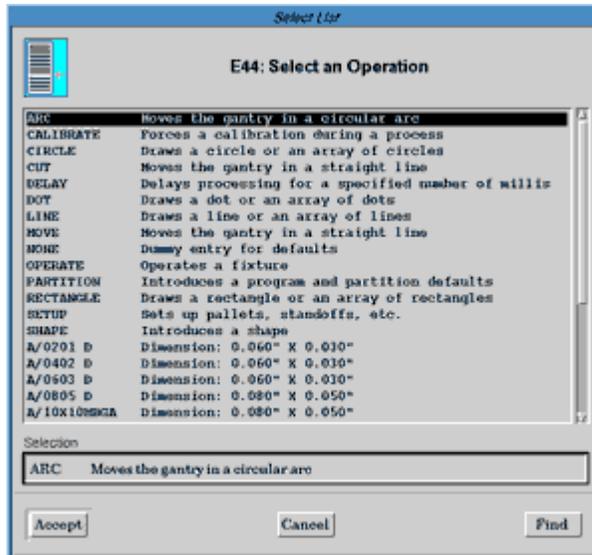
Element	Description
list of programs	Names of the currently available program or shape names as determined by the program selection tools (Edit Programs, Edit Shapes, and Class Filter).
<b>BOARD INFORMATION</b>	
Class	The Class Filter assigned to the current program is entered and displayed here.
Version	Applies to programs only. If a shape name cannot be found, the system looks for the shape name with a version prefix.
Pre-scan Patterns	Requires a complete vision scan be performed before the program runs.
Pre-scan Probes	Requires a complete probe be performed before the program runs.
Point Search	Limits the search area for the vision system.
Skip if No Fiducial	If a fiducial is missing, rather than stopping for operator intervention, the program will skip the board, subboard, or shape.
Pause on Bad Mark	Program will pause for operator intervention if a bad mark is detected.
Suppress Lifter	Suppresses lifter plate operations.
Suppress Hold-Down	Hold-down vacuum on the board will be suppressed.
Double Scan	Performs a second fiducial search. (This option slows the fiducial scanning process.) After the standard process of looking for a fiducial and moving the gantry based on search results is performed, a second fiducial search is performed and the gantry is again moved if a position correction is deemed necessary by the second search.
Width Length Thick	 <p>Reference data required by SMEMA and used with the automatic adjust conveyor:  Width - may be used to set the width of an automatic conveyor.  Length - used to improve conveyor operations.  Thick - may be used to adjust camera calibration.</p>
Reference Point X Y	 <p>The system location (X,Y) of the board data origin (0,0) measured from the lower right corner of the board. The default coordinates (0,0) can usually be used unless converting data.</p> <p>All data points on the product are measured from the reference point. All values and defaults, except those defined as absolute, are referenced from this point. If reference point values are zero, all X coordinates will be negative.</p> <p>As necessary, i.e., when converting data, determine reference point coordinates from product drawings or by measuring the X and Y distances from the lower right hand corner of the product to the reference point.</p>
TEACH	Teaches the X and Y coordinates for the reference point.
MOVE TO	Moves the gantry IMMEDIATELY to the coordinates designated in the X and Y fields.
Taught Angle	Angle at which the shape was taught.

**Table 64: Program Editor window (Continued)**

<b>Element</b>	<b>Description</b>
FIND FIDUCIALS	Makes program adjustments for board orientation while moving the gantry to each fiducial within the current program.
<b>DESCRIPTION</b>	
Description	Optional text field of up to 250 characters long containing any descriptive information.
<b>FIDUCIALS &amp; BAD MARKS</b>	
Fiducial n X, Y	The use of these product orientation points is optional but recommended for accuracy.
Bad Mark X, Y	Bad mark coordinates relative to the reference point.
MOVE TO	Moves the gantry IMMEDIATELY to the coordinates designated in the X and Y fields.
Used	Indicates whether or not the associated pattern is used.
Pattern	Name of pattern up to 24 characters long for use with automatic vision. This name provides reference to the shape of the fiducial or bad mark.
Process if mark present	Determines how a bad mark is detected and used. 0 = no bad mark indicators; process ignores mark if present. 1 = process if mark is present. 2 = process if mark is absent.
Window	Not currently functional. Primarily used to prevent false positives by masking objects similar to the pattern for which you are searching.
Used	Not currently functional. Indicates whether or not the associated window is used.
X, Y	Not currently functional. X, Y size of the search window.
TEACH	Not currently functional. Teaches the window area (X, Y).
Touch Span X, Y	X and Y spacing for automatic touch probe operation.
Alignment Pt X, Y	Alignment point that aligns arrays with board edges.
<b>COMMAND BUTTONS</b>	
ADD ITEM	Add a new program or shape.
DELETE ITEM	Delete the program or shape currently selected.
CLOSE EDITOR	Close the Program Editor to an icon.
EDIT DETAIL LINES	Modify, save, or delete program detail line(s).
VALVE/TOOL MOUNTS	Define the position and type of valve/tool, material, and needle gauge for each mount position to be used in the current program (not applicable to shapes).
MODIFY SUB BOARDS	Define the location and orientation of each subboard in a program (not applicable to shapes).
APPLY EDITS	Implements any changes currently displayed in the Program Editor window and any program line modifications made in the Program Detail window.
MISC PROGRAM SETTINGS	Define program settings for various purposes, e.g., vision calibration, temperature, pressure, or rotation relative to bad marks.
OPERATOR INSTRUCTIONS	Add, modify, or delete instructions associated with the currently selected program (not applicable to shapes). These instructions display in the Mounts Table window.

## Select List

Select List is a basic window type that presents a list of items from which you can make a selection. Select List is used by various features in the selection of a specific item. The appearance and control buttons used on each select list window may vary somewhat but the basic window function is the same.



**Table 65: Select List window**

Element	Description
scrolling list	An alphabetic listing of all available items.
Selection	Used to find a specified item. Type an item name in this field, press FIND, and if found, the name will display in this field and the associated item will be selected in the scrolling list.
ACCEPT	Saves changes and exits this window.
CANCEL	Exits this window without saving changes.
FIND	Finds and selects the scrolling list item for the name typed into the Selection field.

## Set Pressure/Temperature

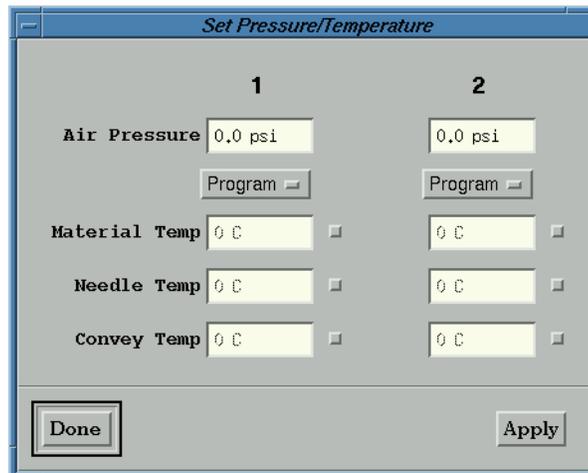
Set Pressure/Temperature is typically used for set up procedures when the system is equipped to handle pressure and temperature control through the software instead of gauge and switch hardware.

This window allows pressure and temperature values to be set independently from values in the program. The operator can set these values when no program is running. The program uses the value set in Air Pressure and the selection made from the drop down menu overrides program actions.

### Example:

- ASSUMPTION 1: The program calls for 5.0 psi to turn off after a period of time.
- ASSUMPTION 2: In the Set Pressure/Temperature window, Air Pressure is set to 8.0 psi and ON is selected from the drop down menu.
- RESULTS: Air pressure will change to 8.0 psi and not turn off as defined in the program.

**TIP:** To access Set Pressure/Temperature, go to the main menu bar and click on Machine Controls > Set Pressure/Temp.



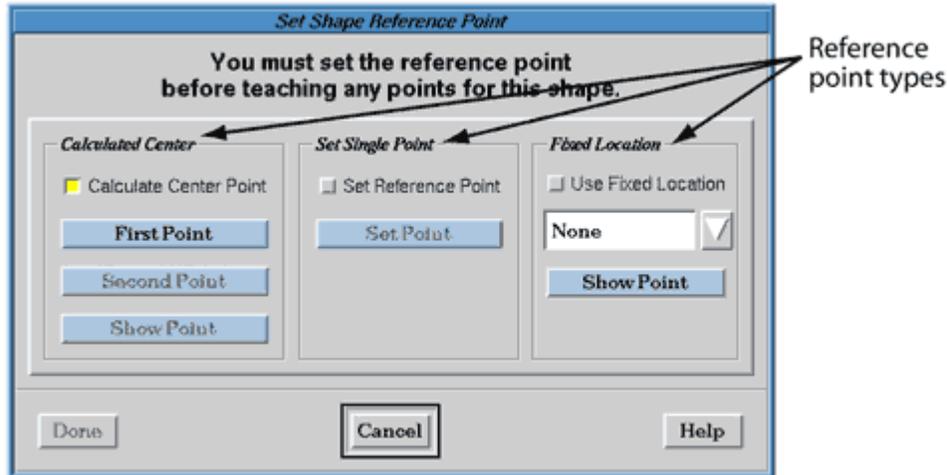
**Table 66:** Set Pressure/Temperature window

Element	Description
Air Pressure	Syringe air pressure; the air pressure applied to the material syringe or FPC sensor (if present).
Program	Drop down menu of program overrides. The override determines how and if the independently set pressure and temperature values will affect the program. <ul style="list-style-type: none"> <li>• <b>PROGRAM</b>: the current program controls this feature.</li> <li>• <b>AUTO</b>: used by older systems to toggle the manual syringe air pressure on/off.</li> <li>• <b>ON</b>: syringe pressure is applied to the syringe.</li> <li>• <b>OFF</b>: no syringe pressure is applied to the syringe.</li> </ul>
Material Temp	Not currently functional. Temperature set point of the material heater.
Needle Temp	Not currently functional. Temperature set point of the needle heater.
Convey Temp	Not currently functional. Temperature set point of the conveyor rail heater.
APPLY	Saves changes and exits this window.
DONE	Exits this window without saving changes.

## Set Shape Reference Point

During the process of re-teaching a shape, the Set Shape Reference Point window is used to tell the system the location of the reference point for the shape being re-taught.

**TIP:** The Set Shape Reference Point window will display automatically during the process of re-teaching a shape, or you may choose to open it manually by selecting Edit Shapes in the Program Editor and then clicking on the FIND FIDUCIALS button.



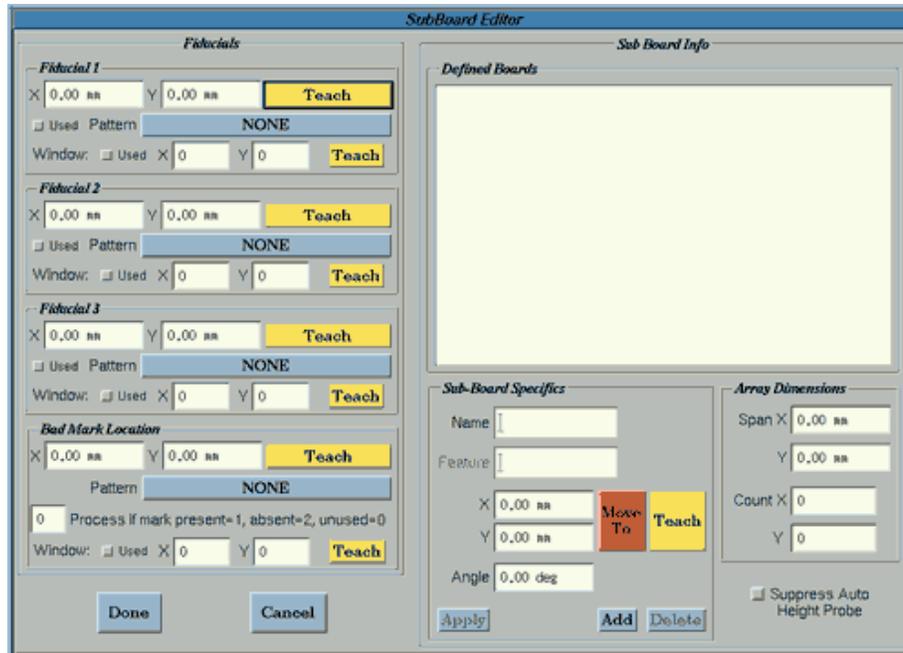
**Table 67:** Set Shape Reference Point window

Element	Description
<b>CALCULATED CENTER</b>	
Calculate Center Point	Activates the Calculated Center type of reference point. Use when the shape is located on a board and the shape reference point can be calculated at the center between two points.
FIRST POINT	Sets the first reference point to the current gantry position.
SECOND POINT	Sets the second reference point to the current gantry position and calculates a shape reference point at the center of a straight line between the first and second set points.
SHOW POINT	The gantry moves the camera to the center of the shape.
<b>SET REFERENCE POINT</b>	
Set Reference Point	Activates the Set Reference Point type of reference point. Use when the shape is located on a board and the shape reference point is a know point.
SET POINT	Sets the reference point to the current gantry position.
<b>FIXED LOCATION</b>	
Use Fixed Location	Not currently functional. Activates the Fixed Location type of reference point. Use when the shape is located off the board at a fixed location (where coordinates are relative to gantry position rather than board coordinates), such as a feeder or pallet.
selection field	Not currently functional. Select a fixed location or type in the name of an existing fixed location.
SHOW POINT	Not currently functional. The gantry moves the camera to the fixed location.

## SubBoard Editor

Use the SubBoard Editor to define the location and orientation of each subboard in a program.

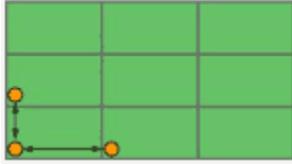
**TIP:** To access SubBoard Editor, open the Program Editor and click on MODIFY SUBBOARDS.



**Table 68:** SubBoard Editor window

Element	Description
<b>F I D U C I A L S</b>	
Fiducial n X, Y	Fiducial coordinates relative to the subboard reference point. Zero, one, two, or three fiducials may be defined as needed.  These fiducials fields only apply to the first subboard in a program. Once created, a single subboard program can be converted into a pallet program (a set of subboards).
Bad Mark Location	Bad mark coordinates relative to the subboard reference point.
TEACH	Use to teach the (0,0) board location or bad mark location.
Used	Indicates whether the associated subboard fiducial or bad mark is used.
Pattern	Pattern name up to 24 characters long for use with automatic vision. This name provides reference to the shape of the fiducial or bad mark.
Process if mark present	Determines how a subboard bad mark is detected and used. 0 = no bad mark indicators; process ignores mark if present. 1 = process if mark is present. 2 = process if mark is absent.
Window	Not currently functional. Primarily used to prevent false positives by masking objects similar to the pattern for which you are searching.
Used	Not currently functional. Indicates whether or not the associated window is used.
X, Y	Not currently functional. X, Y size of the search window.

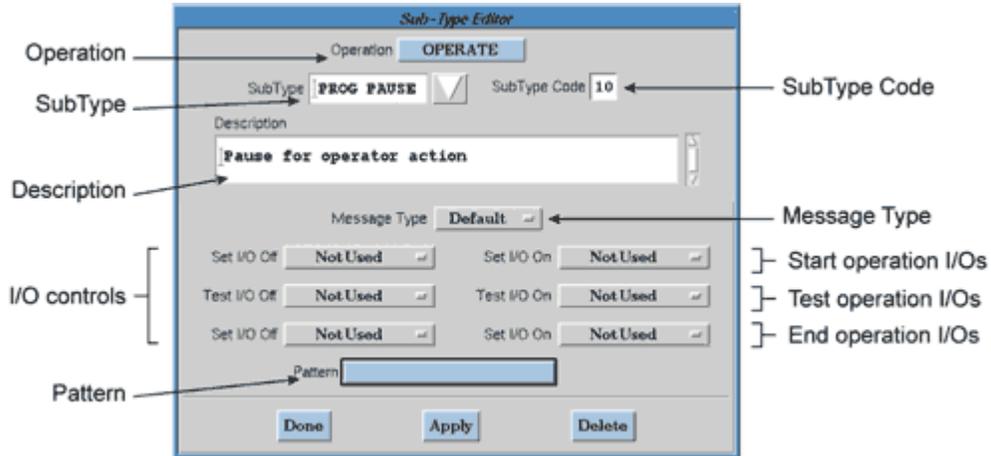
**Table 68: SubBoard Editor window (Continued)**

Element	Description
TEACH	Not currently functional. Teaches the window area (X, Y).
<b>SUB BOARD INFO</b>	
Defined Boards	The name and reference point coordinates for each subboard taught and named with the tools in the SubBoard Specifics panel are displayed here.
<b>SUB BOARD SPECIFICS</b>	
Name	Used only as a reference. Typically, subboard reference names correspond to a number (First, Second, Third, etc.).
Feature	Not currently functional.
X, Y	Subboard reference point coordinates.
MOVE TO	Moves the gantry to the reference point of the selected subboard.
TEACH	Use to teach the subboard reference point location relative to the pallet reference point.
Angle	Degrees of angle of the subboard position relative to the original orientation taught.
<b>ARRAY DIMENSIONS</b>	
Span X, Y	Distance from same position board-to-board in X and Y directions.
	
Count X, Y	Number of subboards in X and Y directions.
Suppress Auto Height Probe	Suppresses automatic probe operation on each board. If N, the elevation of every subboard is checked during processing. If Y, only the height of the first subboard in the pallet is checked.

## SubType Editor

Use the SubType Editor to define and edit subtypes.

**TIP:** To access SubType Editor, open the Program Editor and click on Libraries > SubTypes.



**Table 69:** SubType Editor window

Element	Description
Operation	Defines the operation to which this subtype applies.
SubType	Name of the subtype. May be up to 12 alphanumeric characters long.
SubType Code	<p>A predefined code is automatically entered in this field when a selection is made from the Operation button drop down menu.</p> <p>Details for all operation subtype codes are located in the <i>System Table Definitions: Sub-Type</i> section of the <i>Import/Export Data Reference Guide</i>. A summation is repeated here for the commonly used Operate operation:</p> <p><b>OPERATE Sub Type Codes Defined</b></p> <ul style="list-style-type: none"> <li>0 - obsolete.</li> <li>1 - operate probe.</li> <li>2 - obsolete.</li> <li>3 - operate I/O, skip for test success.</li> <li>4 - halt program.</li> <li>5 - operate pickup.</li> <li>6 - perform place operation with pickup tool.</li> <li>7 - test for missing/present part using test probe.</li> <li>8 - test for presence of a dot using the vision system.</li> <li>9 - suppress all auto-probe operations.</li> <li>10 - pause for operator action.</li> <li>11 - set a flag in current flag word.</li> <li>12 - test a flag in current flag word.</li> <li>13 - take a picture and begin analysis.</li> <li>14 - advance pallet.</li> </ul> <p>~ continued ~</p>

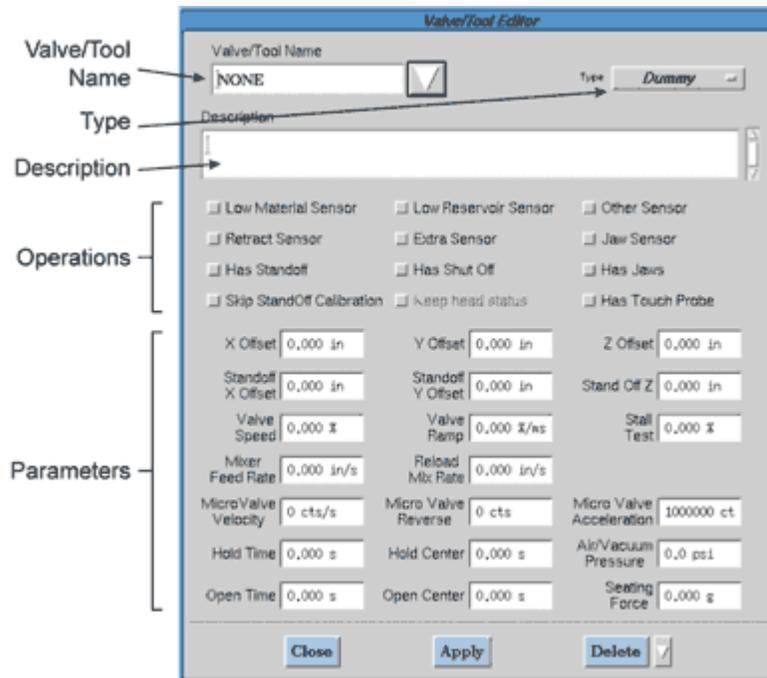
**Table 69: SubType Editor window (Continued)**

Element	Description
	15 - clean needle. 16 - purge valve. 17 - adjust a lens. 18 - seat using a pressure foot. 19 - test using camera 2, pattern. 20 - turn air off.
Description	Comment and description field of up to 250 characters. Text will print fully on printouts. The 40 characters entered up to the first hard return entered will display on some window lists.
Message Type	Code designating a user-defined message to be displayed when a Test I/O fails. Typically, Message Type is only used for SubType Code 3. Creating a user-defined message requires editing the ds.user.msgs file. DO NOT proceed with this action unless you have received specific instructions from GPD Global.
<b>I/O CONTROLS</b>	
<p>These codes are for special I/O (input/output) operations and typically used with SubType Code 3. I/O controls can be defined using Configuration &gt; I/O Definitions. For work and head I/O assignments, refer to the details recorded in the <i>Input/Output Listing</i> section of <i>Mechanical &amp; Electrical Reference Documents</i> located in the dispenser documentation package.</p>	
<b>START OPERATION I/O</b> Set I/O Off Set I/O On	The upper set of Set I/O buttons shown in window: Set I/O Off = an I/O to turn OFF at the START of this operation. Set I/O On = an I/O to turn ON at the START of this operation.
<b>TEST OPERATION I/O</b> Test I/O Off Test I/O On	The middle set of Test I/O buttons shown in window: Test I/O Off = an I/O to test for OFF. Test I/O On = an I/O to test for ON.  If both Test I/O Off and Test I/O On are zero, the operation delays for the amount of time entered in the Operation Time field (on the Program Detail window) before executing the lower set of Set I/O buttons.
<b>END OPERATION I/O</b> Set I/O Off Set I/O On	The lower set of Set I/O buttons shown in window: Set I/O Off = an I/O to turn OFF at the END of this operation. Set I/O On = an I/O to turn ON at the END of this operation.
Pattern	name of a pattern used as part of the subtype function such as dot tests.

## Valve/Tool Editor

The Valve/Tool Editor is used to define the properties and defaults for a new head (valve or tool) or change the characteristics of an existing head.

**TIP:** To access Valve/Tool Editor, open the Program Editor and click on Libraries > Head.



**Table 70: Valve/Tool Editor window**

Element	Description
Valve/Tool Name	Name of the valve or tool. May be up to 18 alphanumeric characters long.
Type	Drop down menu of valve and tool types. The type determines how the head will operate. <b>VALVES:</b> Dummy, Auger, Variable Auger, Drip-less, Syringe. <b>MORE VALVES:</b> Needle, Single Part, Two Part, Micro Valve, Cartridge, MV50/400, NCM. <b>TOOLS:</b> Etch, Rout, Air Drill, Pickup, Other
Description	Optional descriptive field of up to 250 characters. Text displays only in the Valve/Tool Editor window but prints in full for printouts.

### OPERATIONS

Low Material Sensor	Indicates the presence of a low material sensor on the valve or tool.
Low Reservoir Sensor	Indicates the presence of a material level detector on a the valve.
Other Sensor	Indicates the presence of some other sensor on the valve or tool.
Retract Sensor	Indicates the presence of a retract sensor.
Extra Sensor	Indicates the presence of another sensor.
Jaw Sensor	Indicates the presence of a sensor for jaw position.
Has Standoff	Indicates the presence of a stand-off needle on the valve or tool.

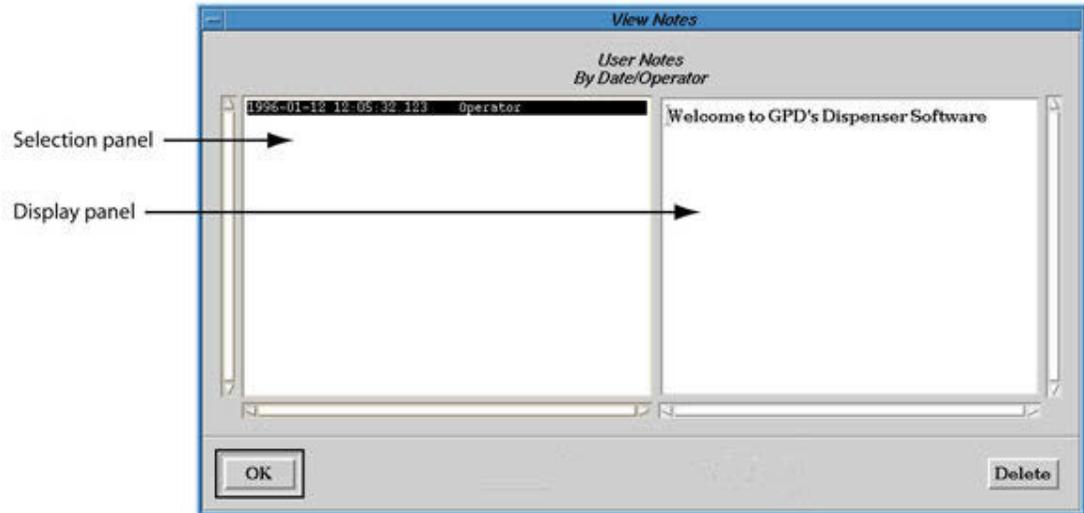
**Table 70: Valve/Tool Editor window (Continued)**

Element	Description
Has Shut Off	Indicates whether or not a valve uses a shutoff control.
Has Jaws	Indicates the presence of centering jaws.
Skip StandOff Calibration	Indicates whether to calibrate this standoff or not.
Keep Head Status	Indicates whether head status (on time, dots dispersed, idle time, etc.) is to be retained across programs.
Has Touch Probe	Indicates the presence of an integral touch probe on the valve or tool.
<b>PARAMETERS</b>	
X Offset	X offset (mm) of the operating point of the valve or tool from the calibration teach tool. This valve allows calibration with the calibration teach tool to be transferred to any valve or tool.
Y Offset	Y offset (mm) of the operating point of the valve or tool from the calibration teach tool. This valve allows calibration with the calibration teach tool to be transferred to any valve or tool.
Z Offset	Z offset (mm) of the operating point of the valve or tool from the calibration teach tool. This valve allows calibration with the calibration teach tool to be transferred to any valve or tool.
Standoff X Offset	X offset required to move a standoff needle from center during calibration. The value depends on the position of the standoff foot.
Standoff Y Offset	Y offset required to move a standoff needle from center during calibration. The value depends on the position of the standoff foot.
Stand Off Z	Z distance to calibrate the standoff needle.
Valve Speed	Percent of full valve speed to run a variable speed valve.
Valve Ramp	Acceleration (percent per millisecond) to ramp up/down a variable speed auger.
Stall Test	Percent of full current at which a variable speed valve is considered stalled. Use this field to prevent the variable speed valve from overheating.
Mixer Feed Rate	Value of mix rate, feed rate, etc. associated with this valve or tool.
Reload Mix Rate	Feed rate to move a mixer valve while reloading the valve.
Micro Valve Velocity	Speed (counts per millisecond) at which a Micro-Dot valve is run for purging or dispensing lines or fills.
Micro Valve Reverse	Value (counts) to operate a Micro-Dot valve in reverse for suckback.
Micro Valve Acceleration	Acceleration (mm/sec/sec) for a Micro-Dot valve.
Hold Time	Not yet functional.
Hold Center	Not yet functional.
Air/Vacuum Pressure	Value of vacuum, pressure, air pressure, etc. associated with this valve/tool.
Open Time	Not yet functional.
Open Center	Not yet functional.
Seating Force	Optional pressure (kPa) used to seat a part with a pressure sensor.

## View Notes

View Notes is where notes entered through the system text feature can be selected for viewing or deletion.

**TIP:** To access View Notes, go to the main menu bar and click Utilities > Notes > View Notes.



**Table 71:** View Notes window

Element	Description
selection panel	Note creation details are listed here chronologically. Selecting an entry here displays the associated text in the display panel.
display panel	Note text for the note selected in the selection panel is displayed here.
OK	Saves changes and exits this window.
DELETE	Deletes the selected note entry.

## Operations (Primitives)

A set of basic, preprogrammed operations is available in the dispenser control software. Each of these *primitive* operations defines an often-used shape or action. This section presents an explanation for each *primitive* operation.

- [Arc](#) (pg 5.108)
- [Calibrate](#) (pg 5.108)
- [Circle](#) (pg 5.109)
- [Delay](#) (pg 5.110)
- [Dot](#) (pg 5.111)
- [Line](#) (pg 5.112)
- [Move](#) (pg 5.112)
- [None](#) (pg 5.112)
- [Operate](#) (pg 5.112)
- [Partition](#) (pg 5.112)
- [Rectangle](#) (pg 5.113)
- [Setup](#) (pg 5.113)
- [Shape](#) (pg 5.113)

**NOTE:** Definitions for fields mentioned in the description of each operation (primitive) can be located here: [Program Detail](#) (pg 5.86).

**NOTE:** Each operation (primitive) has at least a couple SubOps or sub-operations associated with it, and each sub-operation is bound to a specific subtype. For more details, refer to [SubOps & SubTypes](#) (pg 5.114).

### Arc

An arc operation will move the gantry in a circular arc according to the following sequence. The center of the arc is at X and Y through Object Rotation starting at the current location.

1. The head moves at Move Velocity to Settle Z and X, Y at the first point of the arc.
2. The head moves downward at Approach Velocity to Start Z, turning on Valve Prime milliseconds before reaching Start Z if there is sufficient time to do so.
3. The head draws an arc as defined at Dispense Velocity, turning off the valve Valve Off distance before completion of movement.
4. The head moves to Snap Off Z above the product at a rate determined by Snap Off Velocity for the head.

### Calibrate

A calibrate operation forces a calibration during a process as determined by SubOp values.

## Circle

A circle operation draws a circle or an array of circles according to the following sequence. Any unspecified parameters are defaulted.

1. The head dispenses a ring from Start Diameter to End Diameter centered at X, Y.



2. The head moves at Move Velocity to Settle Z and X, Y at the nearest point on the circle of diameter Start Diameter centered at X, Y.
3. The head moves downward at Approach Velocity to Start Z, turning on Valve Prime milliseconds before reaching Start Z if there is sufficient time to do so.
4. The head draws a series of concentric circles of Fill Spacing needle-diameter increments at Dispense Velocity to fill the ring to End Diameter, turning off the valve Valve Off distance before completion of movement.
5. The head moves to Snap Off Z above the product at a rate determined by Snap Off Velocity for Head.

## Delay

A delay operation delays processing for a specified time span. Delay time is set in the Operation Time field (in the Operate panel of Program Detail).

For example:

- For a Dam and Fill application, use Delay to allow material to self-level prior to dispensing the next layer.
- For Underfill applications, use Delay to allow material to fill under the chip if [Resumption Points for Underfill - UltiPath™](#) (pg 4.62) are not used.

## Delay SubOps

For further details about the following subops, refer to [SubOps & SubTypes](#) (pg 5.114).

### Entry

Not currently functional. Delay override at Entry station.

### Exit

Not currently functional. Delay override at Exit station.

### Mark Delay

Used to mark the current time. Must be used in combination with Limit Delay.

### Limit Delay

Used to limit delay at least On Time ms since last mark. Must be used in combination with Mark Delay.

### **Using Limit Delay with Mark Delay**

Limit Delay and Mark Delay can be used in combination. For example, these operations can be applied to underfill dispense to allow a dispense the time needed to wick under a component while another action (needle clean, a second dispense, etc.) occurs simultaneously. To achieve this result, program an underfill dispense, followed by Mark Delay to start the timer, followed by Limit Delay to set the time span that is to occur before the program continues with the next program line.

This combination of delay operations is limited to a single timer for use with a single component size. When various component sizes and/or multiple timers are involved, refer to [Resumption Points for Underfill - UltiPath™](#) (pg 4.62).

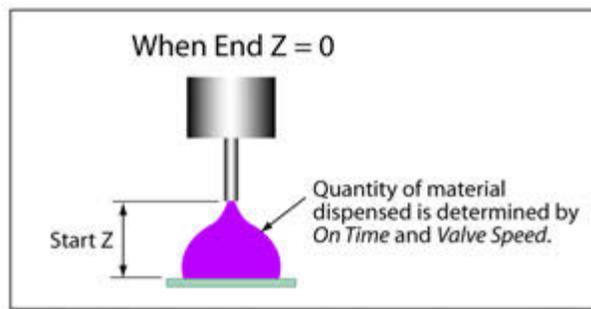
## Dot

A dot operation moves a specified head to given coordinates and dispenses a dot or an array of dots from the named head in one of the following scenarios. Any unspecified parameters are defaulted.

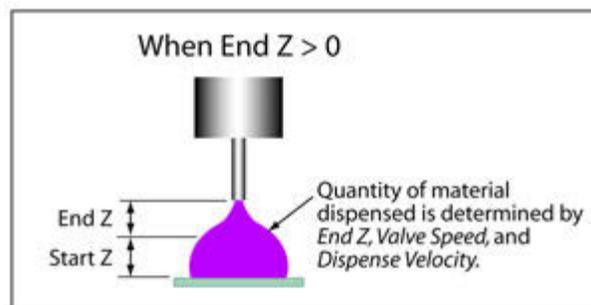
- The head moves to (X, Y, Settle Z) at Move Velocity, then downward at Approach Velocity to Start Z, turning on Valve Prime milliseconds before reaching Start Z if there is sufficient time to do so. When the head reaches Start Z, it delays for the amount of time in On Time or, if End Z is > zero, it dispenses as it approaches End Z at Dispense Velocity. The head then moves to Snap Off Height for Head.

**NOTE:** Start Z is relative to the point at which the surface sensor obtains its reading; when Start Z is zero the needle is positioned at the board surface. Also note that End Z is relative to Start Z.

- If **End Z equals zero**, the system dispenses material at the Start Z position for the specified amount of time in seconds set in the On Time field.



- If **End Z is not equal to zero**, the system turns on the valve, begins dispensing, waits for Start Z Pause (even if it is zero), and then moves to End Z at Dispense Velocity before shutting off the valve. On Time has **no effect** when End Z unequal to zero.

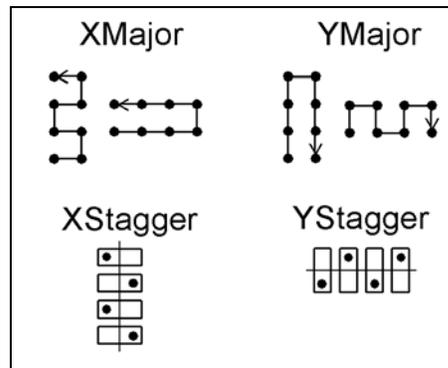


- A Micro-Dot valve works as described above unless End Z is zero, in which case the valve is on for Valve Steps encoder counts. The head then moves to Snap Off Velocity for Head.

## Dot SubOps

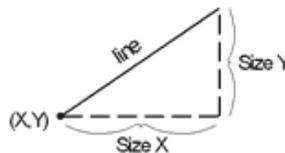
For further details about the following subops, refer to [SubOps & SubTypes](#) (pg 5.114).

Subops for ordinary (major) or staggered arrays of dots are available for the DOT operation.



## Line

A line operation draws a line or an array of lines. A line can be rotated with Object Rotation.



## Move

A move operation moves the gantry from point to point.

## None

A none operation acts as a dummy entry and can be used to include comments.

## Operate

An operate operation operates a fixture as determined by Head and SubOp. An operate should only appear within a fixed partition.

## Partition

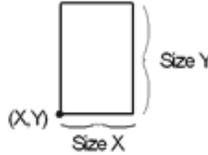
A partition operation introduces a program and partition defaults in accordance with the guidelines listed below. It provides default values and defines sections of the program; partition may appear anywhere within a program. It enables you to enter values only once and then edit these values, which may be used in multiple occurrences, in only one place.

- When sorting points for program optimization, each partition is optimized independently; sorting is suppressed in a fixed partition.
- Parameters in a Partition program line are substituted for omitted fields with corresponding names in all other program lines.
- Omitted parameters in a Partition program line revert to system defaults.

## Rectangle

A rectangle operation draws a rectangle or an array of rectangles in accordance with the following sequence. Rectangle may have a hollow, concentric, or zigzag fill. Any unspecified parameters are defaulted.

1. Dispenses rectangle of (Size X, Size Y) with lower left corner (if SubOp equals Corner) or center (if SubOp is omitted or SubOp equals Center) at (X,Y).



2. If the SubOp is Center/in, Center/out, Corner/in, or Corner/out, the rectangle is drawn as an inward or outward spiral; otherwise, the fill is zigzag.
3. If the SubOp indicates a spiral fill and if Fill Width is between zero and Size X/2, a hollow rectangle is drawn with thickness of sides equal to Fill Width.
4. An individual rectangle can be rotated with Object Rotation. The point of rotation can be changed by selecting one of the various rotation sub-operation choices.
5. If (X,Y) is the first corner, then the head first moves to (X,Y,Settle Z) at Move Velocity, then downward at Approach Velocity to Start Z, turning on Valve Prime milliseconds before reaching Start Z if there is sufficient time to do so.
6. The rectangle is drawn with a series of straight lines of roughly Fill Spacing increments at Dispense Velocity, turning off the valve Valve Off distance before the end of each line.
7. The head then moves to Snap Off Z above the product at a rate determined by the Snap Off Velocity for Head.

## Setup

A setup operation sets up pallets, standoffs, etc. It allows a program to control various activities when the program is first started, such as resetting pallet parameters and some options. It may also reset some fixed parameters or generate request for special operator actions.

Unless otherwise indicated by a SubOp definition (see below), setup lines are effective only if a program is started by clicking the RUN button. If a program is started by clicking the RESTART button, most setup operation lines are ignored. This allows a run to use former pallet positions without requiring fresh pallets or feeders when a program is restarted.

Setup lines can occur anywhere in a program or shape. They are executed in the order in which they appear in a program after the program is read but before any other operation occurs. All setup lines are ignored after actual program execution starts.

## Shape



**CAUTION:** DO NOT USE - this feature is not currently functional.

A shape operation introduces a shape. It defines a particular shape for all following program lines up to the next program or shape program line.

## SubOps & SubTypes

Each shape operation [[Operations \(Primitives\)](#)] (pg 5.108)] has at least a couple SubOps associated with it. Each of those SubOps is bound to a specific and unique Sub Type code.

SubOps are sub-operations; they modify the meaning of the operation. For example, the Rectangle operation can be defined by a corner rather than its center by selecting a corner SubOp rather than a center SubOp.

A specific Sub Type code is bound to each SubOp to define that SubOp. For example, the Center SubOp for the Rectangle operation is always a Sub Type code of 0.

**NOTE:** Some Sub Type codes are available for all machines and some apply only to unique features on a specific machine.

 **WARNING** Care must be taken if subtypes are moved from one machine to another since subtypes relate to both the hardware and software.

<b>ATTENTION</b> <a href="#">Le contenu de cette</a>	<b>WARNUNG</b> <a href="#">Der Inhalt dieses</a>	<b>ATTENZIONE</b> <a href="#">Il contenuto</a>	<b>ADVERTENCIA</b> <a href="#">NO SE RECOMIENDA</a>
---	---	---	--

As of software version 2.9, current subtype codes are as follows:

**Table 72: SubTypes & SubOps by Operation**

Operation	SubOp	Sub Type Code	Description
Arc	Relative or blank	0	Ordinary center/angle arc. Arc starts at last head position with center of arc at X,Y and moves through an angle Object Rotation.
	3-Point	2	Allows arc to be defined with the three points of the arc.
Calibrate	Head	0	Calibrate a single, named head.
	All	1	Calibrate all defined heads.
	Dot	3	Not yet implemented. Recalibrate dot.
	Fiducials	2	Not yet implemented. Recalibrate fiducials.
	Weight	4	Calibrate weight for named head.
Circle	n/a	n/a	not applicable
Delay	Absolute or blank	0	Delay for specified on time.
	Mark	1	Mark current time.
	Limit	2	Limit delay at least On Time ms since last mark.
	Entry	3	Delay override at Entry station.
	Exit	4	Delay override at Exit station.

**Table 72: SubTypes & SubOps by Operation (Continued)**

Operation	SubOp	Sub Type Code	Description
Dot	XMajors	0	For array of ordinary dots only [see <a href="#">Dot</a> (pg 5.111) sample].
	YMajors	1	For array of ordinary dots only [see <a href="#">Dot</a> (pg 5.111) sample].
	XStagger	2	For array of staggered dots only [see <a href="#">Dot</a> (pg 5.111) sample].
	YStagger	3	For array of staggered dots only [see <a href="#">Dot</a> (pg 5.111) sample].
	Circular	4	Not currently functional; circular array.
Line	Direct or blank	0	Start a line at first point by moving to the defined point and dispensing a line defined by X, Y.
	Fast	1	Start a line at the nearest point.
Move	Relative or blank	0	Normal relative move. The head moves to coordinates relative to the current board/subboard.
	Special Locations	1-3	The head moves to Special Location 1, Special Location 2, or Special Location 3.
	Incremental	4	Move incremental.
	Tilt Minus	5	VCI move tilt minus.
	Tilt Plus	6	VCI move tilt plus.
	Calib Forwd	7	Tilts tilt fixture forward to calibrate.
	Calib Rearwd	8	Tilts tilt fixture rearward to calibrate.
Operate	Test	0	Operate I/O controls. Used as on/off controls for devices such as UV wand, etc.
	Probe	1	Operate probe, finding product Z height at specified coordinates. Tests the measured elevation against a set of <a href="#">Z Probe Limits</a> (pg 3.140). Reset Z coordinate.
	---	2	Obsolete.
	---	3	Function without an assigned name. Operate input/output. Skip for success.
	Halt	4	Halt and cancel the program.

Table 72: SubTypes &amp; SubOps by Operation (Continued)

Operation	SubOp	Sub Type Code	Description
Operate (continued)	Pick	5	Operate pickup head to perform part pickup; incremental approach; skip for success.  The selected head is moved to position (X, Y), the piggyback dropped as needed, and the head moved to Settle Z. The head is then moved to Start Z, Pickup control is turned on, and after a delay of On Time, the head is moved to End Z and Pickup_Sense is tested. If Pickup_Sense fails, this will be repeated up to X Count times before declaring total failure. Total failure turns off Pickup control and issues Message R26, allowing the operator to continue or to abort. If the test is successful, Y Count program lines are skipped.
	Place	6	Perform part placement operation with pickup tool with blow-off, pressure; skip for failure or success.  The selected head is moved to (X,Y), the piggyback is dropped as needed, and the head moves to Settle Z. The head then moves to Start Z, Pickup is turned off, and after a delay of On Time, Release_Ctl is actuated. The time used for blow is controlled by Valve Prime. Release_Ctl is turned off, and then the head moves to End Z.
	Z Test	7	Test for missing/present part using test probe. Skip if in range.
	DotTest	8	Test for presence of a dot using the vision system; skip for success.  Uses the result of a PICTURE operation to test for the presence of X Count blobs. If the specified number of blobs is present, the next Y Count program lines are skipped; otherwise, all program lines are executed.
	No Probe	9	Suppress all auto-probe operations.
	Prog Pause	10	Pause program for operator action. Displays a program pause message. Safety violations do not cancel the run, allowing the operator access to the work area. The operator can continue the run or cancel it. Custom versions of this function can be created with unique messages.
	Set Flag	11	Set a flag in the current flag word. Each board has an associated set of 31 status flags (numbered 1-31) that can be set/reset to indicate status conditions on the board. These flags are transported with the board on a multi-gantry system. All flags have the initial value 0 for the board at the first (A) gantry. Set Flag sets flag number (X Count) to on if X Count is less than 0 or to off if X Count is greater than 0. The flag can be tested subsequently with the Test Flag sub-operation.

Table 72: SubTypes &amp; SubOps by Operation (Continued)

Operation	SubOp	Sub Type Code	Description
Operate (continued)	Test Flag	12	Test a flag in current flag word by testing the flag number (X Count). If X Count is greater than or equal to 0 and the addressed flag is off or if X Count is less than 0 and the addressed flag is on, the next Y Count program lines are skipped; otherwise, all program lines are executed. If X Count equals 0, Y Count program lines are skipped unconditionally.
	Picture	13	Take a picture with the camera at (X,Y) and begins a blob analysis. This operation is normally followed by a Dot Test operation to determine whether an acceptable number of blobs are present.  Parameters for the analysis are determined by the vision pattern associated with the Picture operation: Light On Dark ....Y/N: Y = light on dark NumBlobs .....1-50: Max number blobs found LowGray .....1-254: Detection level for 0 HighGray .....1-254: Detection level for 1 MinArea .....Minimum blob area (pixels) MaxArea .....Maximum blob area (pixels) BlobRatio .....Less than 1.0: Measure of elongation
	Advance Feed	14	Advance current pallet.
	Cln Needle	15	Clean needle for current head.
	Purge	16	Purge current head and then clean the needle.
	Set Lens	17	Adjust lens by setting camera parameters: <ul style="list-style-type: none"> <li>• Gain to X Count if Use Camera Adjust is true and X Count is between 0 and 255.</li> <li>• Offset to Y Count if Use Camera Adjust is true and Y Count is between 0 and 255.</li> <li>• Focus to Fill Spacing if Fill Spacing is less than -1.</li> <li>• Zoom to Scale Factor if Scale Factor is less than -1.</li> </ul>
	Press	18	Perform place operation with pickup tool by moving the gantry down slowly until a pressure head registers the pressure specified by the head. Pressure is maintained for On Time seconds.
	---	19	Function without an assigned name. Searches the current field of view for a camera/lens/light/trained pattern. Pattern name is the subop type. If the pattern is found, the next Y Count lines are skipped; otherwise, all program lines are executed. For a fixed upward looking camera, Z will move where taught in Base Locations for pattern training and searching
	Air Off	20	Turn air off to current head.
	---	21	Park head.
	Mixer Reload	22	Reload the mixer valve.
Probe Setup	23	Initiate (VCI) probe operation.	

**Table 72: SubTypes & SubOps by Operation (Continued)**

Operation	SubOp	Sub Type Code	Description
Operate (continued)	Probe Part	24	Probe part without fixture rotation and save values.
	Probe Reset	25	Reset (VCI) probes.
	Probe Skip	26	Probe tilted (VCI) part and skip lines.
	Set Reject	27	Flag current board as Reject.
	Index Probe	28	Index tilt part location.
	Tilt Home	29	VCI home tilt fixture.
	Tilt Forwd	30	VCI tilt forward.
	Tilt Rearwd	31	VCI tilt rearward.
	Mark Repeat	32	Mark start of repeat prior scan/probe.
	Jump Repeat	33	Jump to repeat mark, prior scan/probe.
	Inspection	34	Test for dot inspection needed; then inspect within range.
	Dot Size	35	Obsolete. Get dot size; does nothing with dot size.
	Dot Inspect	36	Obsolete. Unconditional (without dot range set by calibration mirror) dot inspect within range.
	Flip	37	Flip and process second side of board.
	Ctr Set	38	Set/Reset a counter.
	Ctr Inc	39	Increment/Decrement a counter.
	Ctr ValueLE	40	Test a counter less than or equal to a fixed value.
	Ctr TestLE	41	Test a counter less than or equal to another counter.
	Ctr Show	42	Select a counter to display.
	CtrValueG	43	Test a counter greater than a fixed value.
Ctr TestG	44	Test a counter greater than another counter.	
Resume Pt	50	Suspend program execution and resume it at a later point in time.	
Partition	Optimize or omitted	0	Partition can be optimized.
	Fixed	1	Partition cannot be optimized.
Rectangle	Center	0	Locate by center.
	Corner	1	Locate by lower left corner.
	Center/out	2	Center, spiral out.
	Corner/out	3	Lower left corner, spiral out.
	Center/in	4	Center, spiral in.
	Corner/in	5	Lower left corner, spiral in.

**Table 72: SubTypes & SubOps by Operation (Continued)**

Operation	SubOp	Sub Type Code	Description
Setup	Stand Off or omitted	0	Set a standoff. Moves the camera to the (X,Y) coordinates of the setup line and asks the operator to place a stand-off in that location. <i>This feature should be used sparingly since placements require significant operator time.</i>
	Reset Pallets	1	Reset all pallets to start locations.
	Raise Lifter	2	Raise lifter plate.
	Lifter Down	3	Lower lifter plate.
	Entry Delay	4	Set entry station delay.
	Exit Delay	5	Set exit station delay.
	Skip Calibration	6	Skip calibration.
	Cancel MixLd	7	Cancel the AlwaysLoadMixer option.
	No Stretch	8	Cancel fiducial stretch calculation.
	Auto Purge	9	Valve purge during program run (inline applications).
	---	100-199	Reset specified pallet, alter pallet configuration 0-99.
	---	200-299	Alter pallet advance information 0-99.
shapename	XMajors	0	For array of ordinary shapes only.
	XStagger	1	For array of staggered shapes only.
	YMajors	2	For array of ordinary shapes only.
	YStagger	3	For array of staggered shapes only.
	---	100-199	Ignore CoordX, CorrdY; use pallet coordinates 0-99.
	---	200-?	For future use.

## Legacy Controls & Operations

This section includes all content related to the legacy Emergency Stop and Power Off controls previously located on the front control panel of the dispense system.

### Which Control Panel Does My System Use?

Use this chart to determine which version of controls your system uses:

Which front panel is on your system?	 <p>CURRENT</p>	<p>This is the <b>current</b> version. It uses these controls:</p> <ul style="list-style-type: none"> <li>• Emergency Stop</li> <li>• Power On</li> <li>• Power Off</li> </ul> <p>Ignore this <i>Legacy Controls &amp; Operations</i> section.</p>
	 <p>LEGACY</p>	<p>This is the <b>legacy</b> version. It uses these controls:</p> <ul style="list-style-type: none"> <li>• Motion Stop</li> <li>• Power On</li> <li>• Emergency Stop</li> </ul> <p>Use this <i>Legacy Controls &amp; Operations</i> section when directed here at pertinent points in this document.</p>

As of June 2017, these hardware and terminology changes went into effect:

- *Emergency Stop* was replaced with *Power Off*.
- *Motion Stop* was replaced with *Emergency Stop*.

### Legacy Contents

- [Power On](#) (pg 5.121)
- [Power Off](#) (pg 5.121)

## Power On

To power on the machine:

1. Read all safety and operating instructions prior to operating the machine.
2. Verify the red Emergency Stop button is pulled out.
3. Turn on the machine by pressing the green Power On switch. The system will prompt you to home the XYZ gantry when you turn on the power and the booting process has finished. The system must complete the homing sequence before other operations are possible. Refer to [Home the System](#) (pg 2.1).

## Power Off

Before powering off the machine, end any active program and perform a proper shutdown described in the following procedure:

### Prepare for Shutdown

Before you can perform the shutdown procedure, you must end any active program. It is also recommended that you unload all product from the dispense area and remove and clean the heads.

To prepare for shutdown:

1. Stop program execution with one of these methods:
  - If the Mount Board prompt is displayed, click ABORT, or
  - Click CANCEL on the main button bar.
2. After the program has ended, remove all product from the dispense area. For details, refer to [Unload Product](#) (pg 5.8).
3. Unload all heads (valves and tools):
  - a. Click REFRESH on the main button bar to move the gantry to the front of the machine where you can access the heads.
  - b. Remove the heads. For details, refer to [Mount Heads](#) (pg 5.1).
  - c. Clean the heads. For details, refer to head cleaning instructions detailed in *Valves* under *CLEAN* in the *Periodic Operations* section of the *Dispense System Service Guide*.

### Shutdown

The machine can be left powered on as long as the safety system has not been bypassed, however, GPD Global recommends that you power off equipment when it is not in use.

To shutdown and power off the machine:

1. Perform the [Prepare for Shutdown](#) (pg 5.121) procedure.
2. From the main menu bar, click on Operations > Shutdown System. A shutdown verification prompt displays.
3. Click YES to shutdown the system or CANCEL to abort the shutdown. Wait until a System Stopped prompt displays.
4. Power off the machine by pressing the red Emergency Stop button.
5. Perform the [Lock-Out](#) (pg 5.122) procedure.

## Energy Isolation Procedures

### Lock-Out



To ensure energy isolation, lock-out the equipment:

1. Turn off customer-supplied Lock-Out switch.
2. Turn off main power switch.
3. Install a lock or tag per your facility energy isolation procedures.
4. Test if system will start by pressing the Power On switch.
5. Test volt meter on known voltage source:
  - Test for presence of electrical power at TB1 and TB2 or at EMI Filter inlet L1 or L2.
  - Reconfirm volt meter on known voltage source.

### Release Equipment from Lock-Out



To release equipment from customer-supplied Lock-Out switch:

1. Remove all tools, parts, and materials from the system.
2. Verify any and all work to ensure proper installation, polarity, connection.
3. Close all doors, covers, and shields.
4. Using facility-specific procedures, remove customer-supplied locks and/or tags.
5. Pull out the Emergency Stop button.
6. Ensure the power cord is connected.
7. Turn on main power switch, watching for electrical or other failure.
8. Follow the [Power On](#) (pg 5.121) procedure.

# 6 System Management

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This chapter discusses various utilities requiring a top level password for access, account management topics, the routine maintenance of performing various types of backups, and how to boot the system.

- [Security](#) (pg 6.2)
- [Account Management](#) (pg 6.3)
- [Administrative & Housekeeping](#) (pg 6.6)
- [Routine Backups](#) (pg 6.14)
- [Troubleshooting](#) (pg 6.30)

## Security

Access to various system features is controlled by unique, user-defined passwords that protect unauthorized use of the access rights assigned to a user name. Because any combination of access rights can be assigned to any user name, passwords are typically supplied by the person who administers the system.

Whenever the dispenser is powered on, the default password in effect allows minimal access (at the Operator level) to the system.

## Passwords & Access Rights

Following are some of the advantages of using [Passwords & Access Rights Library](#) (pg 5.13):

- An administrator can set up different areas that various operators can use.
- Each operator can have customized functions.
- The system keeps track of who is logged in and their operations.
- Add or delete a user name, change access rights for a user name, or change the password for a user name.

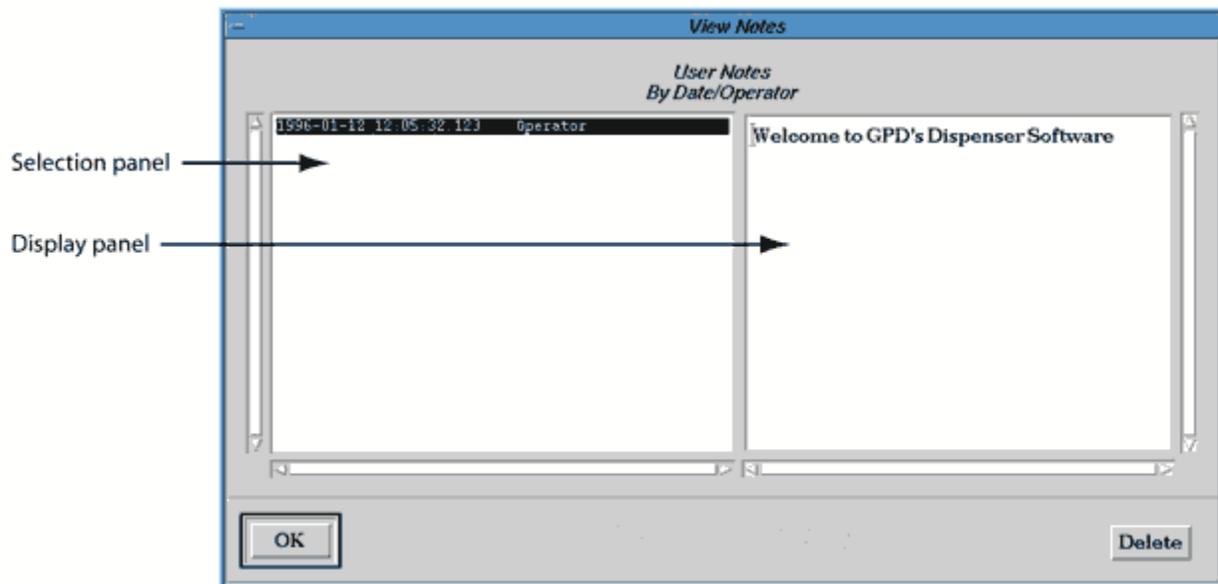
# Account Management

## Notes

Notes is a text facility available to all users. This feature can be used, for example, by an operator to leave notes for the system engineer, technician, or the next shift.

### Review Notes

Use the View Notes window to review and/or delete notes from the system by date or by operator. Notes are displayed in the right hand panel of the View Notes window. The operator who created the note and the date and time the note was created are listed in the left hand panel.



To view and/or delete a note:

1. From the main window menu bar, click Utilities > Notes > View Notes.
2. Click on the date/time/operator details of the note you wish to read or delete. The associated note text will display in the right hand panel.
3. To delete the selected note, click DELETE.
4. To exit the window and accept a deletion, click OK; otherwise, click CANCEL to exit without changes.

### Add Notes

The current user name, date, and time will be assigned automatically to each new note. Each note may contain up to 2,000 characters.

To add a note:

1. From the main window menu bar, click Utilities > Notes > Add Notes. Notes displays.
2. Click inside the blank screen area and then type desired text.
3. Click OK to save the note or CANCEL to exit without saving it.

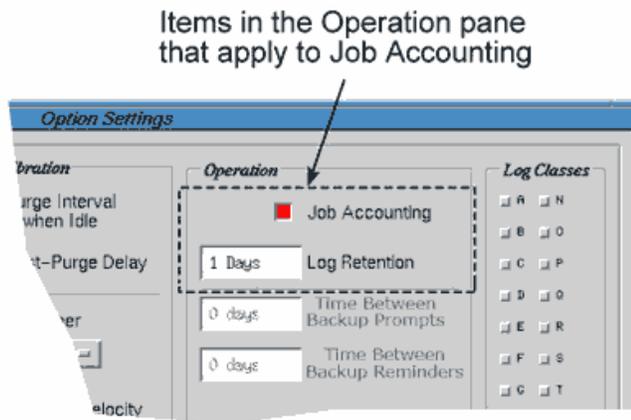
## Management Info

The dispenser system can be set up to collect data about each run of a process. Once data has been collected, reports can be generated to disk or a printer.

Periodic data purges are also necessary to prevent filling the computer hard drive.

## Job Accounting

The job accounting feature must be turned on in order for the system to collect record details about each job run. There are two types of data that can be collected: job accounting data (including start/end times, elapsed operation, elapsed idle times, material, material usage, etc.) and error log information.



To turn on job accounting:

1. From the main window menu bar, click on Configuration > Option Settings to access the Option Settings window.
2. Turn on the Job Accounting used button located in the Operation pane.
3. Enter a value in Log Retention. This determines how many days error log information is retained. If you do not enter a value, the default entry (0) will retain error log data indefinitely, which could potentially cause a hard drive memory problem.
4. Click OK to accept changes; you will be prompted to reboot the machine to make the changes take effect. Click CANCEL to erase any changes made, making a machine reboot unnecessary.

## Report Generation

When the job accounting feature is turned on, it may be necessary to generate periodic reports from the collected data. To generate a report of job accounting data:

1. From the main window menu bar, click on Utilities > Management Info > Show Job Info. The Interim Report Generation window displays.

2. Make the appropriate entries in the Program Name, Operator Name, Report This Many Days, and Earliest Date fields to generate the desired report. For details about how to use each field during the reporting process, refer to Interim Report Generation in the Windows & Fields section of References.
3. Select only one of the output features: Print to Disk, Data to Disk, or Print to Printer.
4. After all sections are made, click OK to generate a report, or click CANCEL to exit without generating a report.

## Purge Accounting Data

Data continues to accumulate, so it must be purged occasionally or else the system may become sluggish, particularly when powering on. Data may be selectively purged.

Although purging is normally the job of the system engineer or administrator, the operator can be authorized to perform this function.

To purge accounting data:

1. From the main window menu bar, click on Utilities > Management Info > Show Job Info. The Interim Report Generation window displays.
2. Enter or select the appropriate items to purge the obsolete data. For details about how to use each field during the purge process, refer to Interim Report Generation in the Windows & Fields section of References.
3. After all selections are made, click OK to purge the file, or click CANCEL to exit without purging.

# Administrative & Housekeeping

## Message Logs

Logging is an engineering tool that collects various types of system and user messages for purpose of analyzing machine performance, process results, failure rates, etc. and exporting the message logs to a spreadsheet.

Logging flags, also referred to as logging classes, determine which logging messages are saved. A single class or any combination of classes can be selected when you set up the system for log retention. The system will collect every instance of logging message for each type of logging class selected.

After the system has collected logging data, the user retrieves the data from the dispenser via an export file which, after some minor format modification, can be used for data analysis.

## Set Up Logging

Prepare the dispenser to capture the logging data you want gathered:

1. From the main menu bar, click on Configuration > Option Settings to open Option Settings.
2. Turn on Job Accounting.
3. Enter a value in Log Retention.

**NOTE:** To ensure logging files are purged periodically, it is strongly recommended that you enter a value of 1 or 2 in order to limit collection to a one or two day period. Logging data collection dramatically increases the size of data backups and exports. If Log Retention is left as zero, logging files are never purged.

- From the following list of logging classes, select each class applicable to the types of data you want to track.

**RULE 1:** The “I” logging class must be used in order for logging to be active.

**RULE 2:** Multiple logging classes may be selected.

**Table 73: Logging Classes**

Description	Log Class
Air or safety problem	A
Calibration errors	C
Operator errors	E
Hardware failure	H
Information to operator	I
Maintenance	M
Operator instructions	O
Program errors	P
Results	R
System errors	S
User messages	U

For further details about log classes, refer to Option Settings in the Windows & Fields section of References.

- Click OK to accept changes and close Option Settings.
- For changes to take affect, perform a normal machine shutdown and then power on the system. For details, refer to Power Off and Power On in the Basic Operations section of the Dispenser Operator Guide.
- When it is time to retrieve collected logging data, proceed with the following Retrieve Logging Data procedure.

## Retrieve Logging Data

To retrieve logging data captured by the dispenser, export the data to a file:

- At the main menu bar, click on Utilities > Import/Export > Export. Data Export displays. For more details about using export data, refer to Export Data in the Existing Programs section of Operating Instructions.
- At the Export File Name field, type in a file name.
- Turn on the Error Log box.
- Turn on the Export ALL FIELDS box.
- Click the EXPORT button at the bottom of the window. A text file will be generated that can be viewed in various Windows platforms.
- Modify the format of the exported file using the following Format Logging Data for Analysis procedure.

## Format Logging Data for Analysis

The exported file generated by the dispenser export process can be viewed as a text file on a Windows system. The following is an example of how this information can be prepared in a usable format for various analytical end uses. Also see [Logging Custom Data](#) (pg 6.9).

To format the exported logging data:

1. Using Microsoft Excel, open the logging data file exported during the preceding Retrieve Logging Data procedure.

### Before Deletion

Delete the @FORMAT cell so the header row will move into proper alignment with the data columns.

@FORMAT	@ERRLOG	IGant	RecID	CurTime	Program	LogLi
	1	31029	47:52.9	1280HS	1	I
	1	31030	51:05.0	1280HS	1	I
	1	31031	51:20.8	1280HS	1	R
	1	31032	51:23.2	1280HS	1	I
	1	31033	51:39.0	1280HS	1	R
	1	31034	51:41.5	1280HS	1	I
	1	31035	51:57.3	1280HS	1	R
	1	31036	51:59.9	1280HS	1	I
	1	31037	52:15.8	1280HS	1	R
	1	31038	52:18.5	1280HS	1	I

### After Deletion

The header row is now properly aligned with the data columns.

@ERRLOG	IGant	RecID	CurTime	Program	LogLevel
1	31029	47:52.9	1280HS	1	I
1	31030	51:05.0	1280HS	1	I
1	31031	51:20.8	1280HS	1	R
1	31032	51:23.2	1280HS	1	I
1	31033	51:39.0	1280HS	1	R
1	31034	51:41.5	1280HS	1	I
1	31035	51:57.3	1280HS	1	R
1	31036	51:59.9	1280HS	1	I
1	31037	52:15.8	1280HS	1	R
1	31038	52:18.5	1280HS	1	I

2. When presented with formatting choices, select Delimited and then Comma.
3. Locate the rows of information applicable to the error log and delete the single cell with contents of "@Format" (refer to the illustration below). This deletion will allow the columns of the header row to align properly with the data columns.
4. Save the results. The data is now ready for analysis. Use the Import/Export Data Reference Guide as an aid when analyzing the logging data.

## Logging Custom Data

### ***IN EFFECT AS OF FLOWare software version 2.5***

You may customize the format file used to export desired data from the machine. The following step-by-step procedure explains how to export both *Probe* data and *Scale* data; this data is often needed in order to chart machine and/or process performance.

In summary, a single format file can be customized to gather the information for both the Probe and the Scale functions because:

- each time the program takes a probe reading, the X, Y, and Z-axis positions are recorded and saved in the data base under the data base names **ErrValue**, **ErrTarget**, and **ErrCorrection**, respectively, and,
- similarly, each time a weighing function is performed, the actual weight, target weight, and percentage of correction are saved in the data base under the same respective data base names: **ErrValue**, **ErrTarget**, and **ErrCorrection**.

For a complete and detailed explanation of these functions, refer to the *Import/Export Data Reference Guide* for FLOWare Software.

### **Customize Export Format File**

To customize the export format file to include both Probe and Scale data, proceed through all of the following steps in the order listed:

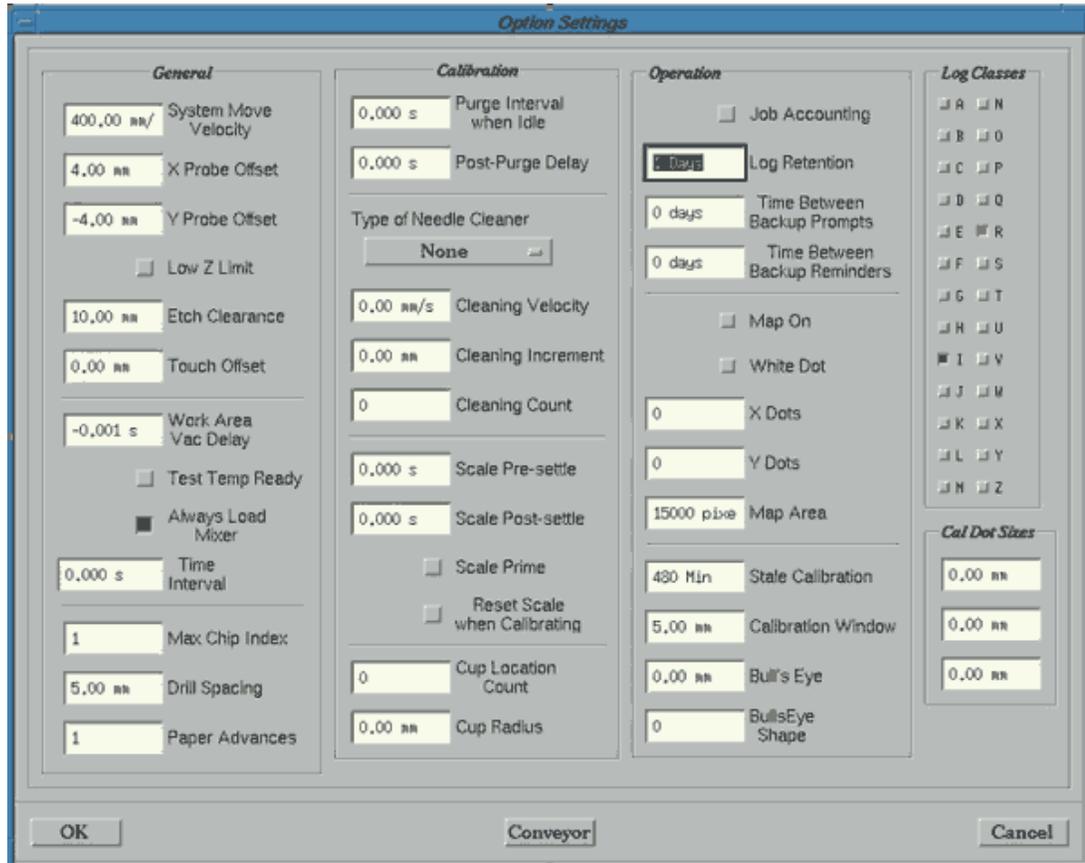
#### **Step 1 - Enable Log Classes**

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To enable the Log Class in the Option Settings Window:

1. From the main menu bar, click **Configuration > Option Settings**.
2. Select **R** and **I** in the **Log Classes** pane.

- Enter the desired number of days over which you wish to retain the log data in the **Log Retention** field.

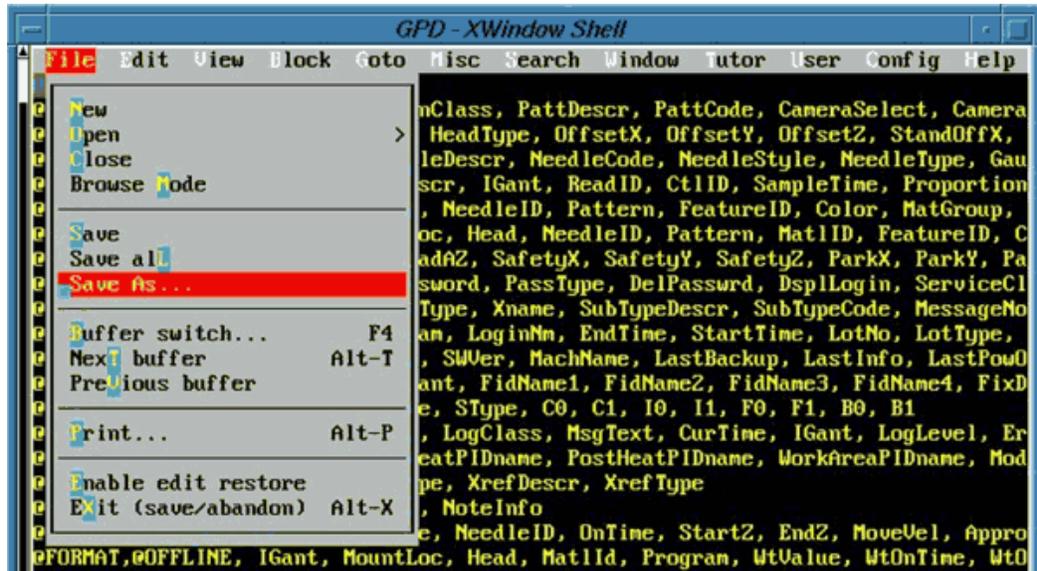


## Step 2 - Customize Format File

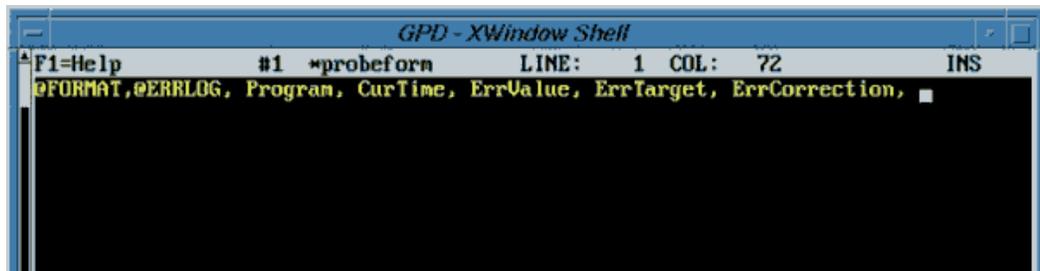
To customize a Format File:

- From the main menu bar, click **System Functions > Shell**.
- At the **\$** prompt, type `vedit exform` and press **Enter**.
- Press **Alt+F** to display the file menu across the top of the Shell window.

- Click on **Select File > Save\_As** as shown in the following image.



- Save the file as `/home/dispenser/probeform`
- Delete all lines except the `@FORMAT@ERRLOG` line.
- From within the `@FORMAT@ERRLOG` line, delete all the data base names except **Program**, **Curtime**, **ErrValue**, **ErrTarget**, and **ErrCorrection**. Use the following image as a reference.



- Save your changes by pressing the **ESC** key, **X** for eXit, and **Y** to save all.

### Step 3 - Restart Machine

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Restart the machine.

### Step 4 - Run program

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Run your program(s) that uses the probes, or weight scale, or both. Logging data will be generated.

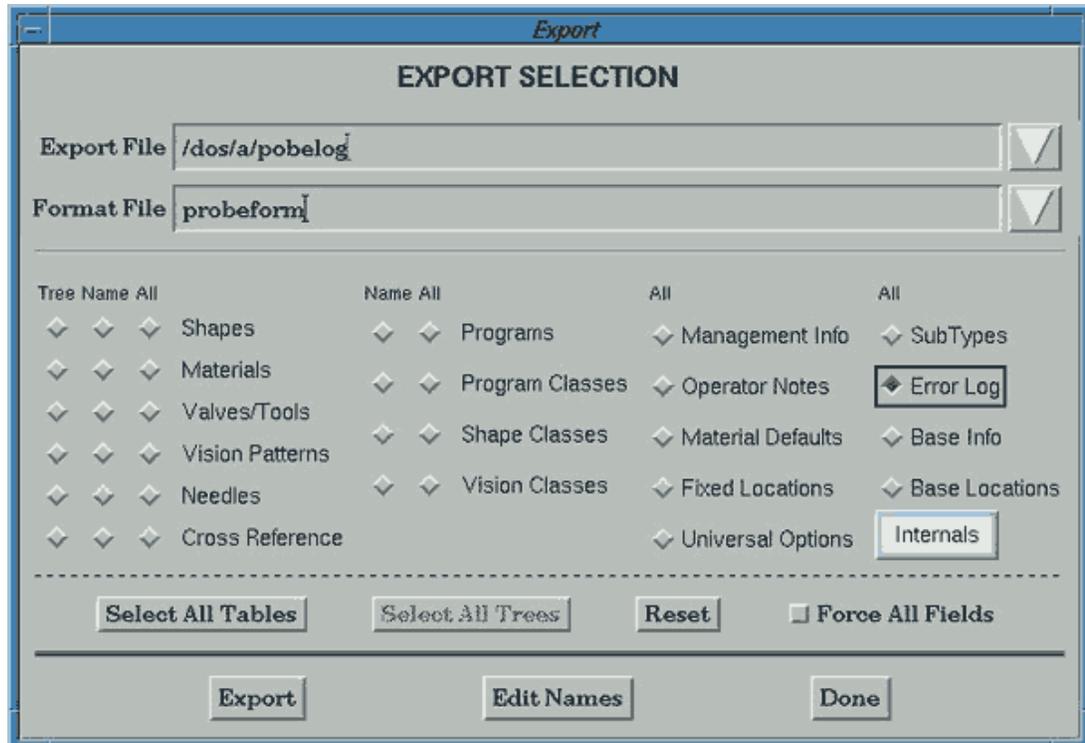
### Step 5 - Export Customized Data

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To export your customized data:

- From the main menu bar, click **Utilities > New Export**.

2. Type the export file name in **Export File** using the correct file path for the type of media you have available:
  - /dos/a/ for floppy diskettes
  - /dos/c/ for USB device
3. To use the custom format file you created, type `probeform` in the **Format File** field.
4. Select **Error Log** as the only data you wish to export.
5. Click on the **Export** button and view the data in a spread sheet at your desktop PC. Use the following image as a reference.



## Installing & Upgrading Software

Installation of software on the dispenser, whether for upgrade or recovery purposes, is detailed in documentation separate from this manual.

### Software Upgrades

FLOware software, the system control software, can be upgraded incrementally from its current version to more recent versions, one upgrade at a time.

A software upgrade is installed using the Utilities > Install Update function found in the main window menu bar. The files needed to perform an upgrade are available from the GPD Global Service Department.

**NOTE:** Detailed instructions for upgrading the control software are provided in software version-specific editions of *Upgrading FLOware Software* (PN 22100086).

### Software Installation

The most current version of the system control software (FLOware software) and all other system software needed to operate the dispenser are installed at the factory.

Should the software system become inoperable due to factors such as a corrupted hard drive, the system software can be re-installed and data can be restored provided the necessary backups are available.

**NOTE:** Detailed instructions for performing the recovery process are described in the following document:

**IN EFFECT AS OF FLOware software version patch-2.9.3-USButils**

*Dispenser Software Recovery* (PN 22144015)

**IN EFFECT PRIOR TO FLOware software version patch-2.9.3-USButils**

*Dispenser Software Recovery* (PN 22100109CD.29)

## Routine Backups

### **IN EFFECT AS OF FLOWare software version patch-2.9.3-USButils**

Detailed instructions for routine backups and disaster recovery are provided in *Dispenser Software Recovery* (PN 22144015). Topics covered include:

- backing up system
- capturing diagnostics
- restoring system
- recovering system
- how to create USB boot device
- how to capture USB boot image

### **IN EFFECT AS OF FLOWare software version 2.8 - 2.9i**

- [Backup Reminder](#) (pg 6.16)
- [Data Backup](#) (pg 6.17)
- [Application Backup](#) (pg 6.20)
- [Full System Backup](#) (pg 6.27)
- [FAQs for Routine Backups](#) (pg 6.29)

The importance of making routine backups can not be stressed enough. There is a saying among computer users, "If you don't do backups now, you will in the future."



**WARNING** GPD Global is NOT responsible for loss of configuration or programs if current backup is not available.

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It is an inevitable reality that the primary hard disk will crash. Reasons underlying a system failure can range from a simple hard disk mechanical failure, data corruption due to outside causes such as electrical spikes or abnormal vibration, memory overload, to other causes that may be related to an operating system malfunction or software glitch.

The good news is that the system is well equipped with a variety of methods that minimize production down time as a consequence of a failure; thereby also alleviating panic for the responsible engineers.

**Table 74: Backup Types Described**

Backup Type	Description
<a href="#">Data Backup</a> (pg 6.17)	<p><b>IN EFFECT AS OF FLOWare software version 1.5b</b></p> <p>A data backup from any FLOWare software LATER than version. 1.5b:</p> <ul style="list-style-type: none"> <li>• contains all essential configuration and calibration as well as all customer programs.</li> <li>• can be restored on any version of software later than 1.5b.</li> </ul> <p><b>IN EFFECT PRIOR TO FLOWare software version 1.5b</b></p> <p>A data backup from any FLOWare software PRIOR to version 1.5b can be restored only on the same machine at the same software level as the backup.</p>
<a href="#">Application Backup</a> (pg 6.20)	An application backup from any version of FLOWare software contains all GPD Global-supplied software in addition to all essential configuration and calibration information. When an application backup is restored, the dispenser reverts to the software level of the backup.

**Table 74: Backup Types Described (Continued)**

<b>Backup Type</b>	<b>Description</b>
<a href="#">Full System Backup</a> (pg 6.27)	A full system backup contains all dispenser software including the QNX operating system, X-Windows system, Sybase data base, and all material from the application backup.

To ensure uninterrupted operations, always perform a backup before and after a software update in addition to periodic back ups. GPD recommends implementing the [Backup Reminder](#) (pg 6.16) feature to automatically remind you to perform periodic backups.

Backups may be performed by whoever is responsible for this function at your facility, be that an operator, engineer, or administrator.

## Backup Reminder

By recording the last time a backup was made, the backup reminder feature serves as a repeating reminder to perform a backup. All backup types (Data Only, Application, and Full System) will automatically reset the backup reminder feature; however, use of the export feature has no effect on the backup reminder.

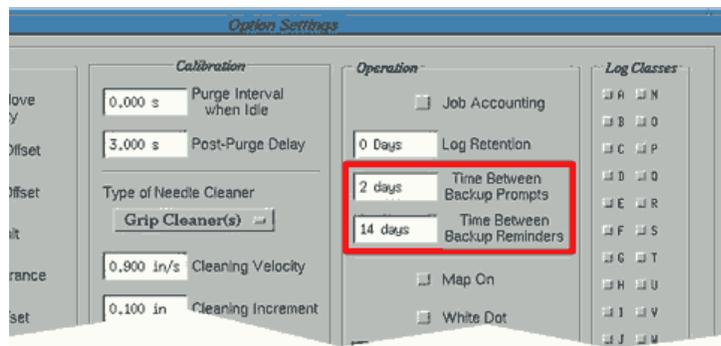
**NOTE:** The backup feature does not perform the backup for you; it only reminds you to do so.

**EXAMPLE:** If you enter a value of 2 in the **Time Between Backup Prompts** field and 14 in the **Time Between Backup Reminders** field, then an initial reminder will display 14 days after the last backup with subsequent reminders continuing to reappear every second day thereafter until a backup is performed.

### Activate Backup Reminder

To activate the backup reminder feature:

1. From the main window, click Configuration > Option Settings.
2. In the Operations panel, enter a value in both fields: Time Between Backup Prompts and Time Between Backup Reminders.



3. Reboot the system to implement the changes.
4. As needed, perform regular backups. All backup choices will automatically reset the Time Between Backup Reminders field. If you do not perform regular backups, the reminder message will prompt you to do so.

## Data Backup

**IN EFFECT AS OF FLOWare software version patch-2.9.3-USButils**

Detailed instructions for routine backups and disaster recovery are provided in *Dispenser Software Recovery* (PN 22144015).

**OBSOLETE AS OF FLOWare software version patch-2.9.3-USButils**

### A data backup includes:

- all machine configurations,
- IO configuration,
- Servo Files, and
- System files

Additionally, all current data used by the machine is saved:

Programs	Classes	Management Info	Error Log
Shapes	Programs	Notes	Management Info
Materials	Needles	Fixed Locations	Base Info
Material Defaults	Vision Patterns	Universal Options	Base Locations
Heads	Cross References	SubTypes	internals

### A data backup excludes:

operating software such as FLOWare operating software, X-Windows, SYBASE, and QNX operating systems.

Data backups can be saved to floppy diskettes or a USB device.

## Data Backup to USB

To create a data backup on a USB device:

1. Change the system password to an access right that permits access to Configuration.
2. From the main menu bar, click Utilities > Backup > Data Only. A prompt displays in the GPD-Data Backup window:

```
GPD Global Dispenser Data Backup
```

```
Back up to USB Device? (Y/n) y
```

```
Press ENTER to use the default backup directory /dos/c/
Backup; Otherwise, enter the name of the desired directory:
```

3. Choose either the typical response of using the default **Backup** directory by pressing Enter, or, if a different name is desired, enter it now; a directory with the new name will be created automatically on the USB device.

```
Current Backups are:
```

The system lists all backups in the selected directory.

Enter a file name for this backup: filename

4. Enter a file name avoiding the use of spaces, dots, and extensions. Name length is not limited.

Do you really want to perform a Data Backup

To /dos/c/Backups/filename (Y/n) y

The system begins the backup. Ignore the following error (this information is for GPD Global use only).

Pax: /etc/samba.setup : No such file or directory

Pax: /etc/start.tcpiip : No such file or directory

The system finishes the backup with:

\* \* \* \*

Remove the USB device

Remove all USB storage devices now.

Remove all USB storage devices now.

Remove all USB storage devices now.

5. Remove the USB device from the machine (or the system will continue repeating the prompt). The following prompt displays:

Backup Complete

Bkset: DB connection

Done Press Enter to Continue

6. Press Enter to exit the Data Backup window.

## Data Backup to Floppy Disk

To create a data backup on floppy disk(s):

1. Change the system password to an access right that permits access to Configuration.
2. From the main menu bar, click Utilities > Backup > Data Only. A prompt displays in the GPD-Data Backup window:

```
GPD Global Dispenser Data Backup
```

```
Back up to USB Device? (Y/n) n
```

```
Do you really want to perform a Data Backup to /dev/fd0 (Y/n)? y
```

The machine begins preparing for the backup and leads to the following prompt:

```
Do you want a reloadable backup on QNX disks? (y/N) y
```

A reloadable backup simply refers to a backup from which you can restore while at the machine.

3. Ignore all error messages preceding the following information and prompt:

```
Total archive size is: 1924 k (size will vary)
```

```
Requiring about 1 disk(s).
```

```
Do you need to format some floppies now? (y/N) y
```

4. ALWAYS format the number of disks suggested by the machine. After formatting all disks, the following prompt displays:

```
Vol: When drive light goes out insert disk 1 and press return
```

When the backup is complete, the following prompt displays; this prompt is for GPD Global factory use only.

```
Do you want a non-reloadable backup on a DOS/Win disk? (y/N) n  
n (Non-reloadable backup is used only by GPD Global factory.)
```

```
Remove last backup disk
```

```
Write Protect all disks. Then press Enter to continue.
```

5. Press Enter to exit the Data Backup window.

## Application Backup

**IN EFFECT AS OF FLOWare software version patch-2.9.3-USButils**

Detailed instructions for routine backups and disaster recovery are provided in *Dispenser Software Recovery* (PN 22144015).

**OBSOLETE AS OF FLOWare software version patch-2.9.3-USButils**

An application backup includes everything included in a Data backup plus the current version of FLOWare operating software. Application backups can be made on floppy diskettes, USB devices, or on the primary hard disk /HD0 of the machine.

- [Application Backup to USB](#) (pg 6.20)
- [Application Backup to Floppy Disk](#) (pg 6.22)
- [Application Backup to Slave Hard Drive: /hd1](#) (pg 6.24)
- [Application Backup to Primary Hard Drive: /hd0](#) (pg 6.25)

### Application Backup to USB

To create an application backup on a USB device:

1. Change the system password to an access right that permits access to Configuration.
2. From the main menu bar, click Utilities > Backup > Application. A prompt displays in the GPD-Data Backup window:

```
GPD Global Dispenser Application Backup
```

```
Back up to USB Device?(Y/n) y
```

```
Press ENTER to use the default backup directory /dos/c/
Backup;
```

```
Otherwise, enter the name of the desired directory:
```

3. Choose either the typical response of using the default **Backup** directory by pressing Enter, or, if a different name is desired, enter it now; a directory with the new name will be created automatically on the USB device.

```
Current Backups are:
```

```
The system lists all backups in the selected directory.
```

```
Enter a file name for this backup: filename
```

4. Enter a file name avoiding the use of spaces, dots, and extensions. Name length is not limited.

```
Do you really want to perform an Application Backup
```

```
To /dos/c/Backups/filename (Y/n) y
```

The system begins the backup. Ignore the following error (this information is for GPD Global use only).

```
Pax: /etc/samba.setup : No such file or directory
```

```
Pax: /etc/start.tcpiip : No such file or directory
```

The system displays the following prompt to indicate the size of the backup:

```
Each dot is 10 seconds, 40 dots per line.
```

```
.....
```

The system finishes the backup with:

```
* * * *
```

```
Remove the USB device
```

```
Remove all USB storage devices now.
```

```
Remove all USB storage devices now.
```

```
Remove all USB storage devices now.
```

5. Remove the USB device from the machine (or the system will continue repeating the prompt). The following prompt displays:

```
Backup Complete
```

```
Bkset: DB connection
```

```
Done Press Enter to Continue
```

6. Press Enter to exit the Application Backup window.

## Application Backup to Floppy Disk

A typical application backup will require the use of 10 floppy disks, making this medium inconvenient for this backup process. It is recommended that Application Backups be created on either a USB device or the hard disk.

To create an application backup on floppy disk(s):

1. Change the system password to an access right that permits access to Configuration.
2. From the main menu bar, click Utilities > Backup > Application. A prompt displays in the GPD-Data Backup window:

```
GPD Global Dispenser Application Backup
```

```
Back up to USB Device?(Y/n) n
```

```
Back up to backup hard disk /hd1? (Y/n) n
```

```
Backup is currently scheduled for placement on floppy disks.
```

```
Do you want to back up to the hard drive hd0 instead?(y/N) n
```

```
Do you really want to perform an Application Backup to /dev/
fd0 (Y/n)? y
```

The machine begins preparing for the backup and leads to the following prompt:

```
Do you want a reloadable backup on QNX disks? (y/N) y
```

A reloadable backup simply refers to a backup from which you can restore while at the machine.

3. Ignore all error messages preceding the following information and prompt:

```
Each dot is 10 seconds, 40 dots per line. ....
```

```
Total archive size is: 44266 k (size will vary, however, most application
backups will be close to the value shown here.)
```

```
Requiring about 10 disk(s).
```

```
Do you need to format some floppies now?(y/N) y
```

4. ALWAYS format the number of disks suggested by the machine. After formatting all disks, the following prompt displays:

Vol: When drive light goes out insert disk 1 and press return

When the backup is complete, the following prompt displays.

Remove last backup disk

Write Protect all disks. Then press Enter to continue.

5. Press Enter to exit the Data Backup window.

## Application Backup to Slave Hard Drive: /hd1

To create an application backup on /hd1, the system slave hard drive:

1. Change the system password to an access right that permits access to Configuration.
2. From the main menu bar, click Utilities > Backup > Application Backup.
3. In the **GPD - Application Backup** window, respond to the prompts as follows:

```
Back up to USB device? (Y/n) n
```

```
Back up to backup hard drive /hd1 ?(Y/n) y
```

```
Enter a file name for this backup: xxxxxx
```

4. Enter the backup file name using letters and numbers only; do not use spaces.

```
Do you really want to perform an Application Backup to /hd1/  
Backups/xxxxxx (Y/n)? y
```

5. At this point, the backup process begins. Near the end of the process, expect to see the following messages:

```
Building Setup Files, please wait...
```

```
Backing up: Application Backup
```

```
To: /hd1/Backups/xxxxxx
```

```
Each dot is 10 seconds, 40 dots per line.
```

```
. . .
```

```
Bakup Complete
```

```
Bkset: DB Connection
```

```
Done: Press ENTER to continue
```

6. Press Enter to complete the backup process and exit the Application Backup window.

## Application Backup to Primary Hard Drive: /hd0

To create an application backup on /hd0, the system primary hard drive:

1. Change the system password to an access right that permits access to Configuration.
2. From the main menu bar, click Utilities > Backup > Application Backup.
3. In the **GPD - Application Backup** window, respond to the prompts as follows:

```
Back up to USB device? (Y/n) n
```

```
Back up to back up hard drive /hd1 ?(Y/n) n
```

```
Application back up is currently scheduled for placement on floppy disks.
```

```
Do you want to back to the hard drive hd0 instead? (Y/n) y
```

4. when the following prompts display:

```
Press ENTER to use the default backup directory;
```

```
Otherwise, enter the name of the desired directory:
```

```
choose either the typical response of using the default directory by pressing Enter, or, if a different name is desired, enter it now; a directory with the new name will be created automatically and used to store the application backup.
```

```
Current Backups are:
```

```
The system lists all backups in the selected directory.
```

```
Enter a file name for this backup: xxxxxx
```

5. Enter a file name avoiding the use of spaces, dots, and extensions. Name length is not limited.

```
Do you really want to perform an Application Backup to /hd0/ Backups/xxxxxx (Y/n)? y
```

6. At this point, the backup process begins. Near the end of the process, expect to see the following messages:

```
Building Setup Files, please wait...
```

```
Backing up: Application Backup
```

```
To: /Backups/xxxxxx
```

```
Each dot is 10 seconds, 40 dots per line.
```

```
. . .
```

```
Bakup Complete
```

```
Bkset: DB Connection
```

```
Done: Press ENTER to continue
```

7. Press Enter to complete the backup process and exit the Application Backup window.

## Full System Backup

### **IN EFFECT AS OF FLOWare software version patch-2.9.3-USButils**

Detailed instructions for routine backups and disaster recovery are provided in *Dispenser Software Recovery* (PN 22144015).

### **OBSOLETE AS OF FLOWare software version patch-2.9.3-USButils**

A full system backup is a comprehensive backup of all data and all operating software including FLOWare operating software, X-Windows, Sybase, and QNX.

This type of backup can only be made on the slave secondary hard disk /HD1.

To create a Full System Backup:

1. Change the system password to an access right that permits access to Configuration.
2. From the main menu bar, click Utilities > Backup > Full System.
3. Take action according to which window displays:

**Table 75: Slave Drive Condition Indicated by Window**

Window Displayed	Action Required
GPD - Full System Backup	This window indicates that the Slave Drive has been recognized. Continue with the standard instructions.
GPD - Application Backup	This window is likely to indicate one of the conditions listed below; inspect and resolve problem(s) and restart the machine until the system recognizes the Slave Drive and displays the GPD - Full System Backup window during this operation.  * The Slave Drive/Backup Hard Drive is not present on your machine.  * The cable connections to the Backup Hard Drive are faulty (scenario A) - The Primary Hard Drive is connected to the MASTER cable connector on the drive end and the EIDE Port 1 of the CPU board. The drive is jumpered as a Master drive. This is recognized by the computer as the PRIMARY MASTER Drive.
GPD - Application Backup (continued)	* The cable connections to the Backup Hard Drive are faulty (scenario B) - The CDROM is connected with a separate cable at the Master connector end while the Slave Hard Drive is connected to the Slave connector end of the same cable. The other end of this shared cable will be connected to EIDE Port 2 of the CPU Board. The CDROM will be recognized as the SECONDARY MASTER DRIVE and will be jumpered as a Master while the Slave hard drive will be recognized as the SECONDARY SLAVE and must be jumpered as a Slave. Refer to the jumper settings shown on the drive itself if there is any question as to the proper jumper configuration.  * EIDE Port #2 is not enabled in the CMOS Setup configuration.  * EIDE Port #2 is faulty on the CPU board.

GPD Global Dispenser System Backup

OK to erase backup hard drive /hd1 ?(Y/n) y

4. The primary hard drive is /hd0, and the slave hard drive is /hd1. A complete wipe of the contents of the slave drive is necessary prior to performing a full system backup, so answer Y.

Do you really want to perform a System Backup to /hd1 (Y/n)?  
y

5. Normally, the drive has already been partitioned and checked so this will not be necessary. If, however, the Slave Drive is brand new, the system needs to mount a partition and perform a surface check. After this operation is completed, the system ends the backup session. You must then start the full system backup again from the beginning.

Typically the machine will prompt:

Erasing backup hard drive /hd1.

Wait...

Press ENTER to continue

6. Press Enter. At this point, the system prepares to perform the backup and displays the following:

Beginning Backup

If any error messages are reported, record them exactly as they appear and contact GPD Global service personnel

Wait . . .

Pax: /Backups : No such file or directory

The above error message is common. It will always display if there are no application backups found on the master hard drive. If this prompt displays, ignore it.

The full system backup can last anywhere from 5 minutes to 20 minutes depending on the amount of data and the speed of data transfer. A typical backup usually takes 7 to 8 minutes.



**CAUTION:** Do not attempt to end the procedure in any way until you receive the following message:

Backup Complete Bkset: DB Connection Done : Press ENTER to continue

7. Press ENTER to end the full system backup procedure and exit the window.

## FAQs for Routine Backups

**NOTE:** Additional FAQs are available from our Service & Support site at <http://helpdesk.gpd-global.com/support/solutions>.

### **IN EFFECT AS OF FLOWare software version patch-2.9.3-USButils**

Detailed instructions for routine backups and disaster recovery are provided in *Dispenser Software Recovery* (PN 22144015).

### **OBSOLETE AS OF FLOWare software version patch-2.9.3-USButils**

#### **Which type of backup will return the system to operational status as quickly as possible?**

GPD Global dispensers use a redundant database system to protect data stored in the database from corruption. This method tests the database integrity at each boot. In addition, backup utilities are included on the machine for creating off-line backups:

- A *data only backup* creates an external backup (either on floppy disk or USB [if equipped]) of all the unique files on the machine.
- An *application backup* creates an internal backup (on the same partition from which the dispenser operates or a separate internal hard drive) of the FLOWare control software.
- A *full system backup* creates a backup of all the files on the primary drive to the secondary internal drive which can restore the dispenser to operation using the included restore utility.

#### **Does a “data” backup contain enough information to restore the system to operational status after the OS is installed?**

A data backup includes the complete database and redundant files (i.e., all information entered into the editor for customer applications and high level configuration) and the configuration files (boot files, network configuration [if applicable], machine specific configuration, unique servo configuration [tunes and contour map]).

#### **Same question as above for the “application” backup.**

An application backup includes all the FLOWare control software required to operate the dispenser.

#### **What are the key differences between the “data” and “application” backups?**

A data backup contains all the unique information required for customer application(s) while an application backup contains the files necessary to access the FLOWare control software.

#### **Is the backup hard drive a separate physical drive or a partitioned drive?**

The backup hard drive is a separate physical drive.

#### **Will physically replacing the hard drive with a “mirror” hard drive completely restore the system?**

Backup tools not included with the dispenser are not supported nor recommended for use. The dispenser uses a specialized operating system that is not compatible with many such tools which results in backups which cannot be restored.

#### **How do we mirror the main hard drive to a hard drive that will be kept off site?**

An excellent way to create a “mirror” of the primary drive is to use the full system backup utility included on the dispenser. If an external system backup is desired or required, use the full system restore process to create a second primary drive. The second primary drive can then be stored externally.

## Troubleshooting

### Boot the System

The boot sequence initializes the computer, loads the operating system, and implements FLOWare software programming changes. Typically, users will use the following *Boot with Shutdown* procedure as a normal step in some procedures, such as teaching base locations. Only in special circumstances will a user be directed to use the *Boot with Reboot* procedure.

#### Boot with Shutdown

Some FLOWare software programming functions, such as teaching base locations, require the system to be booted before changes will take effect.

To boot the system:

1. From the main menu bar, click on Operations > Shutdown System. A shutdown verification prompt displays. Click YES to shutdown the system, or CANCEL to abort the shutdown. Wait until a System Stopped prompt displays, then power off the system per the normal power off procedure.
2. Power on the system per the normal power on procedure. Wait until the system has completed the boot sequence before proceeding with regular operations.

#### Boot with Reboot

The Reboot function is intended for use only by GPD Global personnel. In special instances, the GPD Global Service Department may direct a user on the usage of this feature in order to accomplish a particular objective. Booting the system using the Reboot function requires a special access right which in turn requires a knowledge of the intricacies and variables involved in working at this level of the control software.



**WARNING** The content of this section is NOT recommended for use by anyone besides GPD Global personnel or those working under the direct guidance of GPD Global personnel. Improper application of this information can lead to serious complications in FLOWare Software operations. Any non-GPD Global employee who uses this information beyond the stated application specified by GPD Global Service Department personnel is in danger of causing personal injury and invalidating their machine warranty.

<b>ATTENTION</b> <a href="#">Le contenu de cette</a>	<b>WARNUNG</b> <a href="#">Der Inhalt dieses</a>	<b>ATTENZIONE</b> <a href="#">Il contenuto</a>	<b>ADVERTENCIA</b> <a href="#">NO SE RECOMIENDA</a>
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To reboot the system:

1. Change the password to an access right that permits access to System.
2. From the main menu bar, click on Operations > Reboot. A boot verification prompt displays.
3. Click YES to boot the system, or CANCEL to abort the reboot.
4. Wait until the system has completed the boot sequence before proceeding.

### Software Recovery

Installation of software on the dispenser for recovery purposes is detailed in documentation separate from this manual. For details, refer to [Software Installation](#) (pg 6.13).

# 7 Appendices

**NOTE:** This section provides information which, for the most part, *should only be used while under the direct guidance of GPD Global personnel.*

- [Units of Measure](#) (pg 7.1)
- [Machine Controls](#) (pg 7.4)
- [System Functions](#) (pg 7.7)
- [IO Viewer](#) (pg 7.8)
- [VEdit in Shell Windows](#) (pg 7.12)
- [Interfacility Communications](#) (pg 7.15)
- [Screen Grabber](#) (pg 7.16)

## Units of Measure

### Global Default for Units

Global default settings control whether the control software displays field value units-of-measure using the English system or the metric system. If necessary, these default settings can be changed.

Valid units of measure can be found at [Unit Abbreviations](#) (pg 7.2).



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<b>ATTENTION</b> <a href="#">Le contenu de cette</a>	<b>WARNUNG</b> <a href="#">Der Inhalt dieses</a>	<b>ATTENZIONE</b> <a href="#">Il contenuto</a>	<b>ADVERTENCIA</b> <a href="#">NO SE RECOMIENDA</a>
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To change the units-of-measure global default settings from the English system to the metric system or vice versa:

1. From the main window menu bar, click on Configuration > [Dispenser Configuration](#) (pg 3.136). The GPD - Edit Configuration window will display.
2. Scroll down until you find the following text.  

```
DisplayUnits = n
WeightUnits = n
TemperatureUnits = n
```

Change the DisplayUnits value as needed: 0 represents metric, 1 represents English. DisplayUnits determines which system of units is used to display distances, speeds, accelerations, and most other numeric values. If not set, WeightUnits and TemperatureUnits will revert to the same setting as used for DisplayUnits.

## Unit Abbreviations

Units-of-measure used in value fields can be displayed using the English or metric system. This can be changed on the fly during field value entry or globally by changing default settings.

Units of measure can be entered at the same time a value entry is made. The units entered need not be the same as the units displayed. The entered value will be converted properly and displayed automatically when the entry is applied.

If a more global change is needed to the system of units, the global default settings may be altered - refer to [Global Default for Units](#) (pg 7.1). The default settings for weight units and temperature units can be set independently of all other display units (distances, speeds, accelerations, and most other numeric values), but are usually set to match. Contact the GPD Global Service Dept. for further details.

Abbreviations recognized by the system for valid units-of-measure are defined in the following table.

**Table 76:** Recognized Units-of-Measure Abbreviations

Aspect	Valid Units	Description
Acceleration	mm/s/s cm/s/s m/s/s in/s/s ft/s/s	millimeters per second squared centimeters per second squared meters per second squared inches per second squared feet per second squared
Angular Acceleration	rev/s/s rev/m/m	revolutions per second squared squared revolutions per minute squared
Angular Velocity	rpm rps	revolutions per minute revolutions per second
Angle (Object Rotation)	d deg r rad grad rev	degree degree radian radian gradient revolution
Area	sq_mm sq_cm sq_in sq_ft c_mil	square millimeter square centimeter square inch square foot cubic millimeter
Distance	nm um mm cm dm mil in " ft '	nanometer (x 10 <sup>-9</sup> ) micron (micrometer) (x 10 <sup>-6</sup> ) millimeter (x 10 <sup>-3</sup> ) centimeter (x 10 <sup>-2</sup> ) decimeter (x 10 <sup>-1</sup> ) 0.001 inch inch inch foot foot
Flow	ml/sec cc/sec	milliliter per second cubic centimeter per second

*\* Applicable to mixer valve only*

**Table 76:** Recognized Units-of-Measure Abbreviations (Continued)

Aspect	Valid Units	Description
Force	kg mg g oz lb	kilogram milligram gram ounce pound
Pressure	kPa Pa bar psi mb in mm atm n/sqm	kilo Pascal Pascal Bar pounds per square inch millibar inch of Hg millimeter of Hg atmosphere Newton per square meter
Temperature	C c F f R K	Celsius Celsius Fahrenheit Fahrenheit Rankine Kelvin
Time	ms s us ns m h d	millisecond second microsecond nanosecond minute hour day
Velocity	mm/s cm/s in/s mil/s dm/s m/s ft/s rev/s * cc/s * cc *	millimeter/second centimeter/second inch/second mil/second decimeter per second meter per second foot per second revolutions per second cubic centimeter per second cubic centimeter per second
Volume	cc ml cu_in cu_ft fl_oz l qt pt	cubic centimeter milliliter cubic inch cubic foot fluid ounce liter quart pint
Weight	kg mg g oz lb	kilogram milligram gram ounce pound

*\* Applicable to mixer valve only*

## Machine Controls

Machine Controls allow you to exercise direct control over the dispenser by allowing you to directly manipulate inputs and outputs. A drop-down menu of manual machine choices is available by clicking on Machine Controls in the menu bar of the main window.



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A brief explanation of each machine control choice follows:

### Custom Ctrl's

Custom controls allow the user to directly manipulate various inputs and outputs for some of the devices on the dispenser. Custom controls are typically used to activate a mechanical operation; for example, to extend/retract a board stop, raise/lower a lifter late, turn on/off the conveyor belt, etc. Note that the affected device will be activated *IMMEDIATELY* when these controls are used.

The system must be configured to display the Custom Ctrl's option on the Machine Controls pull-down menu. The contents of the pull-down menu is likely to differ for each machine since it can be customized for local use.

### Lifter Controls

These controls move the lifter plate without damaging fixtures or confusing the program as manual manipulation might. These functions may be performed when adjusting lifter pins or during other setup operations. Note that the affected device will be activated *IMMEDIATELY* when either of these controls is used.

### Offline Operations

Displays a dialog allowing the operator to manually purge a valve. It also allows the filling of a syringe with material or the weighing of a shot of material independently from a program if the dispenser is equipped with a syringe fill station or a precision scale.

### Tilt Adjust

Provides an established operation sequence for purposes of adjusting the tilt position of a Dual Rotation Fixture, one of the many optional mechanical fixtures available from GPD Global. More at [Tilt Adjust Fixture Controls](#) (pg 3.126).

### IO Viewer

Used as a maintenance or troubleshooting tool, this window allows you to manipulate inputs and outputs directly. Because it affords a constant view of the state of any selected set of machine inputs and the ability to control any selected machine outputs, the IO Viewer is usually only available to the machine administrator or programmer. For details, refer to [IO Viewer](#) (pg 7.8).

### View Pressure/Temp

This tear-off window displays the current air pressure, needle temperature and material temperature for each head, as well as heater temperatures in the work area. This window allows the operator to monitor these parameters continuously.

Use the View Pressure/Temp window when your dispenser is equipped to handle pressure and temperature control through the software rather than with a gauge and switch (typically located on the front control panel).

### Set Pressure/Temp

This window is typically used for set up procedures when the system is equipped to handle pressure and temperature control through the software instead of gauge and switch hardware.

[Set Pressure/Temperature](#) (pg 5.99) allows pressure and temperature values to be set independently from values in the program. The operator can set these values when no program is running. The program uses the value set in Air Pressure and the selection made from the drop down menu overrides program actions.

#### Example:

- ASSUMPTION 1: The program calls for 5.0 psi to turn off after a period of time.
- ASSUMPTION 2: In the Set Pressure/Temperature window, Air Pressure is set to 8.0 psi and ON is selected from the drop down menu.
- RESULTS: Air pressure will change to 8.0 psi and not turn off as defined in the program.

### LensAdjust

Provides programmable camera lens adjustment for any dispenser configured with ClearVu Vision™. Use LensAdjust to adjust the focus controls while monitoring focus results in the live video screen that displays alongside the focus controls panel. For details, refer to [Lens Focus](#) (pg 3.77).

### Clear Signal

The system is capable of generating a signal to be used remotely to indicate out-of-range weight on the optional precision scale. This signal is intended to ring a bell in a location perhaps 1,000 feet from the machine and is not cleared remotely; it must be cleared by clicking on Machine Controls > Clear Signal.

### MV50/400 Controls

Select from two choices for the optional MV50/400 Metering Valve:

- MV50/400 Home activates the homing of the valve plungers; they home to their upper-most position (linear stage).
- MV50/400 Jog provides coarse manual control over the downward movement of the valve plungers. Keep the lower left trackball button depressed until the valve plungers move the cartridge valves down as far as desired. Downward movement ceases as soon as you release the trackball button.

## Using Custom Controls

Before proceeding, review the background information available here: [Custom Ctrl's](#) (pg 7.4).



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To use Custom Ctrl's:

1. Enable the Custom Ctrl's feature by reconfiguring the configuration file.
2. From the main menu bar, click on Machine Controls > Custom Ctrl's.
3. Click on the dashed line at the top of the tear-off menu that displays and move it to a convenient place on the screen.
4. Most menu items are toggle controls - click them once to activate a device; click them again to deactivate the same device. Click on the feature you wish to control - **the device will be activated immediately.**



**WARNING:** The affected device will be activated *IMMEDIATELY* when these controls are used.

5. When you are done using the Custom Ctrl's feature, disable it in the configuration file.

## System Functions

System Functions provides tools for direct manipulation of the software systems that run the dispenser. A drop-down menu of choices is available by clicking on System Functions in the menu bar of the main window.



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A brief explanation of each system function choice follows:

### ISQL

SYBASE interactive SQL. Familiarity with an SQL language and the structure of the data base is required. Used to edit the data base directly.

### Shell

Initiates a Korn shell. Familiarity with UNIX-like systems and the structures of the dispenser software is required. Used for any QNX activities.

### Edit Any File

This can be used to edit any files accessible to the dispenser. Familiarity with VEdit and the structure of the dispenser software is required to edit files here. For details, refer to [VEdit in Shell Windows](#) (pg 7.12).

### Show Common Area

Debug tool. Displays the data common to all currently running processes.

### Edit sysinit

### Edit .profile

### Edit .xinitrc

### Edit startup.sh

### Edit .mwmrc

Starts a VEdit shell to edit the specified file. Familiarity with UNIX-like Edit profile systems and the structure of the dispenser software is required. Note that any local changes may be erased when a software update is installed.

## IO Viewer

The IO Viewer may be used as a maintenance or troubleshooting tool to help determine if a device input or output (I/O) is wired properly and receiving the correct voltage. You may force an output device with IO Viewer by clicking on the box next to the I/O label and observing the results. An input cannot be forced, but you can *flag* a sensor and then observe the box next to the I/O label to see if it changes state, or you can observe if an I/O is reading a change of condition.

You may select one or multiple I/Os or all I/Os for a device, turn each output on/off or flag an input device, and then observe the results. For a list of inputs and outputs specific to your machine, refer to the *Input/Output Listing* in the *Mechanical & Electrical Reference Documents* section of the dispenser documentation package.

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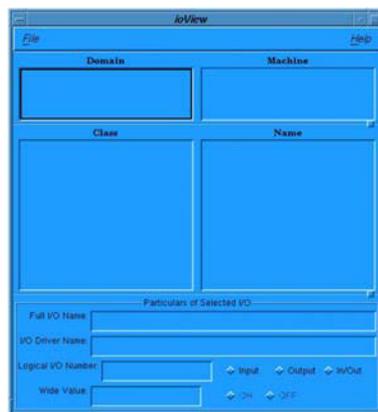
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**NOTE:** Use care when working with IO Viewer functions. A device may respond immediately when the corresponding input or output is activated. Prior to activating an I/O, be sure you know which device it controls, and be sure to clear the area surrounding the device to be tested in order to prevent equipment damage.

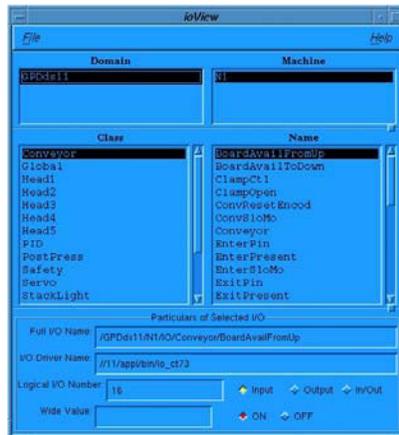
**NOTE:** A successful test with the IO Viewer is not a guarantee that a device is configured properly in the control software. Nor is a lack of visible state change viewed on the IO Viewer a guarantee that a sensor has not changed state; the resulting flicker from a state change may occur too quickly to be visible.

To use IoView:

1. Change the system password to an access right with access to Configuration.
2. From the main menu bar, click Machine Controls > IO Viewer. IoView displays.

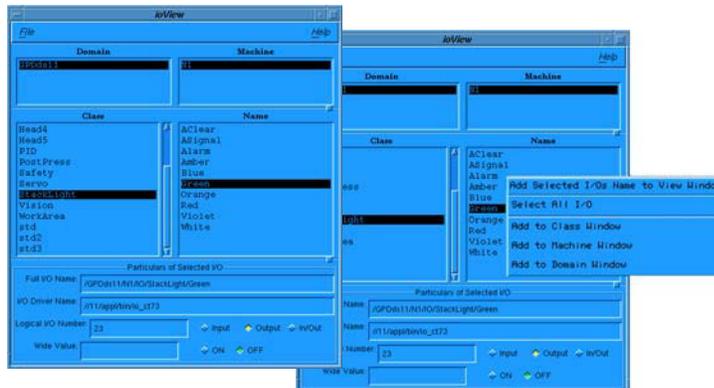


- Click on File > Refresh I/O Information. All available I/O classes display for the current domain and machine.



- Display the I/Os for a particular class by highlighting a selection in the Class pane. A list of I/O names associated with that class displays in the Name pane.

For example, the StackLight class has been selected in the screen shown below at left, resulting in all names associated with the StackLight class being listed in the Names pane.



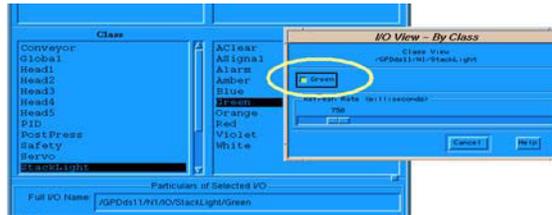
- Select either a single I/O, multiple I/Os, or all I/Os.

**Table 77: Selecting I/Os**

I/O Quantity	Selection Instructions
one	<ol style="list-style-type: none"> <li>Highlight the name of the I/O you wish to select. For example, the StackLight I/O for Green has been selected in the screen shown above at left.</li> <li>Click the trackball PopUp Menu button (lower right-hand button). A pop-up menu displays like the one shown in the screen shown above at right.</li> <li>Click on the menu choice of Add to Class Window.</li> </ol>
multiple	<ol style="list-style-type: none"> <li>Hold down the CTRL key while clicking the cursor on each I/O name you want to select.</li> <li>Click the trackball PopUp Menu button (lower right-hand button). A pop-up menu displays like the one shown in the screen shown above at right.</li> <li>Click on the menu choice of Add to Class Window.</li> </ol>
all	<ol style="list-style-type: none"> <li>Click the trackball PopUp Menu button (lower right-hand button). A pop-up menu displays like the one shown above at right.</li> <li>Click on the menu choice of Select All I/O.</li> </ol>

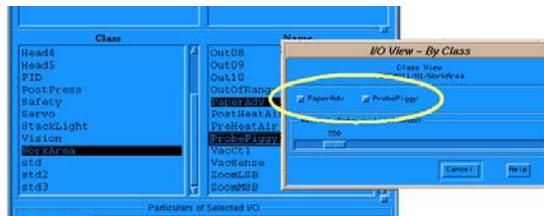
6. Note that the appearance of the IO View By Class window and the types of I/Os displayed in the window may vary somewhat depending on the quantity and type of I/Os selected. The samples shown below illustrate the selection results for a single I/O, multiple I/Os, and all I/Os. Also shown are the different types of I/Os. Each selected I/O name appears as a label with either a toggle box or a value field; the value field indicates a pseudo I/O.

**Single I/O selected** - a single toggle box and label displays for the Green StackLight I/O.

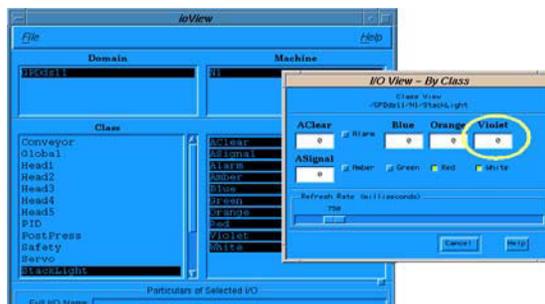


7. Pseudo I/Os are bits of memory used internally by the software; they are not physically connected to an I/O board. A pseudo I/O may contain a value between 0 and 255.

**Multiple I/Os selected** - a toggle box and label for each I/O selected for the WorkArea class.



**All I/Os selected** - the I/O View By Class window expands to accommodate all I/Os selected. **Pseudo I/Os** - display with a value field rather than a toggle box. The Violet, Orange, Blue, AClear, and ASignal I/Os are all examples.



8. If desired, you can add additional I/Os to the I/O View By Class window from other classes.

9. Take action appropriate for each I/O selected:

**Table 78: Using I/Os**

Type of Device or I/O	Action
Output devices	Click the I/O toggle box on and off while observing the response at the associated device. For example, if you click the Green toggle box on and off, the green status tower light should respond by turning on and off.
Input devices	Flag the sensor while observing the associated I/O toggle box for the state changes. For example, manually block and unblock the sensor while observing the toggle box - the toggle box should change states.
Pseudo I/O	A pseudo I/O is the same as other types of I/Os except it is just memory in the computer. Pseudo I/Os can be changed, read, or treated as both an input or an output. To treat a pseudo I/O as an output, type a value in the associated value field. A pseudo I/O may contain a value between 0 and 255.

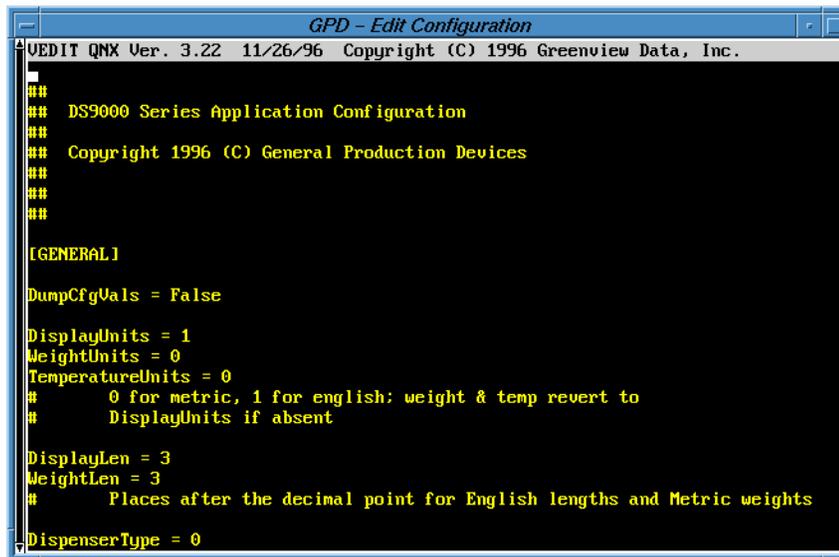
10. When you are done working with the IO Viewer, close it by clicking on File > Exit. All windows subordinate to IoView will also be closed.

**NOTE:** A successful test with the IO Viewer is not a guarantee that a device is configured properly in the control software.

## VEdit in Shell Windows

Occasionally, you may need to edit a file in a shell-style window environment. The file editing utility provided for this function is VEDIT. As an example, you would use VEDIT to change the global units-of-measure default setting by editing the appropriate character in the configuration file.

Example of a file displayed in a shell-style window.



```

GPD - Edit Configuration
VEDIT QNX Ver. 3.22 11/26/96 Copyright (C) 1996 Greenview Data, Inc.
###
### DS9000 Series Application Configuration
###
### Copyright 1996 (C) General Production Devices
###
###
###
[GENERAL]
DumpCfgVals = False
DisplayUnits = 1
WeightUnits = 0
TemperatureUnits = 0
# 0 for metric, 1 for english; weight & temp revert to
# DisplayUnits if absent
DisplayLen = 3
WeightLen = 3
# Places after the decimal point for English lengths and Metric weights
DispenserType = 0

```



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## Navigation Controls

There are several ways within VEDIT to accomplish typical editing features. You can use key stroke combinations, the mouse, or the menu. Here are some hints on how to move around in a file during the edit process:

- Use the ARROW keys to move the cursor around the window. • Press the PAGE UP key or PAGE DOWN key to view the previous or next window of text within the file.
- Use the F1 key to display the help menu. Press the ESC key to exit the help menu.
- To view the menu bar at the top of the window, press F10. To remove all menus, press the CTRL and C keys.

## Search

To search a shell file for specific text, press the F2 key, enter the text you want to locate, and press ENTER.

Press the F3 key for an additional search on the same text. This can be repeated until the end of the file is reached.

To exit the search function, either press the ESC key twice or press the UP or DOWN arrow key to move the cursor out of the selected text.

## Copy Text

1. Put the cursor on the first line of the block to be moved.
2. Press F10 to display the menu.
3. Use the arrow keys to select Block > Set Line Marker. Press ENTER.
4. Use the arrow keys to find the end of the block that you want to move.
5. Press F10 to display the menu.
6. Use the arrow keys to select Edit > Copy to Scratchpad. Press ENTER.

## Copy & Cut Text

1. Put the cursor on the first line of the block to be moved.
2. Press F10 to display the menu.
3. Use the arrow keys to select Block > Set Line Marker. Press ENTER.
4. Use the arrow keys to find the end of the block that you want to move.
5. Press F10 to display the main menu.
6. Use the arrow keys to move to Edit > Cut to Scratchpad. Press ENTER. Notice that all highlighted text lines have been deleted.

## Paste Text

1. Position the cursor on the line immediately following the place where text is to be inserted.
2. Press F10 to display the main menu.
3. Use the arrow keys to select Edit > Paste Scratchpad. Press ENTER. The previously deleted lines will now be inserted.

## Copy & Paste Text Between Files

To copy text from file A and paste it into file B:

### Copy text from file A:

---

1. Put the cursor on the first line of the block to be copied.
2. Press F9 to start a block.
3. Use the arrow keys to find the end of the block to be copied.
4. Press F9 to end the block.
5. Press the ALT + B keys and then the D key.
6. Enter an arbitrary file name and press ENTER.

### Paste text into file B:

---

1. In the file B window, position the cursor on the line immediately following the place where text is to be inserted.
2. Press the ALT + E keys and then the I (for Insert) key.
3. Enter the file name assigned during step 1.f and press ENTER.

## Save Edit

In addition to being able to save the file prior to exiting VEDIT, the file can be saved during the editing process by selecting the File > Save and Continue menu selection.

## Exit Edit

There are several ways to end an edit session:

- Type *exit* and press ENTER.
- Press the ALT and X keys simultaneously.
- Display the menu by pressing the F10 key. Then choose File > Exit, and press ENTER.

Using either of these methods to end an edit session will prompt you to either save the file before exiting or to abandon any changes and exit. Answer YES to save the file before exiting or answer NO to exit without saving.

## Interfacility Communications

Interfacility communications are addressed in a separate document in which procedural details guide you in how to set up TCP/IP (Transmission Control Protocol/Internet Protocol) communications between a GPD Global dispenser and a customer-supplied Windows or UNIX PC to establish the necessary communication to transfer data between the two systems. Request the following document from GPD Global:

*TCP/IP Communications between Dispenser & Windows or UNIX PC* (part no. 22100056M)

## Screen Grabber

Use a screen grab process to capture a FLOWare software window as a file. You have the option of capturing a specific window, the whole screen, or a select area of a window or screen. Follow the procedure pertinent to the version of FLOWare software installed on your dispenser:

- [Screen Grabs \(FLOWare Software v 2.9+\)](#) (pg 7.17)
- [Screen Grabs \(FLOWare Software v 2.7-2.8\)](#) (pg 7.22)
- [Screen Grabs \(FLOWare Software v 2.6 & earlier\)](#) (pg 7.27).



7. You'll notice that in the lower right corner of the control panel, just above the «Quit» button is a button labeled «Grab»:



8. Clicking the «Grab» will open the Screen Grab Dialog:



9. You will use each of the controls/parameters in this dialog differently depending on which of the following scenarios you're using:

#### Delay X Seconds

Setting this value to some number larger than zero has two effects: first, it enables the AutoGrab button and, secondly, it causes a delay of that number of seconds between the time you tell the program to begin the grab and the time when it actually does the grab. This is very useful when capturing menus or other items which require some action from the mouse.

#### Hide XV Windows

This tells xv to hide all of its windows prior to beginning the grab.

#### Grab

Begins a screen grab. Once you have pushed this button, clicking the «bottom left trackball button» will select the window to grab. Optionally, clicking the «top right trackball button» will allow you to grab an arbitrary portion of the screen by drawing a rectangle around the area you want, or clicking the «bottom right trackball button» cancels the screen grab.

#### AutoGrab

Begins a screen grab after the specified number of seconds. The window in which the mouse resides when the time expires is grabbed. This is very handy for capturing menus and other popup items.

#### Cancel

Cancels the screen grab.

10. After grabbing an image, that new image will appear in the window which initially held the splash screen. All images may be viewed in that window.

### Grab a Single Window

1. Click Grab button on the main control panel.
2. Click the Hide XV Windows check box.
3. Click the Grab button.
4. Click on the window you wish to grab.
5. Save the new image file.

### Grab a Partial Window

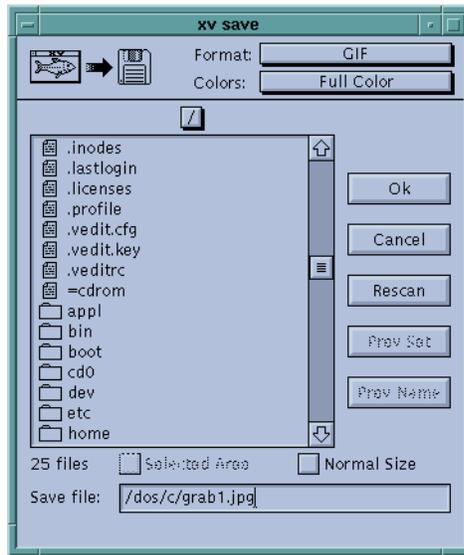
1. Click the Grab button in the main control panel.
2. Click the Hide XV Windows check box.
3. Click the Grab button.
4. When the XV windows have disappeared, use the «middle button» to draw a rectangle around the area you wish to grab.
  - a. When you release the button, XV will grab the region you defined.
  - b. If the region is not exactly what you wanted, simply repeat the procedure until you get the desired area.
5. Save the new image file.

### Grab Window & Menu

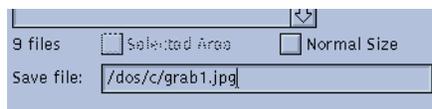
1. Click the Grab button in the main control panel.
2. Click the Hide XV Windows check box.
3. Click the Grab button.
4. Enter some number into the Delay X Seconds area. Typically, 3-5 seconds should be enough.
5. Click AutoGrab
6. At this point you have the number of seconds you entered in which to select the window with the menu in it and get the menu displayed by clicking and holding on the menu's button. Simply hold the button (keeping the menu visible) until the screen grabber has snapped the image and displays it in its main view window.
7. Save the new image file.

## Saving Image

1. Click Save. A «File Dialog» will appear:



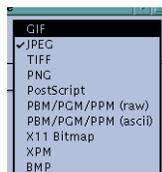
2. Type in the path to your storage media, similar to this:



The path should be one of the following depending upon the media in use:

- For floppy disk: /dos/a/
- For pen/flash drive: /dos/c/

3. Add the file name. If you are capturing more than one screen, it is a good idea to simply number the files, e.g. sgrab1.jpg, sgrab2.jpg, etc.
4. You may specify the type of image file by adding the appropriate extension or by choosing a file type from the Format menu. JPEG is probably your best choice.

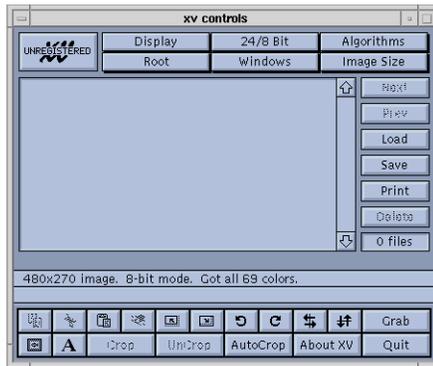


5. Click the Ok button and your image will be saved.

**HINT:** Remember to use proper procedures when [Removing USB](#) (pg 2.9) from the machine.

## Quitting XV

Find the XV Controls window and click the Quit button.





6. You'll notice that in the lower right corner of the control panel, just above the «Quit» button is a button labeled «Grab»:



7. Clicking the «Grab» will open the Screen Grab Dialog:



8. You will use each of the controls/parameters in this dialog differently depending on which of the following scenarios you're using:

#### Delay X Seconds

Setting this value to some number larger than zero has two effects: first, it enables the AutoGrab button and, secondly, it causes a delay of that number of seconds between the time you tell the program to begin the grab and the time when it actually does the grab. This is very useful when capturing menus or other items which require some action from the mouse.

#### Hide XV Windows

This tells xv to hide all of its windows prior to beginning the grab.

#### Grab

Begins a screen grab. Once you have pushed this button, clicking the «bottom left trackball button» will select the window to grab. Optionally, clicking the «top right trackball button» will allow you to grab an arbitrary portion of the screen by drawing a rectangle around the area you want, or clicking the «bottom right trackball button» cancels the screen grab.

#### AutoGrab

Begins a screen grab after the specified number of seconds. The window in which the mouse resides when the time expires is grabbed. This is very handy for capturing menus and other popup items.

#### Cancel

Cancels the screen grab.

9. After grabbing an image, that new image will appear in the window which initially held the splash screen. All images may be viewed in that window.

### Grab a Single Window

1. Click Grab button on the main control panel.
2. Click the Hide XV Windows check box.
3. Click the Grab button.
4. Click on the window you wish to grab.
5. Save the new image file.

### Grab a Partial Window

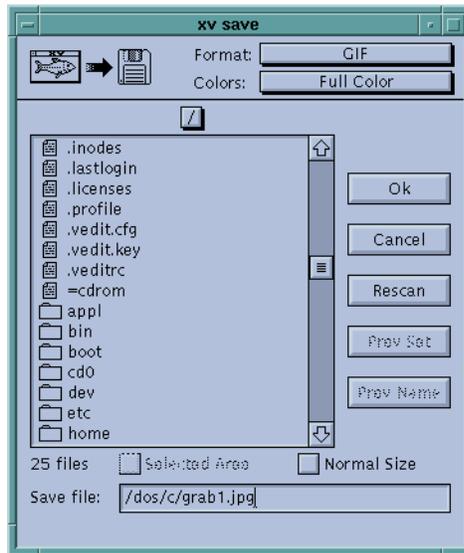
1. Click the Grab button in the main control panel.
2. Click the Hide XV Windows check box.
3. Click the Grab button.
4. When the XV windows have disappeared, use the «middle button» to draw a rectangle around the area you wish to grab.
  - a. When you release the button, XV will grab the region you defined.
  - b. If the region is not exactly what you wanted, simply repeat the procedure until you get the desired area.
5. Save the new image file.

### Grab Window & Menu

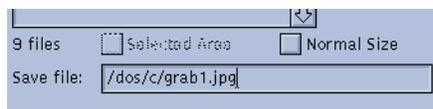
1. Click the Grab button in the main control panel.
2. Click the Hide XV Windows check box.
3. Click the Grab button.
4. Enter some number into the Delay X Seconds area. Typically, 3-5 seconds should be enough.
5. Click AutoGrab
6. At this point you have the number of seconds you entered in which to select the window with the menu in it and get the menu displayed by clicking and holding on the menu's button. Simply hold the button (keeping the menu visible) until the screen grabber has snapped the image and displays it in its main view window.
7. Save the new image file.

## Saving Image

1. Click Save. A «File Dialog» will appear:

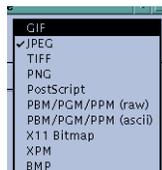


2. Type in the path to your storage media, similar to this:



The path should be one of the following depending upon the media in use:

- For floppy disk: /dos/a/
  - For pen/flash drive: /dos/c/
3. Add the file name. If you are capturing more than one screen, it is a good idea to simply number the files, e.g. sgrab1.jpg, sgrab2.jpg, etc.
  4. You may specify the type of image file by adding the appropriate extension or by choosing a file type from the Format menu. JPEG is probably your best choice.

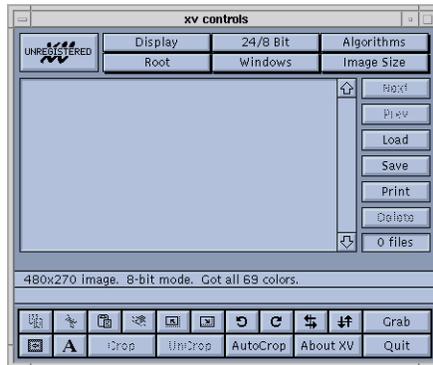


5. Click the Ok button and your image will be saved.

**HINT:** Remember to use proper procedures when [Removing USB](#) (pg 2.9) from the machine.

## Quitting XV

1. Close the XV window by clicking on the <<Quit>> button.
2. To exit the shell, click on the shell window, type `exit` and press the <<Enter>> key.



## Screen Grabs (FLOware Software v 2.6 & earlier)

**IN EFFECT AS OF FLOware software version 2.6**

**IN EFFECT PRIOR TO FLOware software version 2.6**

You may use the screen grab program at any time while the system is running; it should not conflict with any of the basic operations.

### Capture Screen Grab

You must be at a password level of the software that allows access to System activities to perform this procedure. To capture a screen grab:

1. Open the window that you want to capture in FLOware software.
2. Open the screen grabber software:
  - a. Position the cursor at the bottom of the screen until it turns into an X.
  - b. Click and hold down the right mouse button.
  - c. Click on Utilities > Grabber. X-Windows Screen Grabber appears.
3. Define desired Grabber criteria:
  - a. In the Input Option panel, click the screen area selection choice that best fits your needs. Typically, *Click on Window* or *Stretch Rectangle* are used.
  - b. In the Output Format panel, click on BM/XPM3.
  - c. As needed: In the Output Options panel, verify or change the file name that is automatically assigned by positioning the cursor in the *To File* field and then using the right arrow key to scroll to the right until the file name displays. As of this writing, the file path automatically assigned to grabbed files is */home/dispenser*.
  - d. Click OK.
4. Choose one:
  - If you selected *Click on Window*, position the eye cursor on the window to be captured.
  - If you selected *Stretch Rectangle*, position the *right angle* cursor on the upper left corner of the area to be captured, hold the left mouse button down while using the trackball to position the cursor at the lower right hand corner of the area to be captured.
5. X-Windows Screen Grabber reappears for another grab. When you are done grabbing screens, click DISMISS.

### Convert Screen Grab

To convert the file format of the screen grab from .XWD to .GIF:

1. Open the Paint program:
  - a. Position the cursor at the bottom of the screen until the cursor arrow turns into an X.
  - b. Click and hold down the right mouse button.
  - c. Click on Utilities > Paint.

2. Select a screen grab file:
  - a. Click on File > Open.
  - b. Scroll down and highlight the file you created in the previous [Capture Screen Grab](#) (pg 7.27) procedure. File names default to a prefix of *scr#* with a suffix of *xwd*.
  - c. Click BEST GUESS.
  - d. Click OK. The captured screen displays.
3. Convert the file:
  - a. Click on File > Save As.
  - b. Replace the suffix of the displayed file name by typing *.gif* over *.xwd*. For example, a file name of *scr1.xwd* should be changed to *scr1.gif*.
  - c. Click on GIF FORMAT.
  - d. Click OK.
  - e. Click on File > Close.
4. Close the Paint program by clicking File > Quit.

### Copy Screen Grab File to Floppy Diskette

1. Open a Shell:
  - a. Position the cursor at the bottom of the screen until it turns into an X.
  - b. Click and hold down the right mouse button.
  - c. Click on Utilities > Shell.
2. Put a floppy diskette in drive a:
3. Copy GIF file onto the floppy diskette, type:

```
cp /home/dispenser/*.gif /dos/a
```

4. Verify files are on the floppy - type a lower case L to list files:

```
l /dos/a
```

5. Remove GIF files from the hard drive:

```
rm /home/dispenser/*.gif
```

6. Remove original screen capture files from the hard drive:

```
rm /home/dispenser/*.xwd
```

7. To close the shell window, type:

```
exit
```

and press the ENTER key.

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---

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